
HB56H164EJ Series

1,048,576-word $\times$ 64-bit High Density Dynamic RAM Module

HITACHI

ADE-203-697A(Z)

Rev. 1.0

Dec. 27, 1996

Description

The HB56H164EJ belongs to 8 Byte DIMM (Dual In-line Memory Module) family, and has been developed as an optimized main memory solution for 4 and 8 Byte processor applications. The HB56H164EJ is a $1\text{M} \times 64$ dynamic RAM module, mounted 4 pieces of 16-Mbit DRAM (HM5118165) sealed in SOJ package and 2 pieces of 16-bit BiCMOS line driver (74ABT16244) sealed in TSSOP package. The HB56H164EJ offers Extended Data Out (EDO) Page Mode as a high speed access mode. An outline of the HB56H164EJ is 168-pin socket type package (dual lead out). Therefore, the HB56H164EJ makes high density mounting possible without surface mount technology. The HB56H164EJ provides common data inputs and outputs. Decoupling capacitors are mounted on the module board.

Features

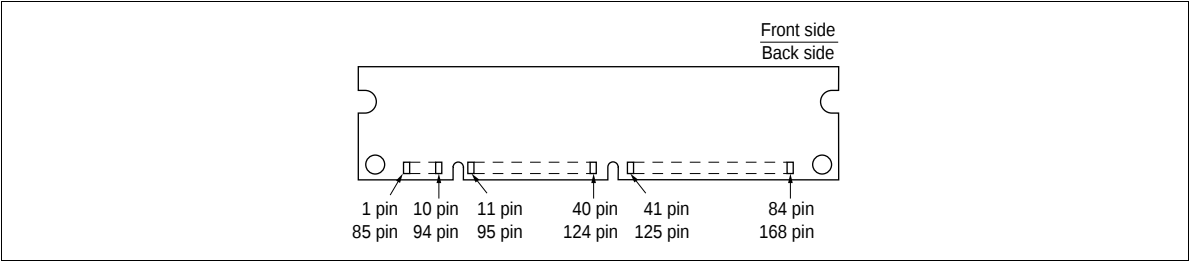
- 168-pin socket type package (Dual lead out)
 - Outline: 133.35 mm (Length) $\times$ 25.40 mm (Height) $\times$ 9.00 mm (Thickness)
 - Lead pitch: 1.27 mm
- Single 5 V ($\pm 5\%$) supply
- High speed
 - Access time: $t_{\text{RAC}} = 60/70$ ns (max)
 - $t_{\text{CAC}} = 20/23$ ns (max)
- Low power dissipation
 - Active mode: 3.906/3.486 W (max)
 - Standby mode (TTL): 378 mW (max)
 - (CMOS): 357 mW (max)
- Buffered input except $\overline{\text{RAS}}$ and DQ
- 4 byte interleave enabled, dual address input (A0/B0)
- JEDEC standard outline buffered 8-byte DIMM
- EDO page mode capability
- 1,024 refresh cycles: 16 ms
- 2 variations of refresh
 - $\overline{\text{RAS}}$ -only refresh
 - $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ refresh
- TTL compatible

HB56H164EJ Series

Ordering Information

Type No.	Access time	Package	Contact pad
HB56H164EJ-6	60 ns	168-pin dual lead out socket type	Gold
HB56H164EJ-7	70 ns		

Pin Arrangement



Pin Arrangement

Pin No.	Pin name	Pin No.	Pin name	Pin No.	Pin name	Pin No.	Pin name
1	V _{SS}	43	V _{SS}	85	V _{SS}	127	V _{SS}
2	DQ0	44	$\overline{\text{OE2}}$	86	DQ36	128	NC
3	DQ1	45	$\overline{\text{RE2}}$	87	DQ37	129	NC
4	DQ2	46	$\overline{\text{CE4}}$	88	DQ38	130	$\overline{\text{CE5}}$
5	DQ3	47	$\overline{\text{CE6}}$	89	DQ39	131	$\overline{\text{CE7}}$
6	V _{CC}	48	$\overline{\text{WE2}}$	90	V _{CC}	132	$\overline{\text{PDE}}$
7	DQ4	49	V _{CC}	91	DQ40	133	V _{CC}
8	DQ5	50	NC	92	DQ41	134	NC
9	DQ6	51	NC	93	DQ42	135	NC
10	DQ7	52	DQ18	94	DQ43	136	DQ54
11	NC	53	DQ19	95	NC	137	DQ55
12	V _{SS}	54	V _{SS}	96	V _{SS}	138	V _{SS}
13	DQ9	55	DQ20	97	DQ45	139	DQ56
14	DQ10	56	DQ21	98	DQ46	140	DQ57
15	DQ11	57	DQ22	99	DQ47	141	DQ58
16	DQ12	58	DQ23	100	DQ48	142	DQ59
17	DQ13	59	V _{CC}	101	DQ49	143	V _{CC}
18	V _{CC}	60	DQ24	102	V _{CC}	144	DQ60
19	DQ14	61	NC	103	DQ50	145	NC
20	DQ15	62	NC	104	DQ51	146	NC
21	DQ16	63	NC	105	DQ52	147	NC
22	NC	64	NC	106	NC	148	NC
23	V _{SS}	65	DQ25	107	V _{SS}	149	DQ61
24	NC	66	NC	108	NC	150	NC
25	NC	67	DQ27	109	NC	151	DQ63
26	V _{CC}	68	V _{SS}	110	V _{CC}	152	V _{SS}
27	$\overline{\text{WE0}}$	69	DQ28	111	NC	153	DQ64
28	$\overline{\text{CE0}}$	70	DQ29	112	$\overline{\text{CE1}}$	154	DQ65
29	$\overline{\text{CE2}}$	71	DQ30	113	$\overline{\text{CE3}}$	155	DQ66
30	$\overline{\text{RE0}}$	72	DQ31	114	NC	156	DQ67
31	$\overline{\text{OE0}}$	73	V _{CC}	115	NC	157	V _{CC}
32	V _{SS}	74	DQ32	116	V _{SS}	158	DQ68
33	A0	75	DQ33	117	A1	159	DQ69
34	A2	76	DQ34	118	A3	160	DQ70

HB56H164EJ Series

Pin No.	Pin name	Pin No.	Pin name	Pin No.	Pin name	Pin No.	Pin name
35	A4	77	NC	119	A5	161	NC
36	A6	78	V _{SS}	120	A7	162	V _{SS}
37	A8	79	PD1	121	A9	163	PD2
38	NC	80	PD3	122	NC	164	PD4
39	NC	81	PD5	123	NC	165	PD6
40	V _{CC}	82	PD7	124	V _{CC}	166	PD8
41	NC	83	ID0 (V _{SS})	125	NC	167	ID1 (V _{SS})
42	NC	84	V _{CC}	126	B0	168	V _{CC}

Pin Description

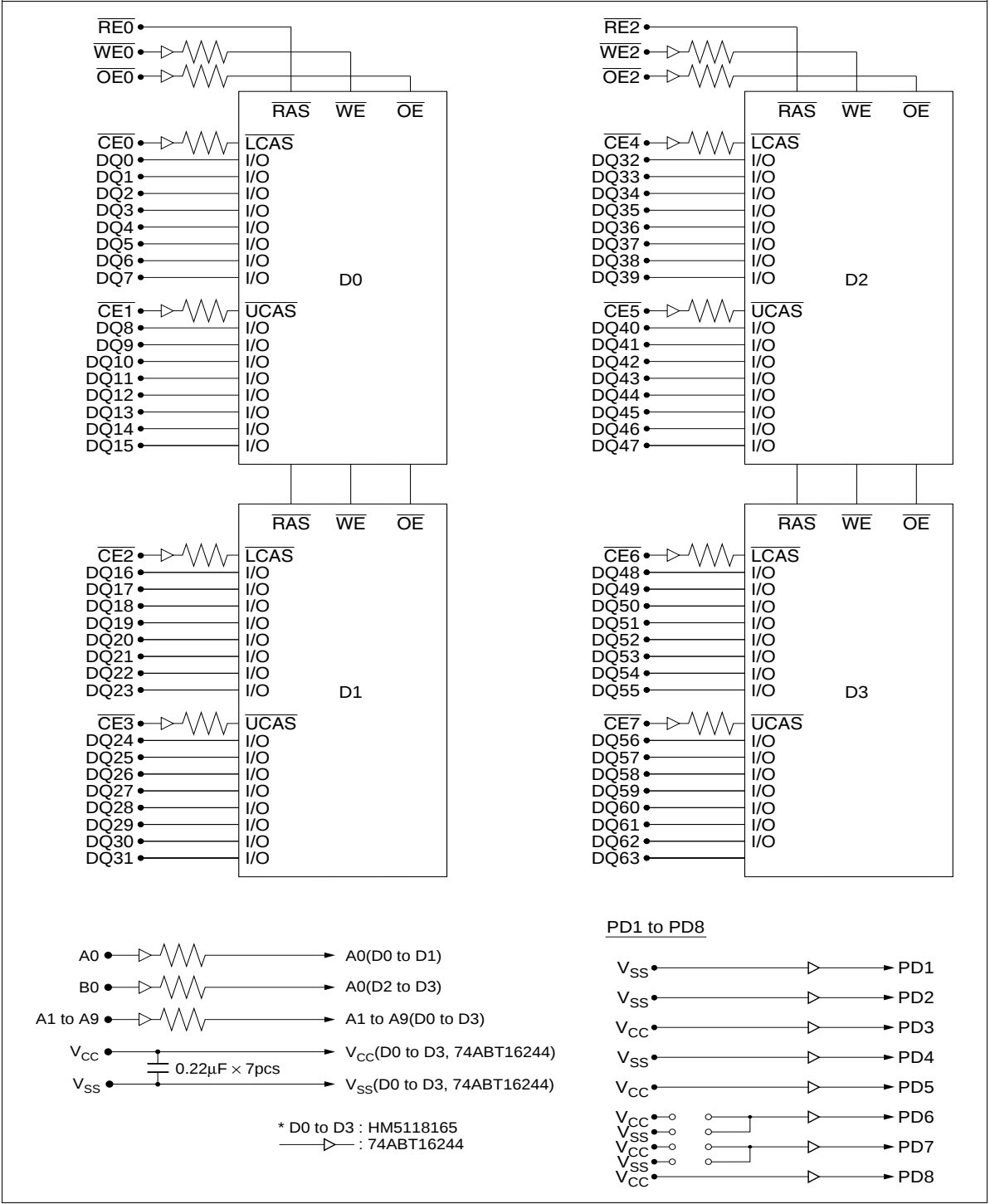
Pin name	Function
A0 to A9, B0	Address input — Row address : A0 to A9, B0 — Column address : A0 to A9, B0 — Refresh address : A0 to A9, B0
DQ0 to DQ7, DQ9 to DQ16, DQ18 to DQ25, DQ27 to DQ34, DQ36 to DQ43, DQ45 to DQ52, DQ54 to DQ61, DQ63 to DQ70	Data-in/data-out
RE0, RE2	Row address strobe ($\overline{\text{RAS}}$)
CE0 to CE7	Column address strobe ($\overline{\text{CAS}}$)
WE0, WE2	Read/Write enable
OE0, OE2	Output enable
V _{CC}	Power supply
V _{SS}	Ground
PD1 to PD8	Presence detect
ID0, ID1	ID bit
PDE	Presence detect enable
NC	No connection

