Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M)

1 Introduction

This document describes the differences between MSC8101 mask set 2K42A and MSC8103 mask set 2K87M. These differences include:

- System Interface Unit (SIU) changes:
 - Internal Memory Map Register (IMMR) MASKNUM field value
 - Addition of the Internal Memory Map Mirror Register (IMMMR)
- Reset changes:
 - Modes
 - Hard Reset Configuration Word (HRCW) layout
- Boot source changes
- Clock changes
 - Clock scheme
 - System Clock Mode Register (SCMR)
 - Addition of the CLKODIS field to the System Clock Control Register (SCCR)
 - Clock modes
 - CLKIN to CLKOUT delay change
 - Maximum clock frequencies change
- Memory map addition of IMMMR
- ORx in UPM mode, bit 27 functionality difference
- Host interface (HDI16) changes
- Direct memory access (DMA) controller transfer code (TC) definitions

CONTENTS

1	Introduction	1
2	Summary of Differences	2
3	SIU	
4	Reset	6
5	Boot	9
6	Clock System	14
7	Memory Map	
8	ORx in UPM Mode	22
9	HDI16	22
10	DMA Transfer Code Definitions	36
11	Interrupt System	36
12	Debugging	36
13	EFCOP	37
14	CPM	
15	Errata	56
A	Bootloader Program	82



Summary of Differences

- Interrupt system changes:
 - CPM Low Interrupt Priority Registers (SCPRR_L and SCPRR_L_EXT) definitions
 - Assignment of interrupt vector 44 to transmission convergence (TC) layer request
- Debugging system changes:
 - JTAG ID
 - EOnCE Status Register (ESR) values
- Removal of Enhanced Filter Coprocessor (EFCOP) support
- Communications processor module (CPM) changes:
 - RISC Controller Configuration Register (RCCR)
 - Dual-port RAM
 - Addition of ROM-based inverse multiplexing for ATM (IMA) microcode
 - Addition of TC layer functionality to the time-slot assigner (TSA) with support through FCC2
 - Addition of new MCC host commands
- Errata
- New bootloader program

2 Summary of Differences

Table 1 lists a summary of the differences between MSC8101 mask set 2K42A and MSC8103 mask set 2K87M.

Table 1. Difference Summary for MSC8101 Mask Set 2K42A and MSC8103 Mask Set 2K87M

Module	Function	MSC8101 Mask Set 2K42A	MSC8103 Mask Set 2K87M
System Interface	Internal Memory Map Register (IMMR)	MASKNUM bit field = 0x02	MASKNUM bit field = 0x12
Unit (SIU)	Internal Memory Map Mirror Register (IMMMR)	Not supported	Added
Reset	Supported modes	Host reset and hardware reset	Host reset, hardware reset, and reduced reset
	Hardware reset configuration word	Seventeen fields defined	Eighteen fields definedsoftware watchdog disable (SWDIS) bit added
Boot	Boot sources supported	From host (HDI16) or external memory (system bus)	From host (HDI16), external memory (system bus), or serial EPROM (I ² C interface)
Clock	Clock Scheme	Clock scheme configures SPLL PDF, SPLL MF, and Bus DF	Clock scheme configures SPLL PDF, SPLL MF, Bus DF, CPM DF, Core DF, CPLL PDF, and CPLL MF
	System Clock Mode Register (SCMR)	Defines seven fields	Defines eight fields
	System Clock Control Register (SCCR)	Defines one field (DFBRG)	Defines two fields (CLKODIS and DFBRG)
	Clock modes	Two valid modes	Twenty-seven valid modes
	CLKIN-to-CLKOUT delay	A function of frequency	Not a function of frequency
	Enabling the DLL	DLL-enabled mode is not supported and designs must use a zero-delay clock buffer.	To enable the DLL, the zero-delay clock buffer recommended for the 2K42A mask set must be placed in PLL-bypass mode or replaced.
	Disabling the DLL	_	For clock modes 5, 6, 46, and 57, apply offsets to DLL-disabled timing.
	Maximum clock frequencies	BCLK/CLKOUT/SCLK = 68.75 MHz CPMCLK = 137.5 MHz DSPCLK = 275 MHz	BCLK/CLKOUT/SCLK = 100 MHz CPMCLK = 200 MHz DSPCLK = 300 MHz

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

Table 1. Difference Summary for MSC8101 Mask Set 2K42A and MSC8103 Mask Set 2K87M (Continued)

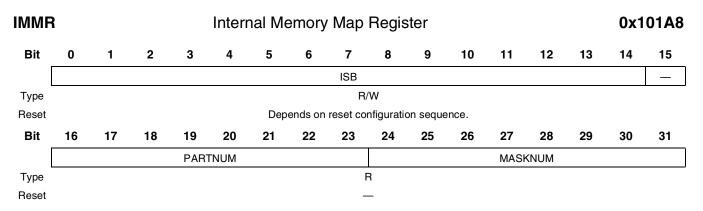
Module	Function	MSC8101 Mask Set 2K42A	MSC8103 Mask Set 2K87M
Memory Map	IMMMR	Not supported	Added
	SCCR	Not supported	Added
Memory Controller	ORx in UPM mode	Bit 27 is a Wait State bit. When bit 27 is set, it add one wait state to the memory cycle.	Bit 27 is reserved.
Host Port (HDI16)	ICR and ISR	ICR and ISR do not support HDI6 bursts of different sizes	ICR and ISR redefined to support HDI16 burst of several sizes.
Direct Memory Access Transfer Code (TC) bit definitions As defined in Table 31 of this document. The Trans are modificulties are modificulties are modificulties are modificulties are modificulties.		The Transfer Code (TC) bit definitions are modified to conform to the original specification as listed in Table 31 of this document.	
Interrupts	SCPRR_L and SCPRR_L_EXT YC1P-YC8P field definitions	The value 100 is reserved.	The value 100 = "TC layer asserts its request in the YCCn position."
	Interrupt vector 44	Reserved	Assigned to TC layer interrupt.
JTAG/	JTAG ID	0x0188101D	0x1188101D
EOnCE system	EOnCE Status Register (ESR) values	ESR[REVNO] = 1 ESR[CORETP] = 0	ESR[REVNO] = 2 ESR[CORETP] = 2
EFCOP	Enhanced Filter Coprocessor	Supported as defined in the MSC8101 Reference Manual	Not supported
СРМ	RISC Controller Configuration Register (RCCR)	Enable RAM Microcode (ERAM) field 3 bits wide	Enable RAM Microcode (ERAM) field changed to 4 bits wide
	Dual-port RAM	24 KB	32 KB
	IMA functionality	Not available	Added
	Serial Interface (SI) and time-slot assigner (TSA)	No TSA layer functionality.	TC layer functionality added to the TSA for ATM with a new interrupt (vector 44)
All	Errata Documented in the current errata list See Table 48 , Table 49 , a details.		See Table 48 , Table 49 , and Table 50 for details.
Bootloader Program	Code list	Available upon request.	Listed in Appendix A

3 SIU

3.1 Internal Memory Map Register (IMMR) Change

The IMMR is updated in 2K87M to reflect the mask change. The MASKNUM bit field has changed to 0x12 to reflect the correct revision level.

3.1.1 2K42A Mask Set IMMR Values

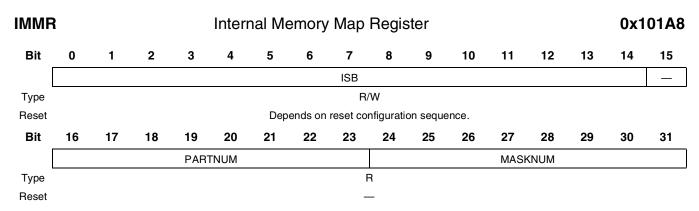


IMMR identifies a specific device as well as the base address for the internal memory map. Software can deduce availability and location of any on-chip system resources from the values in IMMR. PARTNUM and MASKNUM are mask programmed and cannot be changed for any particular device.

Table 2. IMMR Bit Descriptions

Bits	Description	Settings
ISB 0-14	Internal Space Base Defines the base address of the internal memory space. The value of ISB is configured at reset to one of seven addresses; the software can then change it to any value. The default address is based on the ISB bits in the Hard Reset Configuration Word. The default is zero, which maps to address 0xF0000000. ISB defines the 15 msbs of the memory map register base address. IMMR itself is mapped into the internal memory space region. As soon as the ISB is written with a new base address, the IMMR base address is relocated according to the ISB. ISB enables the configuration of multiple-MSC8101 systems.	Implementation-dependent
— 15	Reserved. Write to zero for future compatibility.	
PARTNUM 16–23	Part Number This field is mask-programmed with a code corresponding to the part number of the part on which the SIU is located. It helps factory test and user code that is sensitive to part changes. This field changes when the part number changes. For example, it would change if any new module is added or if the size of any memory module changes. It does not change if the part is changed to fix a bug in an existing module.	The MSC8101 has an ID of 0x50.
MASKNUM 24–31	Mask Number This field is mask-programmed with a code corresponding to the mask number of the part on which the SIU is located. It helps factory test and user code that is sensitive to part changes. It is programmed in a commonly changed layer and should be changed for all mask set changes.	The MSC8101 mask set 2K42A has an ID of 0x02.

3.1.2 2K87M Mask Set IMMR Values



IMMR identifies a specific device as well as the base address for the internal memory map. Software can deduce availability and location of any on-chip system resources from the values in IMMR. PARTNUM and MASKNUM are mask programmed and cannot be changed for any particular device.

Table 3. IMMR Bit Descriptions

Bits	Description	Settings
ISB 0-14	Internal Space Base Defines the base address of the internal memory space. The value of ISB is configured at reset to one of seven addresses; the software can then change it to any value. The default address is based on the ISB bits in the Hard Reset Configuration Word. The default is zero, which maps to address 0xF0000000. ISB defines the 15 msbs of the memory map register base address. IMMR itself is mapped into the internal memory space region. As soon as the ISB is written with a new base address, the IMMR base address is relocated according to the ISB. ISB enables the configuration of multiple-MSC8103 systems.	Implementation-dependent
— 15	Reserved. Write to zero for future compatibility.	
PARTNUM 16–23	Part Number This field is mask-programmed with a code corresponding to the part number of the part on which the SIU is located. It helps factory test and user code that is sensitive to part changes. This field changes when the part number changes. For example, it would change if any new module is added or if the size of any memory module changes. It does not change if the part is changed to fix a bug in an existing module.	The MSC8103 has an ID of 0x50.
MASKNUM 24–31	Mask Number This field is mask-programmed with a code corresponding to the mask number of the part on which the SIU is located. It helps factory test and user code that is sensitive to part changes. It is programmed in a commonly changed layer and should be changed for all mask set changes.	The MSC8103 mask set 2K87M has an ID of 0x12.

3.2 Internal Memory Map Mirror Register (IMMMR)

The 2K87M mask set adds a new Internal Memory Map Mirror Register (IMMMR) which has a fixed address controlled by the QBus Bank 1 (0x00F8FFC0) and the same register fields as the IMMR. It reflects the contents of the IMMR. If the ISB in the IMMR is modified, the base address of all SIU and CPM registers, including the IMMR, changes to the new value selected by the ISB. In such a case, the device or external masters may not be able to access the registers. Since the IMMMR does not reside in the same base memory area, it is always available at its fixed address. You can read the current ISB value from the IMMMR and determine the current internal base address from that value.

4 Reset

The 2K42A mask set offers two options for programming the Hard Reset Configuration Word (HRCW). The 2K87M mask set offers three options. In addition, the structure of the HRCW itself is different between the two mask sets.

4.1 Reset Configuration Options

Table 4 shows the options for programming the HRCW for each of the mask sets.

Table 4. HRCW Programming Options by Mask Set

2K42A	2K87M
Host reset. Through the HDI16 from a host Hardware reset. Through the system bus from external memory	Host reset. Through the HDI16 from a host. Hardware reset. Through the system bus from external memory. Reduced reset. From a serial EPROM using the I ² C protocol. Limited fields of the hard reset configuration word are configured via the appropriate data bus bits on the system bus.

4.1.1 Configuration Modes

The 2K42A mask set defines the configuration modes as shown in **Table 5**.

Table 5. MSC8101 2K42A Mask Set Reset Configuration Modes

RSTCONF	HPE/EE1	BTM[0-1]/ EE[4-5]	Mode
1	1	01	host reset configuration
0	0	00	master hardware reset configuration
1	0	00	slave hardware reset configuration

The 2K87M mask set adds a third "reduced reset configuration" method of programming the reset configuration word, in addition to the host reset and hardware reset configuration methods.

Table 6. MSC8103 2K87M Mask Set Reset Configuration Modes

RSTCONF	HPE/EE1	BTM[0-1]/ EE[4-5]	Mode
1	1	01	host reset configuration
0	0	00	master hardware reset configuration
1	0	00	slave hardware reset configuration
0	0	10	master reduced reset configuration
1	0	10	slave reduced reset configuration

4.1.2 Reduced Reset Configuration Information for Mask Set 2K87M

Reduced reset configuration is executed for serial boot only. Only the NMI_OUT (bit 12), ISB (bits 13–15), SWDIS (bit 26), and DLLDIS (bit 27) fields in the Hard Reset Configuration Word (HRCW) can be programmed using this method. The rest of the bits are programmed to their default values, but they can be reprogrammed later after reset. **Table 7** describes the 2K87M mask set hard reset configuration word.

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

The major features of the reduce reset configuration include:

- The MSC8103 samples the signals described in **Table 6** at the rising edge of PORESET. If the configured boot mode is serial, the values for the NMI_OUT, ISB, SWDIS, and DLLDIS fields are programmed from the system data bus. The mapping of the bits on the data bus is the same as for hardware reset configuration mode.
- MODCK_H cannot be programmed using this method and the value is set by default to 000. Therefore, only clock modes 0–1 and 4–7 can be used with this boot mode.
- In reduced configuration mode, the internal reset is extended for 1024 CLKIN cycles.
- Although there is no default HRCW in this mode, the bits in the HRCW that are not programmed assume the default values.
- During the first 8 CLKIN cycles D[12–15] and D[26–27] are sampled to configure the NMI_OUT, ISB, SWDIS, and DLLDIS fields in the HRCW. All other data bus bits are ignored. The simplest configuration scenario, where all data bus pins are ignored is not available for this mode.
- HRESET in simple slave mode does not change the reset configuration. In master/slave mode, HRESET does cause a new reset configuration.
- Configuration from EPROM for single or multiple chip is available only for the mentioned above 6 bits. All other bits on data bus are ignored.
- Multiple chip configuration in a system with no EPROM is also available only for the mentioned above 6 bits. All other bits on data bus are ignored.

4.2 Hard Reset Configuration Word Changes

The 2K87M mask set of the MSC8103 adds the SWDIS field (bit 26) and changes the definition of the ISB field (bits 13–15).

Bit 0 2 3 7 8 9 12 1 5 6 10 13 14 15 IRQ7 EARB EXMC BPS SCDIS ISPS IRPC DPPC ISB **EBM** NMI INT OUT R/W Type Reset 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 27 16 17 18 19 20 21 22 23 24 25 26 28 29 30 31 Bit BBD TCPC BC1PC SWDIS DLLDIS MODCK_H MMR Type R/W Reset 0 0 0 0 0 0 0 0 0 0 0

MSC8103 2K87M Mask Set Hard Reset Configuration Word

Table 7. MSC8103 2K87M Mask Set Hard Reset Configuration Word Bit Descriptions

Name	Reset	Description	Settings
EARB 0	0	External Arbitration Defines the initial value for PPC_ACR[EARB].	0 = No external arbitration is assumed 1 = External arbitration is assumed
EXMC 1	0	External MEMC Defines the initial value of BR0[EMEMC].	0 = No external memory controller is assumed 1 = External memory controller is assumed
IRQ7 INT	0	IRQ7 or INT_OUT Selection	$0 = \overline{IRQ7/INT_OUT} \text{ pin is } \overline{IRQ7}$ $1 = \overline{IRQ7/INT_OUT} \text{ pin is } \overline{INT_OUT}$
EBM 3	0	External 60x-compatible Bus Mode Defines the initial value of BCR[EBM].	
BPS 4–5	0	Boot Port Size Defines the initial value of BR0[PS], the port size for memory controller bank 0.	00 = 64-bit port size 01 = 8-bit port size 10 = 16-bit port size 11 = 32-bit port size

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

Reset

Table 7. MSC8103 2K87M Mask Set Hard Reset Configuration Word Bit Descriptions (Continued)

Name	Reset	Description	Settings
SCDIS 6	0	SC140 Disabled Enables/disables the SC140. This bit cannot be changed after reset.	0 = SC140 enabled 1 = SC140 disabled
ISPS 7	0	Internal Space Port Size Defines the initial value of BCR[ISPS]. This bit must be set in order to use the host interface. Setting ISPS configures the MSC8103 to respond to accesses from a 32-bit external master to its internal space. This bit cannot be changed after reset.	0 = 60x-compatible data bus is 64 bits wide 1 = 60x-compatible data bus is 32 bits wide (lower 32 bits; upper 32 bits reserved for HDI16
IRPC 8-9	0	Interrupt Pin Configuration Defines the initial value of SIUMCR[IRPC].	
DPPC 10–11	0	Data Parity Pin Configuration Defines the initial value of SIUMCR[DPPC].	
NMI OUT 12	0	NMI OUT Defines the host core to handle a non-maskable Interrupt (NMI) event.	0 = NMI is serviced by SC140 core 1 = NMI is routed to external pin and serviced by the external host
ISB 13–15	0	Initial Internal Space Base Select Defines the initial value of IMMR(ISB[0–14]) and determines the base address of the internal memory space and the DSPRAM base address on the local bus. Note that the SC140 core internal address space spans from 0x00000000–0x00FFFFFF (16 MB). Therefore it is not advisable to map the Internal Memory Map Register (IMMR) in this space, since the SC140 core cannot access the registers of the SIU and CPM. QBus banks are mapped to address 0x00F00000, so using ISB value 101 causes the Dual-Port RAM (DPRAM) address space and the QBus address space to overlap. Modifying the QBus Base Registers to another address allows the user to access the DPRAM address space.	ISB
— 16	0	Reserved. Write to zero for future compatibility.	
BBD 17	0	Bus Busy Disable Defines the initial value of SIUMCR[BBD].	
MMR 18–19	0	Mask Masters Requests Defines the initial value of SIUMCR[MMR].	
— 20–21	0	Reserved. Write to zero for future compatibility.	
TCPC 22–23	0	Transfer Code Pin Configuration Defines the initial value of SIUMCR[TCPC].	
BC1PC 24–25	0	BC1PC Value Defines the initial value of SIUMCR[BC1PC].	
SWDIS 26	0	Software Watchdog Disable Defines the initial state of the Software Watchdog Timer	0 = Software Watchdog Timer enabled 1 = Software Watchdog Timer disabled Note: This field is undefined in the 2K42A mask set.
DLLDIS 27	0	DLL Disable Defines whether the DLL mechanism is disabled.	0 = No DLL bypass 1 = DLL bypass
MODCK_H 28-30	0	MODCK High Order Bits High-order bits of the MODCK bus, which determine the clock reset configuration.	
— 31	0	Reserved. Write to zero for future compatibility.	

5 Boot

The 2K42A mask set does not support a serial boot mode. The 2K87M mask set supports a serial boot mode with a reduced reset configuration. The following sections describe the serial boot mode operations.

5.1 Boot Mode Definition Changes

The boot modes for mask set 2K42A are defined by the values of BTM[0–1] when sampled on the rising edge of PORESET, as follows:

BTM0	BTM1	Boot Source
0	0	External memory
0	1	HDI16
1	0	Reserved
1	1	Reserved

The boot modes for mask set 2K87M are defined by the values of BTM[0–1] when sampled on the rising edge of PORESET, as follows:

ВТМ0	BTM1	Boot Source
0	0	External memory
0	1	HDI16
1	0	Serial interface
1	1	Reserved

5.2 Serial EPROM Boot Procedure

The MSC8103 core programs the I²C registers and parameter RAM and prepares buffers and buffer descriptors (BDs) for the boot loading process. The MSC8103 I²C interface is programmed as the master, and it accesses the slave address 0b1010111 to read the boot source code. Booting the MSC8103 through the serial EPROM is useful for systems in which the MSC8103s are connected only through serial interfaces, such as TDM, Ethernet, ATM, and so forth.

Note: The bootloader supports access to serial EPROMS with a user-defined device address and 2-byte address specifications.

5.3 Software Watchdog Handling

The software watchdog timer can be enabled by clearing the SWDIS bit as part of the reduced reset configuration process. In serial boot mode, if the SWDIS bit is cleared, the bootloader program periodically executes a special service sequence to prevent the time-out of its counter and the assertion of a hardware reset during the bootloading process. For details on the software watchdog, refer to **Section 4.2.5**, *Software Watchdog Timer*, and **Section 4.3**, *SIU Programming Model* in the *MSC8103 Reference Manual*.

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

5.4 Source Program Data Stream Structure

The source program can be organized into several blocks. Each block can be either a data block or an instruction block, and it can be loaded to a different specified destination. Each block contains the block size, the location where the block is loaded, source program words, checksum, checksum enable and the location from which the next block is loaded.

When each block word is loaded, the routine calculates a checksum by XORing the current word bit by bit with the result of XORing previous words. The value of bit *i* of the current result is equal to XORing bit *i* of the current word with bit *i* of the previous result. After the entire block is loaded, the calculated checksum is compared to the loaded checksum. The checksum comparison and calculation can be skipped by clearing checksum enable bit. The last block is a special block that indicates end of code. It contains the boot execution start address. **Figure 1** shows the stream structure.

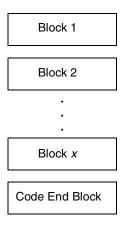


Figure 1. Boot Code Stream Structure

5.5 Source Program Block Structure

The data stream source programs must be structured in the format shown in **Table 8**.

Word	Description
1	Block size + checksum enable bit (see Figure 2 for layout description)
2	Next block address
3	Address where the first block of the source program is to be loaded, most significant part
4	Address where the first block of the source program is to be loaded, least significant part
5	First word of source program
n	Last word of source program
n + 1	Checksum—xor for first block
n + 2	Checksum—xor for first block
2nd offset + 1	Block size + checksum enable bit
2nd offset + 2	Next block address
2nd offset + 3	Address where the second block of the source program is to be loaded, most significant part
2nd offset + 4	Address where the second block of the source program is to be loaded, least significant part
2nd offset + 5	First word of source program
2nd offset + n	Last word of source program
2nd offset +n + 1	Checksum—xor for second block
2nd offset + n + 2	Checksum—xor for second block

Table 8. Block Structure

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

Bit	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Description	CSE ¹		Block Size													

Notes: 1. CSE = checksum enable. Set this bit when a checksum comparison is needed.

2. Since the EPROMS that support the I²C protocol are small, 15 bits are sufficient to define the block size.

Figure 2. Checksum Enable Bit + Block Size

In addition, the following rules apply:

- The source data must be in big-endian format, with the most significant part at the lower-order address.
- To enable checksum, set the CSE bit. To disable checksum, clear the CSE bit.
- Block size includes the checksum and checksum.
- Each address must be aligned on a 16-byte boundary.
- Maximum size for a block is 64 KB.
- Checksum is performed on all block words, including addresses and sizes.
- The block size should be a multiple of 32 bits.
- If the next block address is 0x0, the bootloader treats the next block as sequential.
- All addresses should be located in SRAM. The address should be given as a DSP internal address.

The end of the boot code stream is indicated by a special boot end block with the structure shown in Table 9.

Word	Description
1	0x0000
2	0x0000
3	Boot start address, most significant part
4	Boot start address, least significant part
5	0x0000
6	0x0000
7	Checksum—xor
8	Checksum—xor

Table 9. Structure of the Boot End Block

The first two words indicate the end of the source blocks. At least one block of source code must be loaded when the bootloader is invoked. The boot start address indicates the address at which the boot program execution starts. This address must be aligned on a 16-byte boundary. The bootloader routine expects at least one code block in addition to the boot end block. The sequence is repeated for subsequent blocks, until the final block in the data stream is reached.

5.6 Load Procedure

The bootloader program uses the I^2C serial interface to access data in the EPROM and to program the I^2C parameter RAM and registers. The I^2C uses BDs and buffers to read and write data. The bootloader prepares and keeps track of the BDs and buffers for program loading.

To enable multi-master support, the first 14 bytes of the EPROM are reserved for an address table, which is also accessed in single-master mode. The table entries contain the location of the boot code. The loading process starts by calculating the entry address and reading the boot code location address. Then the code loading starts by reading the first 4 block words from the EPROM. The size of block, where to load it, the location of the next block in EPROM, and checksum enable are extracted.

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

Note: The bootloader supports access to serial EPROMs up to 512 KB with an address specification that is accessed by 2 bytes.

The bootloader allocates a buffer for the first code block according to the address and size given in the opening 4 words and creates a BD that describes it. After the BD is ready, the bootloader starts reading the code block from the EPROM. If checksum is enabled, the bootload calculates a checksum on the block word and compares the calculated checksum to the loaded checksum. If the checksum is correct, the bootloader continues to the next block. If the checksum fails, the bootloader tries to read the block again. After a second unsuccessful try, the bootloader aborts.

To skip the checksum comparison, clear the checksum enable bit. If checksum is disabled, the bootloader program continues loading the next code block after finishing the current one. When all code blocks are loaded, boot execution starts from the start address given in the end block.

The bootloader program polls the BDs to check when a code block has been received. It does not use interrupts.

The load procedure is described in **Figure 3**.

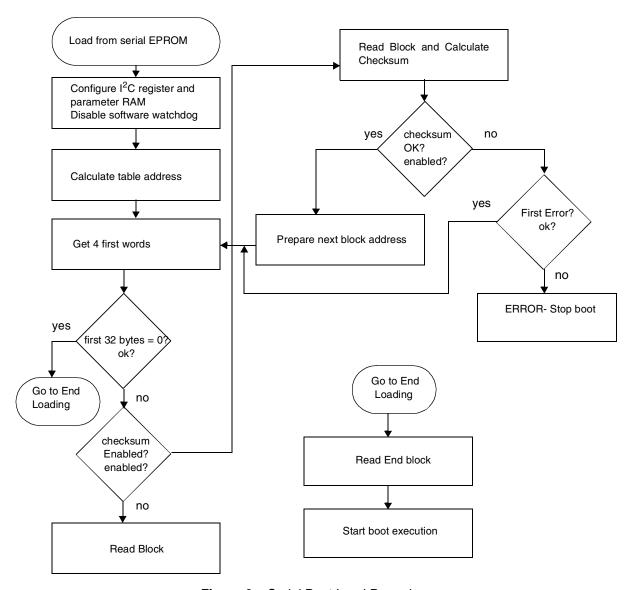


Figure 3. Serial Boot Load Procedure

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

5.7 I²C Clocking

The MSC8103 I²C interface accesses the serial EPROM using a clock frequency derived by dividing the core frequency by 4000. This division sets the I²C clock to 75 KHz or less, a clock frequency that most EPROMs support. If the MSC8103 I²C gets an NAK during transmission, that is, the EPROM does not respond to the address asserted by MSC8103, the boot loader stops execution. If the software watchdog timer is enabled, the counter will eventually expire causing a system reset. After reset, the bootloading process restarts.

5.8 Reset Configuration Word

The only reset configuration mode that can be used while serial boot mode is enabled is reduced configuration word. In the reduced configuration word, only the NMI_OUT, ISB, SWDIS, and DLLDIS fields can be set. For details, see **Section 4.1.2**.

5.9 Default Programming During Boot

The bootloader routine provides default programming for parts of the MSC8103. The routine programs the UPMC and the GPCM as required to support the internal SRAM and peripherals. The UPMC is programmed to support the bus-to-CPM clock ratio. The routine checks the value of the SCMR[BUSDF] bits and selects the bus-to-CPM clock ratio. The routine also programs the correct values for the ELIR[A–F] registers in the programmable interrupt controller (PIC) to determine the interrupt mode (edge-triggered or level-triggered).

5.10 Multi-Processor Booting from a Serial EPROM

The I^2C protocol supports multi-master environments. All MSC8103 booting devices act as I^2C masters and try to access the serial EPROM. The first 14 bytes of the serial EPROM are reserved for an address table. Each master accesses a different entry in the table according to its ISB[0-2] bits in the IMMR, allowing seven I^2C masters in the system. Each entry in the table contains the actual address where the boot program resides in the 2-byte increments. The master accesses the table, reads the boot location address, and starts loading boot from there. If two or more masters try to put information onto the bus, the first to produce a 1 when another produces a 0 loses the arbitration (collision). If a collision occurs, the master that loses the arbitration retries.

Note: If there are less than seven masters and not all 14 bytes of the table are needed, the boot code can start inside the first 14 bytes of the table.

A MSC8103 I²C master should access a table entry equal to its ISB[0–2] value multiplied by two. The bootloading process always starts by accessing the address table. In a single master environment, the boot code may start immediately after the address entry.

Note: During the booting process, multiple masters should not address each other. There is no support for multimaster errors.

