# E2V Technologies CX1151 Hydrogen Thyratron

The data to be read in conjunction with the Hydrogen Thyratron Preamble.

#### **ABRIDGED DATA**

Hydrogen-filled tetrode thyratron, featuring low jitter and low anode delay time drift. Suitable for use at high pulse repetition rates, in parallel for switching higher powers, or for switching long pulses. A reservoir operating from the cathode heater supply is incorporated. The tube is flange mounted with flexible lead connections.

| Peak forward anode voltage |  |  |      | 25                 | kV max   |
|----------------------------|--|--|------|--------------------|----------|
| Peak anode current         |  |  |      | 1.0                | kA max   |
| Average anode current .    |  |  |      |                    |          |
| Anode heating factor       |  |  | 14 x | 10 <sup>9</sup> VA | Apps max |
| Peak output power          |  |  |      | 16.5               | MW max   |

#### **GENERAL**

#### **Electrical**

| Cathode (connected internally to                                |    |
|---|----|
| mid-point of heater) oxide coate                                | ed |
| Heater voltage $\ldots$ $\ldots$ $\ldots$ $\ldots$ 6.3 $\pm$ 5% | V  |
| Heater current  | Α  |
| Tube heating time (minimum) 5.0 mi                              | in |
| Inter-electrode capacitances (approximate):                     |    |
| anode to grid 2 (grid 1 and                                     |    |
| cathode not connected) 13                                       | ρF |
| anode to grid 1 (grid 2 and                                     |    |
| cathode not connected) 7.5                                      | ρF |
| anode to cathode (grid 1 and                                    |    |
| grid 2 not connected) 26  | ΣF |

#### Mechanical

| Seated height                  |  |
|--------------------------------|--|
| (excluding leads)              | 301.0 mm (11.850 inches) max                     |
| Overall diameter (excluding    |  |
|                                | 84.12 mm (3.312 inches) max                      |
| Net weight                     | . 0.7 kg (1 $^{1}$ / <sub>2</sub> pounds) approx |
| Mounting position (see note 1) | any  |
| Top cap (see note 2)           | B.S.448-CT3                                      |
|                                |  |

| Cooling |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | natural |
|---------|--|--|--|--|--|--|--|--|--|--|--|--|--|--|--|---------|
|---------|--|--|--|--|--|--|--|--|--|--|--|--|--|--|--|---------|



### PULSE MODULATOR SERVICE MAXIMUM AND MINIMUM RATINGS (Absolute values)

|                                      | Mir | n Max                      |
|--------------------------------------|-----|----------------------------|
| Anode                                |     |                            |
| Peak forward anode voltage           |     |                            |
| (see note 3)                         |     | 25 kV                      |
| Peak inverse anode voltage           |     |                            |
| (see note 4)                         |     | 25 kV                      |
| Peak anode current                   |     | 1.0 kA                     |
| Peak anode current (pulse repetition |     |                            |
| rate limited to 60 pps max)          |     | 2.0 kA                     |
| Average anode current                |     | 1.25 A                     |
| Rate of rise of anode current        |     |                            |
| (see note 5)                         |     | •                          |
| Anode heating factor                 |     | 14 x 10 <sup>9</sup> VApps |

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## MAXIMUM AND MINIMUM RATINGS (Continued)

|   | Min      | Max  |
|---|----------|--|
| Grid 2  |          |  |
|   | 1.0      | 1000 V - μs - kV/μs 3.0 μs 450 V -150 V      |
| Grid 1 - DC Primed (See note  | 7)       |  |
| DC grid 1 unloaded priming voltage . DC grid 1 priming current  | 75<br>50 | 150 V<br>100 mA                              |
| Grid 1 - Pulsed   |          |  |
| Unloaded grid 1 drive pulse voltage (see note 6) Grid 1 pulse duration Rate of rise of grid 1 pulse (see note 5) Peak inverse grid 1 voltage Loaded grid 1 bias voltage Peak grid 1 drive current | 1.0      | 1000 V - μs - kV/μs 450 V . see note 8 1.0 A |
| Cathode   |          |  |
| Heater voltage  |          | 3 ± 5% V<br>- min                            |
| Environmental   |          |  |
| Ambient temperature   | -50<br>  | +90 °C 3 km 10 000 ft                        |

#### **CHARACTERISTICS**

|                                    | Min | Typical     | Max     |       |
|------------------------------------|-----|-------------|---------|-------|
| Critical DC anode voltage for      |     |             |         |       |
| conduction (see note 9)            | -   | 0.5         | 2.0     | kV    |
| Anode delay time                   |     |             |         |       |
| (see notes 9 and 10)               | -   | 0.15        | 0.25    | μs    |
| Anode delay time drift             |     |             |         |       |
| (see notes 9, 11 and 12)           | -   | 20          | 50      | ns    |
| Time jitter (see notes 9 and 12) . | -   | 1.0         | 5.0     | ns    |
| Recovery time                      |     | see note 13 | 3 and c | urves |
| Heater current (at 6.3 V)          | 18  | 22          | 25      | Α     |
|                                    |     |             |         |       |

## RATINGS FOR SINGLE SHOT OR CROWBAR SERVICE (See note 7)

| DC forward anode voltage                 | . 30        | kV max   |
|--|-------------|----------|
| Peak anode current                       | . 15        | kA max   |
| Product of peak current and pulse length | 0.6         | A.s max  |
| Repetition frequency                     | 1 pulse per | 10 s max |

#### **NOTES**

- 1. The tube must be mounted by the base flange only.
- A large area anode connector, E2V Technologies type MA360A, is recommended.
- The maximum permissible peak forward voltage for instantaneous starting is 20 kV and there must be no overshoot.

