

MX98902A

FEATURES

- Compatible with IEEE 802.3 CSMA/CD standard Ethernet, Cheapernet, and Twisted-Pair (10 BASET)
- Two 16-bit DMA channels
- 16-byte internal FIFO with programmable threshold
- ETHERNET NETWORK CONTROLLER FOR TWISTED-PAIR
 - Network statistics storage
 - 3 levels of loopback
 - Independent system and network clocks
 - CMOS technology, 84-pin PLCC or 100-pin PQFP package
 - NS DP83902 compatible

GENERAL DESCRIPTION

The MX98902 is designed for easy implementation of CSMA/CD local area networks, which include Ethernet (10BASE5), Thin Ethernet (10BASE2), and Twisted-pair Ethernet (10BASE-T). The Media Access Control (MAC) and Encode-Decode (ENDEC) are provided with an AUI interface. The 10BASE-T transceiver functions according to the IEEE 802.3 standards, and the MX98902 10BASE-T transceiver operates in compliance with the IEEE standard.

The MX98902's functional block consists of the receiver, transmitter, collision, heartbeat, loopback, jabber, and link integrity blocks. When combined with equalization resistors, the transceiver transmits or receives filters, and pulse transformers provide physical interface from the MX98902's ENDEC module and the twisted-pair medium.

Manchester encoding and decoding is made possible through the integrated ENDEC module by means of a differential transceiver and phase lock loop decoder at 10 Mbit/sec. Collision detect translator and diagnostic loopback capability are included in this process. Interfacing directly with the transceiver module, the ENDEC module also provides a fully IEEE compliant AUI (Attachment Unit Interface) to connect with other media transceivers.

The Media Access Control function, provided by the Ethernet Network Control (ENC) module, effects an efficient packet transmission and reception control through unique dual DMA channels and an internal FIFO. To lessen board cost and area overheads, bus arbitration and memory control logic are integrated.

Designed for easy interface with other transceivers by means of the AUI interface, the MX98902 provides a thorough single chip solution for 10BASE-T IEEE 802.3

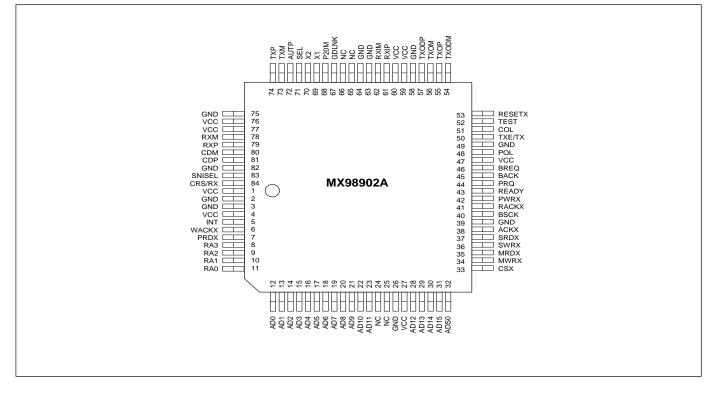
network.

Constraints of CMOS processing require that isolation, whether capacitive or inductive, be used at the AUI differential signal interface for 10BASE5 and 10BASE2 applications.

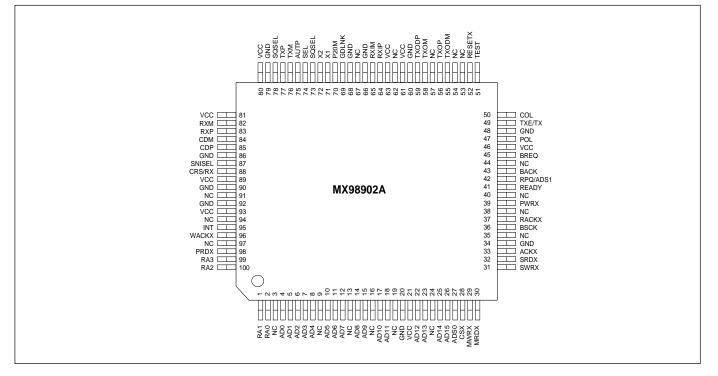


PIN CONFIGURATIONS

84-PIN PLCC

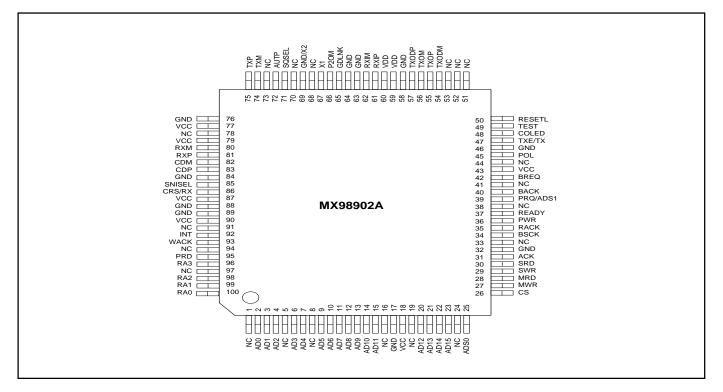


100-PIN PQFP





100-PIN SQFP







PIN DESCRIPTIONS

A. BUS INTERFACE PINS

SYMBOL	PIN TYPE		N NUME PLCC		DESCRIPTION
AD0-AD15	I/O, Z	4-8, 10-12 14,15 17,18 22,23 25,26	12-23 28-31	2-4 6-7 9-15 20-23	 MULTIPLEXED ADDRESS/DATA BUS: Registeaccess,wit DMA inactive, CSX low and ACKX returned fromMX98902, pins AD0-AD7 are used to read/write register data. AD8-AD15 float during I/O transfers. SRDX, SWRX pins an used to select direction of transfer. Bus Master with BACK input asserted. During T1 or memory cycle AD0-AD15 contain address. During T2, T3, T4 AD0-AD15 contain data (word transfer mode). During T2, T3, T4 AD0-AD7 contain data; AD8-AD15 contai address (bytetransfer mode). Direction of transfer is indicated by MX98902 on MWR2 MRDX lines.
ADS0	I/O, Z	27	32	25	ADDRESS STROBE 0: Input with DMA inactive and CS low, latches RA0-RA3 inputs on falling edge. If high, da present on RA0-RA3 will flow through latch. Output when Bus Master latches addresses bits (A0-A15) external memory during DMA transfers.
CSX	Ι	28	33	26	CHIP SELECT: Chip Select places controller in slave more for µp access to internal registers. Must be val through data portion of bus cycle. RA0-RA3 are used select the internal register. SWRX and SRDX select direct tion of data transfer.
MWRX	O, Z	29	34	27	MASTER WRITE STROBE : Strobe for DMA transfers, a tive low during write cycles (T2, T3, TW) to buffer memor Rising edge coincides with the presence of valid output dat TRI-STATE until BACK asserted.
MRDX	O,Z	30	35	28	MASTER READ STROBE : Strobe for DMA transfers, activity during read cycles (T2, T3, TW) to buffer memory. Inp data must be valid on rising edge of MRDX. TRI-STAT until BACK asserted.
SWRX	I	31	36	29	SLAVE WRITE STROBE : Strobe from CPU to write a internal register selected by RA0-RA3.
SRDX	Ι	32	37	30	SLAVE READ STROBE : Strobe from CPU to read an intend nal register selected by RA0-RA3.
АСКХ	0	33	38	31	ACKNOWLEDGE : Active low when MX98902 grants a cess to CPU. Used to insert WAIT states to CPU un MX98902 is synchronized for a register read or write oper tion.
RA0-RA3	Ι	99,100 1,2) 8-11	96 98-100	REGISTER ADDRESS : These four pins are used to select register to be read or written. The state of these inputs ignored when the MX98902 is not in slave mode (CSX high
PRDX	0	98	7	95	PORT READ : Enables data from external latch onto loc bus during a memory write cycle to local memory (remo write operation). This allows asynchronous transfer of da from the system memory to local memory.



PIN DESCRIPTIONS (Continued) A. BUS INTERFACE PINS

SYMBOL	PIN TYPE	PIN NUMBER PQFP PLCC SQFP			DESCRIPTION			
WACKX	I	96	6	93	WRITE ACKNOWLEDGE: Issued from system to ENC to ind cate data has been written to the external latch. The ENC w begin a write cycle to place the data in local memory.			
INT	0	95	5	92	INTERRUPT : Indicates that the MX98902 requires CPU attention after reception, transmission, or completion of DMA transfers. The interrupt is cleared by writing to the ISR. All interruptive are maskable.			
RESETX	I	52	53	50	RESET: Reset is active low and places the MX98902 in a res mode immediately; no packets are transmitted or received to the ENC until STA bit is set. Affects Command Register, Inter rupt Mask Register, Data Configuration Register and Transm Configuration Register. The MX98902 will execute reset with 10 BSCK cycles.			
BREQ	0	45	46	42	BUS REQUEST : Bus Request is an active high signal used request the bus for DMA transfers. This signal is automatical generated when the FIFO needs servicing.			
BACK	I	43	45	40	BUS ACKNOWLEDGE : Bus Acknowledge is an active hig signal that the CPU has granted the bus to MX98902. If immed ate bus access is desired, BREQ should be tied to BACI Tying BACK to VCC will result in a deadlock.			
PRQ, ADS1	O, Z	42	44	39	 PORT REQUEST/ADDRESS STROBE 1: 32-bit mode: If LA is set in the Data Configuration Register, this line is programmed as ADS1; it is used to strobe addresses A16-A31 into extern latches. (A16-A31 are the fixed addresses stored in RSAR RSAR1.) ADS1 will remain at TRI-STATE until BACK is received. 16-bit mode: If LAS is not set in the Data Configuration Register, this line is programmed as PRQ and is used for Remo DMA Transfers. In this mode PRQ will be a standard log output. Note: This line will power up as TRI-STATE until the Data Configuration Register is programmed. 			
READY	I	41	43	37	READY : This pin is set high to insert wait states until a DM transfer. The MX98902 will sample this signal at T3 during DM transfers.			
PWRX	0	39	42	36	PORT WRITE : Strobe used to latch data from the MX98902 in external latch for transfer to host memory during remote real transfers. The rising edge of PWRX coincides with the presence of valid data on the local bus.			
RACKX	I	37	41	35	READ ACKNOWLEDGE: Indicates that the system DMA host CPU has read the data placed in the external latch by th MX98902. The MX98902 will begin a read cycle to update th latch MX98902.			