5.11 Boot Code Changes

The boot code for the 2K87M mask set supports the I²C protocol. In addition, the code reflects changes in the device design that fix a host checksum errata, make the SRAM base address ISB dependent, and allow the software watchdog timer to be enabled or disabled via software. For a detailed listing of the updated boot code, see **Appendix A**.

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

6 Clock System

6.1 Clock Scheme Modifications

The MSC8101 mask set 2K42A and the MSC8103 mask set 2K87M use different clock schemes. The following paragraphs describe the clock schemes.

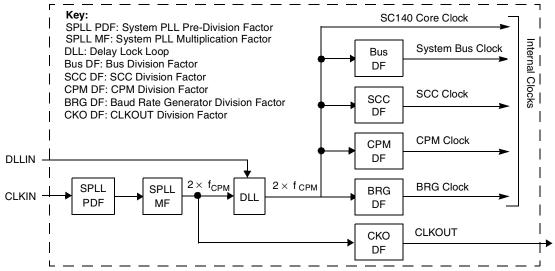
6.1.1 Mask Set 2K42A Clock Scheme

Six bit values map the MSC8101 clocks to one of the valid configuration mode options. Each option determines the CLKIN, SC140 core, system bus, SCC clock, CPM, and CLKOUT frequencies. The six bit values are derived from three dedicated input pins (MODCK[1–3]) and three bits from the reset configuration word (MODCK_H). To configure the SPLL pre-division factor, SPLL multiplication factor, and the frequencies for the SC140 core, SCC clocks, CPM parallel I/O ports, and system buses, the MODCK[1–3] pins are sampled and combined with the MODCK_H values when the internal power-on reset (internal PORESET) is deasserted. Clock configuration changes only when the internal PORESET signal is deasserted.

The following factors are configured:

- SPLL pre-division factor (SPLL PDF)
- SPLL multiplication factor (SPLL MF)
- Bus post-division factor (Bus DF)

Figure 4 shows the functional block diagram for the 2K42A mask set. The 2K42A mask set contains an internal system phase-lock loop (SPLL)



Note: SPLL PDF determined by the clock configuration mode; SPLL MF determined by the clock configuration mode; Bus DF = CLKOUT DF and is 4 or 5, determined by the clock configuration mode; SCC DF is always 4; CPM DF is always 2; BRG DF is set by the System Clock Control Register (SCCR) and is 4, 16 (default), 64, or 256.

Figure 4. MSC8101 Clock Functional Block Diagram for 2K42A Mask Set

The SCC division factor (SCC DF) is fixed at 4 and the CPM division factor (CPM DF) is fixed at 2. The BRG division factor (BRG DF) is configured through the System Clock Control Register (SCCR) and can be 4, 16 (default after reset), 64, or 256.

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

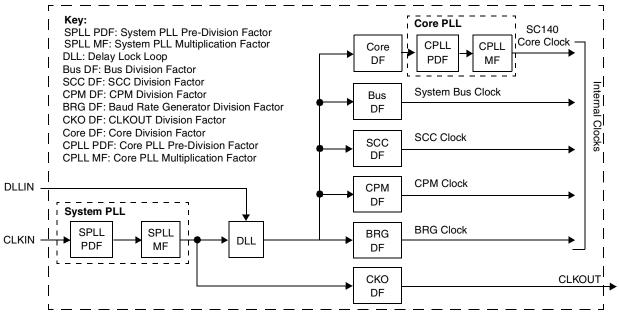
6.1.2 Mask Set 2K87M Clock Scheme

Six bit values map the MSC8101 clocks to one of the valid configuration mode options. Each option determines the CLKIN, SC140 core, system bus, SCC clock, CPM, and CLKOUT frequencies. The six bit values are derived from three dedicated input pins (MODCK[1–3]) and three bits from the hard reset configuration word (MODCK_H). To configure the SPLL pre-division factor, SPLL multiplication factor, and the frequencies for the SC140 core, SCC clocks, CPM parallel I/O ports, and system buses, the MODCK[1–3] pins are sampled and combined with the MODCK_H values when the internal power-on reset (internal PORESET) is deasserted. Clock configuration changes only when the internal PORESET signal is deasserted.

The following factors are configured:

- SPLL pre-division factor (SPLL PDF)
- SPLL multiplication factor (SPLL MF)
- Bus post-division factor (Bus DF)
- CPM division factor (CPM DF)
- Core division factor (Core DF)
- CPLL pre-division factor (CPLL PDF)
- CPLL multiplication factor (CPLL MF)

Figure 5 shows the functional block diagram for the 2K87M mask set. The 2K87M mask set contains an internal system phase-lock loop (SPLL) and a core phase-lock loop (CPLL).



SPLL PDF, SPLL MF, Core DF, CPLL PDF, CPLLMF, and CPM DF are determined by the clock configuration mode; Bus DF = CKO DF and is determined by the clock configuration mode; SCC DF is always 4; BRG DF is set by the System Clock Control Register (SCCR) and is 4, 16 (default), 64, or 256.

Figure 5. MSC8103 Clock Functional Block Diagram for 2K87M Mask Set

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

Note:

6.2 System Clock Mode Register (SCMR) Changes

The 2K42A and 2K87M mask sets use different SCMR definitions. The following sections describe the SCMR definitions for each mask set.

6.2.1 2K42A Mask Set SCMR Field Definitions

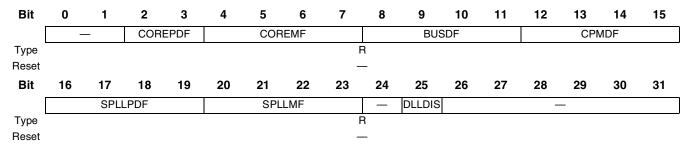


Figure 6. 2K42A Mask Set System Clock Mode Register (SCMR)—0x10C88

SCMR is a read-only register that is updated during power-on reset (PORESET) and provides the mode control signals to the PLLs, DLL, and clock logic. This register reflects the currently defined configuration settings.

Table 10. 2K42A Mask Set SCMR Bit Descriptions

Name	Defa	ults	Description	Cattings
Bit No.	PORESET	Hard Reset	Description	Settings
— 0–1	_	_	Reserved	
COREPDF 2–3	Configuration Pins	Unaffected	Core PLL Pre-Division Factor	Not used.
COREMF 4–7	Configuration Pins	Unaffected	Core Multiplication Factor	Not used
BUSDF 8–11	Configuration Pins	Unaffected	60x Bus Division Factor	0010 Bus DF = 3 0011 Bus DF = 4 0100 Bus DF = 5 All other combinations not used.
CPMDF 12–15	Configuration Pins	Unaffected	CPM Division Factor	0001 CPM DF = 2 All other combinations are not used.
SPLLPDF 16–19	Configuration Pins	Unaffected	SPLL Pre-Division Factor	0000 SPLL PDF = 1 0001 SPLL PDF = 2 0010 SPLL PDF = 3 0011 SPLL PDF = 4 All other combinations not used
SPLLMF 20–23	Configuration Pins	Unaffected	SPLL Multiplication Factor	0110 SPLL MF = 12 0111 SPLL MF = 14 1000 SPLL MF = 16 1001 SPLL MF = 18 1010 SPLL MF = 20 1011 SPLL MF = 22 1100 SPLL MF = 24 1101 SPLL MF = 26 1110 SPLL MF = 28 1111 SPLL MF = 30 All other combinations not used
 24	_	_	Reserved	
DLLDIS 25	Configuration Pins	Unaffected	DLL Disable	DLL operation is enabled DLL is disabled

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

Table 10. 2K42A Mask Set SCMR Bit Descriptions (Continued)

Name	Defa	ults	Description	Settings		
Bit No.	PORESET	Hard Reset	Description	Settings		
 26–31	_	_	Reserved			

6.2.2 2K87M Mask Set SCMR Field Definitions

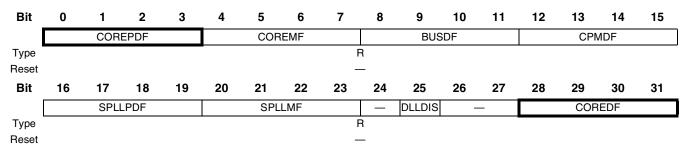


Figure 7. 2K87M Mask Set System Clock Mode Register (SCMR)—0x10C88

SCMR is a read-only register that is updated during power-on reset (PORESET) and provides the mode control signals to the PLLs, DLL, and clock logic. This register reflects the currently defined configuration settings.

Table 11. 2K87M Mask Set SCMR Field Descriptions

	1		·	
Name	Defa	ults	Description	Settings
Bit No.	PORESET	Hard Reset	Description	Settings
COREPDF 0-3	Configuration Pins	Unaffected	Core PLL Pre-Division Factor	0000 CPLL PDF = 1 0001 CPLL PDF = 2 0010 CPLL PDF = 3 0011 CPLL PDF = 4 All other combinations not used.
COREMF 4–7	Configuration Pins	Unaffected	Core Multiplication Factor	0101 CPLL MF = 10 0110 CPLL MF = 12 0111 CPLL MF = 14 All other combinations not used.
BUSDF 8–11	Configuration Pins	Unaffected	60x-compatible Bus Division Factor	0001 Bus DF = 2 0010 Bus DF = 3 0011 Bus DF = 4 0100 Bus DF = 5 0101 Bus DF = 6 All other combinations not used.
CPMDF 12–15	Configuration Pins	Unaffected	CPM Division Factor	0000 CPM DF = 1 0001 CPM DF = 2 0010 CPM DF = 3 All other combinations not used.
SPLLPDF 16–19	Configuration Pins	Unaffected	SPLL Pre-Division Factor	0000 SPLL PDF = 1 0001 SPLL PDF = 2 0010 SPLL PDF = 3 0011 SPLL PDF = 4 0100 SPLL PDF = 5 0101 SPLL PDF = 6 All other combinations not used

Table 11. 2K87M Mask Set SCMR Field Descriptions (Continued)

Name	Defa	ults	Description	Sattings
Bit No.	PORESET	Hard Reset	Description	Settings
SPLLMF 20–23	Configuration Pins	Unaffected	SPLL Multiplication Factor	0101 SPLL MF = 10 0110 SPLL MF = 12 0111 SPLL MF = 14 1000 SPLL MF = 16 1001 SPLL MF = 18 1010 SPLL MF = 20 1011 SPLL MF = 22 1100 SPLL MF = 24 1101 SPLL MF = 26 1110 SPLL MF = 28 1111 SPLL MF = 30 All other combinations not used
 24	_	_	Reserved	
DLLDIS 25	Configuration Pins	Unaffected	DLL Disable	DLL operation is enabled DLL is disabled
— 26–27	_	_	Reserved	,
COREDF 28–31	Configuration Pins	Unaffected	Core Division Factor	0000 CORE DF = 1 0001 CORE DF = 2 0010 CORE DF = 3 0011 CORE DF = 4 0100 CORE DF = 5 0101 CORE DF = 6 All other combinations not used.

6.3 System Clock Control Register (SCCR)

The 2K87M mask set adds a new field (CLKODIS) to the SCCR. The functionality of the common field (DFBRG) is the same. **Figure 8** shows the register layout and **Table 12** lists the bit descriptions.

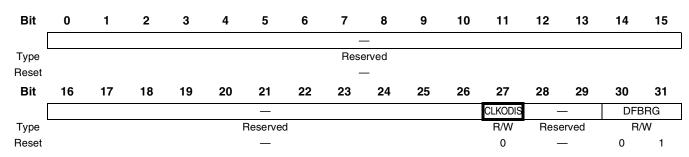


Figure 8. System Clock Control Register (SCCR)—0x10C80

Table 12. SCCR Bit Descriptions

Name	Defau	ılts	Description	Settings			
Bit No.	PORESET	Hard Reset		Settings			
— 0–26		_	Reserved. Write to 0 fro future compatibility.				
CLKODIS 27	0	Unaffected	CLKOUT Disable Disables the CLKOUT signal. The value of CLKOUT when disabled is indeterminate (can be 1 or 0).	O CLKOUT enabled (default) CLKOUT disabled Note: This bit is reserved in mask set 2K42A.			

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

Table 12. SCCR Bit Descriptions (Continued)

Name	Defau	ılts	Description	Settings			
Bit No.	PORESET	Hard Reset			Settings		
 28–29	_	_	Reserved. Write to 0 fro future compatibility.				
DFBRG 30–31	01	Unaffected	Division Factor for the BRG Clock Defines the BRGCLK frequency. Changing this value does not result in a loss of lock condition.	00 01 10 11	Divide by 4 Divide by 16 (default value) Divide by 64 Divide by 256		

6.4 Clock Mode Changes

6.4.1 2K42A Mask Set Clock Configuration Modes

The MSC8101 2K42A mask set supports the following valid clock modes:

Table 13. 2K42A Mask Set Clock Configuration Modes

Mode #	MODCK_H	MODCK[1-3]	SPLL PDF	- ICDII MEI		Ratio Bus:CPM:Core	Bus/ CLKIN
46	101	110	2	16	4	1:2:4	4
57	111	001	2	10	5	1 : 2.5 : 5	1

6.4.2 2K87M Mask Set Clock Modes

The MSC8103 2K87M mask set supports the clock modes listed in **Table 14**.

Table 14. 2K87M Mask Set Clock Configuration Modes

Mode #	MODCK_H ¹	MODCK[1-3] ²	SPLL PDF	SPLL MF	Bus DF	Core DF	CPM DF	CPLL PDF	CPLL MF	Ratio Bus:CPM:Core	Bus/ CLKIN
0	000	000	1	12	4	4	2	4	12	1:2:3	3
1	000	001	2	16	4	4	2	4	12	1:2:3	2
2	000	010		Reserved							
3	000	011					Res	erved			
4	000	100	2	16	4	4	2	4	14	1:2:3.5	2
5	000	101	1	12	4	2	2	5	10	1:2:4	3
6	000	110	3	12	4	2	2	5	10	1:2:4	1
7	000	111	1	10	5	5	2	2	10	1:2.5:5	2
8	001	000	1	16	4	4	2	4	12	1:2:3	4
9	001	001	1	20	4	4	2	4	12	1:2:3	5
10	001	010	3	12	4	4	2	4	12	1:2:3	1
11	001	011	3	12	4	4	2	4	14	1:2:3.5	1
12	001	100	1	12	4	4	2	4	14	1:2:3.5	3
13	001	101	1	16	4	4	2	4	14	1:2:3.5	4
14	001	110					Res	erved			
15	001	111					Res	erved			
16	010	000	1	12	6	2	2	5	10	1:3:6	2
17	010	001	2	12	6	2	2	5	10	1:3:6	1
18	010	010	1	16	8	8	2	2	12	1:4:6	2
19	010	011	2	16	8	8	2	2	12	1:4:6	1
20	010	100					Res	erved			
21	010	101					Res	erved			

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

Table 14. 2K87M Mask Set Clock Configuration Modes (Continued)

Mode #	MODCK_H ¹	MODCK[1-3] ²	SPLL PDF	SPLL MF	Bus DF	Core DF	CPM DF	CPLL PDF	CPLL MF	Ratio Bus:CPM:Core	Bus/ CLKIN		
22	010	110					Res	erved					
23	010	111			_		Res	erved			_		
24	011	000	2	12	6	6	2	3	12	1:3:4	1		
25	011	001	1	12	6	3	2	5	10	1:3:4	2		
26	011	010	1	18	6	3	2	5	10	1:3:4	3		
27	011	011	2	10	5	3	2	5	12	1:2.5:4	1		
28	011	100					Res	erved					
29	011	101					Res	erved					
30	011	110		Reserved									
31	011	111	2	2 12 6 8 2 3 12 1:3:3 1									
32	100	000					Res	erved					
33	100	001	2	16	8	8	4	2	10	1:2:5	1		
34	100	010	1	12	4	4	2	2	10	1:2:5	3		
35	100	011	2	16	8	8	4	2	12	1:2:6	1		
36	100	100	1	16	8	8	4	2	12	1:2:6	2		
37	100	101		Reserved									
38	100	110	Reserved										
39	100	111					Res	erved					
40	101	000					Res	erved					
41	101	001					Res	erved					
42	101	010					Res	erved					
43	101	011					Res	erved					
44	101	100					Res	erved					
45	101	101					Res	erved					
46 ³	101	110	2	16	4	2	2	5	10	1:2:4	2		
47	101	111					Res	erved	•		•		
48	110	000					Res	erved					
49	110	001					Res	erved					
50	110	010					Res	erved					
51	110	011					Res	erved					
52	110	100					Res	erved					
53	110	101					Res	erved					
54	110	110					Res	erved					
55	110	111					Res	erved					
56	111	000					Res	erved					
57 ³	111	001	2	10	5	5	2	2	10	1:2.5:5	1		
58	111	010					Res	erved					
59	111	011					Res	erved					
60	111	100					Res	erved					
61	111	101					Res	erved					
62	111	110					Res	erved					
63	111	111						erved		a ava liated in the tak			

Notes: 1. MODCK_H is a 3-bit field that occupies bits 28–30 of the Hard Reset Configuration Word. The bits are listed in the table in the following order: bit 28, bit 29, bit 30. For example, the value 110 indicates that bit 28 = 1, bit 29 = 1, and bit 30 = 0.

^{2.} MODCK[1–3] are external signal inputs that are either pulled up (1) or pulled down (0) to configure the system clock mode. The values are listed in the table in the following order: MODCK1, MODCK2, MODCK3. For example, the value 110 indicates that MODCK1 is pulled up, MODCK2 is pulled up, and MODCK3 is pulled down.

^{3.} This mode is compatible with the same mode for mask set 2K42A.

21

6.5 CLKIN-to-CLKOUT Delay Change

For the 2K42A mask set, the CLKIN-to-CLKOUT delay is a function of frequency. For the 2K87M mask set, the CLKIN-to-CLKOUT delay is a not a function of frequency. Therefore, the two versions cannot be used together in a DLL-disabled system.

6.6 Enabling the DLL

For the 2K42A, system erratum QSIU14 requires that the MSC8101 use only DLL-disabled mode and a zero-delay buffer. To use the MSC8103 mask set 2K87M in such a design with the DLL-enabled, the zero-delay buffer must either be placed in PLL-bypass mode or replaced.

6.7 Disabling the DLL

The 2K87M AC timing specification listed in the *MSC8103 Technical Data* sheet is for DLL-enabled mode only and is therefore referenced to DLLIN. For 2K87M clock modes 5, 6, 46, and 57 only, apply the following offsets to accommodate for the fact that the signal is referenced to CLKOUT instead of DLLIN:

• For SIU outputs, add 400 ps.

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- For DMA outputs, add 400 ps to specification 76.
- For SIU inputs, subtract 400 ps.
- For DMA inputs, subtract 400 ps from specifications 72–75.

6.8 Clock Frequency Changes

lists the maximum clock frequencies for each mask set.

Table 15. Maximum Clock Frequencies for Each Mask Set

Clock	2K42A Maximum Frequency	2K87M Maximum Frequency
Input Clock (CLKIN)	68.75 MHz	75 MHz
Internal Bus Clock (BCLK)	68.75 MHz	100 MHz
Output Clock (CLKOUT)	68.75 MHz	100 MHz
SCC Clock (SCLK)	68.75 MHz	100 MHz
CPM Clock (CPMCLK)	137.5 MHz	200 MHz
SC140 Core Clock (DSPCLK)	275 MHz	300 MHz

Note: Refer to MSC8103 Technical Data for details on all frequency ranges and limitations.

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

7 Memory Map

The 2K87M mask adds the IMMMR to the memory map. The 2K87M memory map for Bank1 of the QBus is shown in **Table 16**.

 Table 16.
 Mask Set 2K87M QBus Memory Map—Bank1

SC140 Core Internal Address	Mnemonic	Name	Size		
	Boot ROM				
0000-07FF	BOOTROM	MSC8103 boot ROM	2 KB		
0800-FFBF	Reserved	Reserved Leave unchanged for future compatibility 63 KB – 64 bytes			
FFC0	IMMMR	Internal Memory Map Mirror Register	32 bits		
FFC4-FFFF	Reserved	Leave unchanged for future compatibility	60 bytes		

8 ORx in UPM Mode

In UPM mode, the 2K42A mask uses the previously undefined bit 27 in the ORx to add a wait state to the memory cycle when set. In the 2K87M mask set, this bit is undefined.

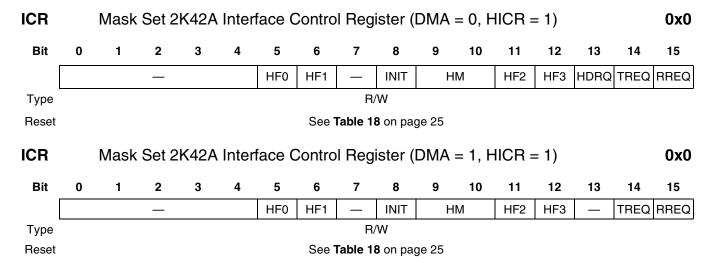
9 HDI16

The 2K87M mask set defines additional bits in the Interface Control Register (ICR) and Interface Status Register (ISR) to support HDI16 bursts of various sizes. This affects the conditions used to assert or deassert the HREQ signal. The following sections compare the register layouts for the two mask sets and indicate the changes to the logic used to assert the HREQ signal.

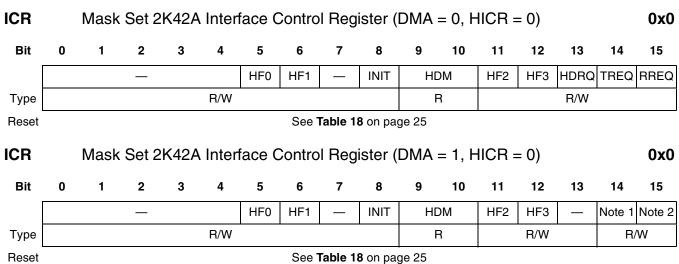
9.1 Interface Control Register (ICR) Changes

The following sections list the ICR layout and definitions for the 2K42A and 2K87M mask sets.

9.1.1 2K42A Mask Set ICR Definitions



Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2



Notes: 1. HDM0 when read, TREQ when written

2. HDM0 when read, RREQ when written

ICR is a read/write control register that allows the use of bit manipulation instructions on control register bits. The host processor uses the ICR to control the HDI16 interrupts and flags. The SC140 core cannot access the ICR. The HPCR[DMA] bit and the HCR[HICR] bit control the function of the ICR bits.

Table 17. Mask Set 2K42A ICR Bit Descriptions

Name	Description	
— 0–4	Reserved. Write to zero for future compatibility.	
HF0 5	Host Flag 0 A general-purpose flag for host-to-core communication. The host processor can set or clear HF0. HF0 is reflected in the HSR on the core side of the HDI16.	
HF1 6	Host Flag 1 A general-purpose flag for host-to-core communication. The host processor can set or clear HF1. HF1 is reflected in the HSR on the core side of the HDI16.	
7	Reserved. Write to zero for future compatibility.	
INIT 8	Force Initialization Used by the host processor to force initialization of the HDI16 hardware (which may or may not be necessary, depending on the software design of the interface). During initialization, the HDI16 transmit and receive control bits are configured. The type of initialization performed when the INIT bit is set depends on the state of TREQ and RREQ in the HDI16. The INIT command, which is local to the HDI16, conveniently configures the HDI16 into the desired data transfer mode. The effect of the INIT command is described in Table 19. When the host sets the INIT bit, the HDI16 hardware executes the INIT command. The interface hardware clears the INIT bit after the command executes.	

Table 17. Mask Set 2K42A ICR Bit Descriptions (Continued)

Name	Description	
HM/HDM 9–10	Host Mode/Host DMA Mode When host DMA mode is enabled, if HCR[HICR] is set, the HREQ pin requests DMA transfers, the TREQ and RREQ bits select the direction of DMA transfers, and the HACK input pin is used as a DMA transfer acknowledge input, if OAE in HPCR is cleared. If the DMA direction is from core to host, the contents of the selected register are written to the host data bus when HACK is asserted. If the DMA direction is from host to core, the selected register is read from the host data bus when HACK is asserted.	
	If HPCR[OAE] is set, a host read or write to host address 0x4 is used as a DMA transfer acknowledge. If the DMA direction is from core to host, the contents of the selected register are written to the host data bus when the host reads from host address 0x4. If the DMA direction is from host to core, the selected register is read from the host data bus when the host writes to host address 0x4.	
	HM also controls the size of the DMA word to be transferred. The HDI16 data register selected during a host DMA transfer is determined by a 2-bit address counter, which is preloaded with the value in HM. The address counter replaces the HA[0–1] bits of the HDI16 during a host DMA transfer. The address counter can be initialized with the INIT bit feature. After each DMA transfer on the host data bus, the address counter is decremented. When the address counter reaches the last register, the address counter is loaded with the value in HM.	
	Thus, 16-bit, 32-bit, 48-bit, or 64-bit data can be transferred in a circular fashion, and the need is eliminated for the DMA controller to supply the HA0–2] pins (HPCR bit OAE=0) or to read/write at host address 0x4 (HPCR bit OAE=1). For 32-, 48-or 64-bit data transfers, the core CPU interrupt rate is reduced by a factor of 2, 3, or 4, respectively, from the host request rate. That is, for every two or three host processor data transfers of one byte each, there is only one 64-bit core CPU interrupt. This bit is available only in ICR mode (HCR[HICR] = 1).	
	When the HDI16 is in ICR priority non-DMA mode (the HPCR[DMA] bit is cleared and HCR[HICR] is set), data transfer size is defined by HM, as described in Table 22 . The transfer size causes the RXx/TXx register read/write at the last (trigger) address to clear the RXDF/TXDE bits, respectively.	
HF2 11	Host Flag 2 A general-purpose flag for host-to-core communication. The host processor can set or clear HF2. HF2 is reflected in the HS on the core side of the HDI16.	
HF3 12	Host Flag 3 A general-purpose flag for host-to-core communication. The host processor can set or clear HF3. HF3 is reflected in the HSR on the core side of the HDI16.	
HDRQ 13	HREQ/HTRQ and HACK/HRRQ Pin Control Controls the HREQ/HTRQ and HACK/HRRQ pins. If HDRQ is cleared, the HREQ/HTRQ pin functions as a single HREQ. If HDRQ is set, the HREQ/HTRQ and HACK/HRRQ pins function as HTRQ and HRRQ, respectively. This bit is available only in non-DMA (interrupt) mode (HPCR[DMA] = 0).	
TREQ/HDM0	HREQ/HTREQ Pin Control Controls the HREQ/HTREQ pin for host transmit data transfers. In non-DMA (interrupt) mode (DMA = 0 in the HPCR), TREQ enables host requests via the host request (HREQ or HTRQ) pin when the Transmit Data Register Empty (TXDE) status bit in the ISR is set. If TREQ is cleared, TXDE interrupts are disabled. If TREQ and TXDE are set, the host request pin is asserted. In DMA modes (HPCR[DMA] = 1 and HCR[HICR] = 1), software must set or clear TREQ to select the direction of DMA transfers. Setting TREQ sets the direction of the DMA transfers as host-to-core and enables the HREQ pin to request data transfers.	
	When HCR[HICR] is cleared and HPCR[DMA] is set, a TREQ read reflects the status of NOT HDM0 in HCR. When written, TREQ affects the INIT mode. See Table 20 .	
RREQ/HDM0 15	HREQ and HRREQ Pin Control Controls the HREQ and HRREQ pins for host receive data transfers. In non-DMA (interrupt) mode (HPCR[DMA] = 0), RREQ enables host requests via the host request (HREQ or HRRQ) pin when the Receive Data Register Full (RXDF) status bit in the ISR is set. If RREQ is cleared, ISR[RXDF] interrupts are disabled. If RREQ is set, the host request pin (HREQ or HRRQ) is asserted if ISR[RXDF] is set.	
	In host DMA mode (DMA = 1 in the HPCR and HICR = 1 in the HCR), RREQ must be set or cleared by software to select the direction of DMA transfers. Setting RREQ sets the direction of the host DMA transfers to core-to-host and enables the HREQ pin to request data transfers. When HICR in HCR is cleared and DMA in HPCR is set, RREQ, when read, reflects the status of HDM0 in HCR.	
	When HCR[HICR] is cleared and HPCR[DMA] is cleared, an RREQ read reflects the status of HCR[HDM0]. When written, RREQ affects the INIT mode. See Table 20 .	

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

Table 18 shows the result of the four kinds of reset on bits in each of the HDI16 registers accessible to the host processor. The hardware reset is caused by asserting the RESET signal. The individual reset is caused by clearing HPCR[HEN].

Table 18. Host-Side Registers After Reset

Do winter	D aviston	Reset	Туре
Register Name	Register Data	Hardware (HW) Reset	Individual (IR) Reset
ICR	All Bits	0	
CVR	NMI	0	0
	HC	0	0
	HV[0-6]	0	
ISR	HREQ	0	1 if TREQ is set; 0 otherwise
	HF[4–7]	0	_
	TRDY	1	1
	TXDE	1	1
	RXDF	0	0
RX	RX[0-3]	empty	empty
TX	TX[0-3]	empty	empty

Table 19 shows the effects of the INIT command in relation to the values of TREQ and RREQ.