Presence Detect Pin Assignment

Pin name	Pin No.	$\overline{\text{PDE}}$ = Low		$\overline{\text{PDE}}$ = High
		60 ns	70 ns	All
PD1	79	0	0	High-Z
PD2	163	0	0	High-Z
PD3	80	1	1	High-Z
PD4	164	0	0	High-Z
PD5	81	1	1	High-Z
PD6	165	1	0	High-Z
PD7	82	1	1	High-Z
PD8	166	1	1	High-Z

Note: 1: High level (Driver output)
0: Low level (Driver output)

Block Diagram



Absolute Maximum Ratings

Parameter	Symbol	Value	Unit
Voltage on any pin relative to V_{SS}	V_T	−0.5 to +7.0	V
Supply voltage relative to V_{SS}	V_{CC}	−0.5 to +7.0	V
Short circuit output current	I_{out}	50	mA
Power dissipation	P_t	5	W
Operating temperature	T_{opr}	0 to +70	°C
Storage temperature	T_{stg}	−55 to +125	°C

Recommended DC Operating Conditions ($T_a = 0$ to 70°C)

Parameter	Symbol	Min	Typ	Max	Unit	Note
Supply voltage	V_{SS}	0	0	0	V	
	V_{CC}	4.75	5.0	5.25	V	1
Input high voltage	V_{IH}	2.4	—	5.5	V	1
Input low voltage	V_{IL}	−0.5	—	0.8	V	1

Note: 1. All voltage referenced to V_{SS} .

DC Characteristics (Ta = 0 to 70°C, V_{CC} = 5 V ± 5%, V_{SS} = 0 V)

Parameter	Symbol	60 ns		70 ns		Unit	Test conditions	Notes
		Min	Max	Min	Max			
Operating current	I _{CC1}	—	744	—	664	mA	t _{RC} = min	1, 2
Standby current	I _{CC2}	—	72	—	72	mA	TTL interface RAS, CAS = V _{IH} Dout = High-Z	
		—	68	—	68	mA	CMOS interface RAS, CAS ≥ V _{CC} − 0.2 V Dout = High-Z	
RAS-only refresh current	I _{CC3}	—	744	—	664	mA	t _{RC} = min	2
Standby current	I _{CC5}	—	84	—	84	mA	RAS = V _{IH} , CAS = V _{IL} Dout = enable	1
CAS-before-RAS refresh current	I _{CC6}	—	744	—	664	mA	t _{RC} = min	
EDO page mode current	I _{CC7}	—	804	—	724	mA	t _{HPC} = min	1, 3
Input leakage current	I _{LI}	−10	10	−10	10	μA	0 V ≤ Vin ≤ 5.5 V	
Output leakage current	I _{LO}	−10	10	−10	10	μA	0 V ≤ Vout ≤ 5.5 V Dout = disable	
Output high voltage	V _{OH}	2.4	V _{CC}	2.4	V _{CC}	V	High Iout = −2 mA	
Output low voltage	V _{OL}	0	0.4	0	0.4	V	Low Iout = 2 mA	

Notes: 1. I_{CC} depends on output load condition when the device is selected, I_{CC} max is specified at the output open condition.
2. Address can be changed once or less while RAS = V_{IL}.
3. Address can be changed once or less while CAS = V_{IH}.

Capacitance (Ta = 25°C, V_{CC} = 5 V ± 5%)

Parameter	Symbol	Typ	Max	Unit	Notes
Input capacitance (Address)	C _{I1}	—	20	pF	1
Input capacitance (CAS, WE, OE)	C _{I2}	—	20	pF	1
Input capacitance (RAS)	C _{I3}	—	29	pF	1
I/O capacitance (DQ)	C _{I/O}	—	20	pF	1, 2

Notes: 1. Capacitance measured with Boonton Meter or effective capacitance measuring method.
2. CAS = V_{IH} to disable Dout.

AC Characteristics ($T_a = 0 \text{ to } 70^\circ\text{C}$, $V_{CC} = 5 \text{ V} \pm 5\%$, $V_{SS} = 0 \text{ V}$)^{*1, *2, *18, *19}**Test Conditions**

- Input rise and fall times: 2 ns
- Input levels: 0 V, 3.0 V
- Input timing reference levels: 0.8 V, 2.4 V
- Output timing reference levels: 0.8 V, 2.0 V
- Output load: 1 TTL gate + C_L (100 pF) (Including scope and jig)

Read, Write, Read-Modify-Write and Refresh Cycles (Common parameters)

Parameter	Symbol	60 ns		70 ns		Unit	Notes
		Min	Max	Min	Max		
Random read or write cycle time	t_{RC}	104	—	124	—	ns	
$\overline{RAS}$ precharge time	t_{RP}	40	—	50	—	ns	
$\overline{CAS}$ precharge time	t_{CP}	10	—	13	—	ns	
$\overline{RAS}$ pulse width	t_{RAS}	60	10000	70	10000	ns	
$\overline{CAS}$ pulse width	t_{CAS}	10	10000	13	10000	ns	
Row address setup time	t_{ASR}	5	—	5	—	ns	
Row address hold time	t_{RAH}	10	—	10	—	ns	
Column address setup time	t_{ASC}	0	—	0	—	ns	
Column address hold time	t_{CAH}	10	—	13	—	ns	
$\overline{RAS}$ to $\overline{CAS}$ delay time	t_{RCD}	20	40	20	47	ns	3
$\overline{RAS}$ to column address delay time	t_{RAD}	15	25	15	30	ns	4
$\overline{RAS}$ hold time	t_{RSH}	20	—	23	—	ns	
$\overline{CAS}$ hold time	t_{CSH}	40	—	45	—	ns	
$\overline{CAS}$ to $\overline{RAS}$ precharge time	t_{CRP}	10	—	10	—	ns	
$\overline{OE}$ to Din delay time	t_{OED}	20	—	23	—	ns	5
$\overline{OE}$ delay time from Din	t_{DZO}	0	—	0	—	ns	6
$\overline{CAS}$ delay time from Din	t_{DZC}	0	—	0	—	ns	6
Transition time (rise and fall)	t_T	2	50	2	50	ns	7
Refresh period (1,024 cycles)	t_{REF}	—	16	—	16	ms	

Read Cycle

Parameter	Symbol	60 ns		70 ns		Unit	Notes
		Min	Max	Min	Max		
Access time from $\overline{\text{RAS}}$	t_{RAC}	—	60	—	70	ns	8, 9
Access time from $\overline{\text{CAS}}$	t_{CAC}	—	20	—	23	ns	9, 10, 17
Access time from address	t_{AA}	—	35	—	40	ns	9, 11, 17
Access time from $\overline{\text{OE}}$	t_{OEA}	—	20	—	23	ns	9, 21
Read command setup time	t_{RCS}	0	—	0	—	ns	
Read command hold time to $\overline{\text{CAS}}$	t_{RCH}	0	—	0	—	ns	12
Read command hold time from $\overline{\text{RAS}}$	t_{RCHR}	60	—	70	—	ns	
Read command hold time to $\overline{\text{RAS}}$	t_{RRH}	5	—	5	—	ns	12
Column address to $\overline{\text{RAS}}$ lead time	t_{RAL}	35	—	40	—	ns	
Column address to $\overline{\text{CAS}}$ lead time	t_{CAL}	18	—	23	—	ns	
$\overline{\text{CAS}}$ to output in low-Z	t_{CLZ}	2	—	2	—	ns	
Output data hold time	t_{OH}	3	—	3	—	ns	22
Output data hold time from $\overline{\text{OE}}$	t_{OHO}	3	—	3	—	ns	
Output buffer turn-off time	t_{OFF}	—	20	—	20	ns	13, 22
Output buffer turn-off to $\overline{\text{OE}}$	t_{OEZ}	—	20	—	20	ns	13
$\overline{\text{CAS}}$ to Din delay time	t_{CDD}	20	—	23	—	ns	5
Output data hold time from $\overline{\text{RAS}}$	t_{OHR}	3	—	3	—	ns	22
Output buffer turn-off time to $\overline{\text{RAS}}$	t_{OFR}	—	15	—	15	ns	22
Output buffer turn-off to $\overline{\text{WE}}$	t_{WEZ}	—	20	—	20	ns	
$\overline{\text{WE}}$ to Din delay time	t_{WED}	20	—	23	—	ns	
$\overline{\text{RAS}}$ to Din delay time	t_{RDD}	15	—	18	—	ns	
$\overline{\text{RAS}}$ next $\overline{\text{CAS}}$ delay time	t_{RNCD}	60	—	70	—	ns	