PIN DESCRIPTIONS (Continued)

B. NETWORK INTERFACE PINS

SYMBOL PIN TYPE		PIN NUMBER PQFP PLCC SQFP			DESCRIPTION			
POL	0	47	48	45	POLARITY : A TTL/MOS active high output. This signal is normally low. When the TPI module detects seven consecu- tive link pulses or three consecutive received packets with reversed polarity POLED is asserted.			
TXE/TX	0	49	50	47	TRANSMIT ENABLE/TRANSMIT : A TTL/MOS active high output. It is asserted for approximately 50 ms whenever the MX98902 transmits data in either the AUI or TPI modes.			
TEST	I	51	52	49	FACTORY TEST INPUT : Used to check the chip's interna function. This should be tied low during normal operation.			
TXODM, TXO TXOM, TXO		O 58,59	55,56 56,57	54,55 56,57	TWISTED-PAIR TRANSMIT OUTPUTS : These high drive CMOS-level outputs are resistively combined external to the chip to produce a differential output signal with equalization to compensate for inter-symbol interference (ISI) on the twisted-pair medium.			
RXIP, RXIM	I	64,65	61,62	61,62	TWISTED-PAIR RECEIVE INPUTS: These inputs feed a differential amplifier which passes valid data to the ENDEC module.			
GDLNK	I/O	69	67	65	GOOD LINK : This pin has a dual input and output functions The function is latched by the MX98902 on the rising edge o the Reset signal i.e.: on the chip returning to normal opera tion after reset. As an output, this pin is configured as ar open drain N-channel device and is suitable for driving ar LED. It will be latched as output on removal of chip reset i connected to an LED or left open circuit. Under norma conditions (the twisted-pair link is not broken) the output will be low, and the LED will be lit. The open drain output will be switched off if the twisted-pair link has been detected to be green. This output will be pulled high in AUI mode by ar internal resistor of approximately 15K Ω . When this pin which has an internal pull-up resistor to VDD, is tied low, i becomes an input and the link integrity checking is disabled.			
P20M	0	70	68	66	20 MHz : This is a TTL/MOS-level signal. It is a buffered version of the oscillator X2. It is suitable to drive externa logic, if a crystal is applied to X1 and X2.			
X1	I	71	69	67	EXTERNAL OSCILLATOR INPUT.			
X2	I	72	70	69	X2: This pin should normally be connected to ground. It is possible to use a crystal oscillator using X1 and X2 if certain precautions are taken.			
SQUEL	1	73	-	71	TPI SQUELCH SELECT : This pin selects the TPI module input squelch thresholds. When tied low, the input squelch threshold on the RXIP, RXIM input complies to 10BASE-T specification. When set high, the RXIP and RXIM input oper- ates with reduced squelch levels, allowing its use with longer lengths of cable or cable with higher losses. Internal pul down.			



PIN DESCRIPTIONS (Continued) B. NETWORK INTERFACE PINS

SYMBOL	PIN TYPE	PIN NUMBER PQFP PLCC SQFP			DESCRIPTION			
SEL	I	74	71	_	MODE SELECT : When high, TXP and TXM are the same voltage when idle. If low, TXP is positive with respect to TXM when idle, at the transformer's primary.			
AUTP	I	75	72	72	AUI/TPI SELECT : A TTL level active high input that selects either the AUI interface or the TPI module for interface with the ENDEC module. When high, the AUI is selected. When low, the TPI is selected.			
TXM, TXP	0	76,77	73,74	74,75	AUI TRANSMIT OUTPUT: Differential driver which sends the encoded data to the transceiver. The outputs are source followers which require 270Ω pulldown resistors.			
RXM, RXP	I	82,83	78,79	80,81	AUI RECEIVE INPUT: Differential receive input pair from the transceiver.			
CDM, CDP	I	84,85	80,81	82,83	AUI COLLISION INPUT: Differential collision pair input from the transceiver.			
SNISEL	I	87	83	85	FACTORY TEST INPUT : For normal operation tied to VCC. When low, it enables the ENDEC module to be tested independently of the MX98902.			
CRS/RX	0	88	84	86	CARRIER SENSE/RECEIVE: A TTL/MOS-level active high signal. It is asserted for approximately 50 ms whenever valid transmit or receive data is detected while in AUI mode or receive data is detected while in TPI mode.			
COL	0	50	51	48	COLLISION : A TTL/MOS active high output. It is asser for approximately 50ms whenever the MX98902A detect collision in either the AVI or TPI modes.			

PIN DESCRIPTIONS (Continued)

C. POWER SUPPLY PIN (DIGITAL)

SYMBOL	PIN TYPE	PIN NUMBER PQFP PLCC SQFP			DESCRIPTION
VCC		21,46 89	1, 27 47	18,43 87	POSITIVE 5V SUPPLY PINS.
GND		20,90	2, 26	17,32	NEGATIVE (GROUND) SUPPLY PINS: It is suggested that
		34,48 68	39,49 64	46 ,64 88	a decoupling capacitor be connected between VCC and GND pins.

D. POWER SUPPLY PINS (ANALOG)

SYMBOL	PIN TYPE				DESCRIPTION				
		PQFP	PLCC	SQFP					
VCC		93	4	90	VCO 5V SUPPLY PIN: Care should be taken to reduce noise on this pin as it supplies power to the analog VCC to the Phase Lock Loop.				
GND		92	3	89	VCO GROUND SUPPLY PIN: Care should be taken to reduce noise on this pin as it supplies ground to the analog VCC to the Phase Lock Loop.				
VCC		63	60	60	TPI RECEIVE 5V SUPPLY: Power pin supplies 5V to the Twisted-pair Interface Receiver.				
GND		66	63	63	TPI RECEIVE GROUND: Ground pin for the Twisted-pai Interface Receiver.				
VCC		61	59	59	TPI TRANSMIT 5V SUPPLY : Power pin supplies 5V to the Twisted-pair Interface Transmitter.				
GND		60	58	58	TPI TRANSMIT GROUND : Ground pin for the Twisted-pai Interface Transmitter.				
VCC		81	77	79	AUI RECEIVE 5V SUPPLY: Power pin supplies 5V to the AUI Interface Receiver.				
GND		86	82	84	AUI RECEIVE GROUND: Ground pin for the AUI Interface Receiver.				
VCC		80	76	77	AUI TRANSMIT 5V SUPPLY: Power pin supplies 5V to AU Interface Transmitter.				
GND		79	75	76	AUI TRANSMIT GROUND: Ground pin for the AUI Interface Transmitter.				





PIN DESCRIPTIONS (Continued)

E. NO CONNECTION

SYMBOL PIN T	YPE PIN NUMBER PQFP PLCC S	
NC	16,19 65,66 1 24,35 2 38,40 3 44,53 2 54,57 5 62,67 6 78,91 7	,5,8 6,19 4,33 8,41 4,51 2,53 8,70 3,78 1,94 7



FUNCTIONAL DESCRIPTION

TWISTED-PAIR INTERFACE (TPI) MODULE

The TPI has five main logical functions:

- 1. The Smart Squelch, responsible for determining when valid data is present on the differential receive inputs (RXI±)
- 2. The Collision function checks for simultaneous transmission and reception of data on the TXO± and RXI± pins.
- 3. The Link Detector/Generator checks the integrity of the cable connecting the two twisted-pair MAUs.
- 4. The Jabber disables the transmitter if it attempts to transmit a longer than legal packet.
- 5. The TX Driver & Pre-emphasis transmit Manchester encoded data to the twisted-pair network via the summing resistors and transformer/filter.

SMART SQUELCH

To make sure that impulse noise on the receive inputs will not be mistaken for a valid signal, the ENC carries out an intelligent receive squelch on the $RX\pm$ differential inputs. The squelch circuitry uses a mix of amplitude and timing measurements to gauge whether the data on the twisted-pair inputs is valid.

Smart squelch checks the signal at the start of packet and any pulses that do not exceed the squelch level, either positive or negative, depending on polarity, is rejected. After this first squelch level is overcome the opposite squelch level must be exceeded within 150 ns. Finally, the signal goes beyond the original squelch level within a further 150 ns in order for the input waveform not to be rejected. The procedure entails the loss of at least three bits at the start of each packet.

