

# XC2300

## Series

### Tri-State Buffer ICs



- ◆ CMOS Low Power Consumption
- ◆ Maximum Operating Frequency : 70MHz
- ◆ Built-In Input Amplifier
- ◆ 3-State Output
- ◆ Divider Circuit
- ◆ Mini Mold SOT-26 Package

## ■ APPLICATIONS

- VCXO modules
- Crystal oscillator modules

## ■ GENERAL DESCRIPTION

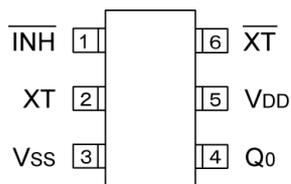
The 2300 Series are a group of high frequency, CMOS low power tri-state buffer ICs with input amplifier, divider and output tri-state buffer circuits built-in.

The series is available in an ultra small SOT-26 package.

## ■ FEATURES

<b>Max. Operating Frequency</b>	: 70MHz
<b>Operating Voltage Range</b>	: 3.3V±10%, 5.0V±20%
<b>Divider Ratio</b>	: fin/1
<b>Output</b>	: 3-State
<b>Ultra Small Package</b>	: SOT-26

## ■ PIN CONFIGURATION



SOT-26  
(TOP VIEW)

## ■ PIN ASSIGNMENT

PIN NUMBER	PIN NAME	FUNCTION
1	/INH	Stand-by Control (*)
2	XT	Clock Input
3	VSS	Ground
4	Q0	Clock Output
5	VDD	Power Supply
6	/XT	Feedback Resistor Connection (Output)

\*Stand-by control pin has a pull-up resistor built-in.

## ■ /INH, Q0 PIN FUNCTION

/INH	Q0
"H" or OPEN	Clock Output
"L"	High Impedance

## PRODUCT CLASSIFICATION

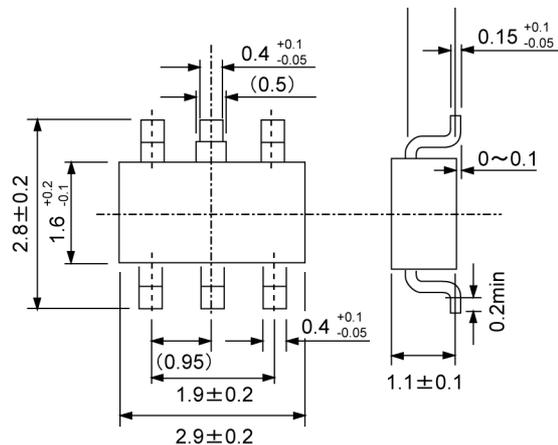
### Ordering Information

XC2300 ①②③④⑤⑥

DESTINATOR	DESCRIPTION	SIMBOL	DESCRIPTION
①	Duty Level	C	: CMOS (V <sub>DD</sub> /2)
②	Fixed Number	2	: -
③	Divider Ratio	1	: Q0=fin/1
④	Output	V	: Tri-state buffer
⑤	Package	M	: SOT-26
⑥	Device Orientation	R	: Embossed tape, standard feed
		L	: Embossed tape, reverse feed

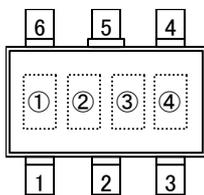
## PACKAGING INFORMATION

### SOT-26



## MARKING RULE

### SOT-26



SOT-26  
(TOP VIEW)

① Represents product series

MARK	PRODUCT SERIES
0	XC2300xxxxxx

② Represents divider ratio

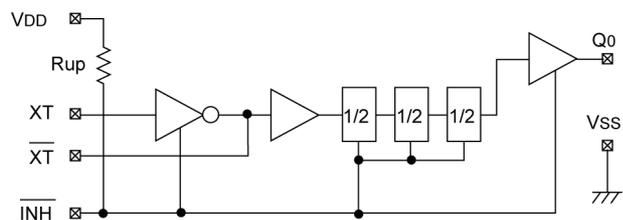
MARK	RATIO	MARK	RATIO
C	fin/1	E	fin/4
D	fin/2	F	fin/8

③ Represents tri-state buffer ICs

MARK
V

④ Represents assembly lot number  
(Based on internal standards)

## ■ BLOCK DIAGRAM



## ■ ABSOLUTE MAXIMUM RATINGS

Ta=25°C

PARAMETER	SYMBOL	CONDITIONS	UNITS
Supply Voltage	VDD	VSS - 0.3 ~ VSS + 7.0	V
Input Voltage	VIN	VSS - 0.3 ~ VDD + 0.3	V
Power Dissipation	Pd	250(**)	mW
Operating Temperature Range	Topr	- 40 ~ + 85	°C
Storage Temperature Range	Tstg	- 55 ~ + 125	°C

\*\* When implemented on a glass epoxy PCB.

