

Figure 2. Functional Block Diagram.

## Pin Functional Description

### DRAIN Pin:

Output MOSFET drain connection. Provides internal bias current during start-up operation via an internal switched high-voltage current source. Internal current sense point.

### CONTROL Pin:

Error amplifier and feedback current input pin for duty cycle control. Internal shunt regulator connection to provide internal bias current during normal operation. Trigger input for latching shutdown. It is also used as the supply bypass and auto-restart/compensation capacitor connection point.

### SOURCE Pin:

Output MOSFET source connection. Primary-side circuit common, power return, and reference point.

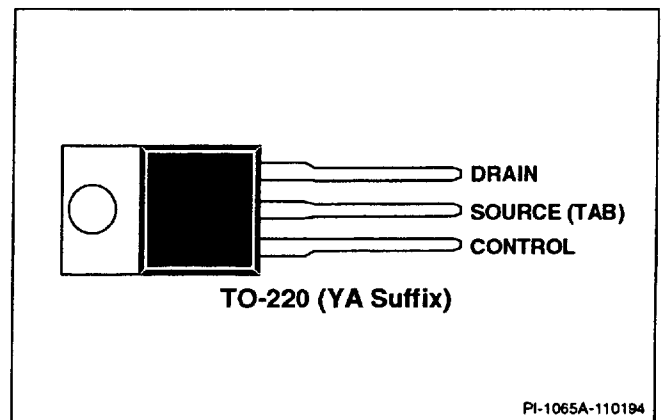


Figure 3. Pin Configuration.

# TOPSwitch Family Functional Description

TOPSwitch is a self biased and protected linear control current-to-duty cycle converter with an open drain output. High efficiency is achieved through the use of CMOS and integration of the maximum number of functions possible. CMOS significantly reduces bias currents as compared to bipolar or discrete solutions. Integration eliminates external power resistors used for current sensing and/or supplying initial start-up bias current.

During normal operation, the internal output MOSFET duty cycle linearly decreases with increasing CONTROL pin current as shown in Figure 4. To implement all the required control, bias, and protection functions, the DRAIN and CONTROL pins each perform several functions as described below. Refer to Figure 2 for a block diagram and Figure 6 for timing and voltage waveforms of the TOPSwitch integrated circuit.

### Control Voltage Supply

CONTROL pin voltage  $V_c$  is the supply or bias voltage for the controller and driver circuitry. An external bypass capacitor closely connected between the CONTROL and SOURCE pins is required to supply the gate drive current. The total amount of capacitance connected to this pin ( $C_T$ ) also sets the auto-restart timing as well as control loop compensation.  $V_c$  is regulated in either of two modes of operation. Hysteretic regulation is used for initial start-up and overload operation. Shunt regulation is used to separate the duty cycle error signal from the control circuit supply current. During start-up,  $V_c$  current is supplied from a high-voltage switched current source connected internally between the DRAIN and CONTROL pins. The current source provides sufficient current to supply the control circuitry as well as charge the total external capacitance ( $C_T$ ).

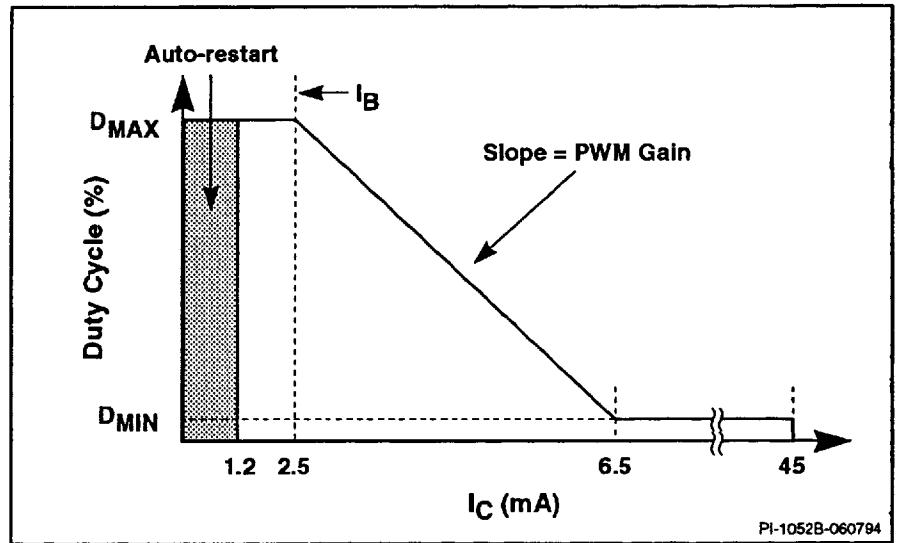


Figure 4. Relationship of Duty Cycle to CONTROL Pin Current.

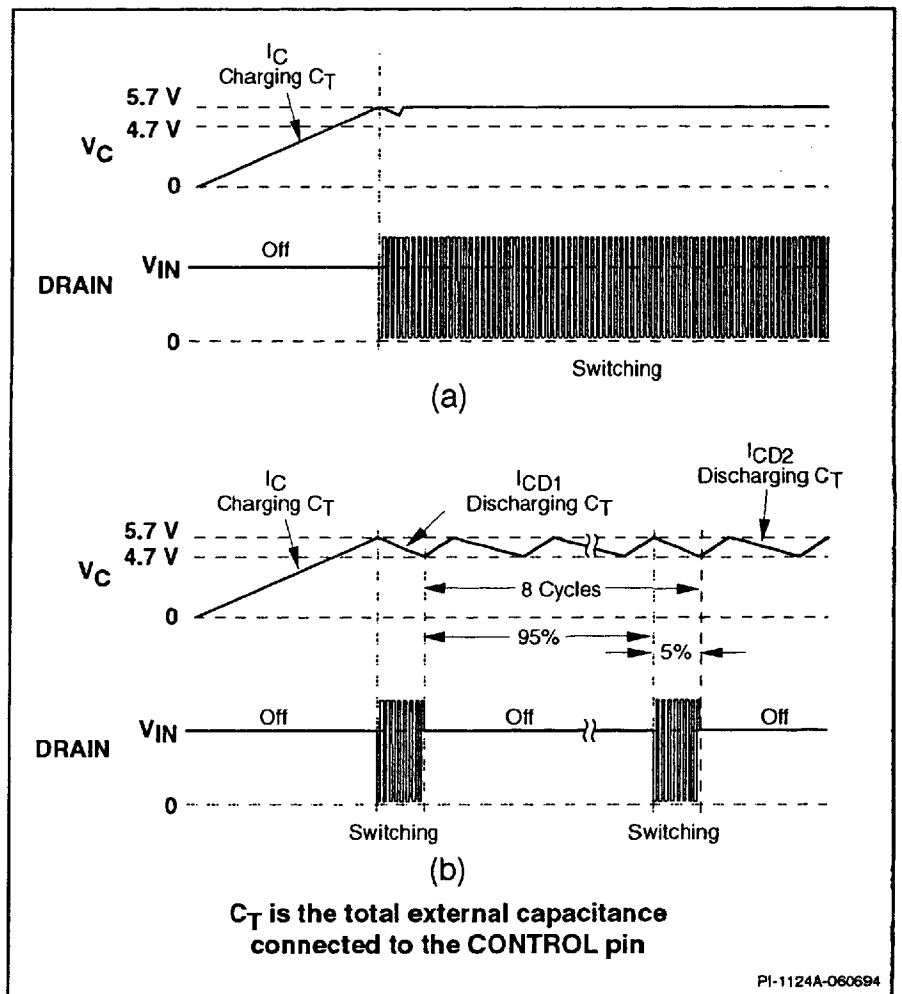


Figure 5. Start-up Waveforms for (a) Normal Operation and (b) Auto-restart.