Table 19. Effects of the INIT Command

TREQ	RREQ	After INIT Execution	Transfer Direction Initialized
0	0	INIT = 0	None
0	1	INIT = 0; ISR[RXDF] = 0; HSR[HTFE/HTFNF] = 1	Core to host
1	0	INIT = 0; ISR[TXDE] = 1; HSR[HRFF/HRFNE] = 0	Host to core
1	1	INIT = 0; ISR[RXDF] = 0; HSR[HTFE/HTFNF] = 1; ISR[TXDE] = 1; HSR[HRFF/HRFNE] = 0	Host to/from core

Table 20 and Table 21 summarize the effect of RREQ and TREQ on the HREQ and HRRQ signals.

Table 20. TREQ and RREQ Modes (HDRQ = 0) in Non-DMA Mode (HICR=1)

TREQ	RREQ	HREQ Signal
0	0	No interrupts (polling)
0	1	ISR[RXDF] request (interrupt)
1	0	ISR[TXDE] request (interrupt)
1	1	ISR[RXDF] and ISR[TXDE] request (interrupts)

Table 21. TREQ and RREQ Modes (HDRQ = 1) in Non-DMA Mode (HICR=1)

TREQ	RREQ	HTRQ Signal	HRRQ Signal
0	0	No interrupts (polling)	No interrupts (polling)
0	1	No interrupts (polling)	ISR[RXDF] request (interrupt)
1	0	ISR[TXDE] request (interrupt)	No interrupts (polling)
1	1	ISR[TXDE] request (interrupt)	ISR[RXDF] request (interrupt)

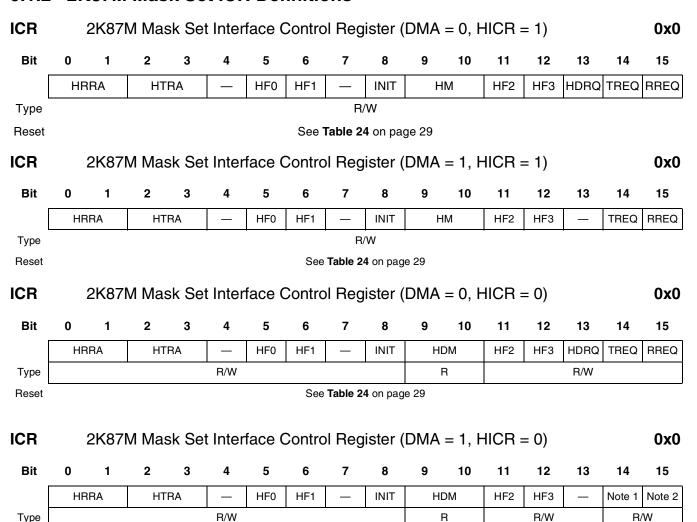
Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

Table 22 shows the valid HM values and their meaning.

Table 22. HM Host DMA Mode Values (HICR=1)

НМ			Mode		
0	1	DMA Mode Non-DMA Mode			
0	0	16-bit words 64-bit words. Last read/write (trigger) address: 0x4			
0	1	32-bit words 48-bit words. Last read/write (trigger) address: 0x5			
1	0	48-bit words 32-bit words. Last read/write (trigger) address: 0x6			
1	1	64-bit words 16-bit words. Last read/write (trigger) address: 0x7			

9.1.2 2K87M Mask Set ICR Definitions



Type Reset

See Table 24 on page 29

R/W

R/W

HDM0 when read, TREQ when written Notes: 1.

HDM0 when read, RREQ when written

ICR is a read/write control register that allows the use of bit manipulation instructions on control register bits. The host processor uses the ICR to control the HDI16 interrupts and flags. The SC140 core cannot access the ICR. The HPCR[DMA] bit and the HCR[HICR] bit control the function of the ICR bits.

Table 23. 2K87M Mask Set ICR Bit Descriptions

Name	Description	Settings
HRRA 0-1	HDI Receive Request Assertion The receive request is asserted a specified time based on the number of data bytes to receive.	00 HRRQ asserted for 8 bytes (RX full) 01 HRRQ asserted for 16 bytes (RX full + 1 HOTX entry full) 10 HRRQ asserted for 32 bytes (RX full + 3 HOTX entries full) 11 Reserved
HTRA 2–3	HDI Transmit Request Assertion The transmit request is asserted a specified time based on the number of data bytes to transmit.	00 HTRQ/HREQ asserted for 8 bytes (TX empty) 01 HTRQ/HREQ asserted for 16 bytes (TX empty + 1 HOTX entry empty) 10 HTRQ/HREQ asserted for 32 bytes (TX empty + 3 HOTX entries empty) 11 Reserved
	Reserved. Write to zero for future compatibility.	
HF0 5	Host Flag 0 A general-purpose flag for host-to-core communication. The host processor can set or clear HF0. HF0 is reflected in the HSR on the core side of the HDI16.	
HF1 6	Host Flag 1 A general-purpose flag for host-to-core communication. The host processor can set or clear HF1. HF1 is reflected in the HSR on the core side of the HDI16.	
- 7	Reserved. Write to zero for future compatibility.	
INIT 8	Force Initialization Used by the host processor to force initialization of the HDI16 hardware (which may or may not be necessary, depending on the software design of the interface). During initialization, the HDI16 transmit and receive control bits are configured. The type of initialization performed when the INIT bit is set depends on the state of TREQ and RREQ in the HDI16. The INIT command, which is local to the HDI16, conveniently configures the HDI16 into the desired data transfer mode. The effect of the INIT command is described in Table 25 on page 30. When the host sets the INIT bit, the HDI16 hardware executes the INIT command. The interface hardware clears the INIT bit after the command executes.	

Table 23. 2K87M Mask Set ICR Bit Descriptions (Continued)

Name	Description	Settings
HM/HDM 9-10	Host Mode/Host DMA Mode When host DMA mode is enabled, if HCR[HICR] is set, the HREQ pin requests DMA transfers, the TREQ and RREQ bits select the direction of DMA transfers, and the HACK input pin is used as a DMA transfer acknowledge input, if OAE in HPCR is cleared. If the DMA direction is from core to host, the contents of the selected register are written to the host data bus when HACK is asserted. If the DMA direction is from host to core, the selected register is read from the host data bus when HACK is asserted. If HPCR[OAE] is set, a host read or write to host address 0x4 is used as a DMA transfer acknowledge. If the DMA direction is from core to host, the contents of the selected register are written to the host data bus when the host reads from host address 0x4. If the DMA direction is from host to core, the selected register is read from the host data bus when the host reads from host address 0x4. HM also controls the size of the DMA word to be transferred. The HDI16 data register selected during a host DMA transfer is determined by a 2-bit address counter, which is preloaded with the value in HM. The address counter replaces the HA[0–1] bits of the HDI16 during a host DMA transfer. The address counter can be initialized with the INIT bit feature. After each DMA transfer on the host data bus, the address counter is decremented. When the address counter reaches the last register, the address counter is loaded with the value in HM. Thus, 16-bit, 32-bit, 48-bit, or 64-bit data can be transferred in a circular fashion, and the need is eliminated for the DMA controller to supply the HA0–2] pins (HPCR bit OAE=0) or to read/write at host address 0x4 (HPCR bit OAE=1). For 32-, 48- or 64-bit data transfers, the core CPU interrupt rate is reduced by a factor of 2, 3, or 4, respectively, from the host request rate. That is, for every two or three host processor data transfers of one byte each, there is only one 64-bit core CPU interrupt. This bit is available only in ICR mode (HCR[HICR] = 1). When the HDI1	
HF2 11	respectively. Host Flag 2 A general-purpose flag for host-to-core communication. The host processor can set or clear HF2. HF2 is reflected in the HSR on the core side of the HDI16.	
HF3 12	Host Flag 3 A general-purpose flag for host-to-core communication. The host processor can set or clear HF3. HF3 is reflected in the HSR on the core side of the HDI16.	
HDRQ 13	HREQ/HTRQ and HACK/HRRQ Pin Control Controls the HREQ/HTRQ and HACK/HRRQ pins. If HDRQ is cleared, the HREQ/HTRQ pin functions as a single HREQ. If HDRQ is set, the HREQ/HTRQ and HACK/HRRQ pins function as HTRQ and HRRQ, respectively. This bit is available only in non-DMA (interrupt) mode (HPCR[DMA] = 0).	

Table 23. 2K87M Mask Set ICR Bit Descriptions (Continued)

Name	Description	Settings
TREQ/HDM0	HREQ/HTREQ Pin Control	
14	Controls the HREQ/HTREQ pin for host transmit data transfers. In non-DMA (interrupt) mode (DMA = 0 in the HPCR), TREQ enables host requests via the host request (HREQ or HTRQ) pin when the Transmit Data Register Empty (TXDE) status bit in the ISR is set. If TREQ is cleared, TXDE interrupts are disabled. If TREQ and TXDE are set, the host request pin is asserted. In DMA modes (HPCR[DMA] = 1 and HCR[HICR] = 1), software must set or clear TREQ to select the direction of DMA transfers. Setting TREQ sets the direction of the DMA transfers as host-to-core and enables the HREQ pin to request data transfers.	
	When HCR[HICR] is cleared and HPCR[DMA] is set, a TREQ read reflects the status of NOT HDM0 in HCR. When written, TREQ affects the INIT mode. See Table 25 .	
RREQ/HDM0	HREQ and HRREQ Pin Control Controls the HREQ and HRREQ pins for host receive data transfers. In non-DMA (interrupt) mode (HPCR[DMA] = 0), RREQ enables host requests via the host request (HREQ or HRRQ) pin when the Receive Data Register Full (RXDF) status bit in the ISR is set. If RREQ is cleared, ISR[RXDF] interrupts are disabled. If RREQ is set, the host request pin (HREQ or HRRQ) is asserted if ISR[RXDF] is set. In host DMA mode (DMA = 1 in the HPCR and HICR = 1 in the HCR), RREQ must be set or cleared by software to select the direction of DMA transfers. Setting RREQ sets the direction of the host DMA transfers to core-to-host and enables the HREQ pin to request data transfers. When HICR in HCR is cleared and DMA in HPCR is set, RREQ, when read, reflects the status of HDM0 in HCR. When HCR[HICR] is cleared and HPCR[DMA] is cleared, an RREQ read reflects the status of HCR[HDM0]. When written, RREQ affects the INIT mode. See Table 25.	

Table 24. Host-Side Registers After Reset

Danistan	Register Data	Reset Type		
Register Name		Hardware (HW) Reset	Individual (IR) Reset	
ICR	All Bits	0		
CVR	NMI	0	0	
	HC	0	0	
	HV[0-6]	0	_	
ISR	TXDE32	1	1	
	TXDE16	1	1	
	RXDF32	0	0	
	RXDF16	0	0	
	HREQ	0	1 if TREQ is set; 0 otherwise	
	HF[4–7]	0	_	
	TRDY	1	1	
	TXDE	1	1	
	RXDF	0	0	
RX	RX[0-3]	empty	empty	
TX	TX[0-3]	empty	empty	

Table 25 shows the effects of the INIT command in relation to the values of TREQ and RREQ.

Table 25. Effects of the INIT Command

TREQ	RREQ	After INIT Execution	Transfer Direction Initialized
0	0	INIT = 0	None
0	1	INIT = 0; ISR[RXDF] = 0; HSR[HTFE/HTFNF] = 1	Core to host
1	0	INIT = 0; ISR[TXDE] = 1; HSR[HRFF/HRFNE] = 0	Host to core
1	1	INIT = 0; ISR[RXDF] = 0; HSR[HTFE/HTFNF] = 1; ISR[TXDE] = 1; HSR[HRFF/HRFNE] = 0	Host to/from core

Table 26 and Table 27 summarize the effect of RREQ and TREQ on the HREQ and HRRQ signals.

Table 26. TREQ and RREQ Modes (HDRQ = 0) in Non-DMA Mode (HICR=1)

TREQ	RREQ	HREQ Signal
0	0	No interrupts (polling)
0	1	ISR[RXDF] request (interrupt)
1	0	ISR[TXDE] request (interrupt)
1	1	ISR[RXDF] and ISR[TXDE] request (interrupts)

Table 27. TREQ and RREQ Modes (HDRQ = 1) in Non-DMA Mode (HICR=1)

TREQ	RREQ	HTRQ Signal	HRRQ Signal
0	0	No interrupts (polling)	No interrupts (polling)
0	1	No interrupts (polling)	ISR[RXDF] request (interrupt)
1	0	ISR[TXDE] request (interrupt)	No interrupts (polling)
1	1	ISR[TXDE] request (interrupt)	ISR[RXDF] request (interrupt)

Table 28 shows the valid HM values and their meaning.

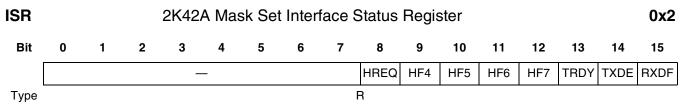
Table 28. HM Host DMA Mode Values (HICR=1)

Н	М		Mode	
0	1	DMA Mode Non-DMA Mode		
0	0	16-bit words 64-bit words. Last read/write (trigger) address: 0x4		
0	1	32-bit words 48-bit words. Last read/write (trigger) address: 0x5		
1	0	48-bit words 32-bit words. Last read/write (trigger) address: 0x6		
1	1	64-bit words 16-bit words. Last read/write (trigger) address: 0x7		

9.2 Interface Status Register (ISR) Changes

The following sections lists the ICR layout and definitions for the 2K42A and 2K87M mask sets.

9.2.1 2K42A Mask Set ISR Definitions



Reset See Table 24, "Host-Side Registers After Reset," on page 29

ISR is a status register by which the host processor interrogates the status and flags of the HDI16. The host processor can write to this address without affecting the internal state of the HDI16. The SC140 core cannot access ISR.

Table 29. 2K42A Mask Set ISR Bit Descriptions

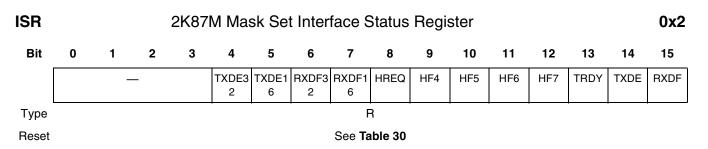
Name	Description	Settings
— 0–7	Reserved. Write to zero for future compatibility.	
HREQ 8	HREQ status HREQ indicates the status of the external transmit and receive request output signals (HTRQ and HRRQ) if HDRQ is set. If HDRQ is cleared, it indicates the status of the external host request output signal (HREQ). The HREQ bit can be set under either or both of two conditions: the Receive Word Registers (RX[0–3]) are full or the Transmit Word Registers (TX[0–3]) are empty. These conditions are indicated by the ISR RXDF and TXDE status bits, respectively. If the interrupt source has been enabled by the associated request enable bit in the ICR, HREQ is set if one or more of the two enabled interrupt sources is set.	If HDRQ is cleared: 0 No host processor interrupts requested. 1 Interrupt requested. If HDRQ is set: 0 No host processor interrupts requested (HTRQ and HRRQ cleared). 1 Interrupt requested (HTRQ or HRRQ set).
HF[4–7] 9–12	Host Flags 4–7 Indicates the state of host flags 4–7 in the HCR on the core side. Only the SC140 core can change HF[4–7].	
TRDY 13	TRDY Status Indicates whether the Transmit Word Registers TX[0–3] and the HORX FIFO are empty. TRDY is set if TXDE is set and HRFNE is cleared. If TRDY is set, the data that the host processor writes to TX[0–3] is immediately transferred to the core side of the HDI16 and can be read by the SC140 core. This feature has many applications. For example, if the host processor issues a host command that causes the SC140 core to read HORX, the host processor can be certain that the data it just transferred to the HDI16 is the same data received by the SC140 core.	0 TX[0-3] and the HORX FIFO are not empty. 1 TX[0-3] and the HORX FIFO are empty.
TXDE 14	Transmit Data Empty Indicates whether the Transmit Word Registers (TX[0–3]) are empty and can be written by the host processor. TXDE is set when the contents of the TX[0–3] registers are transferred to the HORX register. TXDE is cleared when the host processor writes to the transmit data registers (TX) and the HORX FIFO is full. The host processor sets TXDE using the initialize function. TXDE can assert the external HREQ/HTRQ signal if the TREQ bit is set. Regardless of whether the TXDE interrupt is enabled, TXDE indicates whether the TX registers are full and data can be latched in so that the host processor can use polling techniques.	The TX registers are not empty. The TX registers are empty and can be written by the host processor.

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

Table 29. 2K42A Mask Set ISR Bit Descriptions (Continued)

Name	Description	Settings
RXDF 15	Receive Data Full Indicates whether the Receive Word Registers (RX[0–3]) contain data from the SC140 core and can be read by the host processor. RXDF is set when the HOTX is transferred to the RX[0–3] registers. RXDF is cleared when the host processor reads the receive data registers (RX) at the last address and the HOTX FIFO is empty. The host processor can clear RXDF using the initialize function. RXDF can be used to assert the external HREQ/HRRQ signal if RREQ is set. Regardless of whether the RXDF interrupt is enabled, RXDF indicates whether the RX registers are full and data can be latched out, so that the host processor can use polling techniques.	The RX registers are not full. The RX registers are full and can be read by the host processor.

9.2.2 2K87M Mask Set ISR Definitions



ISR is a status register by which the host processor interrogates the status and flags of the HDI16. The host processor can write to this address without affecting the internal state of the HDI16. The SC140 core cannot access ISR.

Table 30. 2K87M Mask Set ISR Bit Descriptions

Name	Description		Settings
— 0–3	Reserved. Write to zero for future compatibility.		
TXDE32	Transmit Queue 32 Bytes Empty	0	< 32 bytes are empty
4		1	32 bytes are empty (24 bytes in HORX and 8 bytes in TX)
TXDE16	Transmit Queue 16 Bytes Empty	0	< 16 bytes are empty
5		1	16 bytes are empty (8 bytes in HORX and 8 bytes in TX)
RXDF32	Receive Queue 32 Bytes Full	0	< 32 bytes are full
6		1	32 bytes are full (24 bytes in HOTX and 8 bytes in RX)
RXDF16	Receive Queue 16 Bytes Full	0	< 16 bytes are full
7		1	16 bytes are full (8 bytes in HOTX and 8 bytes in RX)

Table 30. 2K87M Mask Set ISR Bit Descriptions (Continued)

Name	Description	Settings
HREQ	HREQ Status	If HDRQ is cleared:
8	HREQ indicates the status of the external transmit and receive request output signals (HTRQ and HRRQ) if HDRQ is set. If HDRQ is cleared, it indicates the status of the	No host processor interrupts requested.Interrupt requested.
	external host request output signal (HREQ). The HREQ bit can be set under either or both of two conditions: the	If HDRQ is set:
	Receive Word Registers (RX[0–3]) are full or the Transmit Word Registers (TX[0–3]) are empty. These conditions are	No host processor interrupts requested (HTRQ and HRRQ cleared).
	indicated by the ISR RXDF and TXDE status bits, respectively. If the interrupt source has been enabled by the	Interrupt requested (HTRQ or HRRQ set).
	associated request enable bit in the ICR, HREQ is set if one or more of the two enabled interrupt sources is set.	
HF[4-7]	Host Flags 4–7	
9–12	Indicates the state of host flags 4–7 in the HCR on the core side. Only the SC140 core can change HF[4–7].	
TRDY	TRDY Status	0 TX[0-3] and the HORX FIFO are not empty.
13	Indicates whether the Transmit Word Registers TX[0–3] and the HORX FIFO are empty. TRDY is set if TXDE is set and HRFNE is cleared. If TRDY is set, the data that the host processor writes to TX[0–3] is immediately transferred to the core side of the HDI16 and can be read by the SC140 core. This feature has many applications. For example, if the host	1 TX[0-3] and the HORX FIFO are empty.
	processor issues a host command that causes the SC140 core to read HORX, the host processor can be certain that the data it just transferred to the HDI16 is the same data received by the SC140 core.	
TXDE		0 The TX registers are not empty.
14	Transmit Data Empty Indicates whether the Transmit Word Registers (TX[0–3]) are empty and can be written by the host processor. TXDE is set when the contents of the TX[0–3] registers are transferred to the HORX register. TXDE is cleared when the host processor writes to the transmit data registers (TX) and the HORX FIFO is full. The host processor sets TXDE using the initialize function. TXDE can assert the external HREQ/HTRQ signal if the TREQ bit is set. Regardless of whether the TXDE interrupt is enabled, TXDE indicates whether the TX registers are full and data can be latched in so that the host processor can use polling techniques.	The TX registers are empty and can be written by the host processor. The TX registers are empty and can be written by the host processor.
RXDF	Receive Data Full	0 The RX registers are not full.
15 Note: A st	Indicates whether the Receive Word Registers (RX[0–3]) contain data from the SC140 core and can be read by the host processor. RXDF is set when the HOTX is transferred to the RX[0–3] registers. RXDF is cleared when the host processor reads the receive data registers (RX) at the last address and the HOTX FIFO is empty. The host processor can clear RXDF using the initialize function. RXDF can be used to assert the external HREQ/HRRQ signal if RREQ is set. Regardless of whether the RXDF interrupt is enabled, RXDF indicates whether the RX registers are full and data can be latched out, so that the host processor can use polling techniques.	The RX registers are full and can be read by the host processor.

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

9.3 HREQ Logic Differences

The following sections describe the implementation of HREQ logic for the 2K42A and 2K87M mask sets.

9.3.1 2K42A Mask Set HREQ Logic

When HREQ is connected to the host processor interrupt input, the HDI16 asserts HREQ to request service from the host processor. HREQ is asserted when TXDE is set and/or ISR[RXDF] is set, and the corresponding enable bit (TREQ or RREQ, respectively) is set, as **Figure 9** shows.

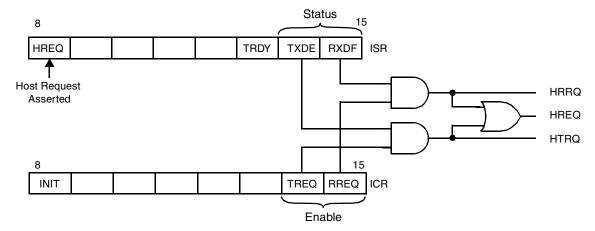


Figure 9. HDI16 Host Request Structure

The host processor acknowledges host interrupts by executing an interrupt service routine. The host processor tests ISR[RXDF] and ISR[TXDE] to determine the interrupt source. The host processor interrupt service routine must read or write the appropriate HDI16 data register to clear the interrupt. HREQ is deasserted under the following conditions:

- The enabled request is cleared or masked.
- The SC140 core is reset.

9.3.2 2K87M Mask Set HREQ Logic

When HREQ is connected to the host processor interrupt input, the HDI16 asserts HREQ to request service from the host processor. HREQ is asserted according to the programming of ICR[HTRA] and the status bits TXDE, TXDE16, and TXDE2 when ICR[TREQ] is set, or according to the programming of ICR[HRRA] and the status bits RXDF, RXDF16, and RXDF32 when ICR[RREQ] is set, as **Figure 10** shows. The programming of HRRA or HTRA chooses the status bit, and depending on its value, HREQ is asserted or deasserted.

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

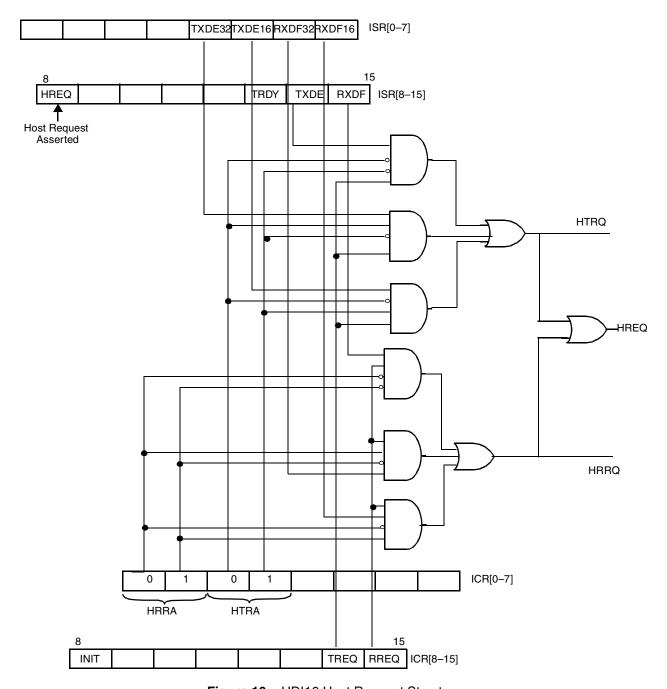


Figure 10. HDI16 Host Request Structure

The host processor acknowledges host interrupts by executing an interrupt service routine. The host processor tests the appropriate status bit (TXDE, TXDE16, TXDE32, RXDF, RXDF16, or RXDF32, depending on the application) to determine the interrupt source. The host processor interrupt service routine must read or write the appropriate HDI16 data register to clear the interrupt. HREQ is deasserted under the following conditions:

- The enabled request is cleared or masked.
- The SC140 core is reset.

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

10 DMA Transfer Code Definitions

The TC code definitions for mask sets 2K42A and 2K87M are as follows:

Table 31. Transfer Code Encoding

TC[0-2]	2K42A	2K87M
000	Reserved	Reserved
001	Reserved	Reserved
010	Reserved	Reserved
011	Reserved	Reserved
100	Reserved	DMA function code 0
101	SC140 core	SC140 core/DMA function code 1
110	SDMA/DMA function code 0	SDMA
111	SDMA/DMA function code 1	SDMA

11 Interrupt System

11.1 SCPRR_L and SCPRR_L_EXT Changes

For mask set 2K87M, the TC layer interrupts are configured with the SCCs using the YCC entries defined by the CPM Low Interrupt Priority Registers (SCPRR_L and SCPRR_L_EXT). For the fields YC1P-YC8P in each register, the value 100 (which was reserved for mask set 2K42A) is reassigned to "TC layer asserts its request in the YCCn position."

11.2 TC Layer Interrupts

The TC layer accesses use interrupt vector 44 (this was reserved for mask set 2K42A).

12 Debugging

12.1 JTAG ID Changes

The JTAG ID value for the 2K42A mask set is 0x0188201D. The JTAG ID value for the 2K87M mask set is 0x1188201D.

12.2 EOnCE Status Register (ESR) Values

For the 2K42A mask set, ESR[REVNO] = 1 and ESR[CORETP] = 1. For the 2K87M mask, ESR[REVNO] = 2 and ESR[CORETP] = 2.

12.3 EOnCE Counter Register Values

For the 2K42A mask set, the Event Counter Value Register (ECNT_VAL) and the Extension Counter Value Register (ECNT_EXT) have a maximum value of 0xFFFFFFF. For the 2K87M mask set, the most significant bit (MSB) of these registers is hard-wired to 0, limiting the maximum register value to 0x7FFFFFF. When reading either register, the MSB is always zero. For future compatibility, always write a 0 to the MSB of these registers.

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

37

Note: When the counter value is written to the trace buffer, it is shifted one position to the left so the debugger can use the least significant bit (LSB) to identify a new entry in the trace buffer.

13 EFCOP

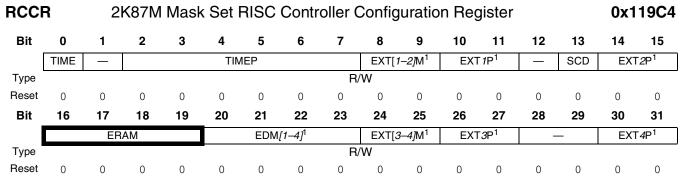
The MSC8103 mask set 2K87M does not support an EFCOP module.

14 CPM

The 2K87M CPM adds functionality. The contents of the RISC Controller Configuration Register (RCCR) changed to accommodate the increased size of the Dual-Port RAM. Support for a ROM-based Inverse Multiplexing for ATM (IMA) microcode was added. Transmission convergence (TC) layer functionality required to support IMA was added to the Time-Slot Assigner (TSA). Also, new MCC host commands are added. The following sections discuss these changes.

14.1 RISC Controller Configuration Register (RCCR) Changes

The 2K87M mask set RISC Controller Configuration (RCCR) expands the Enable RAM Microcode (ERAM) field from 3 to 4 bits wide (adding RCCR to 19 bit which was reserved in the 2K42A mask set) to reflect the availability of dual-port RAM space starting at address 0x4000.



Notes: 1. Reserved for future microcode applications

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

RCCR configures the CP to run microcode from ROM or RAM and controls the CP internal timer.