When these conditions are satisfied a control signal will be generated to show the remainder of the circuitry that valid data is present. Then the smart squelch circuitry is reset.

Valid data is deemed present until either squelch level has not been generated for a time longer than 150 ns,

which shows End of Packet. If good data is detected, the squelch levels are reduced to contain the noise effect which may lead to premature End of Packet detection.

COLLISION

A collision is detected by the TPI module when the receive and transmit channels are active simultaneously. If the TPI is receiving when a collision is detected it is reported to the controller immediately. If, however, the TPI is transmitting when a collision is detected the collision is not reported until seven bits have been received while in the collision state. This prevents a collision being reported incorrectly due to noise on the network. The signal to the controller remains for the duration of the collision.

Approximately 1μ s after the transmission of each packet a signal called the Signal Quality Error (SQE) consisting of typically 10 cycles of 10 MHz is generated. This 10 MHz signal, also called the Heartbeat, ensures the continued functioning of the collision circuitry.

LINK DETECTOR/GENERATOR

This is a timer circuit that generates a link pulse as shown in the 10BASE-T specification. With a width of 100 ns, the pulse is transmitted every 16 ms on the TXO+ output in the absence of transmit data.

The pulse checks the integrity of the connection to the remote MAU, and the link detection circuit checks for valid pulses from the remote MAU. The link detector will disable the transmit, receive, and collision detection functions if valid link pulses are not received.

To determine that a good twisted-pair link exists, the GDLNK output directly drives an LED; the LED will be on during normal conditions.

JABBER

Whenever the transmitter is active for greater than 52 ms, the jabber timer monitors the transmitter and disables the transmission. In this case, the transmitter is then disabled for the time that ENDEC module's inter-

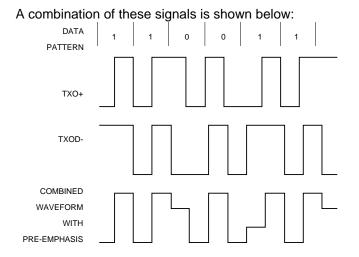


nal transmit enable is asserted. This signal has to be deasserted for about 750 ms before the Jabber reenables the transmit outputs.

TRANSMIT DRIVER

The transmitter has four signals, the true and complement Machester-encoded data (TXO \pm). These signals may be delayed by 50 ns (TXOD \pm).

These four signals are combined, TXO+ with TXODand TXO- with TXOD+. Known as digital pre-emphasis, this process is required to compensate for the twisted-pair cable which acts like a low-pass filter and can greatly weaken the 10 MHz (50 ns) pulses of the Manchester-encoded waveform than the 5 MHz (100 ns) pulses.



STATUS INFORMATION

This information is shown at the ENC on the CRS/RX, TXE/TX, COL and POL outputs as decribed in the pin description table. These outputs can drive status LEDs by means of an appropriate driver circuit.

Normally low, the POL output will be driven high when seven consecutive link pulses or three consecutive link pulses having reversed polarity are detected. A wiring error at either end of the TPI cable can cause polarity reversal. Upon detection of this reversal the condition is latched and POL is asserted. Correcting this error is the TP1 and will also decode received data correctly, thus getting rid of the need to check the wiring error.

MANCHESTER ENCODER AND DIFFERENTIAL DRIVER

On the transformer's secondary, the differential transmit pair drives up to 50 meters of twisted-pair AUI cable. These outputs are source followers requiring two 270Ω pulldown resistors to ground.

The MX98902 enables both half-step and full-step to be compatible with Ethernet and IEEE 802.3. Transmit+ is positive as regards Transmit- with the SEL pin low (for Ethernet 1). With SEL high (for IEEE 802.3), Transmit+ and Transmit- are equal when idle, thus providing zero differential voltage to operate with transformer-coupled loads.

MANCHESTER DECODER

This decoder is composed of a differential receiver and a PLL to separate a Manchester-decoded data stream into internal clocks signals and data. When using the standard 78Ω transceiver drop cable, see that the differential input must be externally terminated with two 39Ω resistors connected in series. These resistors are optional in Thin Ethernet applications. A squelch circuit at the input rejects signals with levels less than - 175 mV to prevent noise from triggering the decoder. And signals negative than -300 mV are decoded; data becomes valid within 5 bit times. The MX98902 may be able to take bit jitter up to 18 ns in the data that is received.

COLLISION TRANSLATOR

If the Ethernet transceiver, when in AUI mode, detects a collision, it generates a 10 MHz signal to the differential collision inputs (CD \pm) of the MX98902. When these inputs are active, the MX98902 uses this signal to cancel its current transmission and reschedule another one.

The collision differential inputs are ended in the same way as the differential receive inputs. The squelch circuitry is also similar, rejecting pulses with levels less than -175 mV.



RECEIVE DESERIALIZER

The receive deserializer starts to work when the input signal Carrier Sense is asserted. It allows incoming bits to be shifted into the shift register by the receive clock provided by the SNC (Serial Network Converter). The serial receive data is also routed to the CRC generator/ checker to detect CRC code. The receive deserializer includes a synch detector that detects the SFD (Start of Frame Delimiter) to establish where byte boundaries within the serial bit stream are located, i.e., when a 1,1 bit sequence is detected, it begins to collect data. After every eight receive clocks, the byte-wide data is transferred to the 16-byte FIFO (two 8-byte FIFOs) alternatively and the receive byte count is incremented. The first six bytes after the SFD are checked for valid comparison by the Address Recognition Logic. If the address recognition Logic does not recognize the packet, the FIFO is cleared.

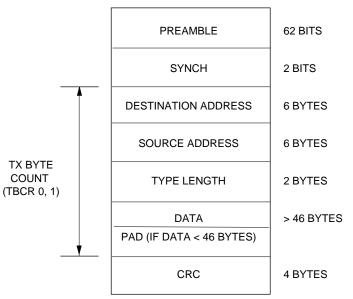
ADDRESS RECOGNITION LOGIC

The address recognition logic compares the destination address field (first 6 bytes of the received packet) with the physical address registers stored in the address register array, one byte at a time, by the 8th receive clock. If any one of the six bytes does not match the preprogrammed physical address, the protocol PLA rejects the packet. This means that the packet does not belong to the node. All multicast destination addresses are filtered using a hashing technique by latching the 6 most significant bits of the CRC generator. If the multicast address indexes a bit that has been set in the filter bit array of the multicast address register array, the packet is accepted. Otherwise, it is rejected by the Protocol PLA. Each destination address is also checked for all 1's which is the reserved broadcast address.

PACKET TRANSMISSION

A complete transmit packet consists of Preamble, Synch, Data, and CRC fields. The data field is a contiguous assembled packet of Destination Address. Source Address, Length Field, and Data with the format shown below. During transmit, Page Start Address Register (TPSR) and the Transmit Byte Count Registers (TBCR0,1), control the DMA transfer. As a transmit command is issued to ENC, the packet of data in buffer memory pointed 0 by these registers will be moved into the FIFO. The ENC will generate and append the preamble, synch and CRC fields. In addition, if transmitting data is smaller than 46 bytes, the packet must be padded to a minimum size of 64 bytes. The programmer is responsible for adding and stripping pad bytes.

GENERAL TRANSMIT PACKET FORMAT



CONDITIONS REQUIRED TO BEGIN TRANSMISSION

To initiate transmission of a packet, the TPSR (Transmit Page Start Register) and TBCR0, TBCR1 (Transmit Byte Count Registers) must be initialized and the TXP bit in the Command Register must be set. The ENC will start to prefetch transmit data from memory, if no neception is currently receiving. Three conditions must be met before transmission:

- 1. The Interframe Gap Timer has timed out the first $6.4 \mu s$ of the Interframe Gap.
- 2. At least one byte has entered the FIFO, which means that burst transfer has begun.
- 3. If collision occurs in the ENC, the backoff timer must expire before retransmit.



If carrier sense is asserted before a byte has been loaded into the FIFO, the ENC will become a receiver.

COLLISION RECOVERY

If transmission has collided with another station, the buffer management logic, which monitors the transmit circuitry will reset the FIFO and restore the Transmit DMA pointers for retransmission of the packet. When collision is detected, the COL bit in TSR will be set and the NCR (Number of Collisions Register) will be incremented. If each of the 15 retransmissions results in a collision, the transmission will be terminated and the ABT bit in the TSR will be set. If excessive collisions (i.e., 16 consecutive collisions) are encountered, NCR reads as zeros and transmission is aborted.

TRANSMIT PACKET ASSEMBLY FORMAT

The following diagrams show the format for assembling packets before they are transmitted for different byteordering schemes. The various formats are selected in the Data Configuration Register.

DA = Destination Address SA = Source Address

T/L = Type/Length Field

BIT	D15 D8	3 D7	D0
	DA1	DA0	
	DA3	DA2	
	DA5	DA4	
	SA1	SAO	
	SA3	SA2	
	SA5	SA6	
	T/T1	T/L0	
	DATA1	DATAO	

BOS = 0, WTS - 1 in Data Configuration Register. This format is used with Series 32000, 808X-type processors.

BIT D	D15 D8	D7 D0
	DA0	DA1
	DA2	DA3
	DA4	DA5
	SA0	SA1
	SA2	SA3
	SA4	SA5
	T/L0	T/L1
	DATA0	DATA1

BOS = 1, WTS = 1 in Data Configuration Register. This format is used with 68000-type processors.