## TOPSwitch Family Functional Description (cont.)

The first time  $V_c$  reaches the upper threshold, the high-voltage current source is turned off and the PWM modulator and output transistor are activated, as shown in Figure 5(a). During normal operation (when the output voltage is regulated) feedback control current supplies the  $V_c$  supply current. The shunt regulator keeps  $V_c$  at typically 5.7 V by shunting CONTROL pin feedback current exceeding the required DC supply current through the PWM error signal sense resistor  $R_E$ . The low dynamic impedance of this pin ( $Z_c$ ) sets the gain of the error amplifier when used in a primary feedback configuration. The dynamic impedance of the CONTROL pin together with the external resistance and capacitance determines the control loop compensation of the power system.

If the CONTROL pin external capacitance ( $C_c$ ) should discharge to the lower threshold, then the output MOSFET is turned off and the control circuit is placed in a low-current standby mode. The high-voltage current source is turned on and charges the external capacitance again. Charging current is shown with a negative polarity and discharging current is shown with a positive polarity in Figure 6. The hysteretic auto-restart comparator keeps  $V_c$  within a window of typically 4.7 to 5.7 V by turning the high-voltage current source on and off as shown in Figure 5(b). The auto-restart circuit has a divide-by-8 counter which prevents the output MOSFET from turning on again until eight discharge-charge cycles have elapsed. The counter effectively limits TOPSwitch power dissipation by reducing the auto-restart duty cycle to typically 5%. Auto-restart continues to cycle until output voltage regulation is again achieved.

### Bandgap Reference

All critical TOPSwitch internal voltages are derived from a temperature-compensated bandgap reference. This reference is also used to generate a temperature-compensated current source which is trimmed to accurately set the oscillator frequency and MOSFET gate drive current.

### Oscillator

The internal oscillator linearly charges and discharges the internal capacitance between two voltage levels to create a sawtooth waveform for the pulse width modulator. The oscillator sets the pulse width modulator/current limit latch at the beginning of each cycle. The nominal frequency of 100 kHz was chosen to minimize EMI and maximize efficiency in power supply applications. Trimming of the current reference improves oscillator frequency accuracy.

### Pulse Width Modulator

The pulse width modulator implements a voltage-mode control loop by driving the output MOSFET with a duty cycle inversely proportional to the current flowing into the CONTROL pin. The error signal across  $R_E$  is filtered by an RC network with a typical corner frequency of 7 kHz to reduce the effect of switching noise. The filtered error signal is compared with the internal oscillator sawtooth waveform to generate the duty cycle waveform. As the control current increases, the duty cycle decreases. A clock signal from the oscillator sets a latch which turns on the output MOSFET. The pulse width modulator resets the latch, turning off the output MOSFET. The maximum duty cycle is set by the symmetry of the internal oscillator. The modulator has a minimum ON-time to keep the current consumption of the TOPSwitch independent of the error signal. Note that a minimum current must be driven into the CONTROL pin before the duty cycle begins to change.

### Gate Driver

The gate driver is designed to turn the output MOSFET on at a controlled rate to minimize common-mode EMI. The gate drive current is trimmed for improved accuracy.

### Error Amplifier

The shunt regulator can also perform the function of an error amplifier in primary feedback applications. The shunt regulator voltage is accurately derived from the temperature compensated bandgap reference. The gain of the error amplifier is set by the CONTROL pin dynamic impedance. The CONTROL pin clamps external circuit signals to the  $V_c$  voltage level. The CONTROL pin current in excess of the supply current is separated by the shunt regulator and flows through  $R_E$  as the error signal.

### Cycle-By-Cycle Current Limit

The cycle by cycle peak drain current limit circuit uses the output MOSFET ON-resistance as a sense resistor. A current limit comparator compares the output MOSFET ON-state drain-source voltage,  $V_{DS(ON)}$ , with a threshold voltage. High drain current causes  $V_{DS(ON)}$  to exceed the threshold voltage and turns the output MOSFET off until the start of the next clock cycle. The current limit comparator threshold voltage is temperature compensated to minimize variation of the effective peak current limit due to temperature related changes in output MOSFET  $R_{DS(ON)}$ .

The leading edge blanking circuit inhibits the current limit comparator for a short time after the output MOSFET is turned on. The leading edge blanking time has been set so that current spikes caused by primary-side capacitances and secondary-side rectifier reverse recovery time will not cause premature termination of the switching pulse.