Table 32. 2K87M Mask Set RCCR Bit Descriptions

	Description	Settings		
0	Timer Enable Enables the CP internal timer that generates a tick to the CP based on the value programmed into the TIMEP field. TIME can be modified at any time to start or stop the scanning of the RISC timer tables.	0	Timer disabled Timer enabled	
0	Reserved. Write to zero for future compatibility.			
0	Timer Period Controls the CP timer tick. The RISC timer tables are scanned on each timer tick, and the input to the timer tick generator is the general system clock (150 MHz) divided by 1,024. The formula is (TIMEP + 1) × 1,024 = (general system clock period). Thus, a value of 0 stored in these bits gives a timer tick of 1 × (1,024) = 1,024 general system clocks and a value of 63 (decimal) gives a timer tick of 64 × (1,024) = 65,536 general system clocks.			
0	External Request Mode	0	EXTx is edge sensitive according to EDMx	
	Controls the external request sensitivity	1	EXTx is level sensitive according to EDMx	
	Note: Reserved for future microcode applications.			
0	External Request Priority Controls the external request priority relative to communication controllers Note: Reserved for future microcode applications.	00	EXTx has higher priority than the communication controllers (default) EXTx has lower priority than the communications controllers	
		10	EXTx has the lowest priority	
		11	Reserved	
0	Reserved. Write to zero for future compatibility.			
0	Scheduler Configuration	0	Normal operation	
	Configure as instructed in the download process of a Freescale-supplied RAM microcode package.	1	Alternate configuration of the scheduler	
0	External Request Priority Controls the external request priority relative to communication controllers Note: Reserved for future microcode applications.	00 01 10 11	EXTx has higher priority than the communication controllers (default) EXTx has lower priority than the communications controllers EXTx has the lowest priority Reserved	
	0 0 0	Enables the CP internal timer that generates a tick to the CP based on the value programmed into the TIMEP field. TIME can be modified at any time to start or stop the scanning of the RISC timer tables. O Reserved. Write to zero for future compatibility. O Timer Period Controls the CP timer tick. The RISC timer tables are scanned on each timer tick, and the input to the timer tick generator is the general system clock (150 MHz) divided by 1,024. The formula is (TIMEP + 1) × 1,024 = (general system clock period). Thus, a value of 0 stored in these bits gives a timer tick of 1 × (1,024) = 1,024 general system clocks and a value of 63 (decimal) gives a timer tick of 64 × (1,024) = 65,536 general system clocks. O External Request Mode Controls the external request sensitivity Note: Reserved for future microcode applications. O External Request Priority Controls the external request priority relative to communication controllers Note: Reserved for future microcode applications. O Reserved. Write to zero for future compatibility. O Scheduler Configuration Configure as instructed in the download process of a Freescale-supplied RAM microcode package. External Request Priority Controls the external request priority relative to communication controllers	Enables the CP internal timer that generates a tick to the CP based on the value programmed into the TIMEP field. TIME can be modified at any time to start or stop the scanning of the RISC timer tables. Timer Period Controls the CP timer tick. The RISC timer tables are scanned on each timer tick, and the input to the timer tick generator is the general system clock (150 MHz) divided by 1,024. The formula is (TIMEP + 1) × 1,024 = (general system clock period). Thus, a value of 0 stored in these bits gives a timer tick of 1 × (1,024) = 1,024 general system clocks and a value of 63 (decimal) gives a timer tick of 64 × (1,024) = 65,536 general system clocks. External Request Mode Controls the external request sensitivity Note: Reserved for future microcode applications. Note: Reserved for future microcode applications. Note: Reserved for future microcode applications. On the external request priority relative to communication controllers Note: Reserved for future compatibility. On the external request priority relative to communication controllers On the external request priority relative to communication controllers On the external request priority relative to the configuration On the external request priority relative to the configure as instructed in the download process of a preescale-supplied RAM microcode package. On the external request priority relative to communication controllers On the external request priority relative to communication controllers On the external request priority relative to communication controllers On the external request priority relative to communication controllers On the external request priority relative to communication controllers On the external request priority relative to communication controllers On the external request priority relative to communication controllers On the external request priority relative to communication controllers On the external request priority relative to communication controllers On the external requ	

Table 32. 2K87M Mask Set RCCR Bit Descriptions (Continued)

Name	Reset	Description		Settings
ERAM	0	Enable RAM Microcode		
16–19		Configure as instructed in the download process of a Freescale-supplied RAM microcode package.	ERAM	RAM Microcode
			0000	Disable microcode program execution from the dual-port RAM.
			For the fo	ollowing, execution starts at 0x0000
			0010	Microcode uses the first 2 KB + 8 KB from 0x4000
			0100	Microcode uses the first 4 KB + 8 KB from 0x4000
			0110	Microcode uses the first 6 KB + 8 KB from 0x4000
			1000	Microcode uses the first 8 KB + 8 KB from 0x4000
			1010	Microcode uses the first 10 KB + 8 KB from 0x4000
			1100	Microcode uses the first 12 KB + 8 KB from 0x4000
			For the fo	ollowing, execution starts at 0x4000 et:
			0011	Microcode uses the first 2 KB starting from 0x4000
			0101	Microcode uses the first 4 KB starting from 0x4000
			0111	Microcode uses the first 6 KB starting from 0x4000
			1001	Microcode uses the first 8 KB starting from 0x4000
			All other	combinations are reserved.
				area was expanded from the 3-bit field used 42A mask set.
EDM[1-4]	0	Edge Detect Mode		w to high change for EXT $x = 0$, active high
20–23		EXTx asserts requests according to settings	for FX	T x = 1
		Note: Reserved for future microcode applications.	1 Hig	th to low change for EXT $x = 0$, active low for $T x = 1$
EXT[3-4]M	0	External Request Mode		Tx is edge-sensitive according to EDMx
24–25		Controls the external request sensitivity		Tx is level-sensitive according to EDMx
		Note: Reserved for future microcode applications.		
EXT3P 26–27	0	External Request Priority Controls the external request priority relative to	cor	T <i>x</i> has higher priority than the nmunication
		communication controllers	'co	ntrollers (default)
		Note: Reserved for future microcode applications.	cor	T <i>x</i> has lower priority than the nmunications
				ntrollers
				T <i>x</i> has the lowest priority served
	0	Reserved for future applications		

Table 32. 2K87M Mask Set RCCR Bit Descriptions (Continued)

Name	Reset	Description	Settings
EXT4P 30–31	0	External Request Priority Controls the external request priority relative to communication controllers	00 EXTx has higher priority than the communication controllers (default)
		Note: Reserved for future microcode applications.	01 EXT <i>x</i> has lower priority than the communications
			controllers
			10 EXTx has the lowest priority
			11 Reserved

14.2 Dual-Port RAM Change

The dual-port RAM has been expanded to 32 KB of static RAM. An extra 8 KB starting at address 0x4000 is available for microcode execution only and cannot be used for data buffers or BDs. However, when not used for microcode, the extra 8 KB can be accessed from the system bus for general purpose internal storage.

14.2.1 2K42A Mask Set 24 KB Dual-Port RAM Memory Map

Figure 11 shows the MSC8101 2K42A mask set memory map of the dual-port RAM.

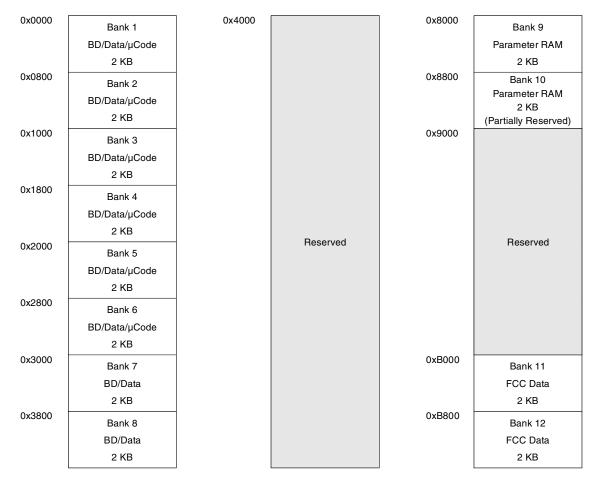


Figure 11. 2K42A Mask Set 24 KB Dual-Port RAM Memory Map

14.2.2 2K87M Mask Set Dual-Port RAM Memory Map

Figure 12 shows the MSC8103 2K87M mask set memory map of the dual-port RAM.

0x0000		0x4000		0x8000	
0.0000	Bank #1	0,4000	Bank #13	0x8000	Bank #9
	BD/Data/µCode		Microcode		Parameter RAM
	2 KB		2 KB		2 KB
0x0800	Bank #2	0x4800	Bank #14	0x8800	Bank #10
	BD/Data/µCode		Microcode		Parameter RAM 2 KB
	2 KB		2 KB		(Partially Reserved)
0x1000	Bank #3	0x5000	Bank #15	0x9000	
	BD/Data/µCode		Microcode		
	2 KB		2 KB		
0x1800	Bank #4	0x5800	Bank #16		
	BD/Data/µCode		Microcode		
	2 KB		2 KB		
0x2000	Bank #5	0x6000			Reserved
	BD/Data/µCode				
	2 KB				
0x2800	Bank #6				
	BD/Data/µCode				
	2 KB		Reserved		
0x3000	Bank #7			0xB000	Bank #11
	BD/Data				FCC Data
	2 KB				2 KB
0x3800	Bank #8			0xB800	Bank #12
	BD/Data				FCC Data
	2 KB				2 KB
	•				

Figure 12. 2K87M Mask Set 32 KB Dual-Port RAM Memory Map

14.3 IMA Functionality

IMA functionality is similar to the updated functionality described in *MPC8266AUMAD/D* for updates to the MPC826x product family. This document can be accessed from the Freescale website listed on the back page of this document.

14.4 TSA Changes

The 2K87M mask set adds functionality required to support the new ATM transmission convergence (TC) layer added to the communications processor module (CPM) in the time-slot assigner (TSA). This functionality can only be configured and used by the fast communications controller 2 (FCC2) for ATM interfaces using the IMA functionality.

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

14.4.1 TC Layer Functionary

Figure 13 shows a block diagram of the SI blocks and TSA. The TSA also contains transmission convergence (TC) layer hardware.

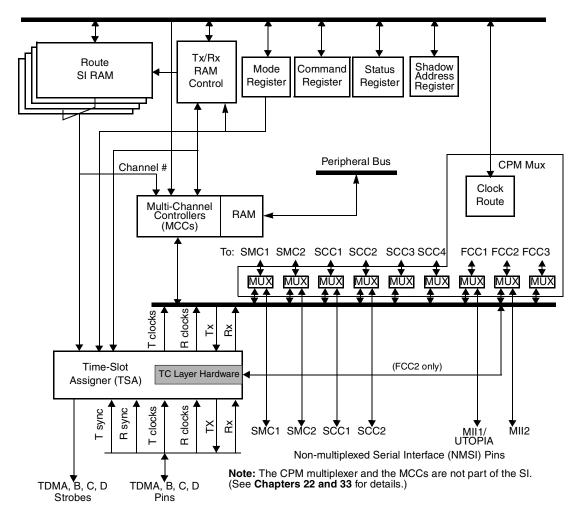


Figure 13. SI Block Diagram

Note: TC layer support for ATM (FCC2 only) with TC layer 1 supported through TDMA1 and TC layers 6–8 supported through TDMB2, TDMC2, and TDMD2, respectively.

For the FCC2 ATM UTOPIA 8, the SI supports the following:

- Four TDM channels routed in hardware to a TC layer block
- Protocol-specific overhead bits may be discarded or routed to other controllers by the SI
- Performing ATM TC layer functions (according to ITU-T I.432)
- Transmit (Tx) updates include:
 - Cell HEC generation
 - Payload scrambling using self synchronizing scrambler (programmable by the user)
 - Coset generation (programmable by the user)
 - Cell rate by inserting idle/unassigned cells
- Receive (Rx) updates include:
 - Cell delineation using bit by bit HEC checking and programmable ALPHA and DELTA parameters for the

delineation state machine

- Payload descrambling using self synchronizing scrambler (programmable by the user)
- Coset removing (programmable by the user)
- Filtering idle/unassigned cells (programmable by the user)
- Performing HEC error detection and single bit error correction (programmable by the user)
- Generating loss of cell delineation status/interrupt (LOC / LCD)
- Serial loop back mode
- · Cell echo mode
- Supports both FCC transmit modes:
 - External rate mode—Idle cells are generated by the FCC (microcode) to control data rate
 - Internal rate mode (sub-rate)—FCC transfers only the data cells using the required data rate. The TC layer generates idle/unassigned cells to maintain the line bit rate
- Supports the TC layer and PMD (physical medium dependant) WIRE interface (according to the ATM-Forum af-phy-0063.000)

14.4.2 ATM TC Layer Support

The MSC8103 supports applications that receive ATM traffic over the standard serial protocols like E1, T1, and xDSL via its serial interface (SIx TDMx and NMSI) ports because the ATM TC-layer functionality is implemented internally. This allows the use of standard low-cost PHY devices in system applications instead of PHYs that support UTOPIA bus devices. A typical TC layer application requires the use of one SI TDM channel per TC block.

As shown in **Figure 14**, all TC blocks are internally connected to FCC2. In addition, **Figure 14** shows FCC1 connected to a UTOPIA 8-bit MPHY bus that can be routed outside and operated independently from the TC block

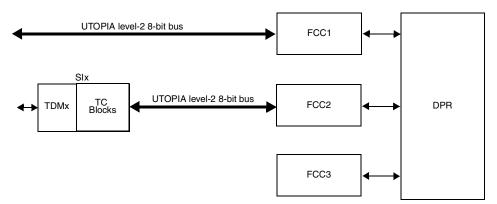


Figure 14. Serial ATM Interface Using FCC2 and TC blocks (single channel)

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

14.4.3 TC Layer Support

The TC layer block is shown in **Figure 15**. The transmit and the receive parts are independent; the only case in which they are synchronized is in cell echo mode.

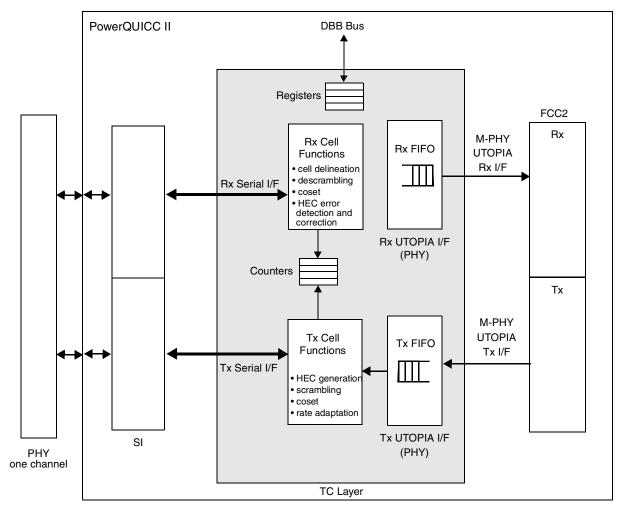


Figure 15. TC Layer Block Diagram

14.4.4 Signals

The TC layer operates via an SI TDM port or NMSI port using a serial protocol. Synchronization signals are required for some applications and must be supported. **Table 33** describes the signals for operating the TC layer.

Signal	Direction	Description	
TXC	Input	Input Transmit Clock. Clocks Tx data out of the TC to external device.	
TXD	Output	ransmit Data from TC to external device.	
Tx Sync	Input	Transmit Synch. Synchronizes the transmit data to the beginning of a frame.	
RXC	CC Input Receive Clock. Clocks the data into the TC.		
RXD	Input	Receive Data. From external device to the TC.	
Rx Sync	Input	Receive Synch. Synchronizes the received data. Not required in NMSI mode.	

Table 33. TC Layer Signals

14.4.5 Receive ATM Cell Functions

The ATM receive cell functions block (RCF) performs the receive functions of the TC block. It performs cell delineation, cell payload descrambling, HEC verification and correction, and idle/unassigned cell filtering.

Cell delineation is the process of framing data to ATM cell boundaries using the header error check (HEC) received in the ATM cell header. The HEC is a CRC-8 calculation over the first four octets of the ATM cell header. The cell delineation algorithm assumes that repetitive correct HEC calculations over consecutive cells indicate valid ATM cell boundaries.

The RCF performs a sequential bit-by-bit hunt for a correct HEC sequence, and the cell delineation state machine is in HUNT state. When a correct HEC is found, the RCF locks on the particular cell boundary and enters the PRESYNCH state, which indicates that the previously detected HEC pattern is not a false indication. If a correct HEC pattern is false, an incorrect HEC is received within the next DELTA cells. If an incorrect cell is detected, there is a transition to the HUNT state. If an incorrect HEC is not detected in the PRESYNCH state, there is a transition to the SYNCH state. In the SYNCH state, the TC is assumed to be synchronized so that other functions can be applied to the received cell. A transition back to the HUNT state is made only after ALPHA consecutive incorrect HEC patterns are detected.

The cell delineation state machine is shown in **Figure 16**. The ALPHA and DELTA parameters determine the robustness of the delineation method. ALPHA determines the robustness against false misalignment due to bit errors. DELTA determines the robustness against false delineation in the synchronization. Both parameters are programmable for each TC block and are provided to help tune the system according to the line error characteristics of a specific application.

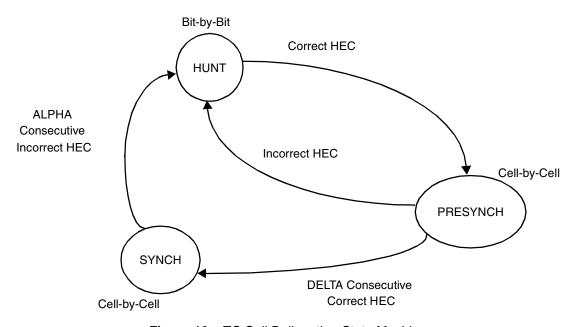


Figure 16. TC Cell Delineation State Machine

The RCF descrambles (programmable) the cell payload using the self-synchronizing descrambler with a polynomial of $x^{43} + 1$.

The HEC calculation is a CRC-8 calculation over the first four octets of the ATM cell header. The RCF verifies the received HEC using the accumulation polynomial, $x^8 + x^2 + x + 1$. The coset polynomial $x^6 + x^4 + x^2 + 1$ is added (modulo 2) to the received HEC octet before comparison with the calculated result (programmable).

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

The RCF can perform single bit error correction on the header. If multiple bit errors are found in the HEC, the cell is discarded. If the single bit error correction mode is not enabled (TCMODE[SBC] = 1), the cell is also discarded when a single bit error is found in the header.

When the cell delineation state machine is in the SYNCH state, the HEC verification state machine (see **Figure 17**) implements the correction algorithm. This state machine ensures that a single cell header is corrected at a time. If consecutive cells are detected with single bit errors in their headers, only the first cell error is corrected and the rest are discarded. This state machine reduces the delivery of cells with headers containing errors under bursty error conditions.

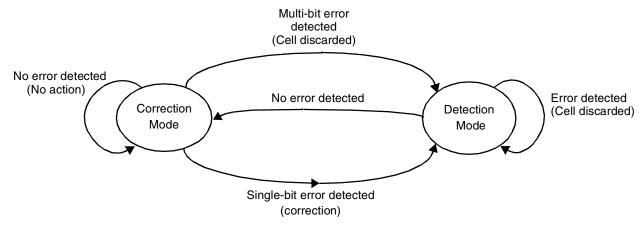


Figure 17. HEC: Receiver Modes of Operation

The RCF can also perform idle/unassigned cell filtering. Both features are programmable (TCMODE[CF]). Cells that are detected to be idle/unassigned are discarded, that is, not forwarded to the UTOPIA interface Rx FIFO.

14.4.6 Receive ATM 2-Cell FIFO

The receive FIFO provides FIFO management and an interface to the UTOPIA receive cell interface. The receive FIFO can hold 2 ATM cells, thereby providing the cell rate decoupling function between the transmission system physical layer and the ATM layer. FIFO management includes filling the FIFO, indicating to the UTOPIA interface that it contains cells, maintaining the FIFO read and write pointers, and detecting FIFO overrun (TCER[OR]) conditions.

14.4.7 Transmit ATM Cell Functions

The transmit ATM cell functions block (TCF) performs the ATM cell payload scrambling and is responsible for the HEC generation and the idle/unassigned cell generation. The TCF scrambles (programmable by the user) the cell payload using the self-synchronizing scrambler with polynomial $x^{43} + 1$. The HEC is generated using the polynomial $x^8 + x^2 + x + 1$. The coset polynomial $x^6 + x^4 + x^2 + 1$ is added (modulo 2) (programmable by the user) to the calculated HEC octet. The result overwrites the HEC octet on the transmitted cell. When the transmit FIFO is empty, the TCF inserts idle/unassigned cells (counted in ICC). The TCF accumulates the number of transmitted assigned cells in a counter (TCC).

14.4.8 Transmit ATM 2-Cell FIFO

The transmit FIFO provides FIFO management and an interface to the UTOPIA transmit interface. The FIFO provides the cell rate decoupling between the transmission system physical layer and the ATM layer.

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

The FIFO management includes emptying cells from the transmit FIFO, indicating to the UTOPIA interface that it is full, maintaining the FIFO read and write pointers, and detecting FIFO underrun (TCER[UR]) conditions.

14.4.9 Rx UTOPIA Interface

The receive interface with the FCC via the UTOPIA bus implements the UTOPIA level-2 (multi-PHY) 8-bit PMD side (slave) interface.

14.4.10 Tx UTOPIA Interface

The transmit interface with the FCC via the UTOPIA bus implements the UTOPIA level-2 (multi-PHY) 8-bit PMD side (slave) interface.

14.4.11 TC Layer Registers

Each TC layer block is controlled by registers in the block and accessed from the 60x-compatible bus.

14.4.12 TC Layer Mode Register (TCMODE)

Each TC layer block is configured using a TC layer mode register TCMODEx, as shown in Figure 18.

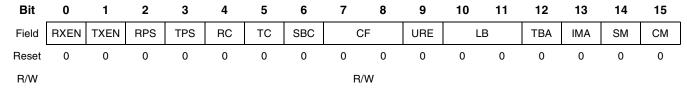


Figure 18. TCMODEx

Table 34 describes TCMODE fields.

Table 34. TCMODE Field Descriptions

Name	Description		Settings
RXEN	TC Layer Receive Enable	0	TC Layer Rx operation disabled
0	Enables the TC Layer Rx block operation	1	TC Layer Rx operation enabled
TXEN	TC Layer Transmit Enable	0	TC Layer Tx operation disabled
1	Enables the TC Layer Tx block operation	1	TC Layer Tx operation enabled
RPS	Receive Payload Descrambling Disable	0	Received payload descrambling
2	Disables payload descrambling on received payload data	1	No received payload descrambling
TPS	Transmit Payload Scrambling Disable		Transmit payload scrambling
3	Disables payload scrambling on transmitted payload data	1	No transmit payload scrambling
RC	Receive Coset Disable		XOR with 0xAA on received HEC
4	Disables XOR with 0xAA on received HEC	1	No XOR with 0xAA on received HEC
TC	Transmit Coset Disable	0	XOR with 0xAA on transmitted HEC
5	Disables XOR with 0xAA on transmitted HEC	1	No XOR with 0xAA i on transmitted
			HEC
SBC	Header Single Bit error Correction Disable	0	Single bit error correction
6	Disables single bit correction on the header according to HEC in Sync mode.	1	No single bit error correction

Table 34. TCMODE Field Descriptions (Continued)

Name	Description	Settings		
CF	Receive Idle/unassigned Cells Filtering	00	No cell filtering is done on Rx cells.	
7–8	cell (ITU-T I.361) is 0b00000000_00000000_00000000_00000001. The header of an unassigned cell (ITU-T I.361) is 0b00000000_00000000_00000000_0000xx0 Physical layer cells bypass the TC layer: they are not filtered. The filter works	01	Idle cell filtering is done and idle cells are discarded.	
		10	Unassigned cell filtering is done and unassigned cells are discarded.	
		11	Idle and unassigned cell filtering is done and both idle and unassigned cells are discarded.	
URE	Underrun interrupt (TCER[UR]) enable	0	Underrun interrupt disabled	
9	An underrun interrupt may be set when an idle cell is generated by the TC.	1	Underrun interrupt enabled	
LB	Loopback/echo modes	00	Normal operation.	
10–11	For echo mode operation, clear TCMODE[SM], independent of the FCC multi- PHY mode configuration.		Cell echo mode operation. Received cells are transmitted and do not go out to the UTOPIA bus.	
		10	Data loopback mode operation. Transmit data stream is connected to the receive data stream.	
		11	Not used.	
TBA 12	Transmit Byte Align Enables alignment of transferred bytes to the Tx Sync signal.	0	Tx data is transferred as soon as it is enabled	
		1	Tx data is transferred byte-aligned to the Tx Sync signal	
IMA	IMA mode	0	Rx is not in IMA	
13	Enables IMA mode.	1	Rx is in IMA mode	
SM	Single Mode	0	TC is not the only PHY on UTOPIA	
14	Indicates whether the TC is the only PHY on the UTOPIA interface.	1	TC is the only PHY on UTOPIA	
CM 15	Cell Counters Mode Disables the counter read and then clear function.	0	Reading a cell counter clears the counter	
		1	Reading a cell counter does not change the counter value	

14.4.13 Cell Delineation State Machine Register (CDSMRx)

The cell delineation state machine register (CDSMR), shown in **Figure 19**, holds the ALPHA and DELTA parameters of the cell delineation state machine.

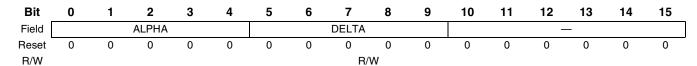


Figure 19. CDSMRx

Table 35 describes the CDSMR fields.

Table 35. CDSMR Field Descriptions

Name	Description				
ALPHA 0-4	ALPHA Consecutive received cells with incorrect HEC are counted by the cell delineation state machine to pass from state SYNCH to state HUNT.				
DELTA 5-9	DELTA Consecutive received cells with correct HEC are counted by the cell delineation state machine to pass from state PRESYNCH to state SYNCH.				
 10–15	Reserved. Write to 0 for future compatibility.				

14.4.14 TC Layer Event Register (TCERx)

The TC layer event registers (TCERx), as shown in **Figure 20**, records error events for each TC block. TCER event bits are cleared by writing ones to them.

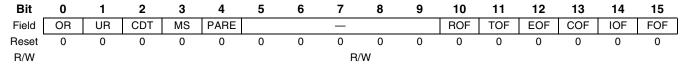


Figure 20. TCERx

The TCER bits are described in **Table 36**.

Table 36. TCER Field Descriptions

Name	Description	Description	
OR 0	Overrun Indicates whether the Rx FIFO is full when a complete cell is received.	 The Rx FIFO is not full or another complete cell is not received. The Rx FIFO is full and another complete cell is received. The cell is discarded. 	
UR 1	Underrun Indicates whether there is no ATM cell to transmit. The interrupt is enabled only if TCMODE[URE] is set.	The Tx FIFO is not empty or the cell transmission is not completed. The Tx FIFO is empty and the cell transmission is completed. An idle cell is sent. The idle cell header is 0x00000001 (I.432), whose HEC is 0x52. The idle cell payload is 0x6A (I.432).	
CDT 2	Cell delineation toggled Indicates whether the cell delineation bit (TCGSR[CD]) bit changed.	TCGSR[CD] did not change.TCGSR[CD] changed.	
MS 3	Misplaced Tx Sync signal Indicates whether the Tx Sync is out of place. The first Tx Sync is by definition always in place.	Tx Sync is not out of place.Tx Sync is out of place.	
PARE 4	Parity event Indicates whether the parity is incorrect.	The transmit parity from UTOPIA is correct.The transmit parity from UTOPIA is wrong.	
— 5–9	Reserved. Write to 0 for future compatibility.		
ROF 10	Received cell counter overflow Indicates that the received cells counter passed its maximum value.	The received cells counter did not pass its maximum value. The received cells counter passed its maximum value.	
TOF 11	Transmitted cell counter overflow Indicates that the transmitted cells counter passed its maximum value.	The transmitted cells counter did not pass its maximum value. The transmitted cells counter passed its maximum value.	
EOF 12	Errorred cells counter overflow Indicates that the errorred cells counter passed its maximum value.	 The errored cells counter did not pass its maximum value. The errored cells counter passed its maximum value. 	
COF 13	Corrected cells counter overflow Indicates that the corrected cells counter passed its maximum value.	 The corrected cells counter did not pass its maximum value. The corrected cells counter passes its maximum value. 	
IOF 14	Tx Idle cells counter overflow Indicates that the Tx idle cells counter passed it maximum value.	 The Tx idle cells counter did not pass its maximum value. The Tx idle cells counter passes its maximum value. 	
FOF 15	Filtered cells counter overflow Indicates that the filtered cells counter passed its maximum value.	 The filtered cells counter did not pass its maximum value. The filtered cells counter passed its maximum value. 	

14.4.15 TC Layer Mask Register (TCMRx)

The TCMRx field description is identical to that of TCER (refer to **Section 14.4.14**). Each bit that is set in TCMR enables an interrupt when the corresponding bit in TCER is set.

14.4.16 TC Layer General Registers

The TC layer general registers are distributed to all of the TC blocks. Each TC block is represented by specific bits. When accessing a general register, each TC block is responsible only for its bits.