DA0
DA1
 DA2
DA3
DA4
DA5
SA0
SA1
 SA2
SA3

BOS = 0, WTS= 1 in Data Configuration Register. This format is used with general 8-bit CPUs.



PHYSICAL ADDRESS REGISTERS (PAR0-PAR5)

The physical address registers are used to compare the destination address of incoming packets for rejecting or accepting packets. It compares physical addresses in

PAR0-PAR5 with incoming data one byte at a time. The bit assignment shown below relates the sequence in PAR0-PAR5 to the bit sequence of the received packet.

					D7	D6 D5	D4 D3	D2 D1	D0
	D7	D6	D5	D4	PA R 8	DA 072 DA	6 DA 9 1DA4	1 DA B 0DA2	
PAR0	DA7	DA6	DA5	DA4	DA1 DA0 DA3	DA2	DA1	DA0	
PAR1	DA15	DA14	DA13	DA12	PABA11		14DA0300A1	12DA01400A01	C
PAR2	DA23	DA22	DA21	DA20	DA9 DA8 DA19	DA18	DA17	DA16	
PAR3	DA31	DA30	DA29	DA28	PAB227	DA233216A	22 DAØ14, Ø5A2	20 DA 18 20 A 18	3
PAR4	DA39	DA38	DA37	DA36	DA17DA10 DA35	6 DA34	DA33	DA32	
PAR5	DA47	DA46	DA45	DA44			30 D A B A D A 2	28 DA Ø 7 DA 26	6
					DA25DA2	4			

PAR4 DA39DA38DA37DA36DA35DA34 DA33DA32

PAR5 DA47DA46DA45DA44DA43DA42 DA41DA40 SOURCE

DESTINATION ADDRESS										
P/S	DA0	DA1	DA2	DA3		DA46	DA47	SA0		

NOTE: P/S = Preamble, Synch

DA0 = Physical/Multicast Bit



DIRECT MEMORY ACCESS CONTROL (DMA)

The DMA capabilities of the ENC greatly simplify use of the MX9890 in typical configuration. The local DMA channel transfers data between FIFO, which is inside the ENC, and memory which is outside the ENC. There are two kinds of local DMA type: Local DMA Read and Local DMA Write. Local DMA Read moves data from memory into FIFO on transmission. Should a collision occur (up to 15 times), the packet is retransmitted with no processor intervention. Local DMA Write transfers data from FIFO to memory on reception.

A remote DMA channel is also provided on the ENC to accomplish transfers between a buffer memory and a system memory whenever the I/O map board design is required. The two DMA channels (local DMA and remote DMA) can alternatively be combined to form a single 32bit address with 8- or 16-bit data.

DUAL DMA CONFIGURATION

Network activity is isolated on a local bus, where the ENC's local DMA channel performs burst transfers between the buffer ring and the ENC's FIFO. The remote DMA transfers data between the buffer ring and the host memory by means of a bidirectional I/O port. Meanwhile, remote DMA provides local addressing capability and is used as a slave DMA by the host. Host side addressing must be provided by a host DMA or the CPU. The ENC allows Local and Remote DMA operations to be interleaved because the ENC takes care of the bus arbitration problem itself.

SINGLE CHANNEL DMA OPERATION

If desirable, the two DMA channels can be combined to provide a 32-bit DMA address. The upper 16 bits of the 32-bit address provided by the remote DMA channel are static and are used to point to a 64-kbyte (or 32k word) page of memory where packets are to be received or transmitted. The lower 16 bits of the 32-bit address provided by Local DMA channel are dynamic and are used to point to a 64-kbyte (or 32 kword) offset of memory.

LOOPBACK MODE

Mode1:LoopbackThroughTheNEC Module(LB1=0,L BO=1)

If this loopback is used, the ENC Module's serializer is connected to the deserializer.

Mode 2 : Loopback through the MCC Module (LB1=1, LBO=0)

If this loopback is to be performed through the MCC, the MX98902 provides a control (LBK) that forces the MCC module to loopback all signals.

Mode3 : Loopback to cable (LB1=1, LBO=1) Packets can be transmitted to the cable in loopback mode to check all of the transmit and receive paths and cable itself

Note : Collision and Carrrier Sense can be generated by the MCC module and are Masket by the ENC module. It is not possible to go directly between the loopback modes, it is necessary to return to normal (OOH) when changing modes.

READING THE LOOPBACK PACKET

The last 8 bytes of a received packet can be examined by 8 consecutive reads of the FIFO register. The FIFO pointer is incremented after the rising edge of the CPU's read strobe by internally synchronizing and advancing the pointer. This may take up to four bus clock cycles, if the pointer has not been incremented by the time the CPU reads the FIFO registers again, the MX98902 will insery wait states..



ALIGNMENT OF THE RECEIVED PACKET IN THE FIFO

Reception of the packet in the FIFO begins at location zero, after the FIFO pointer reaches the last location in the FIFO, the pointer wraps to the top of the FIFO overwriting the previously received data. This process is continued until the last byte is received. The MX98902 then appends the received byte count in the next two locatioms of the FIFO. The contents of the Upper Byte Count are also copied to the next FIFO location. The number of bytes used in the loopback packet determines the alignment of the FIFO. The alignment for a 8 X N byte packet is shown below.

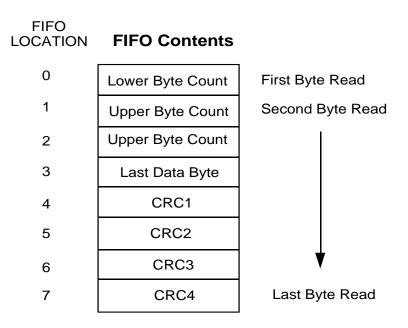


Figure 5.7.3 FIFO Alignment for 8 X N byte



RESTRICTIONS DURING LOOPBACK

The FIFO is split into two halves, one half is used for transmission and the other for reception. Only 8 bit fields can be fetched from memory so two tests are requires (shown in figure 5.7.4) for 16-bit system to verify integrity of the entire data path. During loopback the maximum latency from the assertion of BREQ to BACK is 2.Ous. Figure A in figure 5.7.4 verify the data path for 680x0 CPU yet figure B verify the data path for 32000/80x86 CPUs.

LS Byte(AD8-15) MS Byte(AD0-7)

Destination
Sourec
Length
Data
CRC

WTS="1" BOS="1" (DCR bits)

Figure A. 680X0 CPU data path verification during loopback

LS Byte(AD8-15) MS Byte(AD0-7)

Destination	
Sourec	
Length	
Data	
CRC	

WTS="1" BOS="1" (DCR bits)

Figure B. 32000/80x86 CPU data path verification during loopback

Figure 5.7.4 Data path verification during



EXAMPLES

The following examples show what results can be expected from a properly operating MX98902 during loopback. The restrictions and results of each type of loopback are listed for reference. The loopback tests are divided into two sets of test. One to verify the data path, CRC generation and byte count through all three paths. the second set of test uses internal loopback to verify the receiver's CRC checking and address recognition. For all of the tests the DCR was programmed to 40H.

Path	TCR	RCR	TSR	RSR	ISR
MX9890 Internal	02	1F	53 (Note 1)	02 (Note 2)	02 (Note 3)

Note 1 : Since carrier sense and collision detect are generated in the MCC module, they are blocked during ENC loopbak. Carrier and CD hertbeat are not seen and the CRS and CDH bits are set.

Note 2 : CRC errors are always indicated by the receiver if CRC is appended by the transmitter.

Note 3: Only the PTX bit in the ISR is set, the PRX bit is only set if status is written to memory. In loopback this action does not occur and the PRX bit remains 0 for all loopback modes.

Note 4 : All values are hex.

Path	TCR	RCR	TSR	RSR	ISR
Loopback to MCC	04	1F	43 (Note 1)	02	02

Note 1 : CDH is set, CRS is not set since it is generated by the external MCC module.

Path	TCR	RCR	TSR	RSR	ISR
Loopback to TPI	06	1F	03 (Note 1)	02	02 (Note 2)

Note 1 : CDH should not be set. The TSR however, could also contain 01H,03H,07H and a variety of other Values depending on whether collisions were encountered or the packet was deferred. If collision was encountered during sending preamble, then CRS of TSR may be set depending on whether Receive clock is synchrounous to transmit clock or not.

Note 2 : The ISR will contain 08H if packet is not transmittable.

Note 3: During exteral loopback the MX98902 is now exposed to network traffic. It is threefore possible for the contents of both the Receive portion of the FIFO and the RSR to be corrupted by any other packer on the network. Thus in a live network the contents of the FIFO and RSR should not be depended on. The MX98902 will still abide by the standard CSMA/CD protocol in external loopback mode. (i.e., The network will not be disturbed by the loopback packet.)

Note 4 : All values are hex.



CRC and Address Recognition

The next three tests exercise the address recognitioon logic and CRC. There tests should be performed using internal loopback only so that the MX98902 is isolated from interference from the network. These tests also require the capability to generaye CRC in software (i.e., CRC inhibibit by transmitter).

The address recognition logic cannot be directly tested. The CRC and FAE bits in the RSR are only set if the address in the packet matches the address filter (PARO - PAR5). If errors are expected to be set and type are not set, the packet has been rejected on the basis of an address mismatch. The following sequence of packets will test the address recognition logic. The DCR should be set to 40H and the TCR should be set to 03H with a software generated CRC.