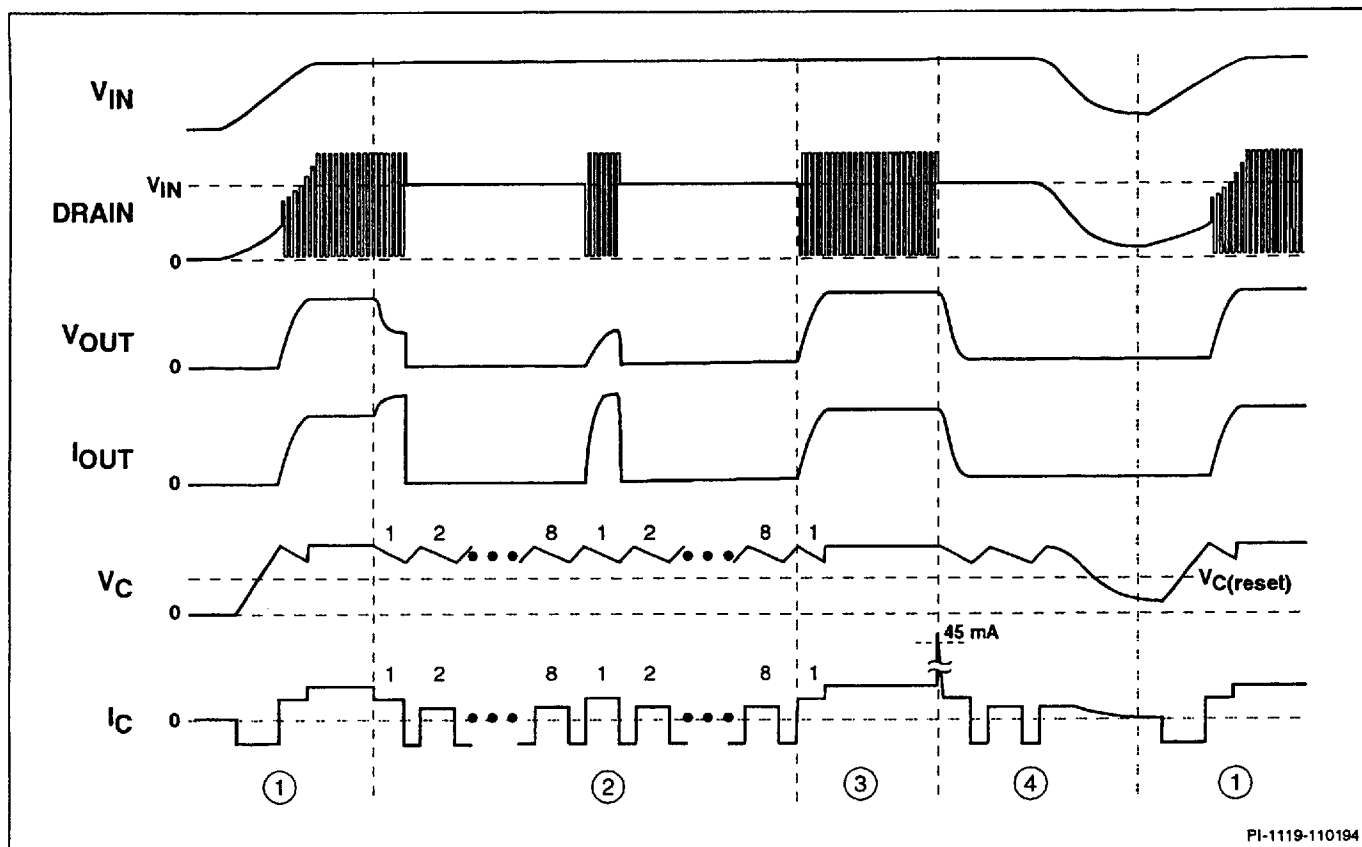


Figure 6. Typical Waveforms for (1) Normal Operation, (2) Auto-restart, (3) Latching Shutdown, and (4) Power Down Reset.

#### Shutdown/Auto-restart

To minimize TOPSwitch power dissipation, the shutdown/auto-restart circuit turns the power supply on and off at a duty cycle of typically 5% if an out of regulation condition persists. Loss of regulation interrupts the external current into the CONTROL pin.  $V_C$  regulation changes from shunt mode to the hysteretic auto-restart mode described above. When the fault condition is removed, the power supply output becomes regulated,  $V_C$  regulation returns to shunt mode, and normal operation of the power supply resumes.

#### Latching Shutdown

The output overvoltage protection latch is activated by a high-current pulse into the CONTROL pin. When set, the latch turns off the TOPSwitch output. Activating the power-up reset circuit by

removing and restoring input power, or momentarily pulling the CONTROL pin below the power-up reset threshold resets the latch and allows TOPSwitch to resume normal power supply operation.  $V_C$  is regulated in hysteretic mode when the power supply is latched off.

#### Overtemperature Protection

Temperature protection is provided by a precision analog circuit that turns the output MOSFET off when the junction temperature exceeds the thermal shutdown temperature (typically 145°C). Activating the power-up reset circuit by removing and restoring input power or momentarily pulling the CONTROL pin below the power-up reset threshold resets the latch and allows TOPSwitch to resume normal power supply operation.  $V_C$  is regulated in hysteretic mode when the power supply is latched off.

#### High-voltage Bias Current Source

This current source biases TOPSwitch from the DRAIN pin and charges the CONTROL pin external capacitance ( $C_C$ ) during start-up or hysteretic operation. Hysteretic operation occurs during auto-restart and latched shutdown. The current source is switched on and off with an effective duty cycle of approximately 35%. This duty cycle is determined by the ratio of CONTROL pin charge ( $I_C$ ) and discharge currents ( $I_{CD1}$  and  $I_{CD2}$ ). This current source is turned off during normal operation when the output MOSFET is switching.



## General Circuit Operation

### Primary Feedback Regulation

The circuit shown in Figure 7 is a simple 5 V, 5 W bias supply using the PWR-TOP200. This universal input flyback power supply employs primary-side regulation from a transformer bias winding. This approach is best for low-cost applications requiring isolation and operation within a narrow range of load variation. Line and load regulation of  $\pm 5\%$  or better can be achieved from 10% to 100% of rated load.

Voltage feedback is obtained from the transformer (T1) bias winding, which eliminates the need for optocoupler and secondary-referenced error amplifier. High-voltage DC is applied to the primary winding of T1. The other side of the transformer primary is driven by

the integrated high-voltage MOSFET transistor within the PWR-TOP200 (U1). The circuit operates at a switching frequency of 100 kHz, set by the internal oscillator of the PWR-TOP200. The clamp circuit implemented by VR1 and D1 limits the leading-edge voltage spike caused by transformer leakage inductance to a safe value. The 5 V power secondary winding is rectified and filtered by D3, C2, C3, and L1 to create the 5 V output voltage.

The output of the T1 bias winding is rectified and filtered by D2, R1, and C5. The voltage across C5 is regulated by U1, and is determined by the 5.7 V internal shunt regulator at the CONTROL pin of U1. When the rectified bias voltage on C5 begins to

exceed the shunt regulator voltage, current will flow into the control pin. Increasing control pin current decreases the duty cycle until a stable operating point is reached. The output voltage is proportional to the bias voltage by the turns ratio of the output to bias windings. C5 is used to bypass the CONTROL pin. C5 also provides loop compensation for the power supply by shunting AC currents around the CONTROL pin dynamic impedance, and also determines the auto-restart frequency during start-up and auto-restart conditions. See DA-8 for more information regarding the use of the PWR-TOP200 in bias supplies.