14.4.17 TC Layer General Event Register (TCGER)

The TC layer general event register (TCGER), shown in **Figure 21**, summarizes the events for all the TC blocks. Each bit stands for an ORed event register of a TC block. When a bit is set, it indicates that one or more event bits are set in the corresponding TC block event register.

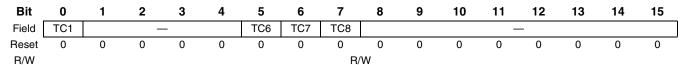


Figure 21. TCGER

Table 37 describes TCGER fields.

Table 37. TCGER Field Descriptions

Name	Description		Settings
TC1	TC1 Event	0	No event.
0	Indicates whether a TC layer 1 event occurred.	1	One or more bits are set in TC1 event register.
_	Reserved. Write to 0 for future compatibility.		
1–4 TC6	TC6 Event		Negriph
TC6		0	No event.
0	Indicates whether a TC layer 6 event occurred.	1	One or more bits are set in TC6 event register.
TC7	TC7 Event	0	No event.
0	Indicates whether a TC layer 7 event occurred.	1	One or more bits are set in TC7 event register.
TC8	TC8 Event	0	No event.
0	Indicates whether a TC layer 8 event occurred.	1	One or more bits are set in TC8 event register.
— 8–15	Reserved. Write to 0 for future compatibility.	•	

14.4.18 TC Layer General Status Register (TCGSR)

Figure 22 shows the TC layer general status register (TCGSR), which records the cell delineation and transmit FIFO status for all TC blocks.

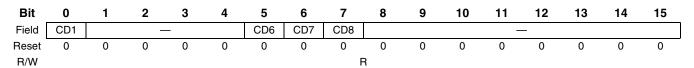


Figure 22. TCGSR

Table 38 describes TCGSR fields.

Table 38. TCGSR Field Descriptions

Name	Description		Settings
CD1 0	Cell Delineation The cell delineation state machine status of TC1.	 Cell delineation state machine is in Hunt or Pre-Synch mode. Cell delineation machine is in Synch mode. 	
— 1–4	Reserved. Write to 0 for future compatibility.		
CD6 0	Cell Delineation The cell delineation state machine status of TC6.	0	Cell delineation state machine is in Hunt or Pre-Synch mode. Cell delineation machine is in Synch mode.
CD7 0	Cell Delineation The cell delineation state machine status of TC7.	0	Cell delineation state machine is in Hunt or Pre-Synch mode. Cell delineation machine is in Synch mode.
CD8 0	Cell Delineation The cell delineation state machine status of TC8.	0	Cell delineation state machine is in Hunt or Pre-Synch mode. Cell delineation machine is in Synch mode.
8–15	Reserved. Write to 0 for future compatibility.		

14.4.19 TC Layer Cell Counters

Each TC block maintains six memory-mapped 16-bit performance cell counters listed in **Table 39** that are updated during operation and can be read by the host. If a counter overflows, it wraps back to zero and generates a maskable interrupt. These counters are automatically cleared when read if TCMODE[CM] = 0; see **Section 14.4.12**.

Table 39. TC Performance Cell Counters

Counter Name	Description
Received Cell Counter (RCC)	This cell counter is updated whenever a received cell without HEC errors is passed to the Rx UTOPIA FIFO.
Transmitted Cell Counter (TCC)	This cell counter is updated whenever the transmission of a cell is completed.
Errored Cell Counter (ECC)	This cell counter is updated whenever a received errored cell (cell with header error) is discarded.
Corrected Cell Counter (CCC)	This cell counter is updated whenever a received cell with a HEC single bit error is corrected. If header single bit error correction is not enabled (TCMODE[SBC] is set), this counter is not updated. (All errored cells are counted by the errored cell counter (ECC).)
Tx IDLE Cell Counter (ICC)	This cell counter is updated whenever an idle cell is transmitted.
Filtered Cell Counter (FCC)	This cell counter is updated whenever an idle/unassigned cell is filtered (discarded). If cell filters are not enabled (TCMODE[CF] is cleared), this counter is not updated.

14.4.20 Programming FCC2

FCC2 is designed to work with the TC blocks. The TC blocks are located on fixed addresses on the UTOPIA bus internally. FCC2 should be programmed to work with the TC blocks as if the TC blocks are external PHYs located on the lowest eight (or fewer) addresses.

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

14.4.21 Programming and Operating the TC Layer

The host should first program the mode registers of each TC block to be active, according to the number of TC channels required. Then, FCC2 is programmed to work on the UTOPIA interface with the active TC blocks. Finally, FCC2 and the PHYs of the TC channels are enabled. The transmit channels for each TC block are enabled by setting TCMODEx[TXEN]. The receive channels for each TC block are enabled by setting TCMODEx[RXEN]. The host polls the CD bits of each enabled TC block to verify that its receive cell delineation state machines are synchronized. For every TC block that is synchronized, the host clears the CDT bit in its event register. When all the enabled TC blocks are synchronized, the host terminates its initialization routine, and the system starts normal operation.

When a TC block gets out of synchronization, the corresponding TCGSR[CD] is cleared. This change causes a TCER[CDT] interrupt to the host (if enabled).

On the receive path, the TC performs the following functions:

- 1. Receives the bit stream via the SI.
- **2.** Attempts to gain synchronization on the ATM cell boundaries by checking each byte (HEC candidate) against the HEC calculated on the preceding 32 bits (ATM cell header candidate).
- **3.** Once synchronized, performs the descrambling function on the cell payload (if enabled), performs the coset function on the HEC (if enabled), checks for HEC errors and corrects single HEC errors when found (again, if enabled). Cells containing multi-bit header errors (at least 2 errors) are discarded. Idle and unassigned cells are filtered (discarded) when detected (if the filters are enabled). Once a cell is processed, it passes to the TC receive FIFO, and the internal TC cell counters are updated. The cell is passed from the TC receive FIFO via the UTOPIA interface to the FCC2 receive FIFO.

An overrun condition occurs when the TC receive FIFO is full, the CP is busy, and the FCC cannot read a cell from it via the UTOPIA interface before another valid cell is received. The incoming cell is discarded and TCER[OR] interrupt is sent to the host (if enabled).

On the transmit path, once enabled, the TC performs the following functions:

- 1. Starts requesting for cells to send via the UTOPIA interface.
- 2. When a cell is passed via the UTOPIA interface to the TC transmit block, it is stored in the TC transmit FIFO.
- **3.** When a cell is to be sent, it is read from the TC transmit FIFO and is processed. The scrambling function is performed on its payload (if enabled), its header HEC value is calculated and the coset function is performed on the HEC (if enabled).
- **4.** The cell is then sent to the PHY via the SI. Once the cell transmission is complete, the relevant TC cell counters are updated.

An underrun condition occurs when a cell is to be sent to maintain the bit rate, but the TC transmit FIFO is empty. An idle cell is sent instead. This condition generates a TCER[UR] interrupt (if not masked) if TCMODE[URE] is set. When a TC cell counter overflows, an interrupt is set (if enabled).

A TC channel provides the data rate dictated by the PMD device by operating the FCC2 in one of two modes:

• External Rate. In this mode, the external device determines the data rate. The CP keeps the FCC FIFO full by inserting ATM cells or idle cells (if ATM cells are not available) into the FCC FIFO whenever it is not full. This operation ensures that the cell stream is the data rate required by the PMD. In general, the TC transmit FIFO is never empty, and thus would not need to generate idle cells. However, if the CP is busy, and the TC is forced to generate an idle cell because its transmit FIFO is empty, an underrun condition occurs. The UR interrupt is sent to the host (if not masked) if TCMODE[URE] is set. See Figure 23. This mode generates a greater CP load than the internal rate mode.

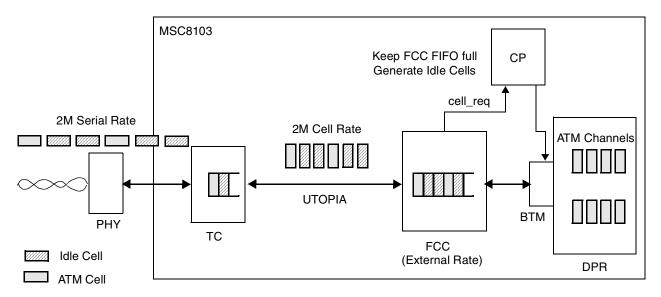


Figure 23. TC Operation in FCC External Rate Mode

• Internal Rate (Sub Rate). In this mode, the FCC supplies only four PHY devices that have four distinct addresses. Each channel is controlled by a dedicated hardware timer that is programmed and tuned to the data rate needed. When a timer expires, a valid cell is sent to the corresponding PHY. The PHY sends idle cells to keep its synchronization and transmission rate. The same is true for the TC. Once activated with FCC2 in this mode, the TC requests cells and sends idle cells (UR interrupts can be disabled by clearing TCMODE[URE]) until a valid cell is transferred via the UTOPIA bus from the FCC. See Figure 24.

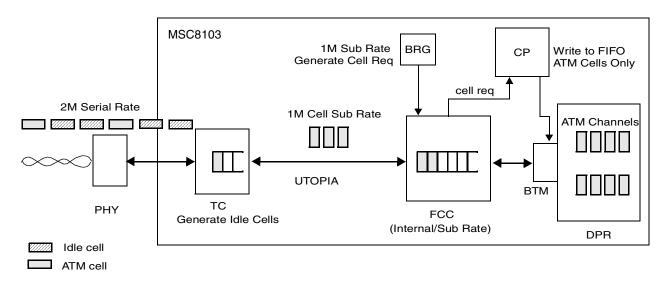


Figure 24. TC Operation in FCC Internal Rate Mode (Sub Rate Mode)

Operation in byte aligned mode (TCMODE[xTBA] = 1) is required for T1/E1 mainly. In this mode, once the TC is enabled, it waits for the first Txsyn pulse to start transmit the first byte of the first cell. This ensures that subsequent Txsyn pulses are byte-aligned to the cell boundaries.

14.4.22 Operating the TC Layer at Higher Frequencies

The operation of the TC layer requires a minimum frequency ratio of 1:2.5 between the serial clock and the UTOPIA clock (in Rx and Tx separately). Using the TC for serial frequencies greater than 10 MHz requires using higher UTOPIA frequencies to preserve that ratio.

14.4.23 Programming a T1 Application

This section describes how to implement a T1 application using a single TC layer block. Using two or more TCs requires FCC2 to work in MPHY mode. Assuming that the required ATM parameters and data structures have been set up and initialized, implementing a T1 application requires the following steps:

1. *Program FCC2*. To set up and initialize FCC2, program the FPSMR and GFMR as shown in **Table 40**. This is for working with one TC block operating in a single PHY environment. The transmitter and receiver should not be enabled at this time. In this example, FCC2 does not discard idle cells.

Table 40. Programming GFMR and FPSMR to Set Up FCC2

Init Values	Description
FPSMR2 = 0x0080_0000	UTOPIA Rx and Tx in master mode, idle cells are not discarded
GFMR2 = 0x0000_000A	ATM protocol mode, receiver and transmitter are disabled

- **2.** *Set up I/O ports and clocks.* Because the FCC2 UTOPIA bus is internally connected to the TC UTOPIA bus, program the parallel ports and BRGs for the active TDM(s).
- **3.** Enable Tx/Rx on FCC2. To enable receiving and transmitting, program FCC2 as shown in **Table 41**.

Table 41. Enable FCC2

Init Values	Description
GFMR2 = 0x0000_003A	Enable Rx and Tx

4. *Program CPM multiplexing*. To define the connection of FCC2, program the CPM multiplexing as shown in **Table 42**.

Table 42. Programming the CPM Multiplexing for a TI Application

Init Values	Description
CMXFCR = 0x0080_0000	FCC2 is connected to the TC Layer
CMXUAR = 0x0000	FCC2 as UTOPIA master

5. *Program the TC block*. The TCx layer block is configured using the TCMODEx and CDSMR1 registers as shown in **Table 43**. Note that the TC layer must be enabled after both FCC2 and the CPM multiplexing are programmed.

Table 43. Programming the TC Layer Block

Init Values	Description
TCMODE1 = 0xC202	Enable TC Layer Rx and Tx, no error correction on header, the TC is the only PHY on UTOPIA
CDSMR1 = 0x3980	ALPHA = 7, DELTA = 6 (default values)

6. Program the serial interface (SI). Program the SI to retrieve the data bits (192 bits) out of the T1 frame (193 bits). The SI frame pattern is programmed in the SI RAM (Rx or Tx), as shown in **Table 44**.

Table 44. Programming the SI RAM (Rx or Tx) for a T1 Application

Init Values	Description
SI_RAM[00] = 0x0000	1 bit is ignored.
SI_RAM[02] = 0x015E	Route 8 bytes to FCC2.
SI_RAM[04] = 0x015E	Route 8 bytes to FCC2.
SI_RAM[06] = 0x015F	Route 8 bytes to FCC2 and go back to the first entry in table.

7. Enable TDM. The Initialize the serial interface registers and enable TDMx—in this case TDMA on SI1, as shown in **Table 45**.

Table 45. Programming SI Registers to enable TDM

Init Values	Description
SI1AMR = 0x0040	Common Receive and Transmit Pins for TDMa
SI1GMR = 01	Enable TDMA

14.5 New MCC Host Commands

Four new MCC commands are added by the 2K87M mask set as part of the CP command opcodes. **Table 46** lists the new CP command opcodes changed in the 2K87M mask set. The fields are identical to those defined in the 2K42A mask set, except that definitions have been added for the MCC.

Table 46. 2K87M Mask Set CP Command Opcodes

	Channel									
Opcode	FCC	scc	SMC (UART/ Transparent)	SMC (GCI)	SPI	I ² C	IDMA	мсс	Timer	Special
0011	ENTER HUNT MODE	ENTER HUNT MODE	ENTER HUNT MODE		1	ı		INIT RX AND TX PARAMS (one channel)		_
0101	GRACEFUL STOP TX	GRACEFUL STOP TX	1	-		-		INIT TX PARAMS (one channel)	_	
0110	RESTART TX	RESTART TX	RESTART TX	_	_	_	_	INIT RX PARAMS (one channel)	_	_
0111	CLOSE RX BD	CLOSE RX BD	CLOSE RX BD	_	CLOSE RX BD	CLOSE RX BD	_	MCC RESET	_	_

Table 47 describes the additional commands listed in **Table 46**; all other commands are unchanged and are as described in the *MSC8101 Reference Manual*.

Table 47. 2K87M Mask Set New Command Descriptions

Command	Description
INIT MCC RX AND TX PARAMS — ONE CHANNEL	Initializes the receive and transmit parameters of the peripheral controller. Differs from INIT RX AND TX PARAMS in that, for the MCCs, issuing INIT RX AND TX PARAMS initializes 32 consecutive channels beginning with the channel number specified in CPCR[MCN]. However, issuing INIT MCC RX AND TX—ONE CHANNEL initializes only the channel in the command.
INIT MCC RX PARAMS— ONE CHANNEL	Initializes MCC receive parameters for only a single channel according to MCC channel number field.
INIT TX PARAMS— ONE CHANNEL	Initializes MCC transmit parameters for only a single channel according to MCC channel number field.
MCC RESET	Provides a hard reset to the MCC FIFOs. To use this command, software should execute the following sequence: 1. Disable the TDM by clearing the appropriate enable bit in SIxGMR[4-7]. 2. Issue the MCC RESET command. 3. Issue the INIT RX AND TX command. 4. Reprogram the specific MCC channel, global parameters, and any BDs that need to be updated. 5. Set the appropriate enable bit in SIxGMR[4-7].

15 Errata

Table 48 lists the functional errata that the 2K87M mask removes and the current 2K87M mask set errata. Always refer to the Freescale website listed on the back page of this document for a current list of device errata.

Table 48. Errata Resolved in Mask Set 2K87M

Errata Number	Errata Description				
SIU1	Wrong Timer Advancement on RCCR Date Added: 5/30/2000: Description: PQ2 treats the RCCR[TIMEP] value (UC timer) differently then QUICC. In QUICC the timer advanced (N+1)*1024 cycles and in MSC8101 and MPC826X the timer advances N*1024 cycles. Workaround: None System Number: 1399	0K40A 1K42A 2K42A			
SIU4	Incorrect Masking of MCP Date Added: 5/30/2000: Description: MCP (Machine Check Interrupt) due to data errors (parity / ECC) is masked by the SWRI bit in SYPCR. Workaround: Clear the SWRI bit in SYPCR to get data errors indication. System Number: 3695	0K40A 1K42A 2K42A			

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

Table 48. Errata Resolved in Mask Set 2K87M (Continued)

Errata Number	Errata Description			
SIU8	Parity Checking Error Date Added: 6/13/2000: Description: During a read from a device with port size less than 64 bits, from an address not aligned to 64 bits, the parity bits for parity check are not taken from the correct locations. For example, for a read of 4 bytes from a 32-bit port size from address 4, the parity is checked against DP[4–7] while it should be checked against DP[0–3]. The bug exists for both normal and rmw parity, and for both System and Local buses. Workaround: None System Number: 5839	0K40A 1K42A 2K42A		
SIU9	Bus Monitor Asserts Spurious TEA After Address Retry. Date Added: 1/28/2001 Description: The bus monitor will not recognize the competition of an Address Retry transaction and will assert TEA if there is no bus activity for a time equal to the expiration time. Workaround: Disable the bus monitor in systems where Address Retry cycles are used (e.g. systems which include PowerSpan).	0K40A 1K42A 2K42A		
SIU10	Strict Enforcement of Requirement to Assert DBG and TS in Same Cycle When Core Enabled Date Added: 1/28/2001 Description: This is a compatibility note. An external arbiter must assert DBG in the same clock in which TS is asserted (there may be a one clock delay if the PPC_ACR[DBGD] bit is set, however, after reset this bit is not set by default). Some external arbiters, including the one implemented in PowerSpan, violate this requirement. As a result, the system hangs following the first bus access after reset. Workaround: Use only a compliant external arbiter or the internal MSC8101 arbiter.	0K40A 1K42A 2K42A		
QSIU3	TEA May Hang 60x-Compatible Bus Date Added: 5/30/2000 Description: TEA may hang the 60x-compatible bus if it is asserted between specific address and data phases during a split transaction. Workaround: Enable Bus Monitor. Fix Plan: Rev. A	0K40A 1K42A 2K42A		
QSIU5	Incorrect Data on 60x-Compatible Bus Date Added: 6/13/2000 Description: The following sequence on the 60x-compatible bus can result in incorrect data: 1. Read transaction with DACK before AACK. 2. Failed atomic write transaction. 3. Write transaction. Workaround: None. System Number: 5823	0K40A 1K42A 2K42A		

Table 48. Errata Resolved in Mask Set 2K87M (Continued)

Errata Number	Errata Description						Applies to Mask
QSIU6	EE[4–5] Pins are Sampled on HRESET, SRESET and PORESET Date Added: 8/31/2000 Description: The EE[4–5] pins should be sampled only on PORESET, but they are sampled on SRESET and HRESET as well. Changing the value of the EE[4–5] pins after PORESET deassertion might prevent the chip from booting, because their value might choose a different or undefined boot configuration. Workaround: The EE[4–5] values should be kept constant and equal to the values on PORESET.					0K40A 1K42A 2K42A	
QSIU7	_	0/6/2000 NOUT pin <mark>IRQ7_INTOUT</mark> :	•	n but not ir	mplemented	d as one.	0K40A 1K42A 2K42A
QSIU12	Limited Clock Modes						1K42A 2K42A
	57	1:2:4	1.0	69 55	138	275	
QSIU13	Software Watchdog Cannot be Enabled after Boot from Host Date Added: 8/5/2001 Description: The software watchdog is disabled when booting from host. It cannot be subsequently enabled because the SYPCR can only be written once. Workaround: None					0K40A 1K42A 2K42A	

Table 48. Errata Resolved in Mask Set 2K87M (Continued)

Errata Number	Errata Description		
	Non-Functional DLL	1K42A	
	Date Added: 11/25/2001	2K42A	
	Description: DLL may fail to lock.		
QSIU14	Workaround: Use DLL disabled mode by setting the DLLDIS bit in the Reset Configuration Word. To maximize bus performance, use a zero-delay buffer for CLKOUT for both single-master and multi-master systems.		
	System Number: 7427		
	60x Compatible Global Transaction Fail on RETRY	0K40A	
	Date Added: 5/30/2000	1K42A	
QSIU15	Description: Data may be lost on RETRY when global transactions are performed in 60x compatible mode.	2K42A	
	Workaround: When global transactions are used, 60x compatible mode cannot be used.		
	System Number: 5678		
	ALE Output During Reset	0K40A	
	Date Added: 2/20/2003	1K42A	
QSIU16	Description: ALE behavior is not guaranteed during reset. This affects only multi-master systems which perform reset configuration from external memory and which use ALE for all memory accesses. ALE recovers with the first access after reset.	2K42A	
	Workaround: None		
	System Number:		
	Fix Plan: RevA		
	DMA Data Corruption on either PPC Bus or Local Bus	0K40A	
	Date Added: 2/19/2002	1K42A	
DMA1	Description: Data transferred by the DMA on either the PPC Bus or Local Bus may be corrupted.	2K42A	
DIVIA	Workaround: For DMA accesses on the PPC Bus - disable PPC bus pipeline by setting BCR[PLDP]=1. For DMA accesses on the Local Bus the UPMC programming patch is available.		
	System Number: 7462		
	Incorrect Checksum for Host Bootload	0K40A	
	Date Added: 8/15/2000:	1K42A	
BOOT1	Description: The host bootload calculates erroneous checksum.	2K42A	
	Workaround: Clear ICR[HF3] so that the host bootload ignores the checksum comparison result.		
	System Number: 6178		

Table 48. Errata Resolved in Mask Set 2K87M (Continued)

Errata Number	Errata Description	Applies to Mask
BOOT2	Boot Interference in Multi-Master System with Shared Memory Date Added: 8/5/2001 Description: The DSPRAM address in the memory map as programmed by the boot loader code in the ROM is the same for all processors. During simultaneous boot, this will cause interference of one processor with another. Workaround: For up to 4 MSC8101's including the configuration master. Boot the processors one after the other, and not at the same time. Reprogram unique DSPRAM address for each processor. The configuration master is set also to be the arbitration master and the memory controller for the system. The configuration word for the master should set the MMR field of the reset word (bits [18:19]) to 2'b11. This will mask all the external bus requests of the configuration slaves. After the master completes its boot, the user should: 1. Clear all external requestors from the Arbitration Level Register (ALR) of the arbitration master. 2. Reprogram the UPM of the DSPRAM bank to unique address (see programming example below) 3. Set priority for the next configuration slave in the Arbitration Level Register (ALR) of the arbitration master. 4. Enable external bus requests by clearing SIUMCR MMR field (bits [16:17]). 5. Repeat stages 2,3 for consecutive slaves. Configuration master programming code: move.1 PPC_ALRH, D7; Step #1 move.1 PPC_ALRL, D8 bmclr.w #\$f,D7.L bmclr.w #\$ff00,D8.H move.1 D8,PPC_ALRH move.1 D8,PPC_ALRH move.1 D8,PPC_ALRH move.1 PPC_ALRH,D7; Step #3 nop bmset.w #\$7,D7.L nop move.1 PPC_ALRH,D7; Step #4 nop bmclr.w #\$c000,D7.L nop move.1 D7,PPC_ALRH	0K40A 1K42A 2K42A
GEN1	Device Withstands MM ESD of 75V Instead of 100V Date Added: 5/21/2002 Description: Device meets the ESD specifications for Human Body Model (HBM) of 1000V and Charged Device Model (CDM) of 500V but does not withstand the Machine Model (MM) requirement of 100V. All pins guaranteed to withstand 75V MM. Workaround: None.	0K40A 1K42A 2K42A

Table 48. Errata Resolved in Mask Set 2K87M (Continued)

Errata Number	Errata Description	Applies to Mask
GEN2	Unexpected Outputs During Boundary Scan Date Added: 10/18/2002 Description: D[32:60] outputs may behave indeterminately during boundary scan. Workaround: Reset the device by asserting PORESET while HPE/EE1=0. Alternatively, assert PORESET throughout boundary scan. Fix Plan: RevA	0K40A 1K42A 2K42A
SC1	PC Cannot Be Updated in Debug Mode Entered From Asynchronous Interrupt Date Added: 10/5/2000 Description: When a DEBUG instruction is executed in a static or dynamic delay slot created by an asynchronous interrupt, the core enters Debug mode, but the PC cannot be updated. Workaround: In the dynamic case, the debugger can use a status bit in the ESR, which indicates whether the core entered a debug in a delay slot. Software workarounds are available for all the static cases. A detailed description was sent by StarCore and can be resent upon request.	0K40A 1K42A 2K42A
SC3	Date Added: 10/5/2000 Description: An erroneous 62-bit value may be written to the trace buffer when the EOnCE is programmed to write both event counters (ECNT_VAL and ECNT_EXT). Workaround: None.	0K40A 1K42A 2K42A
СРМ2	CAM Access Not Atomic Date Added: 5/30/2000: Description: The bus atomicity mechanism for CAM access may not function correctly when the CPM's DMA accesses the CAM. This only affects systems in which multiple CPMs will access the CAM. Workaround: None System Number: 1410	0K40A 1K42A 2K42A
СРМ4	No CTS Lost Indication with HDLC Date Added: 5/30/2000 Description: When CTS is deasserted at the end of hdlc frame, (last flag or one bit before) transmission will be aborted. However there is no CTS-LOST indication. There is only abort indication. Workaround: None System Number: 1670	0K40A 1K42A 2K42A
СРМ5	Data Corruption on SDMA Flyby Date Added: 5/30/2000 Description: The data of a SDMA write, which follows a SDMA flyby read in the local bus may be corrupted. Workaround: None System Number: 1720	0K40A 1K42A 2K42A

Table 48. Errata Resolved in Mask Set 2K87M (Continued)

Errata Number	Errata Description	Applies to Mask
СРМ6	Date Added: 5/30/2000 Description: Spurious overrun indications on the FCC may occur in the following cases: 1. After stop transmit command is issued. 2. Following CTS lost condition. 3. Late collision under ethernet. Workaround: None System Number: 1746	0K40A 1K42A 2K42A
СРМ7	Erroneous Report of Overrun With Fast Ethernet Date Added: 5/30/2000 Description: If the CRS (carrier sense) signal is deasserted while fast ethernet frame is transmitted, an overrun error may occur and the FCC may have to be reset. Workaround: None System Number: 1752	0K40A 1K42A 2K42A
СРМ8	Error on Transmit On Demand Register Date Added: 5/30/2000 Description: The TODR mechanism may freeze serial channels. Workaround: Do not use TODR. System Number: 2484	0K40A 1K42A 2K42A
СРМ9	Date Added: 5/30/2000 Description: Under certain conditions, an ATM receiver may receive cells of PHYs which were not addressed for it. Details of the condition: ATM receiver in UTOPIA slave mode. FIFO full condition occurred (this happens only when the transmitter violates the UTOPIA standard requirements: transmits data without CLAV). Transmitter changed selected PHY number. FIFO full condition ended (CPM read some data from FIFO). Workaround: Use different VPI/VCI for different PHYs or expect the cells to be discarded by higher-level protocol software. System Number: 2493	0K40A 1K42A 2K42A
CPM10	Date Added: 5/30/2000 Description: In ATM, a Transmit internal rate underrun error is not reported correctly in the TIRU field of the FCCE register. In most cases, TIRU is not set in the FCCE when an internal rate underrun error occurs. In some rare cases that depend on internal sequences within the communications controller, the TIRU bit may be set as expected when the error should be reported. Workaround: None System Number: 2611	0K40A 1K42A 2K42A

Table 48. Errata Resolved in Mask Set 2K87M (Continued)

Errata Number	Errata Description	Applies to Mask
CPM11	False Indication of Shared Flag Date Added: 5/30/2000 Description: FCC-TX HDLC - FCT_TXD (data out) changes from 1>0 for 1 ser_clock period, few clocks after the reset command from MAIN is given. A false shared flag can be detected at the receiver if the last bit before reset was 0, and the receiver considers it as a closing flag of the frame. In most of cases, a CRC error is generated and the frame is discarded. Workaround: None System Number: 3024	0K40A 1K42A 2K42A
CPM13	Error in Random Number Generation Date Added: 5/30/2000 Description: In Fast Ethernet transmit, when more then one (up to four) frames reside in the FCC FIFO, random number generation (for collision wait) may produce the same number for all four frames. Workaround: None System Number: 3421	0K40A 1K42A 2K42A
CPM14	Corruption of ATM Cells Date Added: 5/30/2000 Description: Corruption of ATM cells may occur when the following combination is used: AAL1 with UDC in which the user-defined header size is 9 to 12 octets and PM is not used. Workaround: Since this problem appears in a very specific condition as described above, avoiding any of the elements (e.g., using cell header of 8 octets) eliminates it.	0K40A 1K42A 2K42A
CPM15	Corruption of Port D Registers Date Added: 5/30/2000 Description: The PDATA, PDATB, PDATC, and PDATD registers can only be written with a 32-bit write instruction. (i.e., stw). When 8- or 16-bit write instructions (i.e., sth, stb) are used, the bits not being written may be corrupted. Workaround: Use a 32-bit write instruction only to write to the PDATA, PDATB, PDATC, and PDATD registers. System Number: 3679	0K40A 1K42A 2K42A
CPM17	Error in Reporting UTOPIA Error Condition Date Added: 5/30/2000 Description: An FCC receiver which is configured as single PHY master does not detect a UTO-PIA error condition when SOC and CLAV are not asserted simultaneously. System Number: 3728	0K40A 1K42A 2K42A
CPM21	False Indication of Collision in Fast Ethernet Date Added: 5/30/2000 Description: In the Fast Ethernet a false COL is reported whenever a collision occurs on the preamble of the previous frame. Workaround: S/W should ignore COL indications when the CRC of the frame is correct. System Number: 3927	0K40A 1K42A 2K42A