	Packet Conyents	Results	
Test	Address	CRC	RSR
Test A	Matching	Good	01 (Note 1)
Test B	Matching	Bad	02 (Note 2)
Test C	Non-Matching	Bad	01

Note 1 : Status will read 21H if multicast address used

Note 2 : Status will read 22H if multicast address used

Note 3 : In test A, the RSR is set up. In test B the address is found to match since the CRC is flagged as bad. Test C proves that the address recognition logic can distinguish a bad address and does not notify the RSR of the bad CRC. The receiving CRC is proven to work in test A and test B.

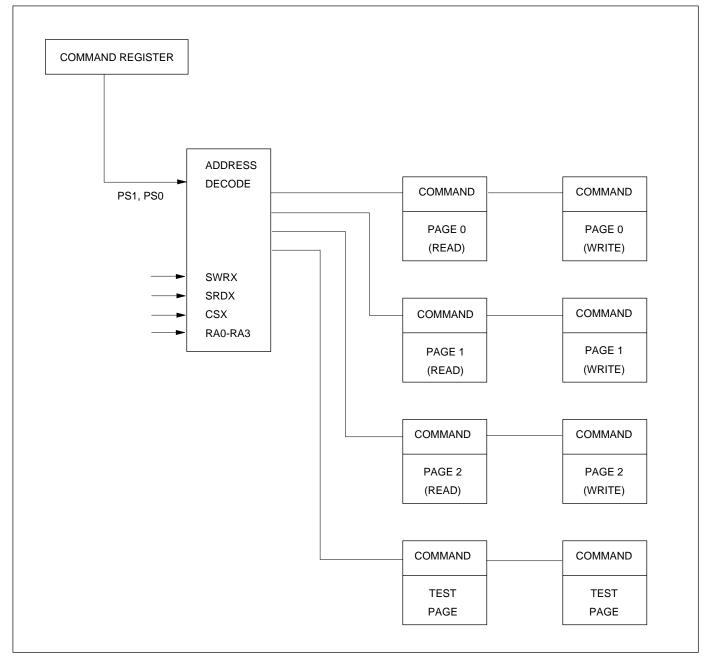
Note 4 : All values are hex.

INTERNAL REGISTERS

All internal registers are mapped into three pages and selected by two bits, PS1 and PS0, of Command Register. Input pins RA0-RA3 are used to address these internal registers which are 8-bit wide and are commonly accessed during ENC register read/write operation. For user's convenience, registers that are commonly accessed during ENC operation are mapped into page 0. Page 1 registers are used primarily for initialization while Page 2 registers are used for diagnostic. Partitioned registers make one write/read cycle possible for accessing those commonly used registers.



REGISTER ADDRESS MAPPING





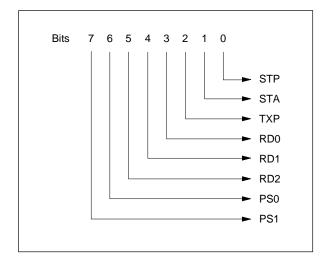
REGISTER DESCRIPTION

A. Command Register (CR) 00H (Read/Write)

The Command Register is used to take the controller on/ off line (STA and STP bits), initiate transmissions (TXP bit), enable or disable Remote DMA operations (RD2, RD1 and RD0 bits), and select register pages (PS1 and PS0). To issue a command, the microprocessor sets the corresponding bit(s). In addition, commands may be overlapped following the guidelines below:

- If a remote DMA operation overlaps a transmission, RD0, RD1 and RD2 must be written with the desired values, and a "0" or "1" may be written to the TXP bit because writing a "0" to TXP has no effect after transmission is activated.
- 2. A remote write DMA may not overlap remote read operation and vice versa. Each operation must either be completed or aborted before starting the other one.

- 3. If a transmit command overlaps with a remote DMA operation, bits RD2, RD1 and RD0 must be maintained for the remote DMA command when setting the TXP bit.
- NOTE: If a remote DMA command is reissued while giving the transmit command, the DMA will complete the process immediately if the remote byte count registers (RBCR1 and RBCR0) have not been reinitialized, i.e., one has to program RBCR0 and/or RBCR1 every time when one needs remote DMA service.
- 4. Bits PS1, PS0, RD2 and STP can be set at any moment.





REGISTER DESCRIPTION (Continued) A. COMMAND REGISTERS (Continued)

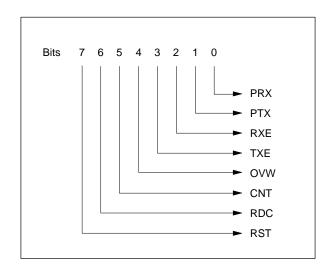
SYMBOL	BIT	DESCRIPTION			
STP	D0	 STOP: Software reset command, takes the controller offline; no Packets will be received or transmitted if this bit is set high. Any reception or transmission in progress will enter the reset state after operation is completed. This bit must be cleared and the STA bit must be set high to exit the reset state. The software reset is executed only when the RST bit in the ISR is set to 1. STP powers up high. Note: If the ENC has previously been in start mode and the STP is set, both the STP and STA bits will remain set. 			
STA	D1	START : This bit is used to activate the ENC after either power-up, or when the ENC has been placed in a reset mode by software command or error. STA powers up low.			
ТХР	D2	TRANSMIT PACKET: This bit must be set to initiate transmission of a packet only after the Transmit Byte Count (TBCR1 and TBCR0) and Transmit Page Start register (TPSR) have been programmed. TXP is internally reset either after the transmission is completed or aborted.			
PD0, PD1, PD2	D3, D4, D5	REMOTE DMA COMMAND : These three encoded bits control operation of the Remote DMA channel. RD2 can be set to abort any Remote DMA command in progress. The Remote Byte Count Registers should be cleared by host whenever a Remote DMA has been aborted. The Remote Start Addresses are not restored to the starting address if the Remote DMA is aborted. Hence, for another remote DMA operaton, host should provide a starting address for ENC in order to operate correctly.			
		RD2RD1RD0000Not Allowed001Remote Read010Remote Write011Send Packet1XXAbort/Complete Remote DMA (Note)			
		Note: If a remote DMA operation is aborted and the remote byte count has not decremented to zero, PRQ will remain high. A read acknowledge (RACKX) or a write acknowledge (WACKX) will reset PRQ low.			
PS0, PS1	D6, D7	PAGE SELECT : These two encoded bits select which register page is to be accessed with addresses RA0-3			
		PS1PS000Register Page 001Register Page 110Register Page 211Reserved			





B. INTERRUPT STATUS REGISTER (ISR) 07H (READ/WRITE)

This register is accessed by the host processor to determine the cause of an interrupt. Any interrupt can be masked in the Interrupt Mask Register (IMR). Individual interrupt bits are cleared by writing a "1" into the corresponding bit of the ISR. The INT signal is active as long as any unmasked signal is set; it will not go low until all unmasked bits in this register have been cleared. The ISR must be cleared after power-up by writing it with all 1's.



SYMBOL	BIT	DESCRIPTION
PRX	D0	PACKET RECEIVED: Indicates packet received with no errors.
PTX	D1	PACKET TRANSMITTED: Indicates packet transmitted with no errors.
RXE	D2	RECEIVE ERROR : Indicates that a packet was received with one or more of the following errors:
		 CRC Error Frame Alignment Error FIFO Overrun Missed Packet
TXE	D3	TRANSMIT ERROR : Set when packet is transmitted with one or more of the following errors:
		Excessive CollisionsFIFO Underrun
OVW	D4	OVERWRITE WARNING: Set when receive buffer ring storage resources have been exhausted. (Current Pointer has reached Boundary Pointer)

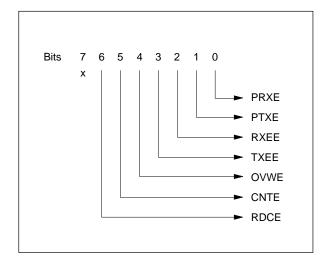


B. INTERRUPT STATUS REGISTER (ISR) 07H (READ/WRITE) (Contiuned)

SYMBOL	BIT	DESCRIPTION
CNT	D5	COUNTER OVERFLOW : Set when MSB of one or more of the Network Tally Counters has been set.
RDC	D6	REMOTE DMA COMPLETE: Set when Remote DMA operation has been completed.
RST	D7	RESET STATUS : Set when ENC enters reset state and cleared when a start command is issued to the CR. This bit is also set when a Receive Buffer Ring overflow occurs and is cleared when one or more packets has been removed from the ring. Writing to this bit has no effect. Note: This bit does not generate any interrupt; it is merely a status indicator.

C. INTERRUPT MASK REGISTER (IMR) 0FH (WRITE)

The Interrupt Mask Register is used to mask interrupts. Each interrupt mask bit corresponds to a bit in the Interrupt Status Register (ISR). If an interrupt mask bit is set, an interrupt will be issued whenever the corresponding bit in the ISR is set. If any bit in the IMR is set low, an interrupt will not occur when the bit in the ISR is set. The IMR powers up all zeros.