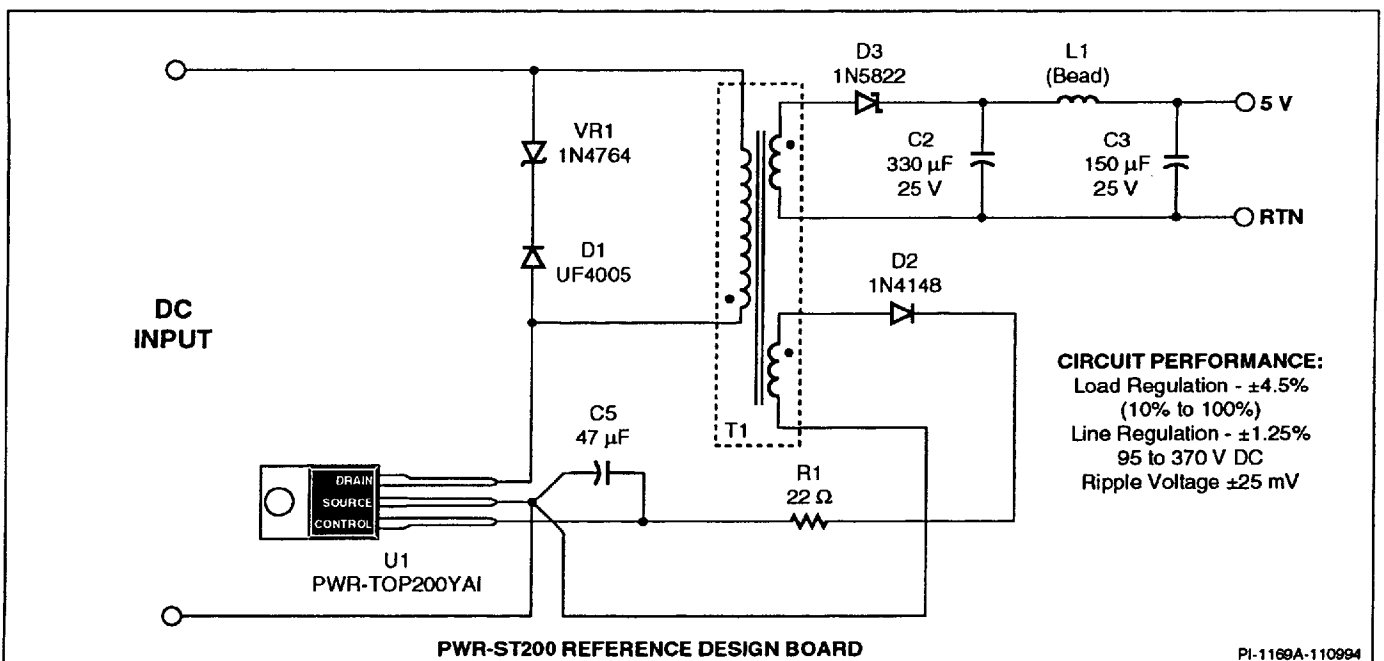


Figure 7. Schematic Diagram of a Minimum Parts Count 5 V, 5 W Bias Supply Utilizing the PWR-TOP200.



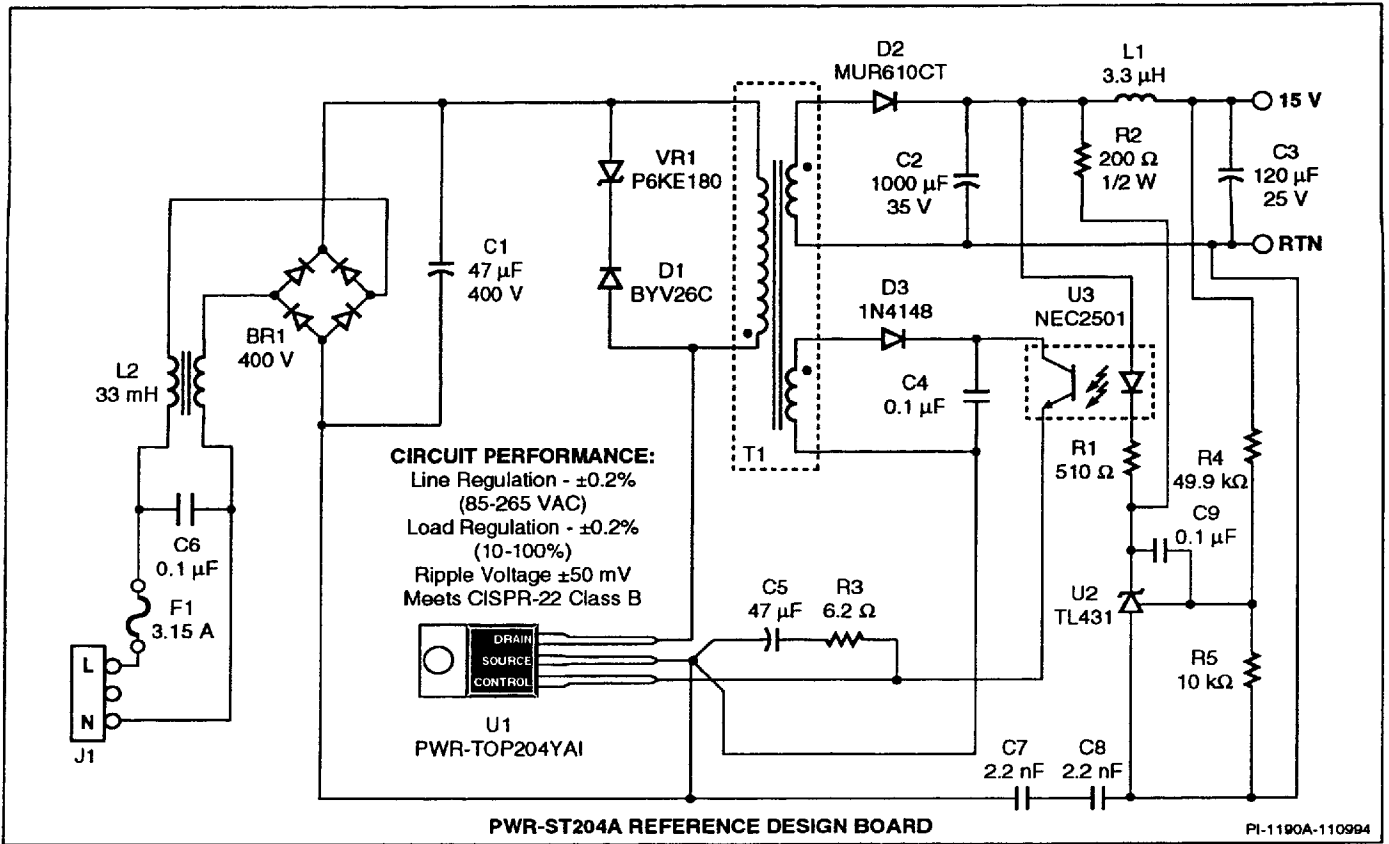


Figure 9. Schematic Diagram of a 30 W Universal Input Power Supply Utilizing the PWR-TOP204 and Accurate Optocoupler Feedback.