Table 48. Errata Resolved in Mask Set 2K87M (Continued)

Errata Number	Errata Description	Applies to Mask
CPM22	False Defer Indication in Fast Ethernet Date Added: 5/30/2000 Description: In the fast ethernet, if a frame is transmitted due to defer and this frame also gets late collision, a false defer indication is indicated for the next frame. Workaround: None System Number: 3981	0K40A 1K42A 2K42A
CPM24	Date Added: 5/30/2000 Description: In the FCC HDLC transmitter, if slow serial clock (cpm_freq/serial_clock > 16) is used, RTS does not transition to IDLE between frames. This means that all the frames are transmitted back-to-back in case there is valid data in the transmitter's FIFO. Workaround: None System Number: 3998	0K40A 1K42A 2K42A
CPM27	Error in Heartbeat Checking in FCC Date Added: 5/30/2000 Description: The heartbeat checking in FCC transmit ethernet 10Mbps does not work properly. The standard requires that the collision pulse from the PHY should be checked within a window of 4 μsec from the falling edge of the carrier sense. The PQ2 samples the collision signal only once at exactly 4 μsec (10 serial clocks) after the falling edge of the carrier sense signal. Workaround: None System Number: 4155	0K40A 1K42A 2K42A
CPM28	Error in Receive Frame Threshold Date Added: 5/30/2000 Description: In the SCC Rx in HDLC mode, RFTHR does not work. There is no way to get interrupts on the receive side after a programmable number of frames. Workaround: RFTHR should be programed to 1. System Number: 4163	0K40A 1K42A 2K42A
CPM29	MAXD1 and MAXD2 May Not Be Less Than MFLR Date Added: 5/30/2000 Description: In SCC Rx ethernet, the option of transferring only part of a frame into memory (MAXD1 and MAXD2 < MFLR) does not work. Workaround: None System Number: 4166	0K40A 1K42A 2K42A
СРМ30	Graceful Stop Command Does Not Work Date Added: 5/30/2000 Description: The graceful stop command does not work in SCC Tx in the following protocols: Ethernet, HDLC, Transparent. Workaround: None System Number: 4167	0K40A 1K42A 2K42A

Table 48. Errata Resolved in Mask Set 2K87M (Continued)

Errata Number	Errata Description	Applies to Mask
СРМ35	Data Corruption in SCC Transparent Mode Date Added: 5/30/2000 Description: When SCC transparent, envelope mode is used and the received frame size is (4*n) + 1, the last byte is corrupted. When GSMR_H(RFW) - rx FIFO width is used, the received data is completely corrupted, not just the last byte. Workaround: The bug can be worked around with a microcode patch. System Number: System number; 4350	0K40A 1K42A 2K42A
СРМ36	Date Added: 5/30/2000 Description: SI's sync signal may not change exactly on clock edge in the following cases. The bug affects operation only when the SI is in one of two modes: fsd = 00, ce = 0, fe = 0, dsc=1 (Sync sampled with falling edge -> Sync should not change on rising edge) fsd = 00, ce = 1, fe = 1, dsc=1 (Sync sampled with rising edge -> Sync should not change on falling edge). Workaround: When working in these modes, the sync signal to the SI should be manipulated such that it does not change on the exact edge of the serial clock. Toggle the sync at least 5ns after the edge. One way to implement such a workaround is to add a noninverting buffer between the device that generates the sync signal and the MSC8101 that uses it. System Number: 3258	0K40A 1K42A 2K42A
СРМ38	Heartbeat Error and Carrier Sense Lost Error On Two Frames Date Added: 5/30/2000 Description: There are rare cases when a heartbeat error and carrier sense lost error are reported on two frames. The error is reported in the frame in which it occurred, but in those rare cases it is also reported on an adjacent frame. Workaround: None System Number: 1547,1550	0K40A 1K42A 2K42A
СРМ39	Corruption in AAL0 Cell Payload Date Added: 5/30/2000 Description: There is a rare case in using the ATM AAL0 transmitter that the AAL0 cell payload may be corrupted. This can occur in certain internal sequence of events that the user cannot detect or control. Workaround: 1. Use the available microcode patch from the web site. 2. When working with AAL0 SAR, place the TCELL_TMP_BASE 64 byte align plus 4. For example use TCELL_TMB_BASE = 0x2d04 not 0x2d00. System Number: 4648a	0K40A 1K42A 2K42A

Table 48. Errata Resolved in Mask Set 2K87M (Continued)

Errata Number	Errata Description	Applies to Mask
СРМ40	Corruption in AAL0 IDLE Cell Date Added: 5/30/2000 Description: There is a rare case when transmitting an ATM idle cell that the idle cell may be corrupted. This can occur in certain internal sequences of events that cannot be controlled or detected by the user. Workaround: Place the Idle Base template at address 64 byte align minus 4. For example use Idle_BASE = 0x2cfc not 0x2d00. System Number: 4648b	0K40A 1K42A 2K42A
CPM41	Limitation in ATM Controller Date Added: 5/30/2000 Description: There are some limitations in the ATM controller. The first limitation is that only the first 8 PM tables can be used instead of 64. When using these 8 tables, the user must clear the 5 most significant bits of TBD_BASE (in case of Tx PM) or RBD_BASE (in case of Rx PM). The second limitation is that only the first 2048 ATM channel numbers can be used. Workaround: There is a microcode patch that can fix the PM limitation. The ATM channel number limitation has no workaround. System Number: 4744	0K40A 1K42A 2K42A
CPM42	Data Corruption in MCC Date Added: 5/30/2000 Description: Data corruption may occur in the receive buffers of MCC channels when more then one TDM slot uses 7 bits of contiguous data. Workaround: It is possible to avoid this problem by splitting the 7 bits slots between two SI ram entries such that one entry will represent 4 bits of the slot and the other SI entry will represent 3 bits of the slot. The errata occurs only when all the 7 bits are represented by one entry in the SI ram. System Number: 4743	0K40A 1K42A 2K42A
CPM43	TxCLAV Ignored By UTOPIA in Single PHY Mode Date Added: 5/30/2000 Description: When the FCC transmitter is configured to work in UTOPIA single PHY master mode, it ignores deassertion of the TxCLAV signal. Therefore, the UTOPIA slave cannot control the flow of cells by deasserting TxCLAV. Note that this bug affects Rev A.1 chips only. Workaround: Configure the FCC to work in multi-master mode but limit the number of PHYs to 1 by programming: FPSMR[LAST PHY] = 5'b0 System Number: 4882	0K40A 1K42A 2K42A
CPM44	Zero Insertion Error on MCC Date Added: 5/30/2000 Description: When the MCC transmitter is used in HDLC super channel mode, a zero insertion at the last bit before the flag fails to occur. Workaround: There is a microcode patch which fixes the problem. System Number: 4941	0K40A 1K42A 2K42A

Table 48. Errata Resolved in Mask Set 2K87M (Continued)

Errata Number	Errata Description	Applies to Mask
CPM45	Date Added: 5/30/2000 Description: In FCC ATM transmit master mode (multiple PHY only), the CLAV signal is sampled 5 clocks before the end of the cell instead of 4 clocks. This is relevant only for back-to-back transmission sequence. Workaround: In multiple PHY fix priority polling mode, by adding a dummy PHY, it is possible to ensure that the dummy PHY is polled at payload 44 (5 clocks before the end of the cell). This is possible since the cell length is constant and the number of PHY to poll is also constant. System Number: 5031	0K40A 1K42A 2K42A
CPM46	Date Added: 5/30/2000 Description: Each of the communication controllers (FCC, MCC, SCC,) issues request for service to the CPM with different priorities in order to receive the necessary assistance in time. Because of an internal connection error, the FCC3 request for service is issued with a much lower priority than intended. Because of this, FCC3 may sporadically overrun when the CPM is heavily loaded. Workaround: None System Number: 5663	0K40A 1K42A 2K42A
CPM48	Error in TDM Date Added: 5/30/2000 Description: Disabling TDMx may interfere with the operation of TDMy if TDMy uses the SI-RAM blocks directly above those used by TDMx. For example: start address of TDMc = 0 start address of TDMb = 2 start address of TDMa = 4 start address of TDMd = 6 when disabling TDMa, TDMb is affected. when disabling TDMb, TDMc is affected. when disabling TDMd, TDMa is affected. when disabling TDMc, No TDM is affected. Workaround: Instead of disabling a TDM, the user can switch to a shadow RAM that contains only non supported slots in its entries. System Number: 5714	0K40A 1K42A 2K42A
СРМ49	Error in FEC CAM address recognition Date Added: 3/14/2002 Description: External CAM address recognition in Fast Ethernet controller does not function. Workaround: Use microcode patch available from Freescale. System Number: 5404	0K40A 1K42A 2K42A

Table 48. Errata Resolved in Mask Set 2K87M (Continued)

Errata Number	Errata Description	Applies to Mask
СРМ50	MCC Transparent Super Channel Loss of Alignment Date Added: 5/30/2000 Description: When the MCC is configured to work in Transparent, super channel first sync slot synchronization, loss of alignment may occur when the first data (idles) on the Rx data line matches the value of the RCVSYNC parameter. Workaround: Write to RCVSYNC a pattern which cannot appear in the Rx data line. System Number: 5833	0K40A 1K42A 2K42A
CPM54	Error in switching to and from shadow SI ram. Date Added: 12/10/2000, modified 15/0/2002 Description: Dynamic switching in SIRAM may not be executed properly. Workaround: In SI RAM, when working with shadow RAM, the last entry (n) and the entry immediately before the last entry (n-1) MUST have at least one common bit in the CNT or BYT fields. For example: SIRAM Entry CNT BYT n-1 000 1 n 010 1 The above is okay n-1 101 0 n 001 0 The above is okay n-1 100 0 n 001 0 The above is not okay. System Number: 6282, 6283	0K40A 1K42A 2K42A
СРМ55	Error in ATM_Transmit command. Date Added: 12/10/2000 Description: The ATM_Transmit command does not execute correctly when used on APC priority above 4. Workaround: None. System Number: 6162	0K40A 1K42A 2K42A
СРМ57	AAL5 Cell Corruption. Date Added: 1/28/2001 Description: The second part of a second cell may overwrite the second part of the first cell in an AAL5 frame. Workaround: Use microcode patch.	0K40A 1K42A 2K42A

Table 48. Errata Resolved in Mask Set 2K87M (Continued)

Errata Number	Errata Description	Applies to Mask
CPM64	AAL5 RxBD[LNE] error generated if PDU length exceeds 65512 bytes Date Added: 5/31/2001 Description: When the CPM receives an AAL5 PDU between 65512-65535 bytes (maximum length) the CPM sets the RxBD[LNE] indicating a receive length error, however the memory buffer contents for the PDU are correct. Workaround: Receive AAL5 PDU less than 65512 bytes or use microcode patch. System Number: 7025	0K40A 1K42A 2K42A
CPM65	SS7 Microcode in ROM does not function correctly Date Added: 8/5/2001 Description: The SS7 microcode in ROM does not function correctly and should not be used. Workaround: Use the Enhanced SS7 microcode package.	0K40A 1K42A 2K42A
СРМ71	CPM does not snoop MCC buffer descriptors. Date Added: 8/5/2001 Description: When the MCC performs a DMA read or write of the buffer descriptor, GBL is not asserted and TC2 is always driven low. Therefore cache snooping will not be enabled for MCC BDs, therefore BDs in memory will not match the data cache. Also the bus used for the DMA is always the 60x, therefore if the BDs are on the local bus then the DMA consumes bandwidth on both the 60x and Local bus. Workaround: If GBL and/or TC2 are set in the MCC TSTATE/RSTATE parameters, use microcode patch available from Freescale which fixes the above problem. If GBL and TC2 are not set to improve performance move the MCC BDs to the 60x bus. The microcode patch will fix both the GBL/TC2 and the bus performance issue. System Number: 7018	0K40A 1K42A 2K42A
СРМ72	MCC Global Underruns Date Added: 8/5/2001 Description: An MCC transmitter global underrun (GUN) error may result from intensive activity on FCC1 (e.g.burst of short back to back Ethernet frames). This is due to the prioritization of the MCC transmitter relative to FCC1 receiver and transmitter as well as the MCC receiver. Workaround: Each serial channel above can request a service at normal or emergency level. In case of emergency, the request is handled before normal (non-emergency) request of the channels at a higher priority level. The proposed change is to allow the MCC transmitter to assert an emergency request instead of normal request. The impact on FCC1 in this case is minimal. This feature will controlled by a new MCC mode bit in future MSC8101 revisions. This new MCC mode bit will allow users to continue to use the current CPM priority scheme in their applications if required.	0K40A 1K42A 2K42A
СРМ73	Date Added: 8/5/2001 Description: (7049)An access to the SI RAM bank from the 60x bus while the corresponding TDM is active may result in data corruption within the SI RAM. Workaround: Associate the SI RAM bank with an inactive TDM before attempting to access it. Once the accesses has been made, the SI RAM bank should be re-assigned to the active TDM. System Number: 7049	0K40A 1K42A 2K42A

Table 48. Errata Resolved in Mask Set 2K87M (Continued)

Errata Number	Errata Description	Applies to Mask
СРМ74	FCC HDLC Controller Stops Transmitting When Using Nibble Mode With MFF=0 Date Added: 8/27/2001 Description: When running an FCC in HDLC nibble mode with the multi-frame per FIFO bit off (MFF=0) the CPM may lose synchronization with the FCC HDLC controller. As a result the HDLC controller will get stuck and stop transmission. Workaround: When running the FCC in HDLC nibble mode set the MFF=1 or alternatively run the FCC in HDLC bit mode.	0K40A 1K42A 2K42A
СРМ76	First transmitted bit zero in FCC Transparent Mode with GFMR[CTSS]=1 Date Added: 8/27/2001 Description: When using an FCC in transparent mode the first bit of a frame is transmitted as zero every time RTS is asserted before CTS is asserted when CTS is sampled synchronously with data (GFMR[CTSS]=1). If CTS is in pulse mode (GFMR[CTSP]=1) only the first frame is affected because CTS is ignored thereafter. If CTS is not in pulse mode (GFMR[CTSP]=0) then every frame is affected separately. Workaround: If the receiver synchronizes on a 8/16-bit sync pattern stored in the FDSR register (GFMR[SYNL]=1x) ensure that the synchronization pattern starts with a "0". If no synchronization pattern is used (GRMR[SYNL]=0x) add a one-byte dummy buffer before sending the real data buffers.	0K40A 1K42A 2K42A
СРМ79	FCC Fast Ethernet Flow Control Date Added: 3/14/2002 Description: When the FCC receives a flow control pause message with MAC parameter =0xffff, it sets a zero delay instead of maximum delay.	0K40A 1K42A 2K42A
CPM80	MCC CES User Template Date Added: 3/14/2002 Description: If the transparent MCC Tx CES channel requires the user template (CHAMR[UTM]=1) only the first 8 bytes of the user defined pattern are transmitted. Then the transmitter will continue to send bytes 4-7 of the pattern continuously until the counter reaches 0. Any bytes defined in the pattern after byte 7 are never transmitted. Workaround: Use a template size of 8 bytes.	0K40A 1K42A 2K42A
CPM85	Only One BSY Interrupt Generated for AAL0 Date Added: 5/21/2002 Description: When using AAL0, only one BSY interrupt will be received regardless of the number of BSY events that are generated. Workaround: None.	0K40A 1K42A 2K42A

Table 48. Errata Resolved in Mask Set 2K87M (Continued)

Errata Number	Errata Description	Applies to Mask
СРМ86	Random PHY Number For FCC RX in Single-PHY Master Mode Date Added: 5/21/2002 Description: When the FCC Receive ATM controller is configured for Single PHY Master mode (FPSMR[RUMP]=0, FPSMR[RUMS]=0) and FPSMR [LAST PHY / PHY ID] is not equal to zero, a random PHY ID might be allocated to the incoming cells instead of the expected zero (for Single-PHY). This will result in a loss of cells. This configuration is typical when using the FCC Transmit ATM controller in Multi-PHY Master mode together with the FCC Receive ATM controller in Single PHY Master mode. Workaround: The Address Lookup Mechanism should be created in such a way that for any PHY Addr input, the Output will be as for PHY 0. MCC Transmit GUN when MCC STOP RX CPCR Command is used	0K40A 1K42A 2K42A
СРМ88	Date Added: 10/15/2002 Description: An MCC may experience a highly intermittent transmit GUN event indication, related to MCC receive channels that have been stopped via the MCC STOP RX host CPCR command. This GUN can happen unrelated to internal CPM loading or other external factors. Workaround: Avoid using MCC STOP RX command using one of the following mechanisms: 1. Simply stop the TDM or 2. Use shadow RAM and dynamically remove the desired MCC RX channel entry from SIRAM programming (see 8260 User manual chapter 14). The following procedure should be utilized, using an extra redundant shadow RAM switch. This is done to provide a full TDM frame's amount of time to ensure receive activity is complete and will avoid the issue: a. Re-program shadow SIRAM to remove channel to be stopped. b. Switch to shadow SIRAM and wait for that TDM's bit in the SIxSTR register to change to indicate switch complete. c. Copy this new shadow RAM programming back to the main SIRAM bank. d. Switch to active RAM, again wait for switch to complete. e. Then software can re-initialize or modify the removed channel's RX parameters. System Number: 2905 Fix Plan: RevA	1K42A 2K42A
СРМ95	ATM False Indication of Mis-Inserted Cells Date Added: 2/25/2003 Description: There is a false indication of unassigned bits in the PHY:VPI:VCI which could cause ATM cells to be treated as mis-inserted cells and therefore be discarded. Workaround: Use microcode patch available from Freescale. Fix Plan: RevA	0K40A 1K42A 2K42A

Table 48. Errata Resolved in Mask Set 2K87M (Continued)

Errata Number	Errata Description	Applies to Mask
CPM100	ABR TCTE Address Miscalculation Description: When using the AAL5 ABR ROM microcode with external ATM channels it is possible for the EXT_TCTE_BASE word value (written by the user to DPRAM) to be misread. In this case calculations performed by the microcode to access the users programmed external TCTE will be incorrect with a high chance of the access resulting in a CPM crash. Workaround: Use the micro code patch available from Freescale. System Number: 9131 Fix Plan: Rev. A	0K42A 1K42A 2K42A
CPM110	Date Added: 12/19/2003 Description: The FCC1 receiver in Ethernet, HDLC, or Transparent controller mode is not elevated to emergency status (priority 4 in Table 19-2 of the Reference Manual, "Peripheral Prioritization"), which may lead to a FIFO overrun if the system is heavily loaded (FCC1 receiver has the highest priority excluding emergency status of other peripherals). Workaround: When allocating FCCs, assign FCC2 and FCC3 for Ethernet, HDLC or Transparent before FCC1, or assign FCC1 to the lowest bit rate interface. If FCC1 is allocated for ATM and requires higher CPM usage than the other FCCs, disable its emergency status. System Number: 11062 Fix Plan:	0K40A 1K42A 2K42A

Table 49. Errata Resolved by Specification Change in Mask Set 2K87M

Errata Number	Errata Description	Applies to Mask
QSIU8	Core TEA Not Supported as NMI Date Added: 9/7/2000 Description: Q2PPC TEA is not supported on PIC NMI5. Workaround: Use PIC IRQ19. Resolution: Specification is changed to reflect this state in mask set 2K87M.	0K40A 1K42A 2K42A 2K87M
SIU15	Data Not Written to the SDRAM in RMW Parity Mode Date Added: 5/21/2002 Description: When using a read-modify-write parity mode and pipelined addresses on the SDRAM interface, the write portion of the RMW might be performed as a read. As a result, the data is not written to the external memory. Workaround: Use BCR[PLDP]=1 for a pipeline depth of zero. Fix Plan: None, specification is changed so that this is defined as normal functionality and becomes a documentation errata.	2K87M

Table 49. Errata Resolved by Specification Change in Mask Set 2K87M (Continued)

Errata Number	Errata Description	Applies to Mask
CPM37	Requirement for Software to Disable FCC After Error Date Added: 5/30/2000 Description: There are four errors in the FCC transmitter that require software to disable and enable the transmitter before it can continue to operate correctly. The four errors are: 1. CTS-LOST indication in the HDLC transmitter 2. Late collision in the fast ethernet transmitter 3. Underrun in any of the FCC transmitter protocols 4. Expiration of RL in fast ethernet Workaround: None available. System Number: 4040, 3980, 2314 Fix Plan: Specification was changed to include details for error handling software.	0K40A 1K42A 2K42A 2K87M

Errata Number	Errata Description	Applies to Mask
SIU13	SDAMUX not Valid in Single-MSC8103 Mode Date Added: 3/14/2002 Description: SDAMUX signal is disabled (stuck at '0') when SDRAM machine handles the memory access and the chip is programmed to single-MSC8103 mode (BCR[EBM]=0). Workaround: None.	0K40A 1K42A 2K42A 2K87M
SIU16	Bus Busy Disable Mode Can Hang 60X Bus in Multi-Master Systems Date Added: 5/21/2002 Description: The bus busy disable mode (SIUMCR[BBD=1]) can not be used if the MSC8103 is not the only master on the 60x-compatible bus. Using this mode in such a system can cause the 60x-compatible bus to hang. Workaround: 1. If the external master supports the ABB signal, do not use the bus busy disable mode and connect this signal to the MSC8103. The DBB signal can either be connected or can be pulled up. 2. If the external master does not support the ABB signal do one of the following: a. Do not use the bus busy disable mode and generate the ABB signal externally. The DBB signal can either be connected or can be pulled up. The following external ABB implementation should be sufficient to work around the problem: Assert the ABB signal whenever a qualified bus grant for the external master is sampled (Bus grant asserted while ARTRY and ABB are deasserted). Deassert the ABB signal when there is no qualified bus grant. The deassertion of ABB should be as follows: Drive ABB to VDD for half a clock cycle and then stop driving it (high impedance). b. If using the internal arbiter and up to two external masters, connect the external bus grants (through an AND gate if more than one) to an available external bus request and define the priority for that request to be the highest in the PPC_ALRH register. The DBB signal can either be connected or can be pulled up.	2K87M

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

Errata Number	Errata Description	Applies to Mask
SIU18	ARTRY Assertion When Using Pipeline Depth of Zero Date Added: 10/15/2002 Description: Internal (60x) slave maintains a pipeline depth of zero by asserting AACK only after TA. When ARTRY is asserted the 60x bus access will be terminated and TA will not be asserted. Therefore the Internal (60x) slave will not assert AACK since TA was not asserted. Workaround: Use a pipeline depth of one (BCR[PLDP]=0) for applications that require memory coherency. Fix Plan: TBD	0K40A 1K42A 2K42A 2K87M
SIU19	Bus Monitor Timeout When Using External Slave Date Added: 10/15/2002 Description: When using an external 60x bus slave with the bus monitor activated, PSDVAL is not asserted when the external slave is accessed, which could cause the bus monitor to time-out and TEA to be asserted. Workaround: The following workarounds 1. Use pipeline depth of zero (BCR[PLDP]=1) when using an external 60x bus slave. 2. Disable 60X bus monitor, SYPCR[PBME]=0.	0K40A 1K42A 2K42A 2K87M
	3. If the external 60x bus slave is another 810x or 826x device, connect the PSDVAL signals together.Fix Plan: TDB	
QSIU4	Extended Mode on Local Bus Date Added: 6/13/2000 Description: Using Extended mode on the local bus can generate incorrect transactions in certain combinations of consecutive reads and writes. Workaround: Do not use Extended mode on the local bus. System Number: 5959 Fix Plan: TBD	0K40A 1K42A 2K42A 2K87M
EFC1	Inaccurate EFCOP IIR Outputs for Two or Fewer Coefficients Date Added: 8/15/2000 Description: When using normal (dual) DMA or flyby DMA transfers which have a maximum transfer size greater than 32 bits with the EFCOP to perform IIR filtering with two or less IIR coefficients, the first output of the IIR filter is lost. The rest of the outputs are shifted and inaccurate. Workaround: Use only DMA 32-bit maximum transfer size for both input and output channels. Fix Plan: TBD	0K40A 1K42A 2K42A 2K87M
GEN3	Device Withstands ESD CDM Stress of 400 V Instead of 500 V Date Added: 10/31/2002 Description: Device meets the ESD specifications for Human Body Model (HBM) of 1000 V and Machine Model (MM) of 100 V but does not withstand the Charged Device Model (CDM) of 500 V. All pins are guaranteed to withstand CDM of 400 V. Workaround: NA Fix Plan: TBD	2K87M

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

Errata Number	Errata Description	Applies to Mask
SC4	SC140 Core May Hang after Write to the PCTL0 Register Date Added: 2/19/2002 Description: Write to the PCTL0 freezes the core immediately for 150–190 cycles. If the system is busy (for example, doing pre-fetch transactions), the core may not exit the freeze state. Workaround: Option A: 1. Ensure the EFCOP is not active.	0K40A 1K42A 2K42A 2K87M
	 Ensure the local bus to L1 memory is not active. Ensure that the program that writes to PCTL0 is in internal memory. Write to PCTL0 immediately after reset before any external accesses. Option B: Do not write to PCTL0. System Number: 7560 	
	Fix Plan: TBD	
SC5	SC140 Core May Hang after Illegal Execution Set Date Added: 2/19/2002 Description: Upon receipt of an illegal execution set, the SC140 core may enter a freeze state that can only be released by reset. Workaround: None available. System Number: 7541 Fix Plan: TBD	0K40A 1K42A 2K42A 2K87M
	 Incorrect Data on Trace Buffer During Core Freeze Date Added: 2/19/2002 Description: After writing data to the Trace Buffer (TB), the TB is disabled in order to read from it. There are two options to read the TB and the problem occurs in both: 1. Reading the TB by software. If a core freeze occurs while the software reads the TB into a core register, data can overwrite the previous data. 2. Reading the TB from JTAG. If a core freeze occurs while the JTAG is reading the TB, the data is not correctly sampled. 	0K40A 1K42A 2K42A 2K87M
SC6	Workaround: 1. Software: Read the TB by software when there is no core freeze: a. Ensure that the program is in internal memory. b. Ensure that the EFCOP is not active. c. Ensure that the local bus to L1 memory is not active. d. Ensure that the Write Buffer is empty. e. Ensure that there are no other MOVE commands except for the TB read. 2. JTAG: a. Read the TB from JTAG only when the core is in Debug mode. b. Before reading the TB, flush the Write Buffer. System Number: 7604 Fix Plan: TBD	

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

Errata Number	Errata Description	Applies to Mask
SC7	Change of Flow May Cause Incorrect Trace-Buffer Data Date Added: 2/19/2002 Description: When the EOnCE module is programmed for tracing events of change of flow (TCHOF) and interrupts (TINT), the Trace Buffer is updated on every event by the source and destination addresses. In the event of a change of flow (CHOF) to another CHOF with an interrupt request in between, the Trace Buffer is updated with additional data. The additional data is incorrect and is not needed for the trace. Workaround: Perform post-processing after reading the Trace Buffer. Search in the data for a source address with its destination listed before it. Delete the source and the previous data. System Number: 7794 Fix Plan: TBD	0K40A 1K42A 2K42A 2K87M
SC8	Debug Exception Request From JTAG is Not Accepted During Core Freeze Date Added: 5/21/2002 Description: JTAG debug exception request is not accepted by the core during freeze. If the request is asserted and deasserted during a core freeze, the request is discarded. Workaround: Assert Debug request from JTAG. When entering the exception routine, use software to assert an external pin (one of the EE pins, for example) to signal that the Exception Service Routine was executed. After that, a new JTAG instruction can be written. Fix Plan: TBD	0K40A 1K42A 2K42A 2K87M
SC9	EE Pins Do Not Enable Different EOnCE Modules During Core Freeze Date Added: 5/21/2002 Description: If EE pins are asserted to enable events in the EOnCE modules during a core freeze and the request is deasserted during the same core freeze, the event is not enabled. Workaround: Poll core status from JTAG. After the core is not in a freeze state, assert the EE pin(s) for at least three cycles. Fix Plan: TBD	0K40A 1K42A 2K42A 2K87M
CPM94	FCC RTS Signal Not Asserted Correctly Date Added: 2/25/2003 Description: At the beginning of an HDLC frame transmission which is preceded by more than one opening flag, RTS will not be asserted if CTS is negated. This may cause a deadlock if the modem waits for the assertion of RTS before asserting CTS. Workaround: Implement one of the following: 1. Transmit no flags between or before frames. 2. Clear FPSMR[NOF] bit. Set GFMR[RTSM]=1 to ensure RTS/ is asserted when FCC is enabled. However no hand shaking activities with the modem will occur for all the proceeding frames. Fix Plan: TBD	2K87M
СРМ96	ATM Performance Monitoring with AAL1 CES Date Added: 2/25/2003 Description: ATM Performance Monitoring with AAL1 CES Data in DPRAM is corrupted when performance monitoring is enabled in the receiver. Workaround: Impelement one of the following: 1. Disable Receive Performance Monitoring RCT[PMT]=0. 2. Use microcode patch available from Freescale. Fix Plan: TBD	0K40A 1K42A 2K42A 2K87M