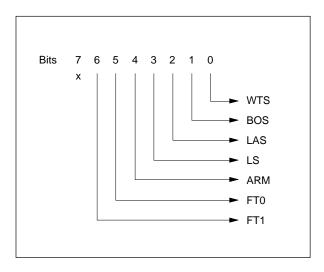
C. INTERRUPT MASK REGISTER (IMR) 0FH (WRITE) (Continued)

SYMBOL	BIT	DESCRIPTION
PRXE	D0	PACKET RECEIVED INTERRUPT ENABLE
		0: Disables Interrupt when packet is received.
		1: Enables Interrupt when packet is received.
PTXE	D1	PACKET TRANSMITTED INTERRUPT ENABLE
		0: Disables Interrupt when packet is transmitted.
		1: Enables Interrupt when packet is transmitted.
RXEE	D2	RECEIVE ERROR INTERRUPT ENABLE
		0: Disables Interrupt when packet is received with error.
		1: Enables Interrupt when packet is received with error.
TXEE	D3	TRANSMIT ERROR INTERRUPT ENABLE
		0: Disables Interrupt when packet transmission results in error.
		1: Enables Interrupt when packet transmission results in error.
OVWE	D4	OVERWRITE WARNING INTERRUPT ENABLE
		 Disables Interrupt when Buffer Management Logic lacks sufficient buffers to store an incoming packet.
		1: Enables Interrupt when Buffer Management Logic lacks sufficient buffers to store an
		incoming packet.
CNTE	D5	COUNTER OVERFLOW INTERRUPT ENABLE
		0: Disables Interrupt when MSB of one or more of the Network Statistics Counters has
		been set. 1: Enables Interrupt when MSB of one or more of the Network Statistics Counters has
		been set.
RDCE	D6	DMA COMPLETE INTERRUPT ENABLE
		0: Disables Interrupt when Remote DMA transfer has been completed.
		1: Enables Interrupt when Remote DMA transfer has been completed.
RESERVED	D7	Reserved



P. NATERRUPFWRASK REGISTER (MRR) OFH (WRITE) (WRITE) (Continued)

This register is used to program the ENC for 8- or 16-bit SYMBOLE BOD, SPESCIIPATION opback operation, select byte ordering in 16-bit application, and establish FIFO threshold. The DCR must be initialized prior to loading the Remote Byte Count Registers. LAS is set on power-up.



SYMBOL	BIT	DESCRIPTION
WTS	D0	WORD TRANSFER SELECT
		0: Selects byte-wide DMA transfers1: Selects word-wide DMA transfers
		WTS establishes byte or word transfer for both Remote and Local DMA transfers. Note: When word-wide mode is selected, up to 32K words are addressable; A0 remains low.
BOS	D1	BYTE ORDER SELECT
		 MS byte placed on AD15-AD8 and LS byte on AD7-AD0 (32000, 80x86) MS byte placed on AD7-AD0 and LS byte on AD15-AD8 (68x0); ignored when WTS is low.
LAS	D2	LONG ADDRESS SELECT
		0: Dual 16-bit DMA mode 1: Single 32-bit DMA mode
		When LAS is high, the contents of the Remote DMA Registers RSAR0, 1 are issued as A16-A31. Power up high.



D. DATA CONFIGURATION REGISTER (DCR) 0EH (WRITE) (Continued)

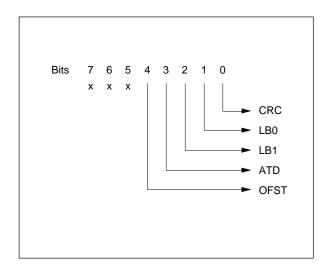
SYMBOL	BIT	DESCRIPTION		
LS	D3	LOOPBACK SEL	ECT	
		0: Loopback mod operation.	le select. Bits LB	0, LB1 of the TCR must be programmed for loopback
			tion. Ignore the	values of LB1 and LB0 of TCR.
ARM	D4	AUTO-INITIALIZ	E REMOTE	
		0: Send Commar control.	nd not excuted,	all packets removed from Buffer Ring under program
		1: Send Commar Ring	nd excited, Remo	ote DMA auto-initilized to remove packets from Buffer
		Note: Send Com right after reception		used with 68x0-type processors and should be issued ompleted.
FT0, FT1	D5,D6	is requested whe indicates the num before bus reques During transmissi FIFO has filled fro threshold is 16 by	n filling or empty nber of bytes (or st (BREQ) is ass ion, the FIFO thr om the Local DM /tes less the rece	reshold indicates the number of bytes (or words) the IA before BREQ is asserted. Thus, the transmissior
		RECEIVE THRES	SHOLDS	
			WORD WIDE	BYTE WIDE
			2 words	2 bytes 4 bytes
		U I		
		1 0	4 words	8 bytes



E. TRANSMIT CONFIGURATION REGISTER (TCR) 0DH (WRITE)

Before transmission of a packet on the network, the Transmit Configuration Register is configured to establish the actions of the transmitter section of the ENC

during transmission of a packet on the network. LB1 and LB0 select loopback mode power-up as 0.



SYMBOL	BIT	DESCRIPTION
CRC	D0	INHIBIT CRC
		0: CRC appended by transmitter
		 CRC inhibited by transmitter In loopback mode CRC can be enabled or disabled to test the CRC logic.
LB0, LB1	D1, D2	ENCODED LOOPBACK CONTROL : The type of loopback to be performed is determined by these encoded bits.
		LB1 LB2
		Mode 0 0 0 Normal Operation
		Mode 1 0 1 Internal Loopback
		Mode 2 1 0 External Loopback to ENDEC
		Mode 3 1 1 External Loopback to TPI
ATD D3		AUTO TRANSMIT DISABLE : Setting this bit allows another station to disable the ENC's transmitter by transmission of a particular multicast packet. The transmitter can be re- enabled by resetting this bit or by reception of a second particular multicast packet.
		0: Normal Operation
		 Reception of multicast address hashing to bit 62 disables transmitter; reception o multicast address hashing to bit 63 enables transmitter.

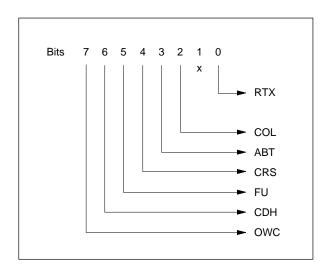


E. TRANSMIT CONFIGURATION REGISTER (TCR) 0DH (WRITE) (Continued)

SYMBOL	BIT	DESCRIPTION	
OFST	D4	COLLISION OFFSET ENABLE : This bit modifies the backoff algorithm to allow prioritization of modes.	
		 0: Normal Backoff algorithm 1: Forces Backoff algorithm modification to 0 to 2 min (3+n, 10) slot times for first three collisions, then follows standard backoff. (For first three collisions station has higher average backoff delay making a low priority mode.) 	
RESERVED	D5	Reserved	
RESERVED	D6	Reserved	
RESERVED	D7	Reserved	

F. TRANSMIT STATUS REGISTER (TSR) 04H (READ)

Each particular bit of this register is set when the corresponding event occurs on the media during transmission of a packet. The contents of this register are not specified until after the first transmission and are cleared upon the start of next transmission initiated by the host. A read of this register is necessary after each transmission.





F. TRANSMIT STATUS REGISTER (TSR) 04H (READ) (Continued)

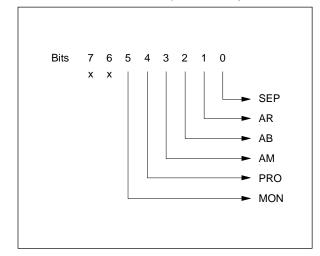
SYMBOL	BIT	DESCRIPTION		
PTX	D0	PACKET TRANSMITTED : Set when transmitted without error. (No excessive collisions or FIFO underrun) (ABT= "0", $FU = "0"$)		
	D1	Reserved		
COL	D2	TRANSMIT COLLIDED: Set when transmission collided at least once with another station on the network. The number of collisions is recorded in the Number of Collisions Registers (NCR).		
ABT	D3	TRANSMIT ABORTED : Set when transmission is aborted because of excessive collisions. (Total number of transmission attempts equals 16).		
CRS	D4	CARRIER SENSE LOST : Set when carrier is lost during transmission of a packet. Carrier Sense is monitored from the end of Preamble/Synch until TXE is dropped. Note that transmission is not aborted on loss of carrier.		
FU	D5	FIFO UNDERRUN : Set when ENC cannot gain access of the bus before the FIFO empties. Transmission of the packet will be aborted.		
CDH	D6	CD HEARTBEAT : Set when the transceiver fails to issue a collision signal after transmission of a packet. The Collision Detect (CD) heartbeat signal must commence during the first 6.4μs of the Interframe Gap following a transmission. However, in some collisions, the CD heartbeat bit will be set even when the transceiver is not performing the CD heartbeat test.		
OWC	D7	OUT-OF-WINDOW COLLISION : Set when a collision occurred after a slot time $(51.2\mu s)$. Transmission will not be aborted.		



G. RECEIVE CONFIGURATION REGISTER (RCR) 0CH (WRITE)

This register determines what types of packets to be accepted and what mode the ENC will be in. The types

include address type and error type. In the error type, when any one bit of SEP and AR is clear and the packet received matches the condition set in SEP or AR, the packet is rejected.