Write Cycle

Parameter	Symbol	60 ns		70 ns		Unit	Notes
		Min	Max	Min	Max		
Write command setup time	t_{WCS}	0	—	0	—	ns	14
Write command hold time	t_{WCH}	10	—	13	—	ns	
Write command pulse width	t_{WP}	10	—	10	—	ns	
Write command to $\overline{RAS}$ lead time	t_{RWL}	15	—	18	—	ns	
Write command to $\overline{CAS}$ lead time	t_{CWL}	10	—	13	—	ns	
Data-in setup time	t_{DS}	0	—	0	—	ns	15
Data-in hold time	t_{DH}	15	—	18	—	ns	15

Read-Modify-Write Cycle

Parameter	Symbol	60 ns		70 ns		Unit	Notes
		Min	Max	Min	Max		
Read-modify-write cycle time	t_{RWC}	136	—	161	—	ns	
$\overline{RAS}$ to $\overline{WE}$ delay time	t_{RWD}	79	—	92	—	ns	14
$\overline{CAS}$ to $\overline{WE}$ delay time	t_{CWD}	34	—	40	—	ns	14
Column address to $\overline{WE}$ delay time	t_{AWD}	49	—	57	—	ns	14
$\overline{OE}$ hold time from $\overline{WE}$	t_{OEh}	15	—	18	—	ns	

Refresh Cycle

Parameter	Symbol	60 ns		70 ns		Unit	Notes
		Min	Max	Min	Max		
$\overline{CAS}$ setup time (CBR refresh cycle)	t_{CSR}	10	—	10	—	ns	
$\overline{CAS}$ hold time (CBR refresh cycle)	t_{CHR}	10	—	10	—	ns	
$\overline{RAS}$ precharge to $\overline{CAS}$ hold time	t_{RPC}	0	—	0	—	ns	

EDO Page Mode Cycle

Parameter	Symbol	60 ns		70 ns		Unit	Notes
		Min	Max	Min	Max		
EDO page mode cycle time	t _{HPC}	25	—	30	—	ns	20
EDO page mode RAS pulse width	t _{RASP}	—	100000	—	100000	ns	16
Access time from CAS precharge	t _{CPA}	—	40	—	45	ns	9, 17
RAS hold time from CAS precharge	t _{CPRH}	40	—	45	—	ns	
Output data hold time from CAS low	t _{DOH}	3	—	3	—	ns	9, 17
CAS hold time refferd OE	t _{COL}	10	—	13	—	ns	
CAS to OE setup time	t _{COP}	5	—	5	—	ns	
Read command hold time from CAS precharge	t _{RCHC}	35	—	40	—	ns	

EDO Page Mode Read-Modify-Write Cycle

Parameter	Symbol	60 ns		70 ns		Unit	Notes
		Min	Max	Min	Max		
EDO page mode read-modify-write cycle time	t _{HPRWC}	68	—	79	—	ns	
WE delay time from CAS precharge	t _{CPW}	54	—	62	—	ns	14

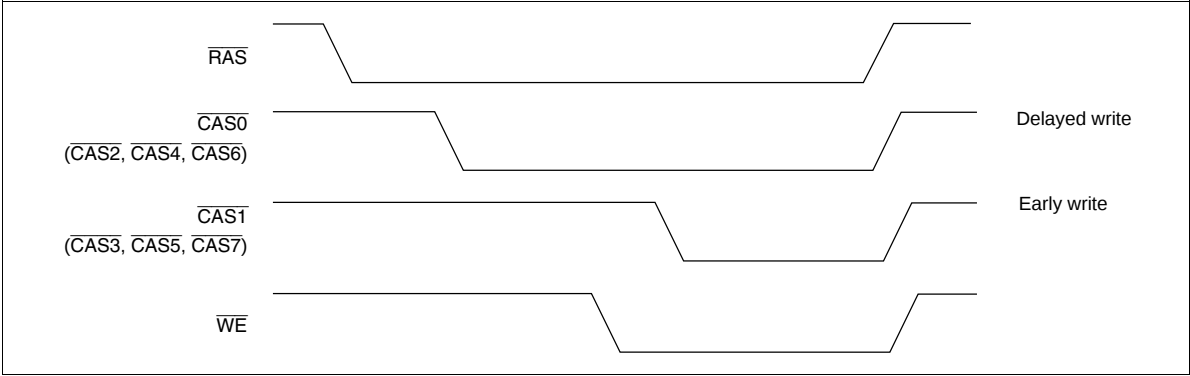
- Notes:
1. AC measurements assume t_r = 2 ns.
 2. An initial pause of 200 μs is required after power up followed by a minimum of eight initialization cycles (any combination of cycles containing RAS-only refresh cycle or CAS-before-RAS refresh). If the internal refresh counter is used, a minimum of eight CAS-before-RAS refresh cycles are required.
 3. Operation with the t_{RCD} (max) limit insures that t_{RAC} (max) can be met, t_{RCD} (max) is specified as a reference point only; if t_{RCD} ≥ t_{RAD} (max) + t_{AA} (max)- t_{CAC} (max), then access time is controlled exclusively by t_{CAC}.
 4. Operation with the t_{RAD} (max) limit insures that t_{RAC} (max) can be met, t_{RAD} (max) is specified as a reference point only; if t_{RAD} is greater than the specified t_{RAD} (max) limit, then access time is controlled exclusively by t_{AA}.
 5. Either t_{OED} or t_{CDD} must be satisfied.
 6. Either t_{DZO} or t_{DZC} must be satisfied.
 7. V_{IH} (min) and V_{IL} (max) are reference levels for measuring timing of input signals. Also, transition times are measured between V_{IH} (min) and V_{IL} (max).
 8. Assumes that t_{RCD} ≤ t_{RCD} (max) and t_{RAD} ≤ t_{RAD} (max). If t_{RCD} or t_{RAD} is greater than the maximum recommended value shown in this table, t_{RAC} exceeds the value shown.
 9. Measured with a load circuit equivalent to 1 TTL loads and 100 pF.
 10. Assumes that t_{RCD} ≥ t_{RCD} (max) and t_{RCD} + t_{CAC} (max) ≥ t_{RAD} + t_{AA} (max).
 11. Assumes that t_{RAD} ≥ t_{RAD} (max) and t_{RCD} + t_{CAC} (max) ≤ t_{RAD} + t_{AA} (max).
 12. Either t_{RCH} or t_{RRH} must be satisfied for a read cycles.
 13. t_{OFF} (max) and t_{OEZ} (max) define the time at which the outputs achieve the open circuit condition and are not referred to output voltage levels.

14. t_{WCS} , t_{RWD} , t_{CWD} , t_{AWD} , and t_{CPW} are not restrictive operating parameters. They are included in the data sheet as electrical characteristics only; if $t_{WCS} \geq t_{WCS}(\min)$, the cycle is an early write cycle and the data out pin will remain open circuit (high impedance) throughout the entire cycle; if $t_{RWD} \geq t_{RWD}(\min)$, $t_{CWD} \geq t_{CWD}(\min)$, and $t_{AWD} \geq t_{AWD}(\min)$ or $t_{CWD} \geq t_{CWD}(\min)$, $t_{AWD} \geq t_{AWD}(\min)$ and $t_{CPW} \geq t_{CPW}(\min)$, the cycle is a read-modify-write and the data output will contain data read from the selected cell; if neither of the above sets of conditions is satisfied, the condition of the data out (at access time) is indeterminate.
15. These parameters are referred to $\overline{CAS}$ leading edge in early write cycles and to $\overline{WE}$ leading edge in delayed write or read-modify-write cycles.
16. t_{RASP} defines $\overline{RAS}$ pulse width in EDO page mode cycles.
17. Access time is determined by the longest among t_{AA} , t_{CAC} and t_{CPA} .
18. In delayed write or read-modify-write cycles, $\overline{OE}$ must disable output buffer prior to applying data to the device. After $\overline{RAS}$ is reset, if $t_{OE} \geq t_{CWL}$, the DQ pin will remain open circuit (high impedance); $t_{OE} < t_{OE}$, invalid data will be out at each DQ.
19. All the V_{CC} and V_{SS} pins shall be supplied with the same voltages.
20. $t_{HPC}(\min)$ can be achieved during a series of EDO page mode write cycles or EDO page mode read cycles. If both write and read operation are mixed in a EDO page mode $\overline{RAS}$ cycle (EDO page mode mix cycle (1), (2)), minimum value of $\overline{CAS}$ cycle ($t_{CAS} + t_{CP} + 2t_T$) becomes greater than the specified $t_{HPC}(\min)$ value. The value of $\overline{CAS}$ cycle time of mixed EDO page mode is shown in EDO page mode mix cycle (1) and (2).
21. When output buffers are enabled once, sustain the low impedance state until valid data is obtained. When output buffer is turned on and off within a very short time, generally it causes large V_{CC}/V_{SS} line noise, which causes to degrade $V_{IH}(\min)/V_{IL}(\max)$ level.
22. Data output turns off and becomes high impedance from later rising edge of $\overline{RAS}$ and $\overline{CAS}$. Hold time and turn off time are specified by the timing specifications of later rising edge of $\overline{RAS}$ and $\overline{CAS}$ between t_{OHR} and t_{OH} , and between t_{OFF} and t_{OFF} .
23. XXX: H or L (H: $V_{IH}(\min) \leq V_{IN} \leq V_{IH}(\max)$, L: $V_{IL}(\min) \leq V_{IN} \leq V_{IL}(\max)$)
 //: Invalid Dout
 When the address, clock and input pins are not described on timing waveforms, their pins must be applied V_{IH} or V_{IL} .