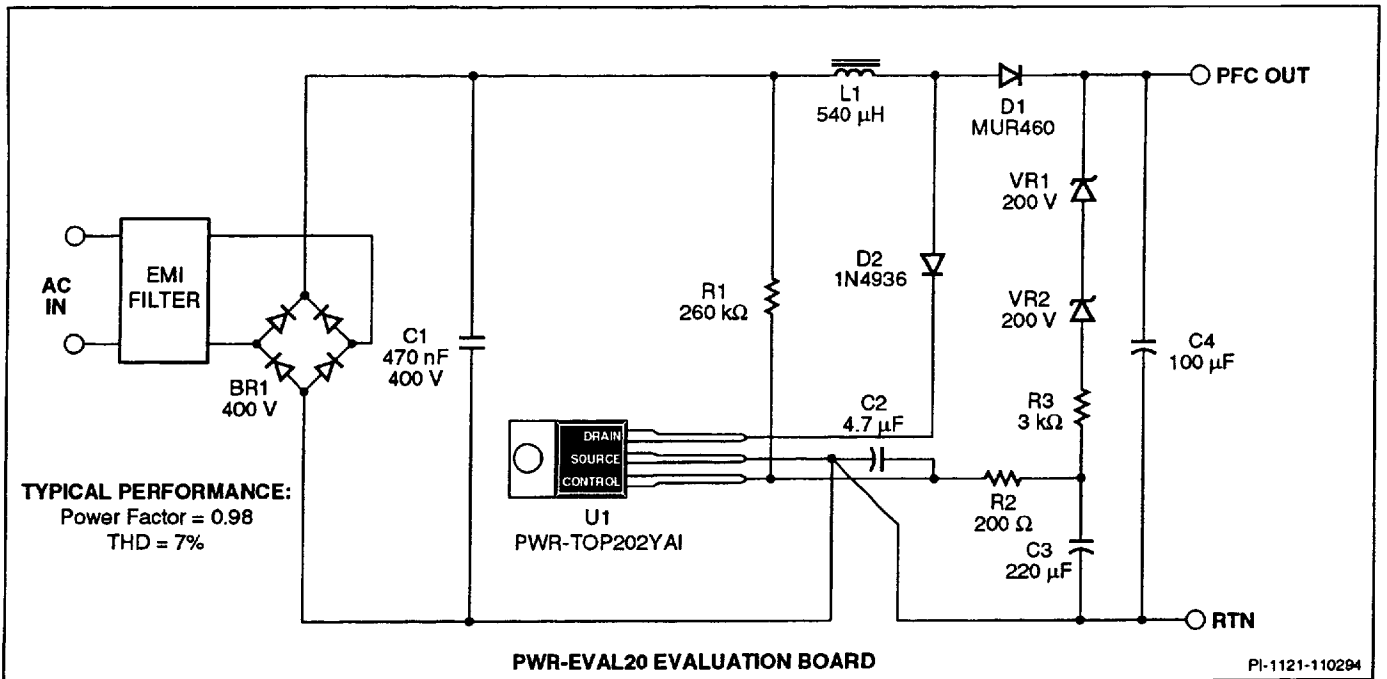


Figure 10. Schematic Diagram of a 70 W 230 VAC Input Boost Power Factor Correction Circuit Utilizing the PWR-TOP202.





## General Circuit Operation (cont.)

### Boost PFC Pre-regulator

TOPSwitch can also be used as a fixed frequency, discontinuous mode boost pre-regulator to improve Power Factor and reduce Total Harmonic Distortion (THD) for applications such as power supplies and electronic ballasts. The circuit shown in Figure 10 operates from 230 VAC and delivers 70 W at 430 VDC with typical Power Factor over 0.98 and THD of 7%. Bridge Rectifier BR1 full wave rectifies the AC input voltage. L1, D1, C4, and TOPSwitch make up the boost power stage. D2 prevents reverse current through the TOPSwitch body diode due to ringing voltages generated

by the boost inductance and parasitic capacitance. R1 generates a pre-compensation current proportional to the instantaneous rectified AC input voltage which directly varies the duty cycle. C2 filters high frequency switching currents while having no filtering effect on the line frequency pre-compensation current. R2 decouples the pre-compensation current from the large filter capacitor C3 to prevent an averaging effect which would increase total harmonic distortion. C1 filters high frequency noise currents which could cause errors in the pre-compensation current.

When power is first applied, C3 charges to typically 5.7 volts before TOPSwitch starts. C3 then provides TOPSwitch bias current until the output voltage becomes regulated. When the output voltage becomes regulated, series connected zener diodes VR1 and VR2 begin to conduct, drive current into the TOPSwitch control pin, and directly control the duty cycle. C3 together with R3 perform low pass filtering on the feedback signal to prevent output line frequency ripple voltage from varying the duty cycle. For more information, refer to design aid DA-7, "Using the TOPSwitch Family in PFC Circuits".

## Key Application Issues

Keep the SOURCE pin length very short. Use a Kelvin connection to the SOURCE pin for the CONTROL pin bypass capacitor. Use single point grounding techniques at the SOURCE pin as shown in Figure 11.

Minimize peak voltage and ringing on the DRAIN voltage at turn-off. Use a Zener or TVS Zener diode to clamp the DRAIN voltage.

Do not plug the TOPSwitch device into a "hot" IC socket during test. External CONTROL pin capacitance may deliver a surge current sufficient to trigger the shutdown latch which turns the TOPSwitch off.

Under some conditions, externally provided bias or supply current driven into the CONTROL pin can hold the TOPSwitch in one of the 8 auto-restart cycles indefinitely and prevent starting. Shorting the CONTROL pin to the SOURCE pin will reset the TOPSwitch. To avoid this problem when doing bench evaluations, it is recommended that the  $V_c$  power supply be turned on before the DRAIN voltage is applied.

CONTROL pin currents during auto-restart operation are much lower at low input voltages (< 20 V) which increases the auto-restart cycle period (see the  $I_c$  vs. Drain Voltage Characteristic curve).

Short interruptions of AC power may cause TOPSwitch to enter the 8-count auto-restart cycle before starting again. This is because the input energy storage capacitors are not completely discharged and the CONTROL pin capacitance has not discharged below the pin internal power-up reset voltage.

In some cases, minimum loading may be necessary to keep a lightly loaded or unloaded output voltage within the desired range due to the minimum ON-time.

For additional applications information regarding the TOPSwitch family, refer to AN-14.

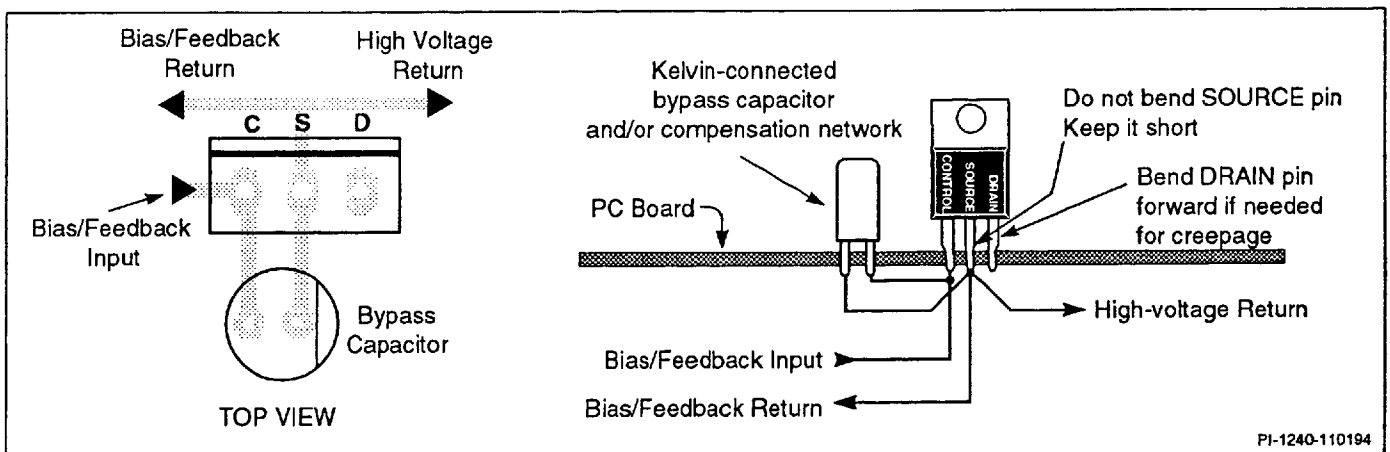


Figure 11. Recommended TOPSwitch Layout.