SYMBOL	BIT	DESCRIPTION		
SEP	D0	SAVE ERROR PACKETS.		
		 Packets with CRC and Frame Alignment errors are rejected. Packets with CRC and Frame Alignment errors are accepted. 		
AR	D1	ACCEPT RUNT PACKETS : This bit allows the receiver to accept packets that are smaller than 64 bytes. The packet must be at least 8 bytes long to be accepted as a runt.		
		0: Packets with fewer than 64 bytes rejected.		
		1: Packets with fewer than 64 bytes accepted.		
AB	D2	ACCEPT BROADCAST : Enables the receiver to accept a packet with an all 1's destination address.		
		0: Packets with broadcast destination address rejected.		
		1: Packets with broadcast destination address accepted.		
AM	D3	ACCEPT MULTICAST : Enables the receiver to accept a packet with a multicast address; all multicast addresses must pass the hashing array.		
		0: Packets with multicast destination address not checked.		
		1: Packets with multicast destination address checked.		

G. RECEIVE CONFIGURATION REGISTER (RCR) 0CH (WRITE)

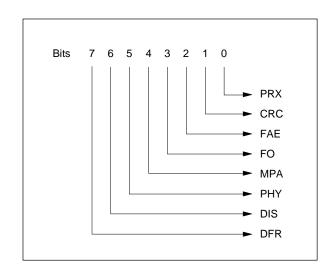
SYMBOL	BIT	DESCRIPTION
PRO	D4	PROMISCUOUS PHYSICAL: Enables the receiver to accept all packets with a physical address.
		0: Physical address of mode must match the station address programmed in PAR0-PAR5.1: All packets with physical addresses accepted.
MON	D5	MONITOR MODE : Enables the receiver to check addresses and CRC on incoming packets without buffering to memory. The Missed Packet Tally Counter will be incremented for each recognized packet.
		0: Packets buffered to memory.1: Packets checked for address match, good CRC and frame alignment but not buffered to memory.
RESERVED	D6	Reserved
RESERVED	D7	Reserved

Note: D2 and D3 are "OR'd" together, i.e., if D2 and D3 are set the ENC will accept broadcast and multicast addresses as well as its own physical address. To establish full promiscuous mode, bits D2, D3 and D4 should be set. In addition, the multicast hashing array must be set to all 1's in order to accept all multicast addresses.



H. RECEIVE STATUS REGISTER (RSR) 0CH (READ)

This register records status of the received packet. It includes information on errors, the type of address match, either physical or multicast, and the aborted packet type. The contents of this register are written to buffer memory by the DMA after receiving a good packet. If packets with errors are to be saved the receive status is written to memory at the head of the erroneous packet, when an erroneous packet is received. If packets with errors are to be rejected the RSR will not be written to memory. The contents will be cleared when the next packet arrives. CRC errors, frame alignment errors and missed packets are counted internally by the ENC which relinquishes the host from reading the RSR in real time to record errors for Network Management Functions. The contents of this register are not specified until after the first reception.



SYMBOL	BIT	DESCRIPTION	
PRX	D0	PACKET RECEIVED CORRECTLY : Indicates Packet received without error. (Bits CRC, FAE, FO and MPA are zero for the received packet.) Set when packets are received complete.	
CRC	D1	CRC ERROR : Indicates packet received with CRC error. Increments Tally Counter (CNTR1). This bit will also be set for Frame Alignment errors. Set when packets are received complete.	
FAE	D2	FRAME ALIGNMENT ERROR : Indicates that the incoming packet did not end on a byte boundary and the CRC did not match at last byte boundary. Increments Tally Counter (CNTR0). Set when packets are received complete.	
FO	D3	FIFO OVERRUN: This bit is set when the FIFO is not serviced causing overflow during reception. Reception of the packet will be aborted.	
MPA	D4	MISSED PACKET : Set when packet intended for node cannot be accepted by ENC because of a lack of receive buffers, or if the controller is in monitor mode and did not buffer the packet to memory increments Tally Counter (CNTR2).	



H. RECEIVE STATUS REGISTER (RSR) 0CH (READ) (Continued)

SYMBOL	BIT	DESCRIPTION
PHY	D5	PHYSICAL/MULTICAST ADDRESS : Indicates whether received packet has a physical or multicast address type. Set/reset when Destination Address has been received.
		0: Physical Address Match 1: Multicast/ Broadcast Address Match
DIS	D6	RECEIVER DISABLED: Set when receiver is disabled by entering Monitor mode. Reset when receiver is re-enabled when exiting the Monitor mode.
DFR	D7	DEFERRING : Set when CRS or COL inputs are active. If the transceiver has asserted the CD line as a result of the jabber, this bit will stay set indicating the jabber condition.

Note: The following coding applies to CRC and FAE bits

FAE	CRC	Type of Error
0	0	No Error (Good CRC and < 5 Dribble Bits)
0	1	CRC Error
1	0	Illegal, will not occur
1	1	Frame Alignment Error and CRC Error



REGISTER DESCRIPTION I. REGISTER ADDRESS ASSIGNMENTS (Continued)

PAGE 0 ADDRESS ASSIGNMENTS (PS1 = 0, PS0 = 0)

RA3-RA0	READ	WRITE
00H	Command Register (CR)	Command Register (CR)
01H	Current Local DMA Address 0 (CLDA0)	Page Start Register (PSTART)
02H	Current Local DMA Address 1 (CLDA1)	Page Stop Register (PSTOP)
03H	Boundary Pointer (BNRY)	Boundary Pointer (BNRY)
04H	Transmit Status Register (TSR)	Transmit Page Start Address (TPSR)
05H	Number of Collisions Register (NCR)	Transmit Byte Count Register 0 (TBCR0)
06H	FIFO (FIFO)	Transmit Byte Count Register 1 (TBCR1)
07H	Interrupt Status Register (ISR)	Interrupt Status Register (ISR)
08H	Current Remote DMA Address 0 (CRDA0)	Remote Start Address Register 0 (RSAR0)
09H	Current Remote DMA Address 1 (CRDA1)	Remote Start Address Register 1 (RSAR1)
0AH	Reserved	Remote Byte Count Register 0 (RBCR0)
0BH	Reserved	Remote Byte Count Register 1 (RBCR1)
0CH	Receive Status Register (RSR)	Receive Configuration Register (RCR)
0DH	Tally Counter 0 (Frame Alignment Error) (CNTR0)	Transmit Configuration Register (TCR)
0EH	Tally Counter 1 (CRC Error) (CNTR1)	Data Configuration Register (DCR)
0FH	Tally Counter 2 (Missed Packet Error) (ENT	R2) Interrupt Mask Register (IMR)



REGISTER DESCRIPTION (Continued) I. REGISTER ADDRESS ASSIGNMENTS (Continued)

PAGE 1 ADDRESS ASSIGNMENTS (PS1 = 0, PS0 = 1)

RA3-RA0	READ	WRITE
00H	Command Register (CR)	Command Register (CR)
01H	Physical Address Register 0 (PAR0)	Physical Address Register 0 (PAR0)
02H	Physical Address Register 1 (PAR1)	Physical Address Register 1 (PAR1)
03H	Physical Address Register 2 (PAR2)	Physical Address Register 2 (PAR2)
04H	Physical Address Register 3 (PAR3)	Physical Address Register 3 (PAR3)
05H	Physical Address Register 4 (PAR4)	Physical Address Register 4 (PAR4)
06H	Physical Address Register 5 (PAR5)	Physical Address Register 5 (PAR5)
07H	Current Page Register (CURR)	Cruuent Page Register (CURR)
08H	Multicast Address Register 0 (MAR0)	Multicast Address Register 0 (MAR0)
09H	Multicast Address Register 1 (MAR1)	Multicast Address Register 1 (MAR1)
0AH	Multicast Address Register 2 (MAR2)	Multicast Address Register 2 (MAR2)
0BH	Multicast Address Register 3 (MAR3)	Multicast Address Register 3 (MAR3)
0CH	Multicast Address Register 4 (MAR4)	Multicast Address Register 4 (MAR4)
0DH	Multicast Address Register 5 (MAR5)	Multicast Address Register 5 (MAR5)
0EH	Multicast Address Register 6 (MAR6)	Multicast Address Register 6 (MAR6)
0FH	Multicast Address Register 7 (MAR7)	Multicast Address Register 7 (MAR7)



I. REGISTER ADDRESS ASSIGNMENTS

PAGE 2 ADDRESS ASSIGNMENTS (PS1 = 1, PS0 = 0)

RA3-RA0	READ	WRITE
00H	Command Register (CR)	Command Register (CR)
01H	Page Start Register (PSTART)	Current Local DMA Address 0 (CLDA0)
02H	Page Start Register (PSTOP)	Current Local DMA Address 1 (CLDA1)
03H	Remote Next Packet Pointer	Remote Next Packet Pointer
04H	Transmit Page Start Address (TPSR)	Reserved
05H	Local Next Packet Pointer	Local Next Packet Pointer
06H	Address Counter (Upper) (ACU)	Address Counter (Upper) (ACU)
07H	Address Counter (Lower) (ACL)	Address Counter (Lower) (ACL)
08H	Reserved	Reserved
09H	Reserved	Reserved
0AH	Reserved	Reserved
0BH	Reserved	Reserved
0CH	Receive Configuration Register (RCR)	Reserved
0DH	Transmit Configuration Register (TCR)	Reserved
0EH	Data Configuration Register (DCR)	Reserved
0FH	Interrupt Mask Register (IMR)	Reserved

Note: Page 2 registers should only be accessed for diagnostic purposes. They should not be modified during normal operation. Page 3 should never be modified.