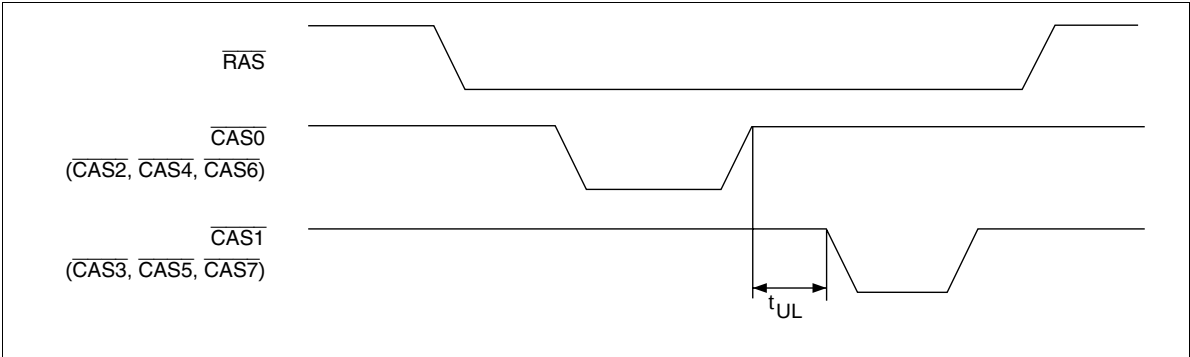
Notes concerning 2CAS control

Please do not separate the 2CASs ($\overline{\text{CAS0}}$ and $\overline{\text{CAS1}}$ (or $\overline{\text{CAS2}}$, $\overline{\text{CAS4}}$, $\overline{\text{CAS6}}$ and $\overline{\text{CAS3}}$, $\overline{\text{CAS5}}$, $\overline{\text{CAS7}}$)) operation timing intentionally. However skew between 2CASs are allowed under the following conditions.

- 1. Each of the 2CASs should satisfy the timing specifications individually.
- 2. Different operation mode for upper/lower byte is not allowed: such as following.



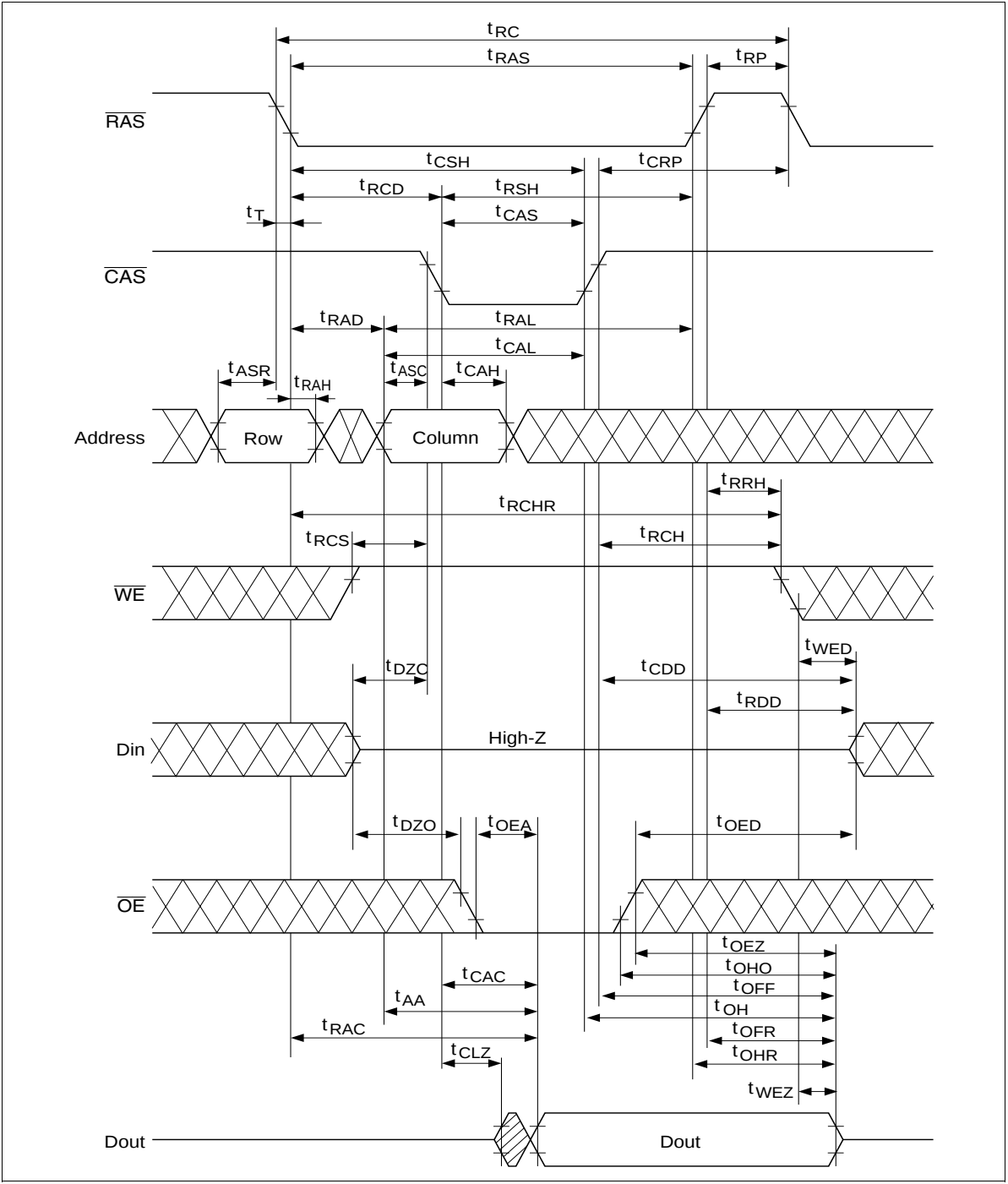
- 3. Closely separated upper/lower byte control is not allowed. However when the condition ($t_{\text{CP}} \leq t_{\text{UL}}$) is satisfied, page mode can be performed.



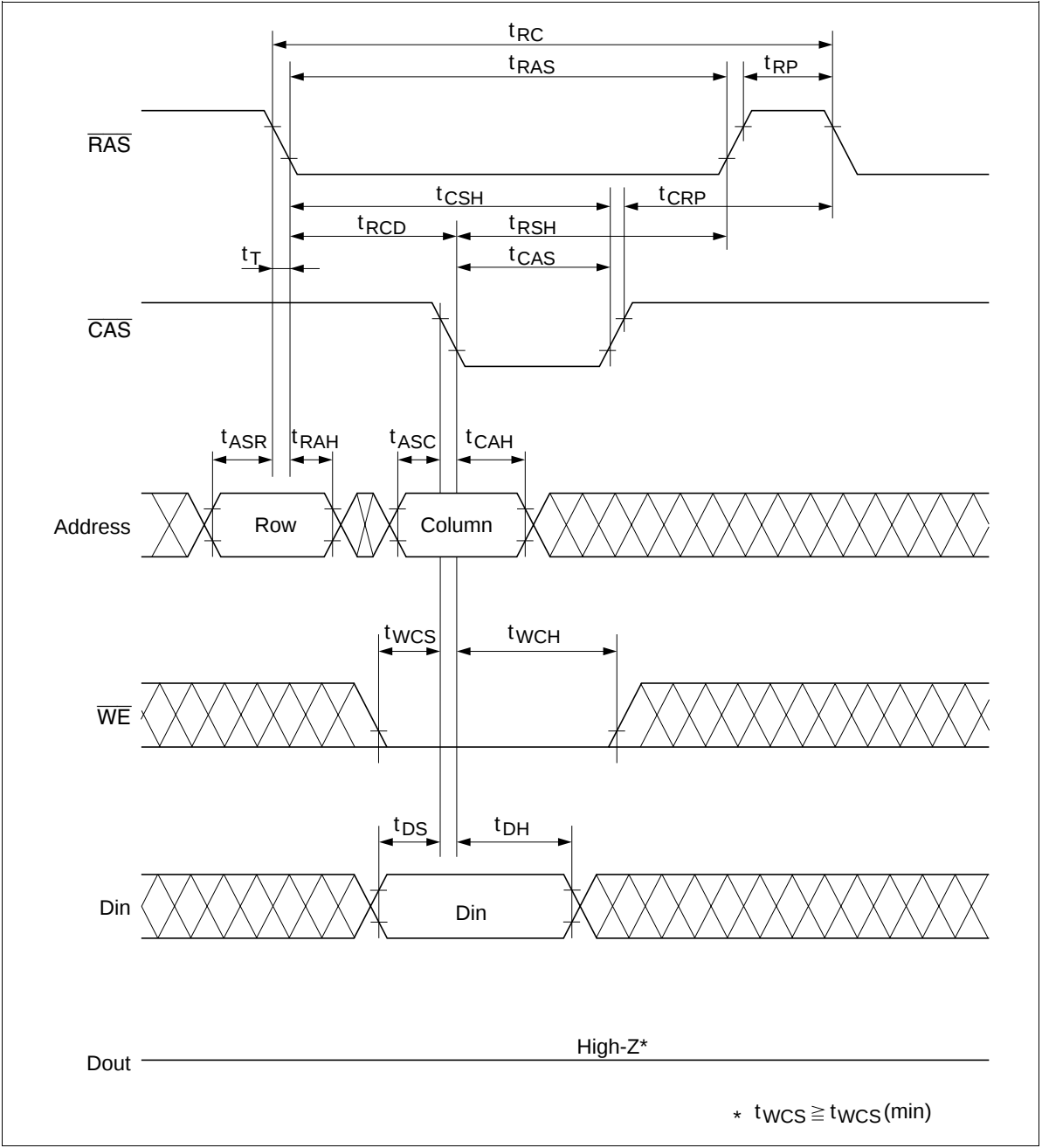
- 4. Byte control operation by remaining $\overline{\text{CAS0}}$ ($\overline{\text{CAS2}}$, $\overline{\text{CAS4}}$, $\overline{\text{CAS6}}$) or $\overline{\text{CAS1}}$ ($\overline{\text{CAS3}}$, $\overline{\text{CAS5}}$, $\overline{\text{CAS7}}$) high is guaranteed.