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Electrical Characteristics

5.0V operation

(Unless otherwise stated, V<sub>DD</sub>=5.0V, No Load, T<sub>a</sub>=25°C)

PARAMETER	SYMBOL	CONDITIONS		MIN.	TYP.	MAX.	UNITS
Operating Supply Voltage	V <sub>DD</sub>			4.0	5.0	6.0	V
Input Voltage "High"	V <sub>IH</sub>	/INH pin		2.4	-	-	V
Input Voltage "Low"	V <sub>IL</sub>	/INH pin		-	-	0.4	V
Output Voltage "High"	V <sub>OH</sub>	Q <sub>0</sub> pin, V <sub>DD</sub> =4.5V, I <sub>OH</sub> = -8mA		3.9	4.2	-	V
Output Voltage "Low"	V <sub>OL</sub>	Q <sub>0</sub> pin, V <sub>DD</sub> =4.5V, I <sub>OL</sub> =8mA		-	0.3	0.4	V
Supply Current 1	I <sub>DD1</sub>	/INH=OPEN, Q <sub>0</sub> =OPEN Fin=70MHz	XC2300C21V (fin/1)	-	21.0	-	mA
Supply Current 2	I <sub>DD2</sub>	/INH="L", fin=70MHz		-	0.05	-	mA
Input Pull-Up Resistance 1	R <sub>up1</sub>	/INH="L"		2.0	4.0	8.0	MΩ
Input Pull-Up Resistance 2	R <sub>up2</sub>	/INH=0.7V <sub>DD</sub>		50	100	200	kΩ
Output Off Leak Current	I <sub>oz</sub>	Q <sub>0</sub> pin, /INH="L"		-	-	10	μA

3.3V operation

(Unless otherwise stated, V<sub>DD</sub>=3.3V, No Load, T<sub>a</sub>=25°C)

PARAMETER	SYMBOL	CONDITIONS		MIN.	TYP.	MAX.	UNITS
Operating Supply Voltage	V <sub>DD</sub>			2.97	3.30	3.63	V
Input Voltage "High"	V <sub>IH</sub>	/INH pin		2.4	-	-	V
Input Voltage "Low"	V <sub>IL</sub>	/INH pin		-	-	0.4	V
Output Voltage "High"	V <sub>OH</sub>	Q <sub>0</sub> pin, V <sub>DD</sub> =4.5V, I <sub>OH</sub> = -4mA		2.2	2.4	-	V
Output Voltage "Low"	V <sub>OL</sub>	Q <sub>0</sub> pin, V <sub>DD</sub> =4.5V, I <sub>OL</sub> =4mA		-	0.3	0.4	V
Supply Current 1	I <sub>DD1</sub>	/INH =OPEN, Q <sub>0</sub> =OPEN Fin=50MHz	XC2300C21V (fin/1)	-	8.0	-	mA
Supply Current 2	I <sub>DD2</sub>	/INH ="L", fin=50MHz		-	0.05	-	mA
Input Pull-Up Resistance 1	R <sub>up1</sub>	/INH ="L"		4.0	7.0	14.0	MΩ
Input Pull-Up Resistance 2	R <sub>up2</sub>	/INH =0.7V <sub>DD</sub>		70	130	250	kΩ
Output Off Leak Current	I <sub>oz</sub>	Q <sub>0</sub> pin, /INH ="L"		-	-	10	μA

## ■ ELECTRICAL CHARACTERISTIC (Continued)

### ● AC Electrical Characteristics

5.0V operation

 (Unless otherwise stated,  $V_{DD}=5.0V$ , No Load,  $T_a=25^{\circ}C$ )

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNITS
Maximum Operating Frequency	fmax		70	-	-	MHz

5.0V operation (Reference value)

 (Unless otherwise stated,  $V_{DD}=5.0V$ , No Load,  $T_a=25^{\circ}C$ )

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNITS
Input Amplitude (SIN wave)	V <sub>ipp</sub>		0.5	-	-	V <sub>pp</sub>
Output Duty Cycle (*1)	DUTY	f <sub>in</sub> =70MHz, C <sub>L</sub> =15pF, V <sub>ipp</sub> =0.5V <sub>pp</sub>	45	-	55	%
Output Rise Time (*2)	t <sub>r</sub>	f <sub>in</sub> =70MHz, C <sub>L</sub> =15pF, V <sub>ipp</sub> =0.5V <sub>pp</sub>	-	(3.0)	5.0	ns
Output Fall Time (*3)	t <sub>f</sub>	f <sub>in</sub> =70MHz, C <sub>L</sub> =15pF, V <sub>ipp</sub> =0.5V <sub>pp</sub>	-	(1.5)	5.0	ns

 \*1) 0.5V<sub>DD</sub>

 \*2) 0.1V<sub>DD</sub>→0.9V<sub>DD</sub>

 \*3) 0.9V<sub>DD</sub>→0.1V<sub>DD</sub>

3.3V operation

 (Unless otherwise stated,  $V_{DD}=3.3V$ , No Load,  $T_a=25^{\circ}C$ )

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNITS
Maximum Operating Frequency	fmax		50	-	-	MHz

3.3V operation (Reference value)