**ABSOLUTE MAXIMUM RATINGS<sup>(1)</sup>**

DRAIN Voltage .....	-0.3 to 700 V	Thermal Impedance ( $\theta_{JA}$ ) .....	70°C/W
CONTROL Voltage .....	- 0.3 V to 9 V	Thermal Impedance ( $\theta_{JC}$ ) <sup>(4)</sup> .....	2 °C/W
Storage Temperature .....	-65 to 125°C		
Operating Junction Temperature <sup>(2)</sup> .....	-40 to 150°C		
Lead Temperature <sup>(3)</sup> .....	260°C		

1. Unless noted, all voltages referenced to SOURCE,  $T_A = 25^\circ\text{C}$ .
2. Normally limited by internal circuitry.
3. 1/16" from case for 5 seconds.
4. Measured at tab closest to plastic interface.

Specification	Symbol	Test Conditions, Unless Otherwise Specified: See Figure 14 SOURCE = 0 V $T_j = -40$ to $125^\circ\text{C}$		Test Limits			Units
				MIN	TYP	MAX	
<b>CONTROL FUNCTIONS</b>							
Output Frequency	$f_{\text{OSC}}$	$I_c = 4$ mA, $T_j = 25^\circ\text{C}$		90	100	110	kHz
Maximum Duty Cycle	$DC_{\text{MAX}}$	$I_c = 2$ mA, See Figure 12		64	67	70	%
Minimum Duty Cycle	$DC_{\text{MIN}}$	$I_c = 10$ mA, See Figure 12	PWR-TOP200/1/2	1.0	1.8	3.0	%
			PWR-TOP203/4/14	1.0	2.0	3.5	
PWM Gain		$I_c = 4$ mA, $T_j = 25^\circ\text{C}$ See Figure 4		-11	-16	-21	%/mA
PWM Gain Temperature Drift		See Note 1			-0.05		%/mA/°C
External Bias Current	$I_B$	See Figure 4		1.5	2.5	4	mA
Dynamic Impedance	$Z_c$	$I_c = 4$ mA, $T_j = 25^\circ\text{C}$ See Figure 13		10	15	22	$\Omega$
Dynamic Impedance Temperature Drift	$\Delta Z_c$				0.18		%/°C
<b>SHUTDOWN/AUTO-RESTART</b>							
CONTROL Pin Charging Current	$I_c$	$T_j = 25^\circ\text{C}$	$V_c = 0$ V	-2.4	-1.9	-1.2	mA
			$V_c = 5$ V	-2	-1.5	-0.8	
Charging Current Temperature Drift	$\Delta I_c$	See Note 1			0.4		%/°C
Auto-restart Threshold Voltage		S1 open			5.7		V



Specification	Symbol	Test Conditions, Unless Otherwise Specified: See Figure 14 SOURCE = 0 V $T_j = -40$ to $125^\circ\text{C}$	Test Limits			Units
			MIN	TYP	MAX	
<b>SHUTDOWN/AUTO-RESTART (cont.)</b>						
UV Lockout Threshold Voltage		S1 open		4.7		V
Auto-restart Hysteresis Voltage		S1 open		1.0		V
Auto-restart Duty Cycle		S1 open		5	8	%
Auto-restart Frequency		S1 open		1.2		Hz
<b>CIRCUIT PROTECTION</b>						
Self-protection Current Limit	$I_{\text{LIMIT}}$	PWR-TOP200 $di/dt = 80 \text{ mA}/\mu\text{s}, T_j = 25^\circ\text{C}$	0.415		0.585	A
		PWR-TOP201 $di/dt = 170 \text{ mA}/\mu\text{s}, T_j = 25^\circ\text{C}$	0.830		1.17	
		PWR-TOP202 $di/dt = 250 \text{ mA}/\mu\text{s}, T_j = 25^\circ\text{C}$	1.25		1.75	
		PWR-TOP203 $di/dt = 330 \text{ mA}/\mu\text{s}, T_j = 25^\circ\text{C}$	1.50		2.10	
		PWR-TOP214 $di/dt = 420 \text{ mA}/\mu\text{s}, T_j = 25^\circ\text{C}$	1.88		2.63	
		PWR-TOP204 $di/dt = 500 \text{ mA}/\mu\text{s}, T_j = 25^\circ\text{C}$	2.25		3.15	
Leading Edge Blanking Delay		$I_c = 4 \text{ mA}$		150		ns
Current Limit Delay		$I_c = 4 \text{ mA}$		100		ns
Thermal Shutdown Temperature		$I_c = 4 \text{ mA}$	125	145		$^\circ\text{C}$
Latched Shutdown Trigger Current	$I_{\text{SD}}$	See Figure 13	25	45	75	mA
Power-up Reset Threshold Voltage	$V_{\text{C(reset)}}$	S2 open	2.3	3.3	4.2	V



Specification	Symbol	Test Conditions, Unless Otherwise Specified: See Figure 14 SOURCE = 0 V $T_j = -40$ to $125^\circ\text{C}$		Test Limits			Units			
				MIN	TYP	MAX				
<b>OUTPUT</b>										
ON-State Resistance	$R_{\text{DS(ON)}}$	PWR-TOP200 $I_D = 50$ mA	$T_j = 25^\circ\text{C}$		15.6	18.0	$\Omega$			
			$T_j = 100^\circ\text{C}$		25.7	29.7				
		PWR-TOP201 $I_D = 100$ mA	$T_j = 25^\circ\text{C}$		7.8	9.0				
			$T_j = 100^\circ\text{C}$		12.9	14.9				
		PWR-TOP202 $I_D = 150$ mA	$T_j = 25^\circ\text{C}$		5.2	6.0				
			$T_j = 100^\circ\text{C}$		8.6	9.9				
		PWR-TOP203 $I_D = 200$ mA	$T_j = 25^\circ\text{C}$		3.9	4.5				
			$T_j = 100^\circ\text{C}$		6.4	7.5				
		PWR-TOP214 $I_D = 250$ mA	$T_j = 25^\circ\text{C}$		3.1	3.6				
			$T_j = 100^\circ\text{C}$		5.2	6.0				
		PWR-TOP204 $I_D = 300$ mA	$T_j = 25^\circ\text{C}$		2.6	3.0				
			$T_j = 100^\circ\text{C}$		4.3	5.0				
		OFF-State Current	$I_{\text{DSS}}$	Device in Latched Shutdown $I_C = 4$ mA, $V_{\text{DS}} = 560$ V, $T_A = 125^\circ\text{C}$					900	$\mu\text{A}$
		Breakdown Voltage	$BV_{\text{DSS}}$	Device in Latched Shutdown $I_C = 4$ mA, $I_D = 500$ $\mu\text{A}$ , $T_A = 25^\circ\text{C}$		700				V
Rise Time	$t_r$	Measured With Figure 8 Schematic			100		ns			
Fall Time	$t_f$	Measured With Figure 8 Schematic			50		ns			
<b>SUPPLY</b>										
DRAIN Supply Voltage		See Note 2		36			V			
Shunt Regulator Voltage		$I_C = 4$ mA		5.5	5.8	6.1	V			
Shunt Regulator Temperature Drift					$\pm 50$		ppm/ $^\circ\text{C}$			
CONTROL Supply/ Discharge Current	$I_{\text{CD1}}$	Output	PWR-TOP200/1/2	0.6	1.2	1.6	mA			
		MOSFET enabled	PWR-TOP203/4/14	0.7	1.4	1.8				
	$I_{\text{CD2}}$	Output MOSFET Disabled		0.5	0.8	1.1				



**NOTES:**

1. For specifications with negative values, a negative temperature coefficient corresponds to an increase in magnitude with increasing temperature, and a positive temperature coefficient corresponds to a decrease in magnitude with increasing temperature.
2. It is possible to start up and operate TOPSwitch at DRAIN voltages well below 36 V. However, the CONTROL pin charging current is reduced, which affects start-up time and auto-restart frequency and duty cycle. Refer to the characteristic graph on CONTROL pin charge current ( $I_C$ ) vs. DRAIN voltage for low voltage operation characteristics.