Timing Waveforms*23

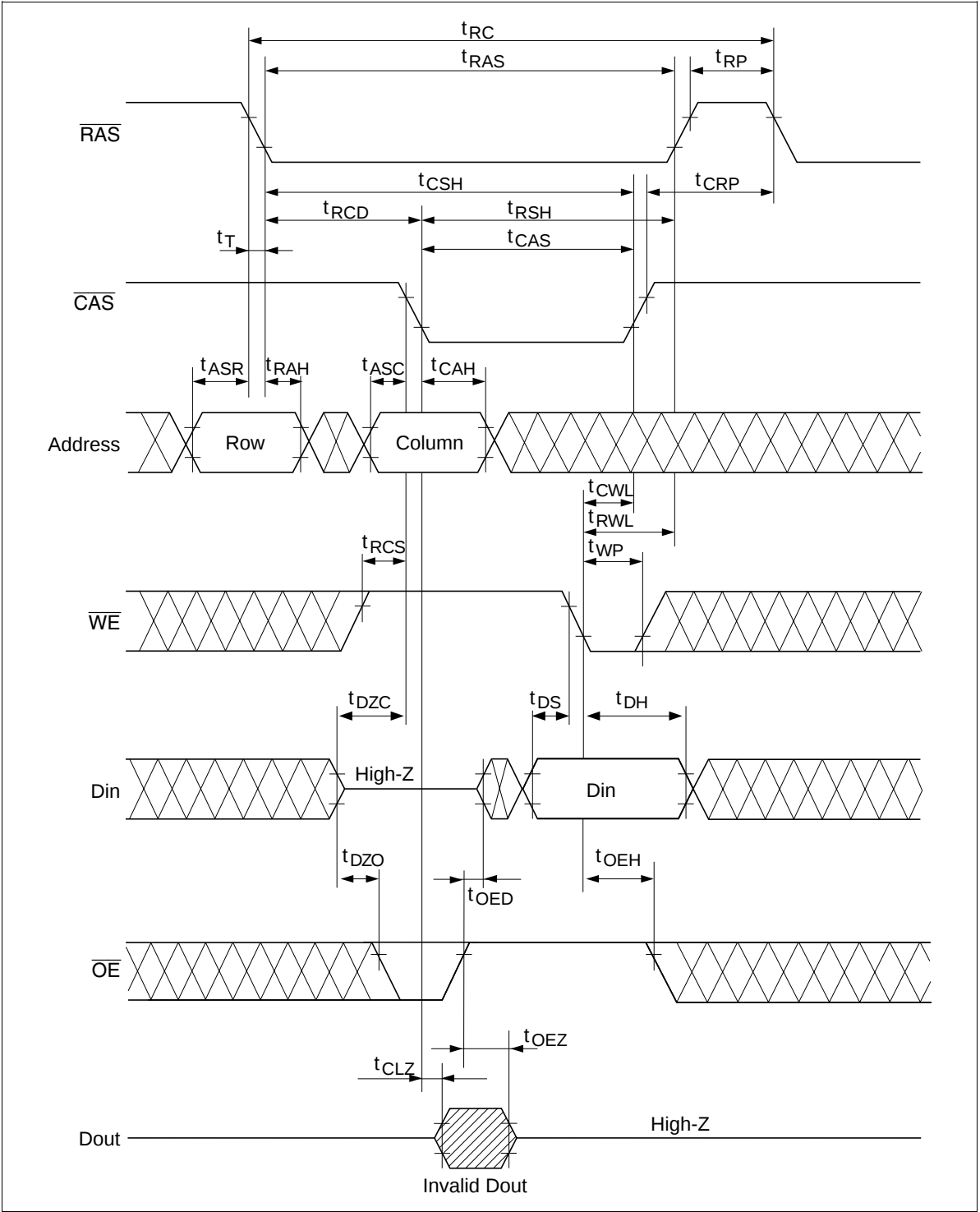
Read Cycle



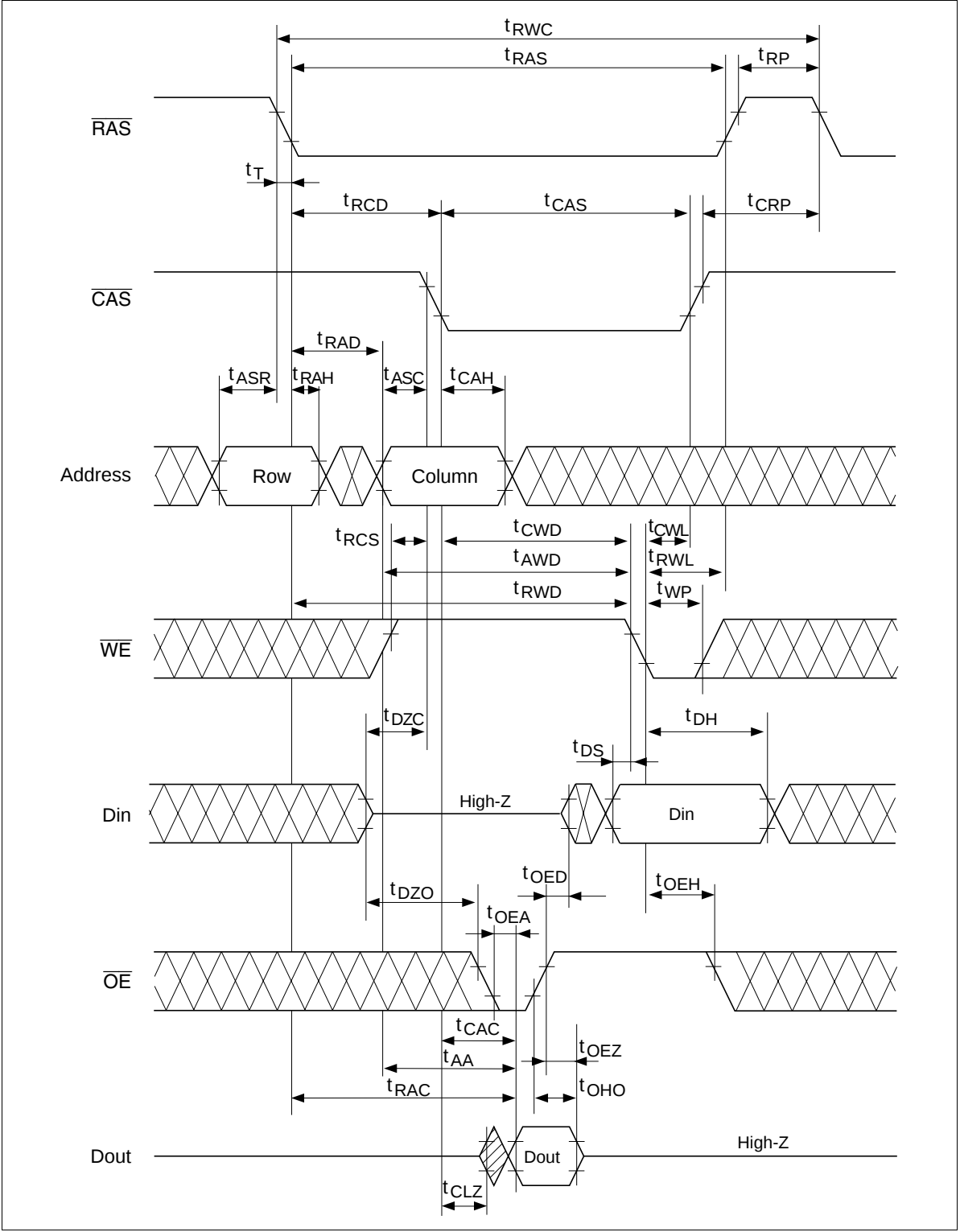
Early Write Cycle



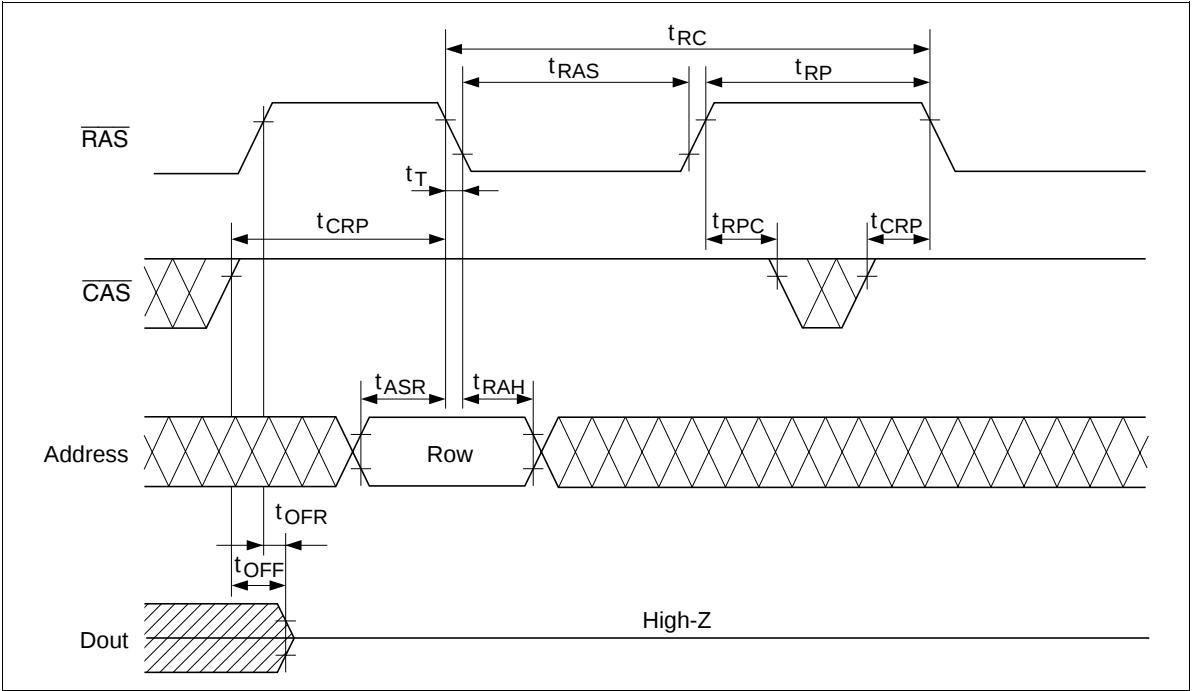
Delayed Write Cycle*18



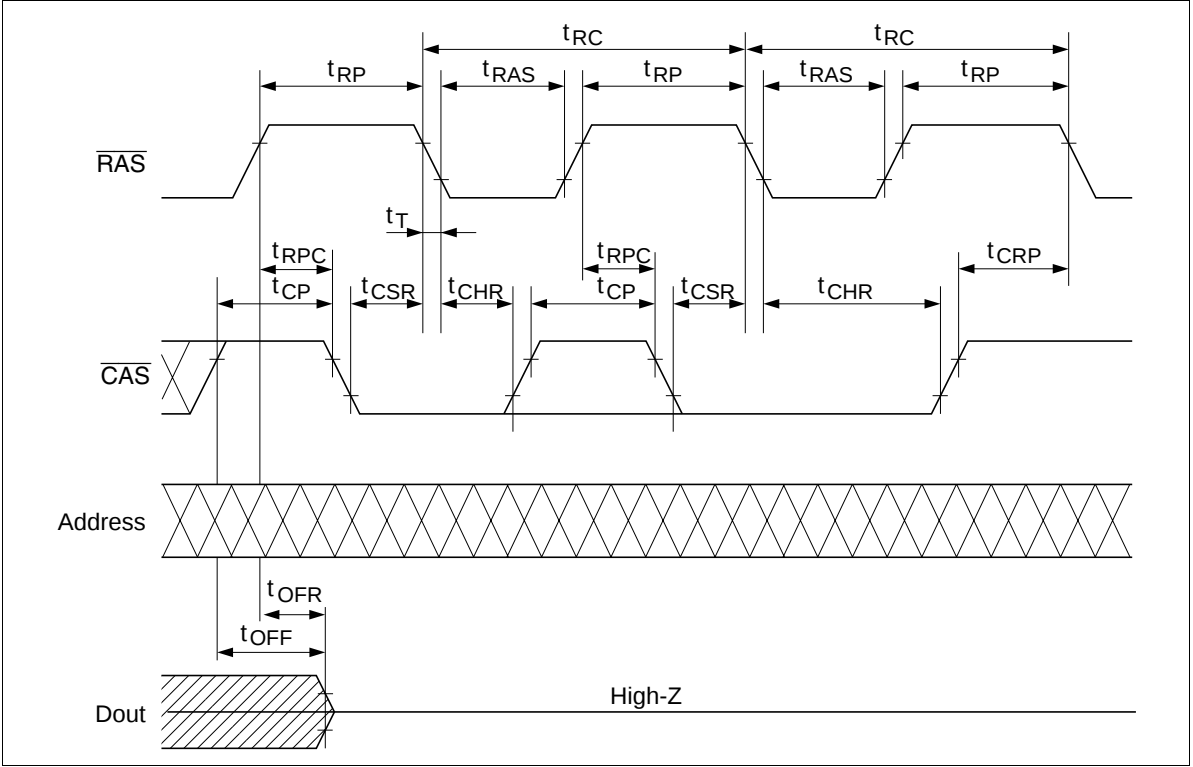
Read-Modify-Write Cycle*18



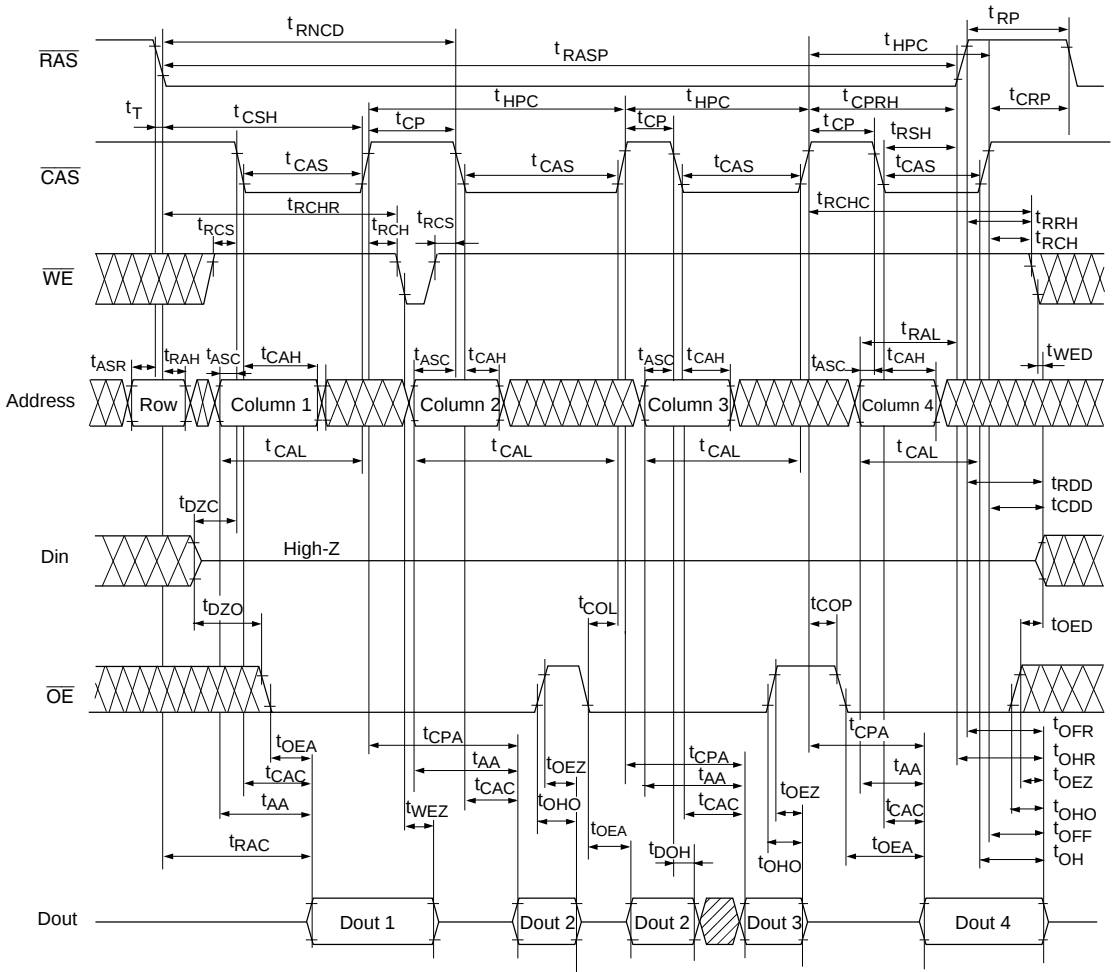
RAS-Only Refresh Cycle



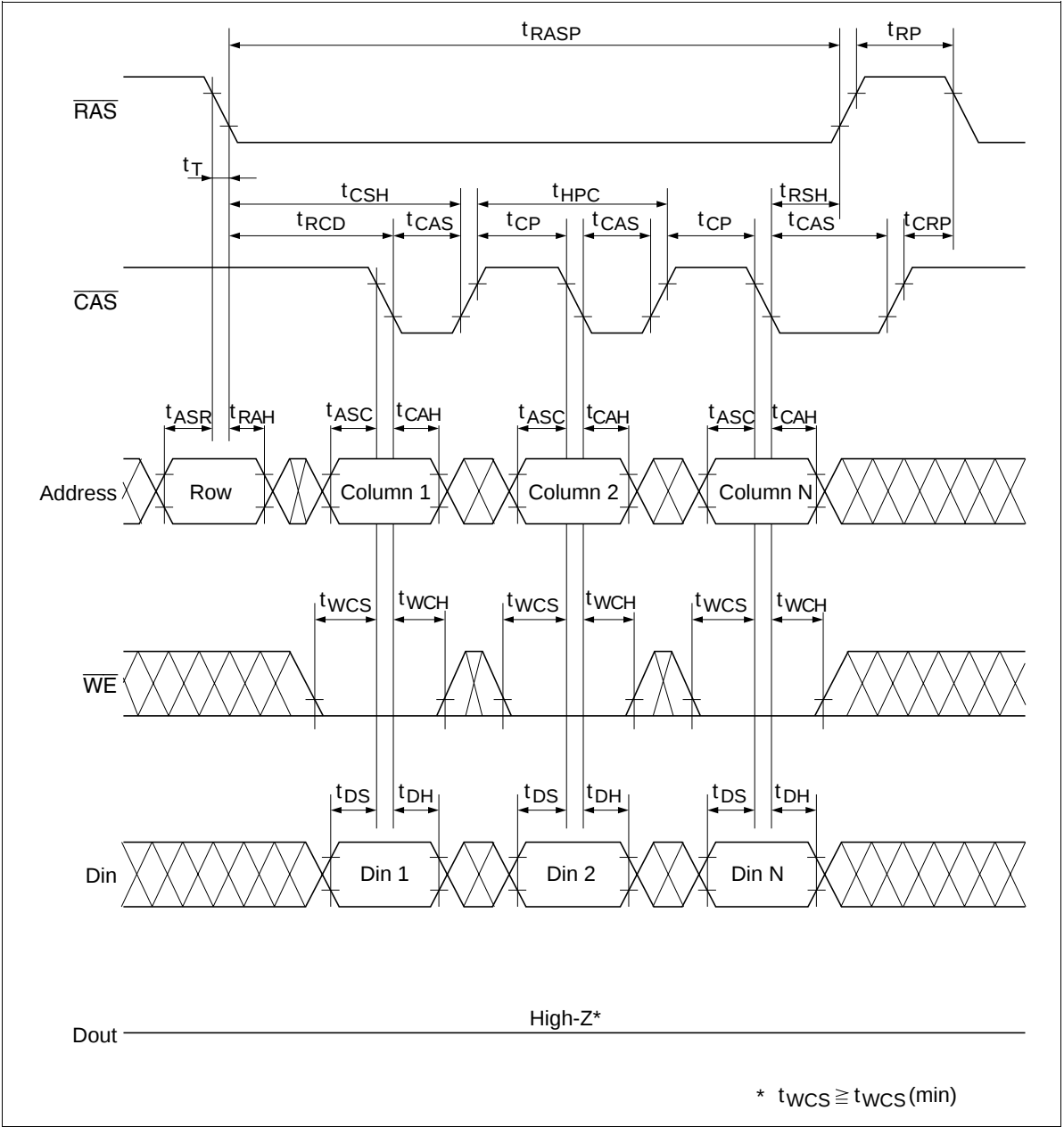
CAS-Before-RAS Refresh Cycle



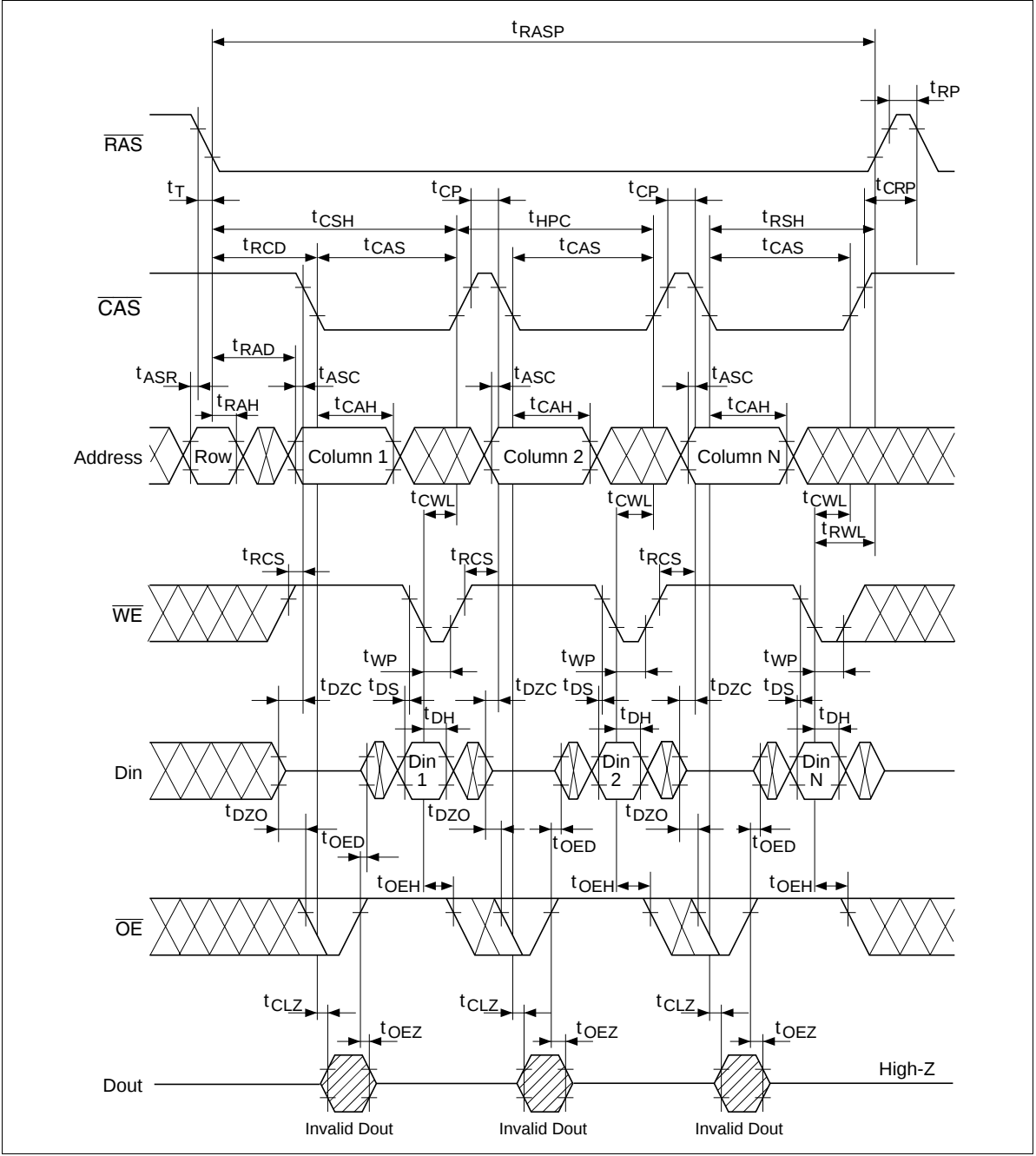
EDO Page Mode Read Cycle