J. DMA REGISTERS

The DMA Registers are partitioned into three groups: Transmit, Receive, and Remote DMA Registers, as the diagram show on the next page.

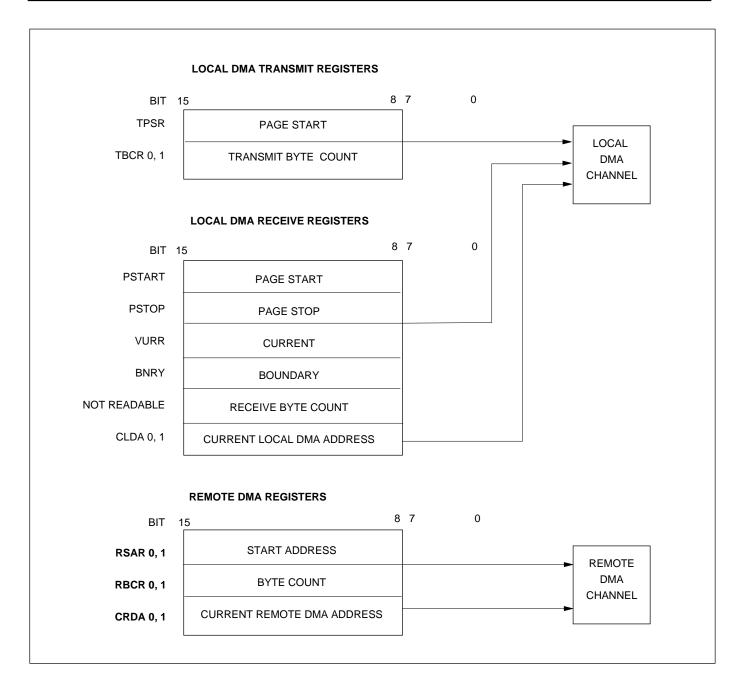
The Transmit group contains three registers: TPSR, TBCR0 and TBCR1. Registers in this group are used to initialize the Local DMA Channel for transmission of packets.

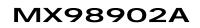
PSTART, PSTOP, CURR, BNRY, Receive Byte Counter, CLDA0 and CLDA1 are located in the receive group. They are used to initialize the Local DMA Channel for packet reception. Meanwhile, the Page Start, Page Stop, Current and Boundary Registers are also used by the Buffer Management Logic to supervise the Receive Buffer Ring.

The Remote DMA Registers are used to initialize the Remote DMA. Six registers are included: RSAR0, RSAR1, RBCR0, RBCR1, CRDA0 and CRDA1.

The diagram on the next page shows 8- and 16-bit registers. For slave mode read/write, the 16-bit internal registers are also accessed as 8-bit registers by the host. Thus, the 16-bit Transmit Byte Count Register is broken into two 8-bit registers, namely, TBCR0 and TBCR1. Similarly, Remote Start Address and Remote Byte Count are broken into RSAR0, RSAR1, and RBCR0, RBCR1. Registers TPSR, PSTART, PSTOP, CURR and BNRY only check or control the upper 8 bits of address information on the bus. Thus, they are shifted to position 15-8, as shown in the diagram on the next page.









REGISTER DESCRIPTION (Continued) J. DMA REGISTERS (Continued)

TRANSMIT DMA REGISTER (TPSR)

This register points to the page where the assembled packet is ready to be transmitted. Only the eight higher order addresses are specified since all transmit packets are assembled on 256-byte page boundaries. The bit assignment is shown below. The values placed in bits D7-D0 will be used to initialize the higher order address (A15-A8) of the Local DMA for transmission while the lower order bits (A7-A0) are initialized to zero.

BIT ASSIGNMENT

т	Ρ	S	R

	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
SR	A15	A14	A13	A12	A11	A10	A9	A8

(A7-A0 initialized to zero)

TRANSMIT BYTE COUNT REGISTER 0, 1 (TBCR0, 1)

These two registers indicate the length of the packet to be transmitted in bytes. The count must include the number of bytes in the source, destination, length and data fields (CRC field is exclusive). The maximum number of transmit bytes allowed is 64 kbytes. The ENC will not truncate transmissions whenever packet length is longer than 1500 bytes. Hence, in order to meet the IEEE 802.3 standard, software driver on upper layer must take care of maximum length problem by itself. The bit assignment is shown below:

	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
TBCR1	L15	L14	L13	L12	L11	L10	L9	L8

-	ГВС	CR	(

	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RO	L7	L6	L5	L4	L3	L2	L1	LO



REGISTER DESCRIPTION (Continued) J. DMA REGISTERS (Continued)

LOCAL DMA RECEIVE REGISTERS

PAGE START/STOP REGISTERS (PSTART, PSTOP)

The Page Start and Stop Registers program the starting and stopping page address of the Receive Buffer Ring. Since the ENC uses fixed 256-byte buffers aligned on page boundaries, only the upper eight bits of the start and stop address are specified.

PSTART, PSTOP bit assignment.

PSTART,	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PSTOP	A15	A14	A13	A12	A11	A10	A9	A8

BOUNDARY REGISTER (BNRY)

This register is used to prevent overflow of the Receive Buffer Ring. Buffer Management compares the contents of this register to the next buffer address when linking buffers together. If the contents of this register match the next buffer address, the Local DMA operation is aborted and the corresponding bit in ISR will be set.

	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	5 0
BNRY	A15	A14	A13	A12	A11	A10 BARY	A9 A15	A8 	A13
					A12	A11	A10	A9	A8

CURRENT PAGE REGISTER (CURR)

This register is used internally by the buffer management logic as a backup register for reception. CURR contains the address of the first buffer to be used for a packet reception, and is used to restore DMA pointers if receive errors occur. This register is initialized to the same value as PSTART, and should not be written to unless the controller is reset.

	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RR	A15	A14	A13	A12	A11	A10	A9	A8

CURR



J. DMA REGISTERS

again

EURRENT PAGE REGISTER (CURA)(CLDA0, 1)

The temporary local DMA address will be stored in these This cases of the used internal serves the putter. Manageonento Legitanse a backup of guist calles receptionse toure contains the address to the cliest buffeetto (be used for a tracket are controns, fand is Used to restore DMA pointers if receive errors occur. This register is initialized to the same value as PSTART. and ishould not be written to it

These two registers can be accessed to determine the current local DMA address.

as PSTART, a	an e lisho	<u>uldBnott</u>	e writter	1 10 8it 4	Bit 3	Bit 2	Bit 1	Bit 0
unless the co	ntroller	is rese t.	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
CLDA1	A15	A14	A13	A12	A11	A10	A9	A8

	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
CLDA0	A7	A6	A5	A4	A3	A2	A1	A0

REMOTE DMA REGISTER

REMOTE START ADDRESS REGISTERS (RSAR0, 1)

Remote DMA operations are programmed through the Remote Start Address (PSAR0, 1) and Remote Byte Count (RBCR0, 1) registers. The Remote Start Address is used to point to the start of the block of data to be transferred, while the Remote Byte Count is used to indicate the length of the block (in bytes)

	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RSAR1	A15	A14	A13	A12	A11	A10	A9	A8

	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RSAR0	A7	A6	A5	A4	A3	A2	A1	A0





J. DMA REGISTER (Continued)

REMOTE DMA REGISTERS (RBCR0, 1)

DEMOTE START				D O							
REMOTE START (RSAR0, 1)	ADDF Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0			
RBCR1	BC15		BC13	BC12	BC11	BC10	BC9	BC8			
Remote DMA ope	erations	s are pr	'ogramn '	1ed 🚽		1					
through the Remote Start Address (PSAR0, 1)											
and Remote Byte (The Remote Start A	Count (I	PBCR0, 1 Bit 6	I) registe	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0			
The Remote Start A	ddress i	s used to	point to	the							
start of the keock of					BC3	BC2	BC1	BC0			
the Remote Byte C	ount is	used to	indicate	the							
length of the block											

Note:

- RSAR1 programs the start address bits A8-A15
- RSAR0 programs the start address bits A0-A7
- Address incremented by two for word transfers, and by one for byte transfers
- RBCR1 programs MSB byte count
- RBCR0 programs LSB byte count
- Byte count decremented by two for word transfers, and by one for byte transfers

CURRENT REMOTE DMA ADDRESS (CRDA0, 1)

The Current Remote DMA Registers contain the current address of the Remote DMA. CRDA1/0 are similar to CLDA1/0 except that CRDA1/0 store the temporary ad-

dress of the Remote DMA. The bit assignment is shown below:

	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
CRDA1	A15	A14	A13	A12	A11	A10	A9	A8

	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
CRDA0	A7	A6	A5	A4	A3	A2	A1	A0



J.. DMA REGISTER (Continued)

FIFO CURRENT REMOTE DMA ADDRESS (CRDA0, 1)

This is an 8-bit register which allows the CPU to examine The Guerest Remote DMA Registers pontaino the concentradares saud the Remote DMAth CROAd (9) are similar to CLDA1/0 except that CRDA1/0 store the temporary address of the Remote DMA. The bit assignment is shown below: packet. Sequential reads from the FIFO will advance a pointer in the FIFO automatically and reading of all 8 bytes.

The bit assig	nment i	s shown	below:	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
FIFO	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0

Note: The FIFO should only be read when the ENC has been programmed in the loopback mode.