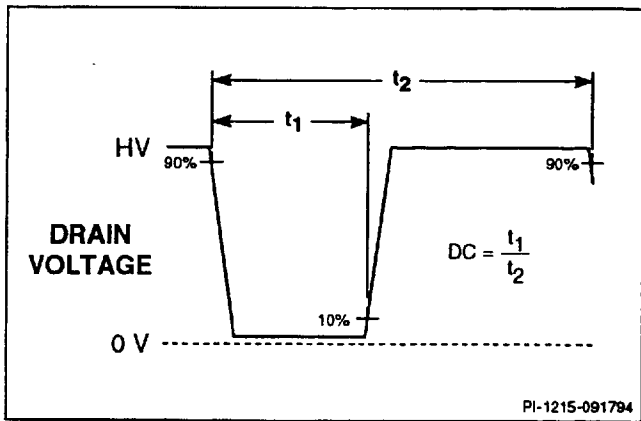


Figure 12. TOPSwitch Duty Cycle Measurement.

**CONTROL PIN I-V CHARACTERISTIC**

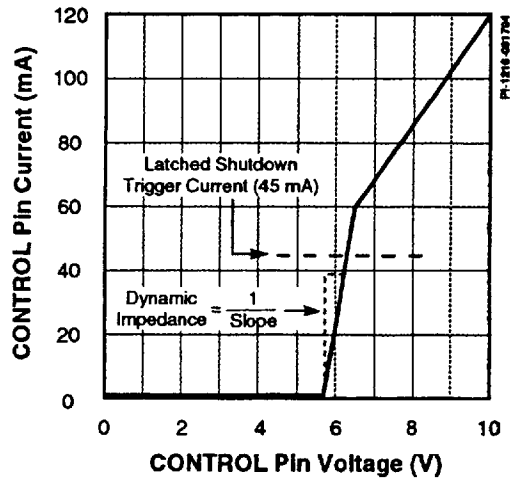
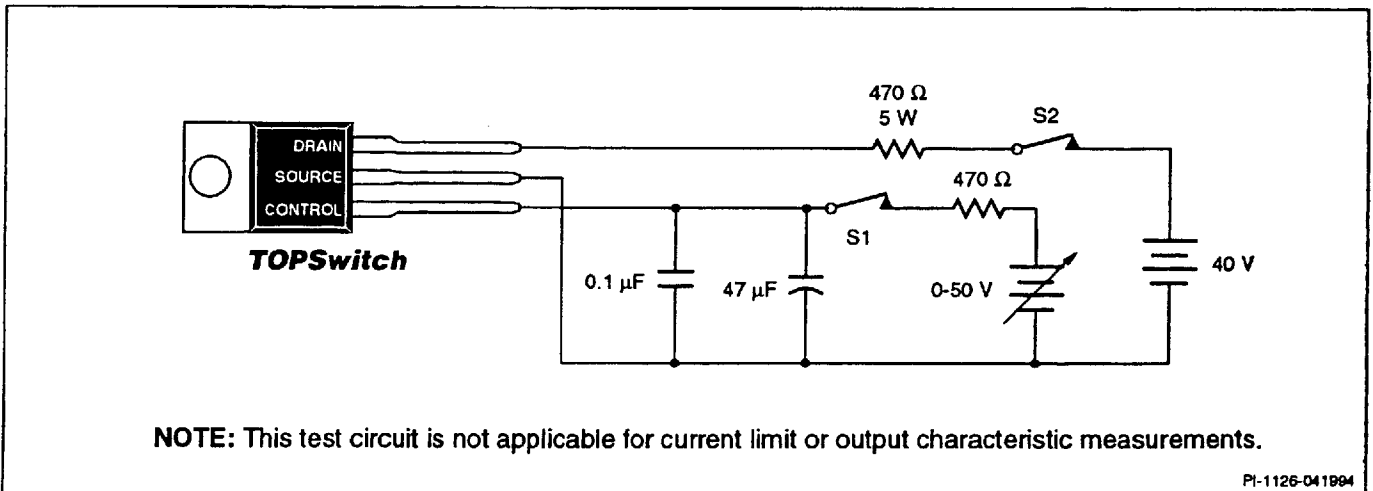


Figure 13. TOPSwitch CONTROL Pin I-V Characteristic.



**NOTE:** This test circuit is not applicable for current limit or output characteristic measurements.

PI-1126-041894

Figure 14. TOPSwitch General Test Circuit.



**BENCH TEST PRECAUTIONS FOR EVALUATION OF ELECTRICAL CHARACTERISTICS**

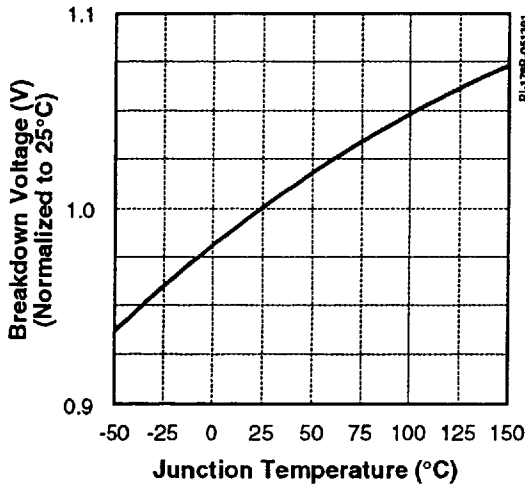
The following precautions should be followed when testing TOPSwitch by itself outside of a power supply. The schematic shown in Figure 14 is suggested for laboratory testing of TOPSwitch.

When the DRAIN supply is turned on, the part will be in the auto-restart mode.