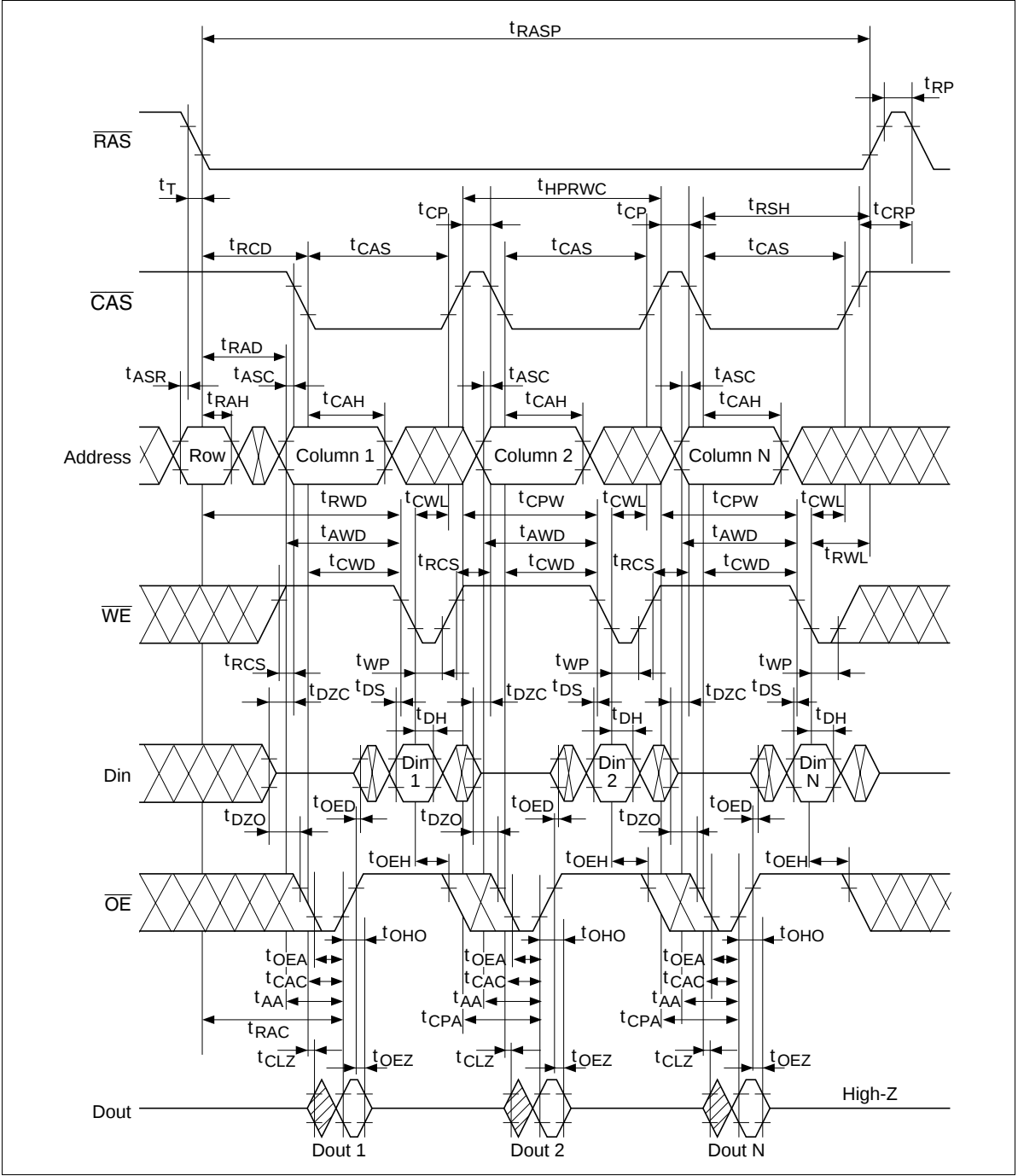
EDO Page Mode Early Write Cycle



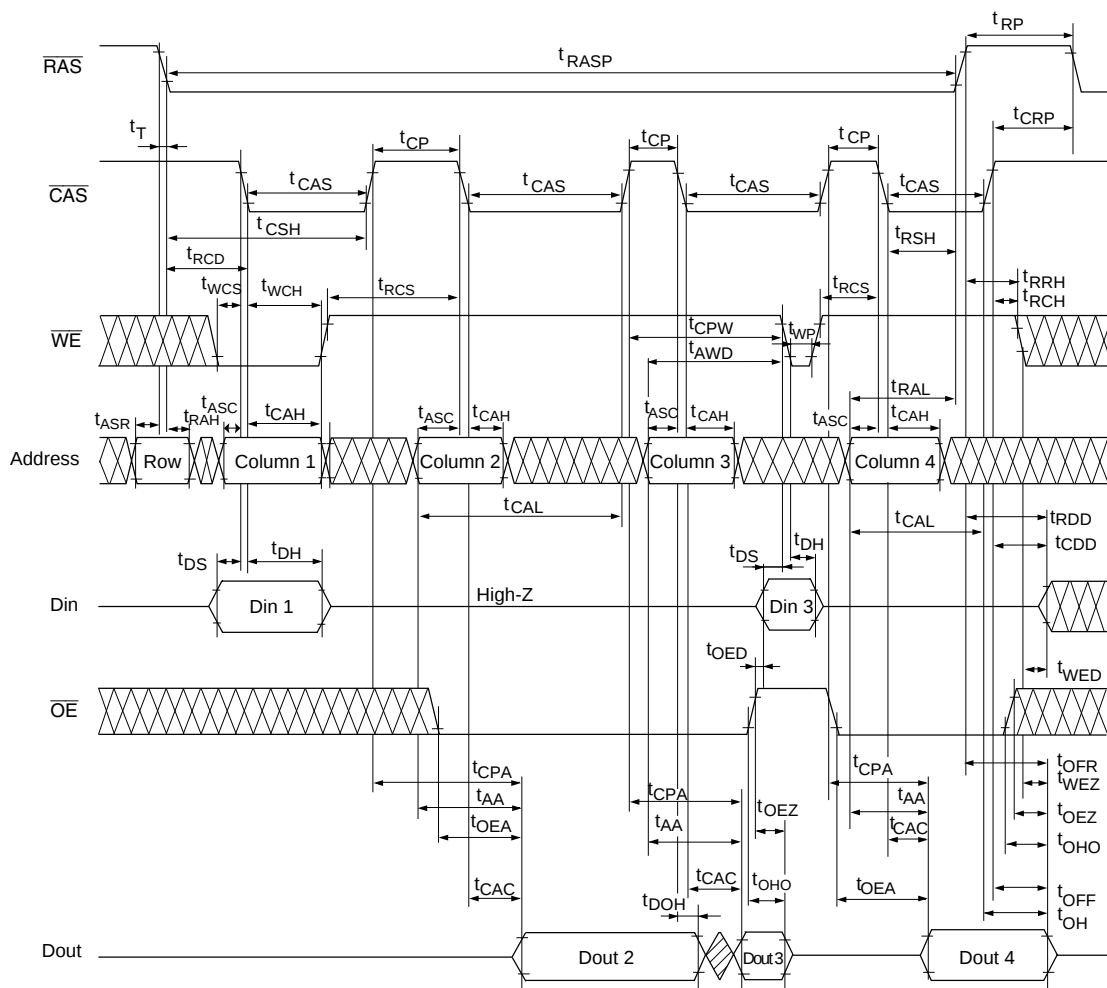
EDO Page Mode Delayed Write Cycle*18

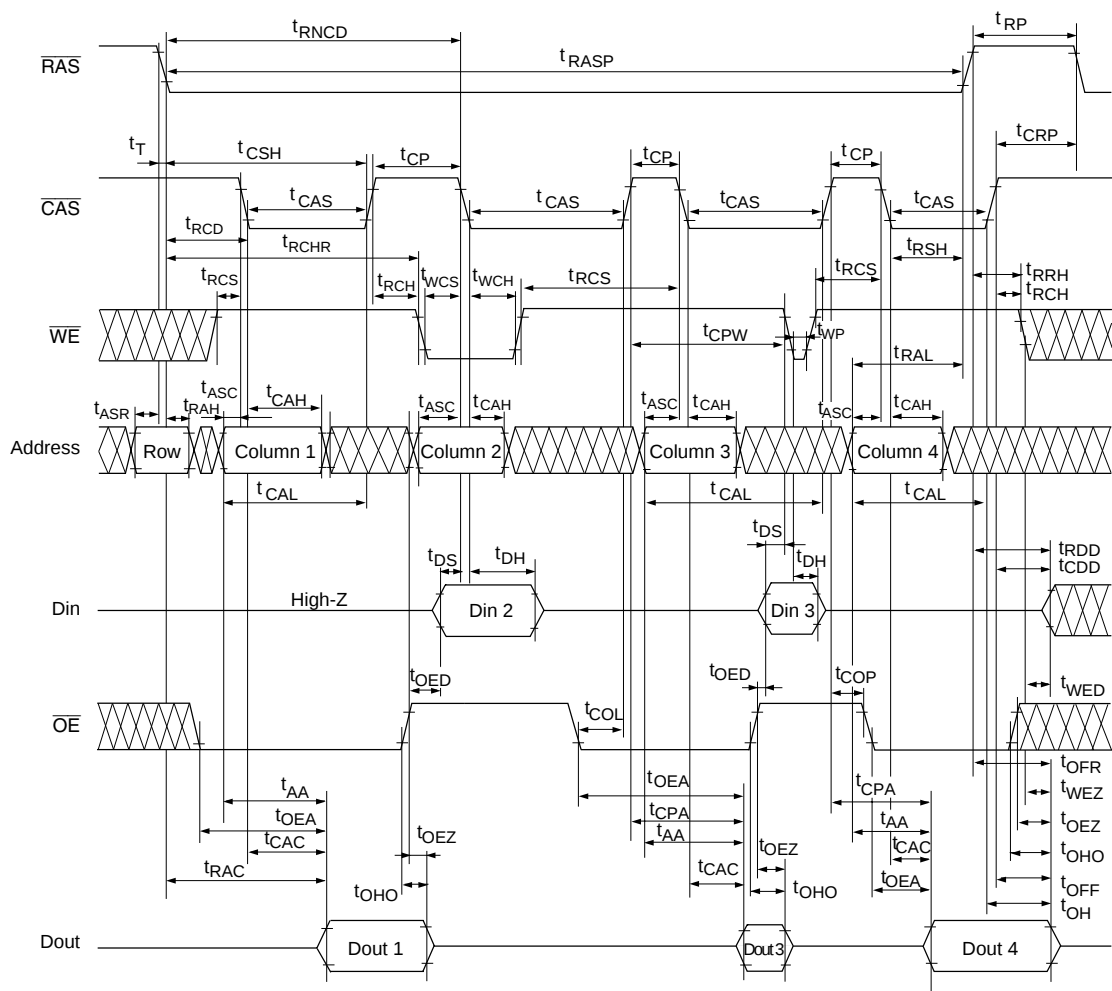


EDO Page Mode Read-Modify-Write Cycle*18



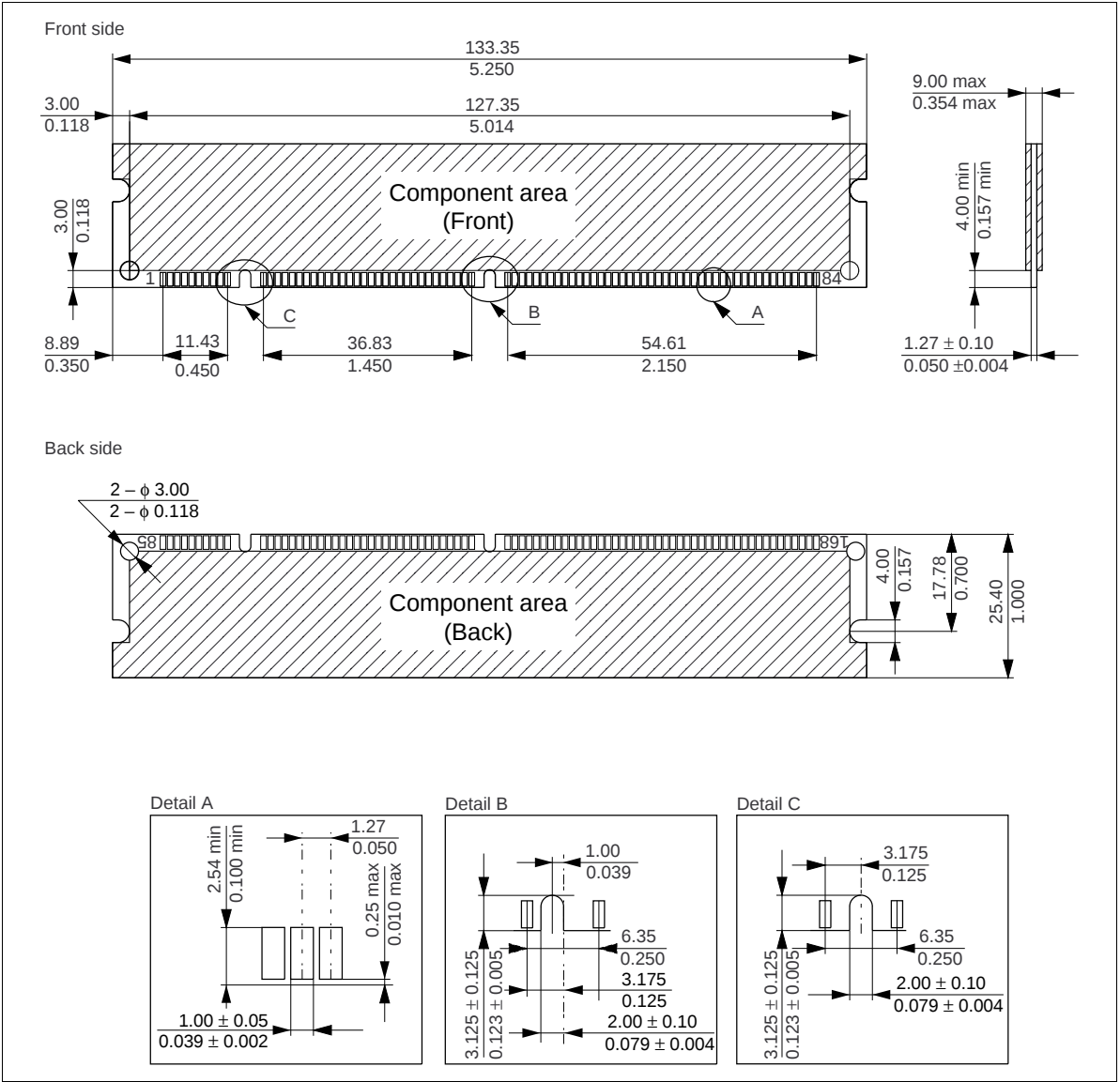
EDO Page Mode Mix Cycle (1)





Physical Outline

Unit: mm/inch



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HITACHI

Hitachi, Ltd.

Semiconductor & IC Div.
Nippon Bldg., 2-6-2, Ohte-machi, Chiyoda-ku, Tokyo 100, Japan