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

Errata Number	Errata Description	Applies to Mask
СРМ97	MCC SS7 - No SUERM interrupt generated after an ABORT Date Added: 2/25/2003 Description: Octet Count Mode is not entered properly when idles are received after an ABORT. Therefore N_Cnt is not decremented and no SUERM interrupt will be generated. This problem only affects the SS7 micro code in ITU-T / ANSI mode (SS7_OPT[STD]=0). Workaround: Use the latest RAM based SS7 micro code package available from Freescale. Fix Plan: TBD	2K87M
СРМ98	I ² C Erratic behavior can occur if extra clock pulse is detected on SCL Date Added: 8/25/2003 Description: The I ² C controller has an internal counter that counts the number of bits sent. This counter is reset when the I ² C controller detects a START condition. When an extra SCL clock pulse is inserted in between transactions (before START and after STOP conditions), the internal counter may not get reset correctly. This could generate partial frames (less than 8 bits) in the next transaction. Workaround: Do not generate extra SCL pulses on the I ² C bus. In a noisy environment the digital filter I2MOD[FLT] and additional filtering capacitors should be used on SCL to eliminate clock spikes that may be misinterpreted as clock pulses. System Number: 9133 Fix Plan: TBD	0K42A 1K42A 2K42A 2K87M
СРМ99	ABR TCTE[ER-TA] Corruption Date Added: 8/25/2003 Description: When using the AAL5 ABR ROM microcode it is possible for the TCTE[ER-TA] field to be overwritten with an erroneous value. This, in turn, will cause the TCTE[ER-BRM] to be updated with this value. As TCTE[ER-BRM] holds the maximum explicit rate value allowed for B-RM cells an erroneous value in this field could have a detrimental effect on the network performance. Workaround: Use the micro code patch available from Freescale. System Number: 9132 Fix Plan: TBD	0K42A 1K42A 2K42A 2K87M

Table 50. 2K87M Errata

Errata Number	Errata Description	Applies to Mask
CPM101	Date Added: 1/15/2004 Date Revised: 11/05/2004 Description: FCC ATM Receive UTOPIA slave mode. When the RxFIFO is full, RxClav is negated 2 cycles before the end of the cell transfer, instead of 4. A master that polls RxClav or pauses 3 or 4 cycles before the end of the cell transfer may sample a false RxClav, and an overrun condition may occur. The dashed line in the timing diagram below depicts the actual RxClav negation (two cycles before the end of the cell transfer instead of four cycles). The signals in the timing diagram are with respect to the master, so the Tx interface is shown. Workaround: 1. The master should not poll RxClav or pause a cell transfer 4 cycles before the end of a cell transfer. The master should poll 2 cycles before the end of the current cell or later. This can be achieved by introducing cell-to-cell polling (and transfer) delay, which is equal or larger than one cell transfer time. If this can be achieved, the impact on performance is minimal. 2. Configuring ATM only on FCC1 and setting FPSMR[TPRI] ensures the highest priority to FCC1 Rx. In addition, for CPM usage lower then 80 percent (as reported by the CPM performance tool based on UTOPIA maximal bus rate), the CPM performance is enough to guarantee that the RxFIFO does not fill up. TxClav TxClav TxClav TxClav TxClav TxClav TxClav TxSOC 1 2 3 4 50 51 52 53 54 55 56 57 58 Clock cycles from end of cell: 5 4 3 2 1	0K40A 1K42A 2K42A 1K87M
CPM111	FCC Missing Reset Date Added: 1/15/2004 Description: The TxBD may not close for the FCC in Half-Duplex 10BaseT Ethernet. There may be a mismatch between the actual transmitted BD and the BD for which the status is updated. As a result, the status of one to three BDs may not be updated. They appear to be "ready" although the associated frames have been transmitted (assuming a frame per BD). Workaround: Use microcode patch provided by Freescale. System Number: 11064 Fix Plan:	0K40A 1K42A 2K42A 2K87M

Errata Number	Errata Description	Applies to Mask
CPM112	FCC Missing Reset at OverRun Date Added: 12/19/2003 Description: TxBD may not be closed for FCC in Half-duplex 10BaseT Ethernet. There may be a mismatch between the actual transmitted BD and the BD for which status is updated. As a result, the status of one to three BDs may not be updated, and they would appear "Ready", although the associated frames have been transmitted (assuming a frame per BD). Workaround: Use microcode patch provided by Freescale. System Number: 11064, 11067 Fix Plan: N/A	0K40A 1K42A 2K42A 2K87M
CPM113	Incorrect Return Value from Event Register Read (SCC, SPI, I ² C, and SMC) Date Added: 12/19/2003 Description: When the Event Register is read while the SCC, SPI, I ² C, or SMC is active, it is sometimes read as 0, even though it has some bits set. Workaround: System Number: 11068 Fix Plan:	0K40A 1K42A 2K42A 2K87M
CPM115	APC Transmits Unwanted Idle Cells Date Added: 12/19/2003 Description: In heavily loaded ATM applications, if the ATM pace controller (APC) is configured for multiple priority levels and a burst of traffic for transmission is sustained long enough on the highest priority APC table, then an unwanted idle cell can be trasmitted on the lower priority APC tables when there are cells available in lower priority APC scheduling table for transmission. The transmission of the unwanted idles could cause the valid ATM cells on lower-priority APC scheduling tables not to be transmitted. This transmission of unwanted idles can affect all ATM channels that are not located in the highest-priority APC scheduling table. Workaround: Increase the size of lower-priority APC scheduling tables so they are large enough to absorb any burst or back-to-back bursts on the highest-priority APC scheduling table. Otherwise, use the microcode patch available from Freescale. System Number: 11069 Fix Plan:	0K40A 1K42A 2K42A 2K87M
CPM116	Pointer 93 in Partially Filled (PFM) Mode Date Added: 1/15/2004 Description: In PFM mode, the pointer value of 93 is not generated, causing the loss of synchronization at the far end. Also, when the pointer value of 93 is received, the synchronization is lost, which causes a loss of data and the resynchronization routine. Workaround: Use microcode patch provided by Freescale. System Number: 11912 Fix Plan:	0K40A 1K42A 2K42A 2K87M

Errata Number	Errata Description	Applies to Mask
CPM117	 False Address Compression Date Added: 11/05/2004 Description: If there are active AAL0 channels and a CRC-10 error has been received, VP-level address compression might have false results, which could lead to one of the following: Wrong calculation of a VP pointer address Cells might be falsely discarded as misinserted cells Misidentification of misinserted cells (in CUAB mode) This is a statistical error, which is conditional on the reception of AAL0 cells with a CRC-10 error. The probability of false address compression is directly correlated with higher CPM bit rate and longer system bus latency. While the false address compression is possible only if there are active AAL0 channels, it may have an impact on all AAL types. However, it cannot occur unless AAL0 cells with CRC-10 error have been received beforehand. 	0K40A 1K42A 2K42A 1K87M
	Workaround: Use the microcode patch supplied by Freescale. System Number: 17129	
CPM118	Aborted HDLC Frame Followed by a Good Frame Date Added: 7/11/2004 Description: When an aborted HDLC frame is followed by a good frame, the receive data buffer may contain the data of the aborted frame followed by the data of the good frame. Workaround: Use the microcode patch provided by Freescale. System Number: 15905 Fix Plan:	0K40A 1K42A 2K42A 2K87M
CPM119	Ethernet Collision Occurs on the Line 125 Clocks after TX_EN Assertion Date Added: 7/11/2004 Description: When an ethernet collision occurs on the line 125 clocks after TX_EN assertion, late collision will be reported even though this is only 63 bytes into the frame instead of 64. When a collision occurs 124 cycles after TX_EN assertion, no event is reported, the TxBD is not closed, and transmission halts. Retransmission behavior is correct for collisions occurring between assertion of TX_EN and 123 clocks. Workaround: Use the microcode patch provided by Freescale. System Number: 15907 Fix Plan:	0K40A 1K42A 2K42A 2K87M
CPM120	SS7_OPT[FISU_PAD] parameter has no effect on the number of flags between FISUs Date Added: 12/22/2004 Description: The SS7_OPT[FISU_PAD] parameter has no effect on the number of flags between FISUs. Regardless of the value of this field, one flag will be present between back-to-back FISUs. Workaround: Use the latest SS7 microcode package provided by Freescale. System Number: 18767 Fix Plan: None at this time.	2K87M

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

Errata Number	Errata Description	Applies to Mask
	TDM Data Frame Corruption	0K40A
	Date Added: 11/05/2004	1K42A
CPM121	Description: During a write to one of the SI registers (GMR, AMR, BMR, CMR, DMR) while one or more TDMs are working, one data frame of a working TDM may become corrupted.	2K42A 1K87M
	Workaround: Work with the shadow RAM when changing data and do not disable and then enable the TDM.	
	System Number: 17460	

A Bootloader Program

This appendix lists the boot program for mask set 2K87M of the MSC8103.

Note: The first instruction in the boot code sets the stack address to 0x68000. In the event of a hard or soft reset, user data at this location is overwritten by the boot code. In addition, source code should not be bootloaded to this address due to corruption of the stack during the bootload program execution.

```
;/*
                                                          */
;/* File : boot_code_revA.asm
                                                          */
;/* (C) Copyright Freescale Inc, 2002.
;/* All rights reserved
                                                          */
;/*
                                                          */
;/*
                                                          */
;/* Description:
;/* This file contains the MSC8103 RevA boot code as
;/* specified in the boot section of the Reference Manual.
                                                          */
;/*
;/*
                                                          */
;/* Modifications from Rev0:
                                                          */
     - Host checksum fixed (Erratum Boot1)
     - SRAM base address is ISB dependent (Erratum Boot2)
                                                          */
     - Software watchdog handled in host code instead of
                                                          */
;/*
;/*
         disabled.
                                                          */
     - Added I2C serial boot
                                                          */
;/*
STACK_ADDR equ $68000
BOOT_BYPASS_ADD equ $0
; BANKS
              $00f0ff00
MASKO_A equ
BASEO_A equ
              $00f0ff02
BASEO_D equ
              $00f00000
BASE1_A equ
              $00f0ff06
BASE_ROM_ADDRESS equ $00f80000
BASE_EXEPTION_TABLE equ $00f80000
EXTERNAL_MEM_BOOT_TABLE equ $fe000110
; BOOT_REV_REG
BOOT_REV_REG equ BASE_ROM_ADDRESS+$ffa0
; Host Interface Registers
; Dsp Side
HCR
                 BASE0_D+$0000
           equ
HPCR
           equ
                 BASE0_D+$0020
```

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

```
BASE0_D+$0040
HSR
             equ
                   BASE0_D+$0060
HCVR
             equ
                   BASE0_D+$0080
HOTX
             equ
HORX
             equ
                   BASE0_D+$00a0
                   BASE0_D+$1c20
ELIRE
             equ
ELIRF
                   BASE0_D+$1c28
             equ
; the registers to be used are :
      d4,d5 for reading from the host fifo
            for holding the block address
;
            for holding the size
      d6
;
           for holding the checksum
      d7
;
      d2
            for holding the ~checksum
      d1,r6
               for holding the IMMR
      r5 for holding the SRAM BASE MEM
;
      d12,r15 for sw watchdog handling
      During the loading proces the checksum is calculated for the whole
;
      long and at the end of the block the two words in the calculated
      checksum are XORed to generate the real checksum.
;----- NMI0 (HDI16) offset 0xe00 -----
      section nmi0
                      p:$0e00+BASE_EXEPTION_TABLE
      org
nmi0
      rte
      endsec
;----- NMI1 (TEA) offset 0xe40 -----
      section nmi1
      org p:$0e40+BASE EXEPTION TABLE
nmi1
      rte
      endsec
;----- NMI2 (bus controller , memory write errors) offset 0xe80 ----
      section nmi2
      org p:$0e80+BASE_EXEPTION_TABLE
nmi2
      rte
      endsec
;----- NMI3 (bus controller non aligned error) offset 0xec0 ----
      section nmi3
      org p:$0ec0+BASE EXEPTION TABLE
nmi3
      rte
```

Bootloader Program

```
endsec
;----- NMI4 (bus controller bus error) offset 0xf00 -----
      section nmi4
      org p:$0f00+BASE_EXEPTION_TABLE
nmi4
      rte
      endsec
;----- NMI5(reserved) offset 0xf40 ----
      section nmi5
      org p:$0f40+BASE_EXEPTION_TABLE
nmi5
      rte
      endsec
;---- NMI6 (reserved) offset 0xf80 ----
      section nmi6
      org p:$0f80+BASE EXEPTION TABLE
nmi6
      rte
      endsec
;----- NMI7 (sic nmi,s/w wd,external nmi, parity) offset 0xfc0 ----
      section nmi7
      org p:$0fc0+BASE_EXEPTION_TABLE
nmi7
      rte
      endsec
;----- illegal exeption offset 0x80 ------
      section illegal exeption
      org p:$0080+BASE_EXEPTION_TABLE
illegal_exeption
      rte
      endsec
;----- debug exeption offset 0xc0 -----
      section debug exeption
      org p:$00c0+BASE_EXEPTION_TABLE
debug_exeption
      rte
      endsec
```

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

```
;----- overflow exeption offset 0x100 -----
      section overflow_exeption
      org p:$0100+BASE_EXEPTION_TABLE
overflow_exeption
      rte
      endsec
;----- auto nmi exeption offset 0x180 -----
      section auto_nmi_exeption
      org p:$0180+BASE_EXEPTION_TABLE
auto_nmi_exeption
      rte
      endsec
;----- auto ir exeption offset 0x1c0 -----
      section auto_ir_exeption
      org p:$01c0+BASE_EXEPTION_TABLE
auto_ir_exeption
      rte
      endsec
;----- in address 0 goto 0x1000 -----
      section start
      org p:$0000+BASE_ROM_ADDRESS
start
      ; exeption stack pointer initialization
      move.1 #BASE_EXEPTION_TABLE, vba; init vba
      move.1 #STACK ADDR,r0
      nop
      tfra r0,sp ; init ESP
      ; stack initialization
      move.1 #0,d3
      move.1 d3, (r0)
      jmp $1000+BASE ROM ADDRESS
      endsec
      section boot
      org
                  p:$1000+BASE_ROM_ADDRESS
Fmain
      move.1 emr,d1
```

```
extractu #2, #17, d1, d3 ; get EE4, EE5 -> d3
      nop
       cmpeq.w #$3,d3
       jt to_boot_bypass
      move.1 emr,d1
       extractu #3, #19, d1, d3
             ; d3 xor 3'b100 to recover original isb
       eor #$4,d3.1
      move.1 d3,d13; Added for serial BOOT
       jmp find_siubase
return_find_siu
       ; SRAM INIT
      jmp sram_init
return sram init
       ; initialize ELIRE
      move.w #$8000,d0
      nop
      move.w d0, ELIRE
       ; initialize ELIRF
      move.w #$0008,d0
      nop
      move.w d0, ELIRF
       ; check the scmr to see which upm routine to load
      move.1 (r6+$c88),d1
                               ;scmr,d1
       ; extract the busdf from scmr
       extractu #4, #20, d1, d3
       jmp upmc_init
check boot
      move.1 emr,d1
      ;get EE4,EE5 -> d3
      extractu #2, #17, d1, d3
      nop
      cmpeq.w #$0,d3
      jt external_memory
      cmpeq.w #$1,d3
       jt from_host
       cmpeq.w #$2,d3;added for serial boot
       jt from_serial
       cmpeq.w #$3,d3;added for serial boot
       jt to boot bypass
       stop
external_memory
       ;d3 < -isb[0,1,2]
       extractu #3, #19, d1, d3
       ; d3 xor 3'b100 to recover original isb
       eor #$4,d3.1
       ;r3 <- d3
```

87

```
move.1 d3,r3
      nop
      ; FIND IMMR FROM ISB
      ;r3 *= 4 so the offset will be in long instead of bytes
      ;r3 = r3 << 2
      asl2a r3
      ; put the address of the external memory boot table in r4
      move.1 #EXTERNAL_MEM_BOOT_TABLE,r4
      nop
      adda r4,r3
      nop
      ; move the address from the table into r3
      move.1 (r3), r3
      nop
      ;jump to that address
      jmp r3
to_boot_bypass
      jmp BOOT_BYPASS_ADD
      nop
from_host
      ; software watch dog is not disabled
      ; it will be handled in the load from fifo routine if it is enabled
      move.1 #$0,d15;clear d15, software watchdog is not enabled
      move.1 (r6+$4),d1;get sypcr value
      bmtsts #$0004,d1.1
      jf HDI_en
      nop
      move.l d15,r15; clear watchdog handle counter
      move.1 #$1,d15; indicate software watchdog enabled
      move.1 #$0100,r15; initialize watchdog handle counter
      ; set the HEN bit in hpcr
HDI en
      move.w HPCR,d3
             or #$0080,d3.1
      move.w d3, HPCR
      ;get the 8bit bit from hpcr (which is in d3)
      ;if (8bit ) goto load_8bit else goto load_16bit
      bmtsts #$0040,d3.1
      jt load_8bit
      jmp load_16bit
load_last_long_2_16
      ; if the size left to load is only 2 words (4 bytes)
      ; and the mode is 16-bit so every load action is of 4 words
      ; in this case the load action already loaded the checksum
      ; and the ~checksum, so it is a special case which needs handling
      ; by itself
      jsr load_from_fifo
```

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

```
; move the last 2 words to their address (which is kept in r3)
      move.1 d4, (r3)
      adda #$4,r3
       ;write checksum , ~checksum at the and of the block
      move.1 d5,(r3)
       ; calculate the checksum of these words
       eor d4,d7
       ;calculate ~checksum -> d2
       ;get the real checksum from d7 and
       ;get it into d7.1 as explained in the beggining of the file
       ;d2 = (0xffff0000 & d7) >> 16
       extractu #16, #16, d7, d2
       ;d2 = d2 \& 0x0000ffff
       and #$0000ffff,d2,d2
       ; d7 = d7 \& 0x0000ffff
      and #$0000fffff,d7,d7
       ;d7 = d7 ^ d2 = checksum
       eor d2,d7
       ;d2 = (\sim d7 \& 0x0000ffff) = \sim checksum
      not d7,d2
       and #$0000ffff,d2,d2
       ;get loaded checksum , ~checksum from d5
       ; get checksum into d4
       extractu #16, #16, d5, d4
      and #$0000ffff,d4,d4
       ; delete the checksum from d5
       and #$0000ffff, d5, d5
       ;if ( ~checksum_loaded |= ~Checksum_calculated ) goto set sticky bit
      cmpeq d5,d2
      nop
       iff jsr set_sticky_bit
       ;if (checksum loaded |= Checksum calculated) goto set sticky bit
      cmpeq d4,d7
      nop
       iff jsr set_sticky_bit
       ; goto loading the next block
       ;goto load_16bit
load 16bit
       ;d7 = checksm =0 , clear the calculated checksum register
      move.1 #0,d7
             ;load the size and address
       jsr load from fifo
       ; move the size into d6
      move.1 d4,d6
       ;move the address into r3
      move.1 d5,r3
       ; should be calculated on data and address also
```

```
eor d4,d7
      eor d5,d7
      ; check if the finished (HF4) bit is set ,if it is set clear it
      ; and the sticky bit .( it means there was an error and
      ; the blocks are being loaded for the second time
      move.w HCR, d4
      bmtsts.w #$8000,d4.1
      jf continue_loading_16
      move.w HCR, d4
      and #$6fff,d4.1
      move.w d4, HCR
continue loading 16
      ;if (size == 0 ) in the beggining of a block it means no more blocks
      ; then jump to the address loaded in r3 (from d5)
      tsteq d6
      jt end_of_loading_16
load loop 16
      ;if (size ==2) it is a special case so goto load_last_long_2_16
      move.1 #$0000002,d4
      cmpeq d4,d6
           load_last_long_2_16
      jt
      ;load 2 data words
      jsr load from fifo
      ;load the first 2 data words (4 bytes) to the address
      move.1 d4, (r3)
      ;increment the address by 4 bytes
      adda #$4,r3
      ;load the second 2 data words (4 bytes) to the address
      move.1 d5, (r3)
      ; increment the address by 4 bytes
      adda #$4,r3
      ; CALCULATE CHECKSUM
      eor d4,d7
      eor d5,d7
      ; decrease the size by 4 words
      sub #$4,d6
      ; jump to loading the next words
      jmp load_loop_16
load 8bit
      move.1 #0,d7; un-initialized dalu register.
      ;load the size into d6
      jsr load_from_fifo
```

```
; check if the finished bit (HF4) is set , if it is set clear it
       ; and the sticky bit .( it means there was an error and
       ; the blocks are being loaded for the second time
      move.w HCR,d6
      bmtsts.w #$8000,d6.1
      jf continue_loading_8
      move.w HCR, d6
      and #$6fff,d6.1
      move.w d6, HCR
continue loading 8
                 ; checksum is calculated on size
       eor d5,d7
      move.1 d5,d6
       ;if (size == 0) it means the last block was loaded
       ; so goto end of loading
       tsteq d6
              end of loading
      jt
       ;load the address
       jsr load from fifo
      move.1 d5,r3
       eor d5,d7 ;checksum is calculated on address
load_loop_8
       ;load data word
       jsr load from fifo
      move.1 d5,(r3)
       ; add 4 bytes to the address
      adda #$4,r3
       ;CALCULATE CHECKSUM d7 = d7 ^ d5
       eor d5,d7
       ; subtract 2 words from the size
       sub #$2,d6
       ;if (size | = 0) go to load_loop_8
       tsteq d6
       jf
              load_loop_8
       ;get the checksum into d7.1
       ;d2 = (0xffff0000 \& d7) >> 16
       extractu #16, #16, d7, d2
       ;d2 = d2 \& 0x0000ffff
      and #$0000ffff,d2,d2
       ;d7 = d7 \& 0x0000ffff
      and #$0000ffff,d7,d7
       ; d7 = d7 ^ d2
      eor d2,d7
       ;d2 = (\sim d7 \& 0x0000ffff) = \sim checksum
      not d7,d2
      and #$0000ffff, d2, d2
       ;load the checksum ,~checksum
       jsr load_from_fifo
       ;get ~checksum into d4
       extractu #16, #16, d5, d4
       ;delete the ~checksum from d4
```

```
and #$0000ffff, d5, d5
       ;if ( checksum_loaded |= Checksum_calculated ) goto set sticky bit
       cmpeq d5,d2
      nop
       iff jsr set_sticky_bit
       ;if ( ~checksum_loaded |= ~Checksum_calculated ) goto set sticky bit
       ;clean d4.h
       and #$0000ffff,d4,d4
       cmpeq d4,d7 ; d4,d7 contain checksum
      nop
       iff jsr set_sticky_bit
       ;goto load the next block
       jmp load_8bit
end of loading 16
       jsr load_from_fifo
       ;get the checksum into d7.1
       ;d2 = (0xffff0000 \& d7) >> 16
      extractu #16, #16, d7, d2
       ;d2 = d2 \& 0x0000ffff
       and #$0000ffff,d2,d2
       ;d7 = d7 \& 0x0000ffff
      and #$0000ffff,d7,d7
       ; d7 = d7 ^ d2
       eor d2,d7
       ;d2 = (\sim d7 \& 0x0000ffff) = \sim checksum
      not d7,d2
       and #$0000fffff,d2,d2
       ;get checksum into d4
       extractu #16, #16, d5, d4
       ; delete the checksum from d5
      and #$0000ffff,d5,d5
       ;if ( ~checksum loaded |= ~Checksum calculated ) goto set sticky bit
                    ;d5 and d2 contain ~checksum
       cmpeq d5,d2
      nop
      iff jsr set_sticky_bit
       ;clean d4.h
      and #$0000ffff, d4, d4
       ;if ( checksum_loaded |= Checksum_calculated ) goto set sticky bit
      cmpeq d4,d7
      nop
       iff jsr set sticky bit
       ;set HF4 bit in HCR to show that loading is finished
      move.w HCR, d6
      or #$00008000,d6.1
      move.w d6, HCR
       ; check if the checksum bit is set ( HF3 in HSR (HSR[3] )
      move.w HSR, d6
      and #$00001000,d6,d6
```

```
; check if the sticky bit is set ( HF7 in HCR (HCR[3]) )
      move.w HCR, d4
      and #$00001000,d4,d4
       ; if both of the flags are set start the loading again
      and d4,d6
      tsteq d6
       jf from_host
       ; if everything is OK jump to the address in r3
       jmp
end_of_loading
             ;load the destination address into r3
       jsr load_from_fifo
      move.1 d5,r3
       eor d5,d7
       jsr load_from_fifo ; reads 0
       jsr load from fifo ; reads checksum to d5
       ; get the checksum into d7.1
       ;d2 = (0xffff0000 \& d7) >> 16
       extractu #16,#16,d7,d2
       ;d2 = d2 \& 0x0000ffff
      and #$0000ffff,d2,d2
       ; d7 = d7 \& 0x0000ffff
      and #$0000ffff,d7,d7
       ; d7 = d7 ^ d2
       eor d2,d7
       ;d2 = (\sim d7 \& 0x0000ffff) = \sim checksum
      not d7,d2
      and #$0000ffff,d2,d2
       ;get ~checksum into d4
       extractu #16, #16, d5, d4
       ;delete the ~checksum from d5
       and #$0000ffff,d5,d5
       ;if ( checksum_loaded |= Checksum_calculated ) goto set sticky bit
      cmpeq d5, d2
      nop
      iff jsr set_sticky_bit
       ;clean d4.h
      and #$0000ffff,d4,d4
       ;if ( ~checksum loaded |= ~Checksum calculated ) goto set sticky bit
      cmpeq d4,d7
      nop
       iff jsr set_sticky_bit
       ; set HF4 bit in HCR to show that loading is finished
      move.w HCR, d6
      or #$8000,d6.1
      move.w d6, HCR
```

```
; check the check sticky bit is set ( HF3 in HSR (HSR[3) )
      move.w HSR, d6
      and #$00001000,d6,d6
      ; check if the sticky bit is set ( HF7 in HCR(HCR[3]) )
      move.w HCR, d4
      and #$00001000,d4,d4
      ; if both of the flags are set start the loading again
      and d4,d6
      tsteq d6
      jf from_host
      nop
      ; jump to the destination address
      jmp r3
load from fifo
      tsteq d15; check flag if watchdog disabled
      jt load_no_wd
load_wd deceqa r15
      nop
      ift jsr watchdog_handle
HSR_read move.w HSR,d4
      bmtsts.w #$0001,d4.1
      jf
            load_wd
      nop
      jmp read fifo
      nop
load no wd
      ; if the host is empty wait for it to fill
             move.w HSR, d4
      bmtsts.w #$0001,d4.1
            load no wd
      ; the host is not empty so load 8 bytes from it
read_fifo move.1 #HORX,r0
      nop
      move.21 (r0),d4:d5
      rts
; Set the sticky bit (HF7) if there is an error in loading the program
set sticky bit
      ;set the HF7 bit in HCR
      move.w HCR, d6
      or #$00001000,d6.1
      move.w d6,HCR
      rts
watchdog handle
      move.1 #$0100,r15
      move.w #$556c,d12
      move.w d12, (r6+$e); write $556c to swsr
      move.w #$aa39,d12
      move.w d12,(r6+$e); write $aa39 to swsr
      rts
```