 (Unless otherwise stated,  $V_{DD}=3.3V$ , No Load,  $T_a=25^{\circ}C$ )

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNITS
Input Amplitude (SIN wave)	V <sub>ipp</sub>		0.5	-	-	V <sub>pp</sub>
Output Duty Cycle (*1)	DUTY	f <sub>in</sub> =50MHz, C <sub>L</sub> =15pF, V <sub>ipp</sub> =0.5V <sub>pp</sub>	45	-	55	%
Output Rise Time (*2)	t <sub>r</sub>	f <sub>in</sub> =50MHz, C <sub>L</sub> =15pF, V <sub>ipp</sub> =0.5V <sub>pp</sub>	-	(4.0)	8.0	ns
Output Fall Time (*3)	t <sub>f</sub>	f <sub>in</sub> =50MHz, C <sub>L</sub> =15pF, V <sub>ipp</sub> =0.5V <sub>pp</sub>	-	(2.0)	8.0	ns

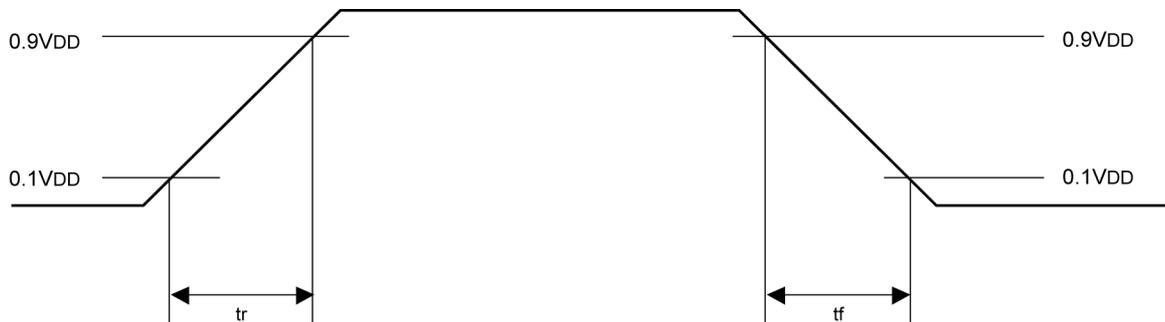
 \*1) 0.5V<sub>DD</sub>

 \*2) 0.1V<sub>DD</sub>→0.9V<sub>DD</sub>

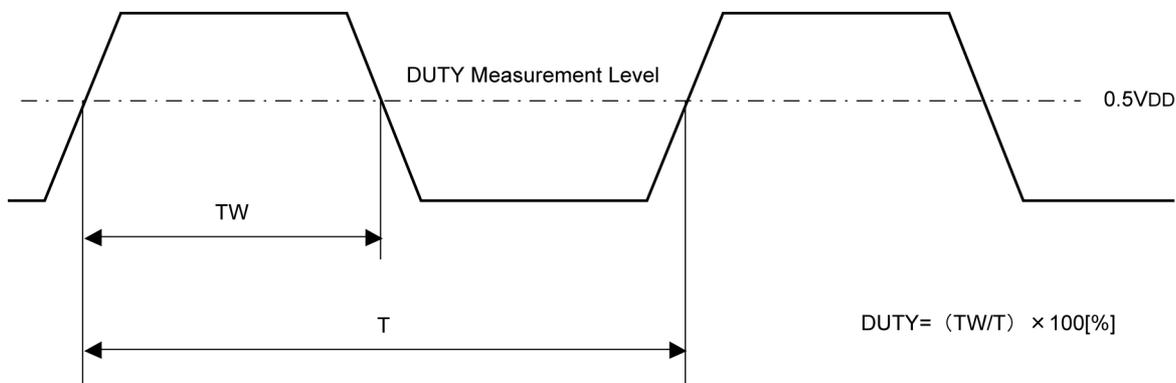
 \*3) 0.9V<sub>DD</sub>→0.1V<sub>DD</sub>

## SWITCHING WAVEFORMS

### (1) Switching Time



### (2) Duty Cycle



## SUPPLY CURRENT, DUTY TEST CIRCUIT

- \*) The feedback resistor (fixed)  $R_f$  must be connected.
- \*) When the duty needs to be adjusted because of power supply and/or input amplitude, duty resistor (fixed)  $R_b$  should be connected.

<Reference Peripheral Values:  $R_f$ ,  $R_b$ ,  $C_{IN}$ >

$V_{DD}=5.0V$ ,  $f_{in}=70MHz$ ,  $V_{ipp}=0.5V_{pp}$

$C_{IN} = 10000$  [pF]

$R_f = 100$  [k $\Omega$ ]

$R_b = 720$  [k $\Omega$ ]

$V_{DD}=3.3V$ ,  $f_{in}=50MHz$ ,  $V_{ipp}=0.5V_{pp}$

$C_{IN} = 10000$  [pF]

$R_f = 100$  [k $\Omega$ ]

$R_b = 820$  [k $\Omega$ ]