Tel: Tokyo (03) 3270-2111
Fax: (03) 3270-5109

For further information write to:

Hitachi America, Ltd.
Semiconductor & IC Div.
2000 Sierra Point Parkway
Brisbane, CA. 94005-1835
U S A
Tel: 415-589-8300
Fax: 415-583-4207

Hitachi Europe GmbH
Electronic Components Group
Continental Europe
Dornacher Straße 3
D-85622 Feldkirchen
München
Tel: 089-9 91 80-0
Fax: 089-9 29 30 00

Hitachi Europe Ltd.
Electronic Components Div.
Northern Europe Headquarters
Whitebrook Park
Lower Cookham Road
Maidenhead
Berkshire SL6 8YA
United Kingdom
Tel: 0628-585000
Fax: 0628-778322

Hitachi Asia Pte. Ltd.
16 Collyer Quay #20-00
Hitachi Tower
Singapore 0104
Tel: 535-2100
Fax: 535-1533

Hitachi Asia (Hong Kong) Ltd.
Unit 706, North Tower,
World Finance Centre,
Harbour City, Canton Road
Tsim Sha Tsui, Kowloon
Hong Kong
Tel: 27359218
Fax: 27306071

Revision Record

Rev.	Date	Contents of Modification	Drawn by	Approved by
1.0	Dec. 27, 1996	Initial issue		