Bootloader Program

```
find_siubase
      ; read IMMR using siureg1
      move.l #$00f8ffc0,r7;move Address of IMMR (using siureg1) into d9
      move.1 (r7),d1;read IMMR into d1
      nop
      extractu #$20, #0, d1, d1; remove the extend bits
      nop
      and #$ffff0000,d1,d1;Leave only ISB bits on IMMR
      move.1 d1, d9
                          ;Added for serial boot
                          ;d9 gets the IMMR value
      inc.f d1
                   ; d1+$10000->d1
      jmp return_find_siu
sram init
      move.l d1,r6
      move.1 #$00000200,d1; base address for bank 10
      move.1 #$00000100,d2; delta/2
      imac d2, d3, d1; (d1+d3.1*d2.1) -> d1
      aslw d1,d1 ; d1<<16
      move.1 #$01f00000,d0; offset 2 (for bank 11)
                  ; multiply d3 by 0x10,000
      aslw d3,d2
      add d2, d0, d0
      move.1 d1,r5;
      bmset #$00c1,d1.1
      move.1 #$fff80000,d7
      move.1 d7, (r6+$154); SET OR10
      move.1 d1, (r6+$150); SET BR10
      ; gpcm_init
      move.1 #$ffff0000,d1; SET OR11 MASK 64 KB
      bmset #$0021,d0.1; changed the machine select to gpcm.
      move.1 d1, (r6+$15c); SET OR11 MASK 64 KB
      move.1 d0, (r6+$158); SET BR11 TO $01f0_0000
      jmp return sram init
upmc init
; ----- READ SINGLE -----
      move.1 #$90051240,d7
      move.1 d7, (r6+$178);
      move.1 #$00030040,d7
      move.1 d7,(r6+$188);
      cmpeq.w #$2,d3
      jf continue_upmc1
      move.w #$0,(r5);
      move.1 #$00030040,d7
      move.1 d7, (r6+$188);
continue_upmc1
      move.w #$0,(r5);
      move.1 #$00030045,d7
      move.1 d7, (r6+$188);
```

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

95

```
move.w #$0,(r5);
; ----- READ BURST ------
     move.1 #$90051248,d7
     move.1 d7, (r6+$178);
     move.1 #$00030c48,d7
     move.1 d7, (r6+$188);
     move.w #$0,(r5);
     move.1 #$00030c4c,d7
     move.1 d7, (r6+$188);
     move.w #$0,(r5);
     move.1 #$00030c4c,d7
     move.1 d7, (r6+$188);
     move.w #$0,(r5);
     move.1 #$00030044,d7
     move.1 d7, (r6+$188);
     move.w #$0,(r5);
     move.1 #$00030045,d7
     move.1 d7, (r6+$188);
     move.w #$0,(r5);
 ----- WRITE SINGLE -----
     move.1 #$90051258,d7
     move.1 d7, (r6+$178);
     move.1 #$00000040,d7
     move.1 d7, (r6+$188);
     cmpeq.w #$2,d3
     jf continue_upmc2
     move.w #$0,(r5);
     move.1 #$00000040,d7
     move.1 d7, (r6+$188);
continue_upmc2
     move.w #$0,(r5);
     move.1 #$00000045,d7
     move.1 d7, (r6+$188);
     move.w $0,(r5);
 ----- WRITE BURST -----
     move.1 #$90051260,d7
     move.1 d7, (r6+\$178);
     move.1 #$00000c48,d7
     move.1 d7, (r6+$188);
     move.w #$0,(r5);
     move.1 #$00000c4c,d7
     move.1 d7, (r6+$188);
     move.w #$0,(r5);
```

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

```
move.1 #$00000c4c,d7
     move.1 d7, (r6+$188);
     move.w #$0,(r5);
     move.1 #$00000044,d7
     move.1 d7, (r6+$188);
     move.w #$0,(r5);
     move.1 #$00000045,d7
     move.1 d7, (r6+$188);
     move.w #$0,(r5);
; ----- EXCEPTION ------
     move.1 #$9005127c,d7
     move.1 d7,(r6+$178);
     move.1 #$ff000001,d7
     move.1 d7, (r6+$188);
     move.w #$0,(r5);
; ----- RESUME NORMAL OPERATION -----
     move.1 #$80011240,d7
     move.1 d7, (r6+$178);
     jmp check_boot
; serial boot code here
equ $2160 ;TX Buffer Pointer
RXB
     equ $2170; Rx Buffer Pointer
TIMEOUT equ $80000 ; Time Out till system is consider dead
SERBIT16 equ $1000;
;I2c Parameter Ram
I2C_BASE equ $8afc
I2C BASE VAL equ $3e00
;To these
RBASE equ
           $3e00
RBASEVAL equ$3e50
TBASEVAL equ$3e40
RTBASEVAL equ $3e503e40
RFCR equ $3e04
RSTATE equ
           $3e08
RPTR equ $3e0c
RBPTR equ
          $3e10
RTEMP equ $3e14
TSTATE equ$3e18
TPTR equ
         $3e1c
TBPTR equ
          $3e20
TTEMP equ $3e24
```

```
$3ea0
DEBUGPTR equ
DEBUGEND equ
              $3ef0
; Backup of registers
        equ $3f00
SCCRB
PODRBB equ$3f04
PSORBB
       equ$3f08
PPARBB equ
            $3f0c
PDIRBB equ $3f10
; SYPCR equ$0004
SWSR equ $000e
SCCR
              $0c80
      equ
CPCR equ
           $19c0
;I2C Register
I2MOD equ
            $1860
I2ADD equ$1864
I2BRG equ
            $1868
I2CER equ
           $1870
I2CMR equ
           $1874
I2COM equ
           $186c
;PB Regs
PODRB
      equ$0d2c
PSORB equ$0d28
PPARB equ
            $0d24
            $0d20
PDIRB equ
PDATB equ$0d30
PDATC equ$0d50
I2MODVAL equ$001a;GCD=1, FLT=1 , PDIV = 01
I2MODVALE equ$001b;GCD=1, FLT=1, PDIV = 01, EN = 1
I2BRGVAL equ$0007
ARSLAVEADDRESS equ $af000000; Aligned Read Slave address
AWSLAVEADDRESS equ $ae000000; Aligned Write Slave address
; RESERVED REGISTER:
     d5: The address for read bd function (Byte Shifted)
     d7: The Rx Buffer Lenght for read_bd function
;
     d8:
;
     d9: IMMR - Setted by previous boot_code
;
     d10: Block counter ( count the numer of loaded blocks )
```

Bootloader Program

```
d12: Used for watchdog handler function.
   d14: Tx buffer address, for read_db function.
;
    r2: Pointer to address of Block data on EEPROM
    r5: The Rx Buffer pointer for read_bd function
     r6 : IMMR + $0001_0000
;
     r7 : IMMR
;The follow registers were initiated by the previous code (boot_code_revA1.)
     d13:Contain the ISB Bits
     d9:IMMR
; ----- SERIAL BOOT CODE START HERE ------
from serial
     move.1 d9,r7
                  ;d9&r7 will have always IMMR value
     move.1 r7,d11
     move.1 #$10000,d12
     add
           d11,d12,d11
     move.l dl1,r6;r6<-IMMR+$10000 for registers access
Configure I2 Register &
    Parameter RAM
move.1 d9,r3
                     ;r3 <- IMMR
     bmset
           #I2C_BASE,r3.1;r3 receive I2C page base address
     ;sw watchdog
     move.1 #$0,d11;clear d11, software watchdog is not enabled
     move.1 (r6+$4),d12;get sypcr value
     bmtsts #$0004,d12.1
     jf init_
     nop
     move.l d11,r15; clear watchdog handle counter
     move.1 #$1,d11; indicate software watchdog enabled
     move.1 #$0100,r15 ; initialize watchdog handle counter
; Initiate I2C BASE
init_ move.w #I2C_BASE_VAL,d4
     nop
                           ; inserted due to restriction 6.4.4.a.2
     move.w d4,(r3);Save d4 into I2C_BASE
; Initiate Parameter RAM
     move.1 #RTBASEVAL,r1; RBASE=3e50, TBASE=3e40
                           ; due to restriction 6.4.4.a.2
     move.1 r1, (r7+RBASE);$00
     move.1 #$1212ff00,r1; RFCR=12(use local BUS), TFCR=12, MRLBR=ff00
```

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

```
; due to restriction 6.4.4.a.2
     nop
     move.l r1, (r7+RFCR); $04
     move.1 #$0000000,r1;RSTATE
                            ; due to restriction 6.4.4.a.2
     nop
     move.1 r1, (r7+RSTATE);$08
     move.lr1,(r7+RPTR);0c
     move.1 r1, (r7+RBPTR);$10
     move.1 r1, (r7+RTEMP);$14
     move.1 r1, (r7+TSTATE);$18
     move.1 r1, (r7+TPTR) ;$1c
     move.1 r1, (r7+TBPTR); $20
     move.1 r1, (r7+TTEMP);$24
     move.1 #$10000,d1
     nop
                            ; due to restriction 6.4.4.a.2
     add
           d1,d9,d4
                       ;d4 receive IMMR +1 0000
     nop
                            ; due to restriction 6.4.4.a.2
                            ;R6 <-IMMR +1_0000
     move.1 d4,r6
     ;Initiate I2C command - Page = 01010,code=01011
     move.1 #$29610000,r1
     nop
     move.1 r1, (r6+CPCR); Write the cmd to CPCR
; Save registers in the backup area of DP ram
move.1 (r6+SCCR),r1
     nop
     move.1 r1, (r7+SCCRB)
     move.1 (r6+PODRB),r1
     nop
     move.1 r1, (r7+PODRBB)
     move.1 (r6+PSORB),r1
     move.1 r1, (r7+PSORBB)
     move.1 (r6+PPARB),r1
     move.l r1, (r7+PPARBB)
     move.1 (r6+PDIRB),r1
     nop
     move.l r1, (r7+PDIRBB)
; Initiate SCCR to 01 -> divide by 16
     move.1
             #1,r1
     move.1 r1, (r6+SCCR)
;;Initiate IO Port
; Configure port B SCL=PB18,SDA=PB19
     move.1 #$00003000,r1
                       ; due to restriction 6.4.4.a.2
     nop
```

```
move.1 r1, (r6+PODRB); PODRB[18,19]=1
     move.l r1, (r6+PSORB); PSORB[18,19]=1
     move.1 r1, (r6+PPARB);
     move.1 #$0000000,r1
                       ; due to restriction 6.4.4.a.2
     move.1 r1, (r6+PDIRB);
;;Initiate I2C Registers
move.w #$0,r1
     move.br1,(r6+I2MOD);Clear i2mod
     move.br1, (r6+I2CMR); Disable All Interrupt
     move.w #$ec,r1
     move.br1, (r6+I2ADD); Slave Address= 00 (optional)
     move.w #$0017,r1
     move.br1, (r6+I2CER)
                         ;Clear all previous events
     move.w #I2MODVAL,r1
     move.b r1, (r6+I2MOD); I2MOD[GCD]=1, [FLT]=1
            #I2BRGVAL,r1
     move.w
     move.br1, (r6+I2BRG)
                         ; I2BRG[DIV] = 6
     move.w #$0001,r1
     move.br1,(r6+I2COM)
                         ;I2COM[M/s]=1 ( Master mode )
     move.w #I2MODVALE,r1
     move.br1,(r6+I2MOD);Set I2MO[EN]
· ***********
;SRAM base moved to r7 due to register usage
· **********************
     move.1 r5, (r5)
     nop
     move.1 (r5), r7
; Initiate debug area at IMMR + Debug Pointer
move.1 #DEBUGPTR,d10 ;
           d9,d10,d10;d10 <- ptr to debug area
     move.l d10,r1;r1 <- ptr to debug area
     add
           #$4,d10
                       ;d10 <- ptr to empty space in debug area
     move.1 d10, (r1); save the the ptr in r1
     move.1 d10,r1
                       ; move empty ptr to r1
      ; This lines will move a empty pattern (a5)
      ; to all the debug area
     move.w #$a5a5,d10;d10 receive empty pattern
iloop move.b d10,(r1)+; save empty pattern in r1 and increment r1
                       ;added due to restriction
     nop
     move.l r1,d8; Move r1 to d8
                       ; added due to restriction
     nop
```

```
extractu #$f,#0,d8,d8 ;Leave only offset in d8
    nop
                   ; added due to restriction
    cmpeq.w #DEBUGEND, d8; compare if end of debug
    jf iloop
             ; if not jmp to the loop
                   ; added due to restriction
Calculate Table Address &
    Get the code Address
move.1 d13,d5; d5 receive ISB
    move.1 #$0,d10 ; reset the Blocks counter ( d10 )
Read first Block Address
;D5 <- D5 x 2 + byte shift left
    asll #$9,d5 ;d5 <- Address(1 Byte shifted)
    move.1 #$2,d7;d7 <- Rx BD lenght
    move.1 #TXB,d4;prepare Tx buffer address in d14
    move.l r5,d14;r5 holds SRAM base address
    non
    add d4,d14,d14;add sram base
    move.1 #RXB,r5 ;r5 <-Rx Buffer Ofset from SRAM
    move.1 r7,d4 ;d4 <-SRAM base
    bsr read bd
    ; In the read_bd routine , the start of code address ( 2 bytes )
    ; was read to the RX Buffer at address RXB
    move.w (RXB), d5; d5 Receive the code start address
    bmclr #$FFFF,d5.h;clear unreaded upper bits
    move.1 d5,d8;Back d5 it into d8
; Prepare for read First Block Header
;D5 <- D5 x 2 + byte shift left
    asll #$8,d5 ;d5 <- Address(1 Byte shifted)
    move.1 #$8,d7;d7 <- Header lenght(4 words)</pre>
    ; Calculate the address for Head at DPRAM
    move.1 #RXB,d2; d2<- Block Header (Ofset from IMMR)
                   ; due to restriction 6.4.4.a.2
Get 4 first word
Get4FWord
    move.1 d2,r5; r5<-Head Pointer (RXB)
    move.1 #$8,d7; d7 <- Header lenght(4 words)
    bsr read_bd ; Call read_bd to read the first 4 words
  Read the Block Header Data
    move.l r5,d6; d6<-Head Pointer Offset
    nop
                   :due to restriction 6.4.4.a.2
    add
         d4,d6,d6; d6<-Head Pointer Offset + RAMptr
    move.1 d6,r8; r8<-Head Pointer Offset + RAMptr
                   ; due to restriction 6.4.4.a.2
    move.w (r8),d7;d7 <- CS Enabled bit | Block size
```

```
extractu #$e, #0, d7, d7; remove the extend bits and CS
; if Block size == 0 goto Boot_loaded ( end )
tsteq d7
                ; compare d7 to 0
       Boot_loaded; if d7 = 0->jmp to Boot Loaded
    jt
    nop
                ; due to restriction 6.4.4.a.3
; Read Block Data
move.1 (r8+$4),r5;Address to save the data on DPRAM (offset from SRAM)
    move.1 d8,d5
                ;d5<-Block data address on seeprom
    nop
                ; due to restriction 6.4.4.a.2
    add
                ;increment d5 so it points to data (first 8 bytes = Header )
        #$8,d5
    asll #$8,d5 ;Byte shift d5 (prepare for read bd)
read block
    move.1 #$0,d0
                ;Reset Status Bit in d0
read_block2
    move.1 r7,d4
    bsr read bd
    move.1 d2,r4;r4<-Head Pointer
    nop
                ; due to restriction 6.4.4.a.2
    move.w (r4),d8;d8<- CSE | Block size
;Checksum Enabled ????
bmtsts #$8000,d8.1; Test with CS bit is setted
    jt
       calc cs
                ; if checksum enable jump to calc CS
                ;; due to restriction 6.4.4.a.3
    nop
; Prepare Next Block Address
PrepareNextBAdd
    add #$1,d10 ; increment the BD counter
    move.w (r4+$2),d8;d8<- Next Block Address
    move.1 d8,d5; Restore address from d8
    asll #$8,d5 ;d5 <- Address for next Block(1 Byte shifted)
    jmp Get4FWord; jmp to Get 4 First words
    nop
;Start Boot Execution
Boot loaded
    move.1 #$80,d0
                ;Set Boot Loaded flag on d0
    move.1 (r8+$4),r3;r3 receive Boot Start Address
    ; Reset all I2C Parameter to their default value
    move.1 #$0,r1
    move.br1,(r6+I2MOD);Clear i2mod
    move.br1,(r6+I2ADD);Slave Address= 00 (optional)
```

```
move.br1, (r6+I2CMR); Disable All Interrupt
    move.br1, (r6+I2BRG)
                    ; I2BRG[DIV] = 6
    move.b r1, (r6+I2COM)
                    ;I2COM[M/s]=1 ( Master mode )
    move.w #$0017,r1
    move.br1,(r6+I2CER)
                    ;Clear all previous events
; Reload saved registers values from the backup area of DP ram
move.1 d9,r7
    nop
    move.1 (r7+SCCRB),r1
    nop
    move.1 r1, (r6+SCCR)
    move.1 (r7+PODRBB),r1
    nop
    move.1 r1, (r6+PODRB)
    move.1 (r7+PSORBB),r1
    nop
    move.1 r1, (r6+PSORB)
    move.1 (r7+PPARBB),r1
    nop
    move.1 r1, (r6+PPARB)
    move.1 (r7+PDIRBB),r1
    nop
    move.1 r1, (r6+PDIRB)
    jmp end
END OF MAIN CODE FLOW
calc_cs
;Calculate checksum
; For this we will use the follow register
    d1 : Calculated CS
    d6: words Count
    r1 : Adddress of word to be read
move r5,d6
                  ; due to restriction 6.4.4.a.2
    nop
    add
        d4,d6,d6;d6<-First RX Buffer Pointer
                  ; due to restriction 6.4.4.a.2
    nop
    move.1 d6,r1
                  :rl receive the address of first word
                  ;start xor with getting 1'st 2 words of block
    move.1 (r4), d1
    move.1 (r4+4),d6; get 2'nd 2 words
    eor
        d6,d1
                 ;xor with previous value
```

```
move.1 #$0,d6
               ; reset the word count
cs_loop
   move.1 (r1)+,d3;read long data into d3
        #$4,d6
    add
   cmpeq d6,d7
               ;if d6 = d7 ->Last Block word (CS)
       calc_rchecksum; then jump to calc_checksum
               ; due to restriction 6.4.4.a.3
   nop
    eor
       d3,d1
                   else CS <- ( CS xor data )
       cs_loop
    jmp
   nop
calc_rchecksum
   aslw d1,d6
               ; shift left word d1 into d6
       d1,d6
    eor
    extractu #$20, #0, d6, d6; remove the extend bits
   bmclr #$FFFF,d6.1;Leave only the checksum on d6.h
              ; Move it (word shift right) to d1
   not
       d1.1
               ;Obtain inverted CS (CS_b) on d1
    add
       d1,d6,d6;Obtain CS CS b on d6
    extractu #$20, #0, d3, d3; remove the extend bits
; CheckSum Ok ?
cmpeg d6,d3
               ;Compare to received CS
       PrepareNextBAdd; if equal jump to received BD
    jt
   nop
               ; due to restriction 6.4.4.a.3
;Got a CS Error
;If this is the first CS error for this BD , Set Flag and Retry
  Else jmp to CS error
bmtsts #$0001,d0.1;Test with previous CS error ocurr
cs_error; If yes jump to CS error routine
    jt
   nop
               ; due to restriction 6.4.4.a.3
   bmset #$0001,d0.1;set CS Fail flag
       read block2; retry to read the block
; Set bit 1 in d0 ( to indicate a CS error) and abort
cs error
   bmset #$0002,d0.1;set CS Error flag
    jmp reset
read bd
;This Routine will read a BD
```

```
;This routine will create 2 Tx BD and one Rx BD That receive the data
;Before enter these routine the registers must be setted as follow:
     d9: IMMR
     d4 : Rx Buffer Pointer base (SRAM base)
     d5 : The address of EEPORM to be read (Shifted 1 byte)
;
     d14: Tx buffer address
            left, e.g add=$4 -> d5 = $0400)
     d7: The lenght for RX BD
     r6 : IMMR + $1_0000
     r5 : Rx Buffer Pointer offset
;Corrupted registers:
     d1,d3,d6 ,r0,r1,r3
retry
     move.w #$0017,r1
     move.br1,(r6+I2CER)
                         ;Clear all previous events
      ;Prepare the 2 TX & 1 Rx BD's to read 2 bytes from add8ess at d5
     move.1 #TBASEVAL,d1
                        ; d1<-TBASE
     nop
                        ; due to restriction 6.4.4.a.2
     add
            d9,d1,d1; d1<-TX BD ptr
                       ; r0<-TX BD ptr
     move.1 d1,r0
·**************
;Prepare 2 Tx & 1 Rx BD
; First Tx BD
     move.1 $$4000003,d1;BD STATUS(R=1,I=1,L=0,S=1)|DATA Lenght = 3
     move.1 d1, (r0)
     move.1 d14, (r0+$4); Tx buffer address
      ; Write TX Buffer DATA
     move.1 d14,r3
                       ;r3 receive the Tx Buffer ptr
     move.1 #AWSLAVEADDRESS,d6
      extractu #$20,#0,d6,d6;remove the extend bits
            d5,d6,d6
                          ;d5=SLAVE ADDRESS | ADDRESS WORD
      add
     move.1 d6, (r3)
      ; 2nd TX BD
     move.1 \#$bc000001,d3;BD STATUS(R=1,I=1,w=1,L=1,S=1)|Lenght = 1
           d7,d3,d3;set Lenght = d7 + 1
     move.1 d3, (r0+$8)
     move.1 d14,d6
     add
            #$4,d6
                        ; d6<-2nd TX Buffer Pointer
     move.1 d6, (r0+$c)
      ; Write TX Buffer DATA for second Buffer
     move.1 #ARSLAVEADDRESS,d6
      extractu #$20,#0,d6,d6;remove the extend bits
     move.1 d6, (r3+4)
      ; Prepare the Rx BD
     move.1 #RBASEVAL,d1; d1<- RBASE
           d9,d1,d1; d1<- BD ptr
      add
     nop
                        ; due to restriction 6.4.4.a.2
     move.1 d1,r1
                        ; r1<- BD ptr
                        ; due to restriction 6.4.4.a.2
     nop
```

```
move.1 \#$b8000000,d1;BD STATUS(E=1,W=1,I=1,L=1)|DATA Lenght = 0
                     ; due to restriction 6.4.4.a.2
     nop
     move.1 d1, (r1)
                    ;Write BD STATUS + lenght
     move
          r5,d1
                     ;d1 receive Buffer ptr offset
     nop
     add
          d1,d4,d1; added buffer base to d1
     nop
     move
          d1,r3
     nop
                     ; due to restriction 6.4.4.a.2
     move.1 r3, (r1+$4); Write RX Buffer Pointer
;Set Start on i2COM
· ****************
i2com_ move.w #$8181,r3
     move.br3,(r6+I2COM)
                      ;I2COM[STR]=1 => Start transmission
     move.1 r6,d6
     move.1 #I2CER,d1
     add d1, d6, d6
                    ; r3<-I2CER Adrress
     move.1 d6,r3
     move.1 #TIMEOUT,d1
read_i2cer
     move.1 #SERBIT16,d15
     ; We insert a delay here in order to have
     ; less BUS activity
     ser_cnt sub#$1,d15
     tsteg d11; check flag if watchdog disabled
     jt tst_no_wd
     decega r15
     nop
     ift jsr watchdog handle
tst_no_wd tsteqd15
     jf ser_cnt
     nop
     ;;Decrement Counter if zero goto dead i2cer
     sub
          #$1,d1
     tsteq d1
     jt dead_i2cer
               ; due to restriction 6.4.4.a.3
     move.b (r3),d6
                 ;Read I2CER
     nop
     cmpeq.w #$0000,d6
I2cer == 0 ??
```

```
jt read_i2cer;if I2CER =0 => Read Again
                   ; due to restriction 6.4.4.a.3
    nop
BD & I2CER OK ???
; The following lines test BD and I2CER
; To check that we received data correctly.
; If not, we will retry if possible or abort (depending on error type)
bmtsts #$04,d6.1; Test BSY bit
         BSYError; If true Abort
    jt
    nop
                   ; due to restriction 6.4.4.a.3
    move.w(r0),d3
                  ; Read the BD status of the 1st TXBD
    nop
    bmtsts #$01,d3.1;Test Colision BIt
    it
         colision; If true retry
    nop
                   ; due to restriction 6.4.4.a.3
    bmtsts #$04,d3.1; Test NAK BIt
                   ; If true abort
    jt
         nAK
    nop
                   ; due to restriction 6.4.4.a.3
    move.w (r0+$8),d3; Read the BD status of the 2nd TXBD
    nop
    bmtsts #$01,d3.1; Test Colision BIt
         colision2; If true retry
    jt
                   ; due to restriction 6.4.4.a.3
    nop
    bmtsts #$04,d3.1; Test NAK BIt
    jt
         nAK
                   ; If true abort
                   ; due to restriction 6.4.4.a.3
    nop
         cmpeq.w #$0003,d6;If not I2cer[TXB]=1,I2CER[RXB]=1
    jf read i2cer; read again
    nop
                   ; due to restriction 6.4.4.a.3
    move.w(r1),d3
                   ; Read the BD status of the RxBD ( r1 contain RX BD ptr )
    cmpeq.w #$3800,d3
    jf read i2cer
                   ; due to restriction 6.4.4.a.3
    nop
; write to debug area at IMMR + Debug Pointer
wdebug
    move.1 #DEBUGPTR,d3
```

Bootloader Program

```
add
          d9,d3,d3;d3 <- ptr to debug area
     nop
     move.1 d3,r1;r1 receive d13
                     ; due to restriction
     move.1 (r1),d3
                     ;d3 receive available address on debug area
     move.1 d3,r0;r0 receive available address on debug area
     ; Check with end of debug area
     move.1 r0,d6
     nop
     extractu #$f,#0,d6,d6 ;remove the extend bits and CS
     cmpeq.w #DEBUGEND,d6
         wdebugend; if end of debug area jmp to end of debug
     nop
     ;;;;;;;;;;
     move.w #0,d6
     move.b d6,(r0)+;write 0 and increment d3
     nop
     move.1 r0, (r1)
wdebugend nop
return_rts
                      ;return from sub routine
; End of read_bd Function
dead_i2cer
     move.1 #$deadead,d0
reset
     move.1 #$0,r1
     ; Reset port B SCL=PB18,SDA=PB19
     move.1 r1, (r6+PODRB)
     move.1 r1, (r6+PSORB)
     move.1 r1, (r6+PPARB)
     move.1 r1, (r6+PDIRB)
     debug
colision
colision2
```

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

```
; write to debug area at IMMR + Debug Pointer
move.1 #DEBUGPTR, d3
          d9,d3,d3;d3 <- ptr to debug area
     add
     nop
     move.1 d3,r1;r1 receive d13
     nop
                      ; due to restriction
     move.1 (r1),d3
                      ;d3 receive available address on debug area
     move.1 d3,r0;r0 receive available address on debug area
     ; Check with end of debug area
     move.1 r0,d6
     nop
     extractu #$f,#0,d6,d6 ;remove the extend bits and CS
     nop
     cmpeq.w #DEBUGEND,d6
     jt
         wdebugend2
     nop
     ;;;;;;;;;;;
     move.w #1,d6
     move.b d6,(r0)+;write 0 and increment d3
     nop
     move.1 r0, (r1)
wdebugend2
restart
; Close RX BD Command routine + wait
move.1 #$29610007,r1
     move.1 r1, (r6+CPCR); Close BD command - Page = 01010, code=01011
     ; ***wait for command flag to be clear
wait move.l (r6+CPCR),d1
     bmtsts #$0001,d1.h; Test with CS bit is setted
     jt
          wait
                      ; if flag is still setted goback to wait
     nop
                      ; due to restriction 6.4.4.a.3
;Initiate Parameter RAM
     move.1 #RTBASEVAL,r1; RBASE=3e50, TBASE=3e40
                      ; due to restriction 6.4.4.a.2
     move.1 r1, (r7+RBASE);$00
     move.1 #$1212ff00,r1; RFCR=12(use local BUS), TFCR=12, MRLBR=ff00
                      ; due to restriction 6.4.4.a.2
     nop
```

Bootloader Program

```
move.1 r1, (r7+RFCR); $04
     move.1 #$0000000,r1;RSTATE
                     ; due to restriction 6.4.4.a.2
     move.1 r1, (r7+RSTATE); $08
     move.1 r1, (r7+RPTR); $0c
     move.1 r1, (r7+RBPTR);$10
     move.1 r1, (r7+RTEMP);$14
     move.1 r1, (r7+TSTATE);$18
     move.1 r1, (r7+TPTR);$1c
     move.1 r1, (r7+TBPTR); $20
     move.1 r1, (r7+TTEMP);$24
; Init Page Command routine + wait
move.1 #$29610000,r1
     nop
     move.1 r1, (r6+CPCR); Init command - Page = 01010, code=01011
     ; ***wait for command flag to be clear
wait2 move.1 (r6+CPCR),d1
     nop
     bmtsts #$0001,d1.h; Test with CS bit is setted
     jt
          wait2
                     ; if flag is still setted goback to wait
                     ; due to restriction 6.4.4.a.3
     nop
jmp retry
     nop
nAK
     move.1 #$a1caaaa,d0
     debug
BSYError
     move.1 #$bbbbbbbb,d0
     debug
end_
    nop
          r3
     qmj
                     ;jmp to Boot start Address
     endsec
```

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

Bootloader Program

Functional Differences Between MSC8101 (Mask 2K42A) and MSC8103 (Mask 2K87M), Rev. 2

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