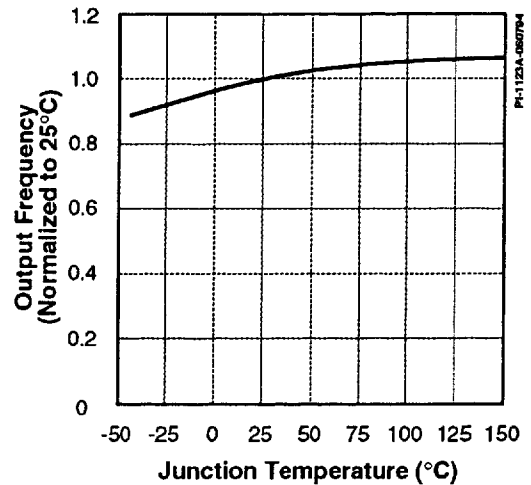
The control pin voltage will be oscillating at a low frequency from 4.7 to 5.7 V and the DRAIN is turned on every eighth cycle of the CONTROL pin oscillation. If the CONTROL pin power supply is turned on while in this auto-restart mode, there is only a 12.5% chance that the control pin oscillation will be in the correct state (DRAIN active state) so

that the continuous DRAIN voltage waveform may be observed. It is recommended that the  $V_C$  power supply be turned on first and the DRAIN power supply second if continuous drain voltage waveforms are to be observed. The 12.5% chance of being in the correct state is due to the 8:1 counter.

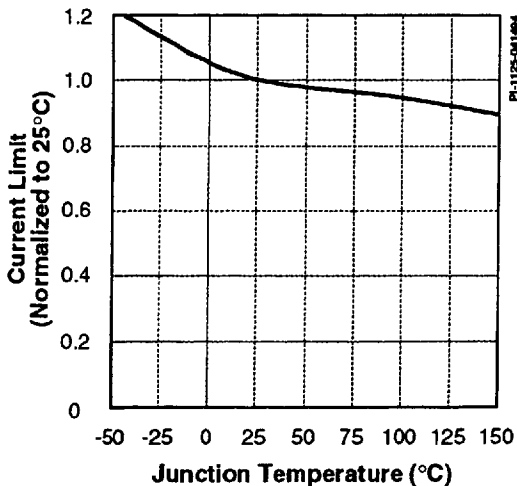
**BREAKDOWN vs. TEMPERATURE**



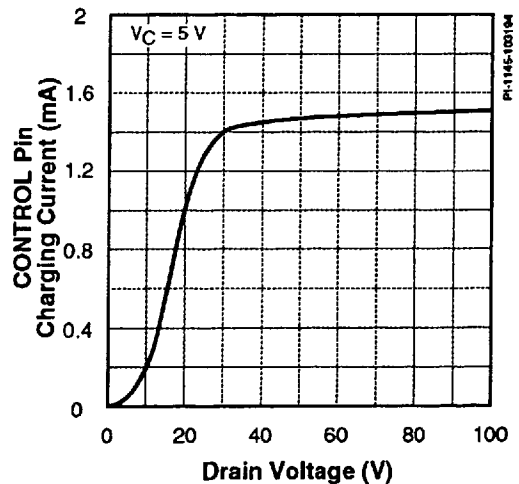
**FREQUENCY vs. TEMPERATURE**



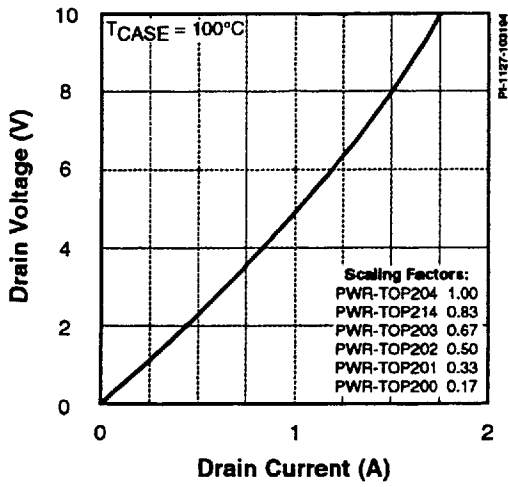
**CURRENT LIMIT vs. TEMPERATURE**



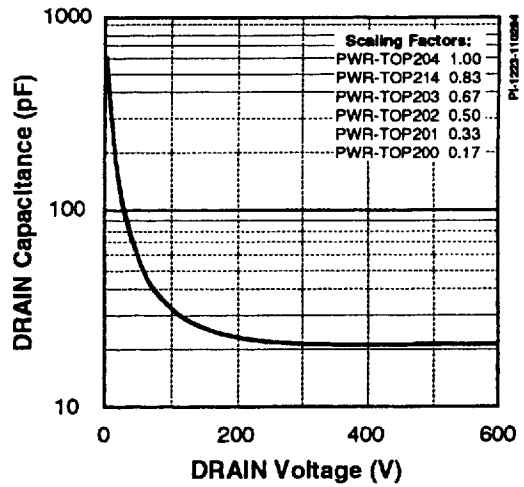
**$I_C$  vs. DRAIN VOLTAGE**



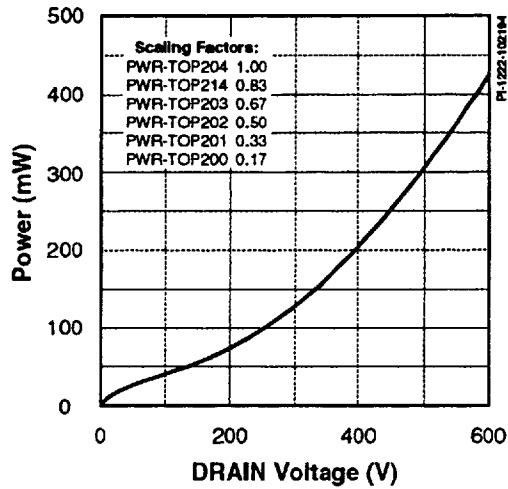
**OUTPUT CHARACTERISTICS**



**COSS vs. DRAIN VOLTAGE**

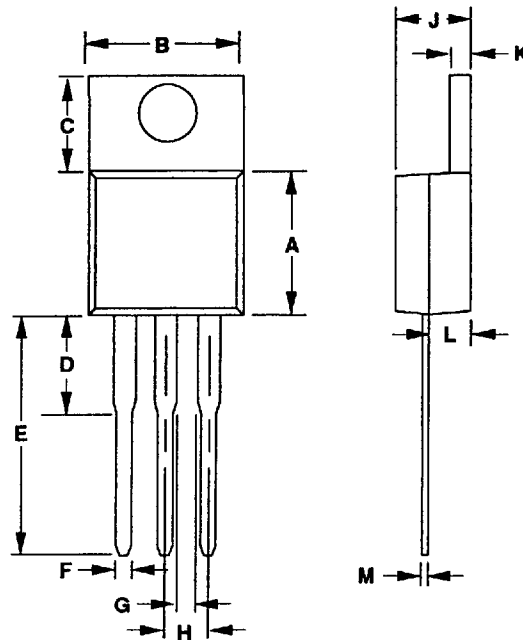


**DRAIN CAPACITANCE POWER**



TO-220  
YA Suffix

DIM	Inches	mm
A	.313-.380	7.95-9.65
B	.380-.415	9.65-10.54
C	.236-.260	5.99-6.60
D	.220-.240	5.59-6.10
E	.500-.562	12.70-14.27
F	.025-.038	.06-.09
G	.045-.055	1.14-1.40
H	.092-.108	2.34-2.74
J	.160-.190	4.06-4.83
K	.045-.055	1.14-1.40
L	.080-.115	2.03-2.92
M	.013-.020	.33-.51



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