- 4. The peak inverse voltage must not exceed 25 kV for the first 25  $\mu s$  after the anode pulse.
- 5. This rate of rise refers to that part of the leading edge of the pulse between 25% and 75% of the pulse amplitude.
- 6. Measured with respect to cathode. In certain cases the maximum drive pulse voltage may be exceeded without damage to the tube; a maximum value of 2.5 kV is then recommended. When grid 1 is pulse driven, the last 0.25  $\mu s$  of the top of the grid 1 pulse must overlap the corresponding first 0.25  $\mu s$  of the top of the delayed grid 2 pulse.
- When DC priming is used on grid 1, a negative bias of 100 to 200 V must be applied to grid 2 to ensure anode voltage hold-off. DC priming is recommended for crowbar service.
- 8. DC negative bias voltages must not be applied to grid 1. When grid 1 is pulse driven, the potential of grid 1 may vary between -10 and +5 V with respect to cathode potential during the period between the completion of recovery and the commencement of the succeeding grid pulse.
- Typical figures are obtained on test using conditions of minimum grid drive. Improved performance can be expected by increasing the grid drive.
- 10. The time interval between the instant at which the rising unloaded grid 2 pulse reaches 25% of its pulse amplitude and the instant when anode conduction takes place.
- 11. The drift in delay time over a period from 10 seconds to 10 minutes after reaching full voltage.
- 12. For equipment where jitter and anode delay time drift are not important, the tube may be triggered by applying a single pulse to grid 2 and connecting grid 1 to grid 2 via a 1000 pF capacitor shunted by a 0.1 M $\Omega$  resistor.
- The recovery characteristics are controlled on a sampling basis.

#### **HEALTH AND SAFETY HAZARDS**

E2V Technologies hydrogen thyratrons are safe to handle and operate, provided that the relevant precautions stated herein are observed. E2V Technologies does not accept responsibility for damage or injury resulting from the use of electronic devices it produces. Equipment manufacturers and users must ensure that adequate precautions are taken. Appropriate warning labels and notices must be provided on equipments incorporating E2V Technologies devices and in operating manuals.



#### High Voltage

Equipment must be designed so that personnel cannot come into contact with high voltage circuits. All high voltage circuits and terminals must be enclosed and fail-safe interlock switches must be fitted to disconnect the primary power supply and discharge all high voltage capacitors and other stored charges before allowing access. Interlock switches must not be bypassed to allow operation with access doors open.



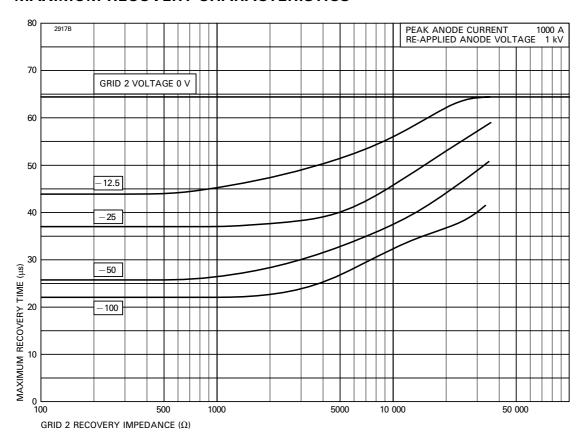
#### X-Ray Radiation

All high voltage devices produce X-rays during operation and may require shielding. The X-ray radiation from hydrogen thyratrons is usually reduced to a safe level by enclosing the equipment or shielding the thyratron with at least 1.6 mm ( $^{1}$ / $_{16}$  inch) thick steel panels.

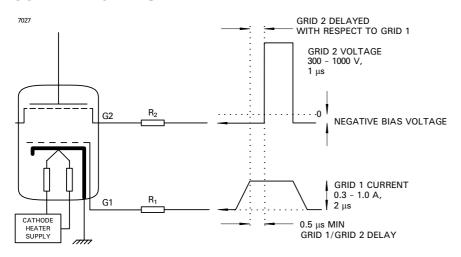
Users and equipment manufacturers must check the radiation level under their maximum operating conditions.

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#### **MAXIMUM RECOVERY CHARACTERISTICS**



#### **SCHEMATIC DIAGRAM**



#### RECOMMENDED GRID AND CATHODE HEATER CONNECTIONS

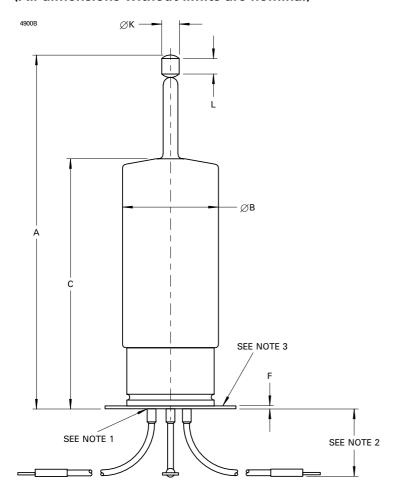
R<sub>1</sub> = Grid 1 series resistor. 12 W vitreous enamelled wirewound is recommended, of a total impedance to match the grid 1 drive pulse circuit.

 $R_2 = Grid\ 2$  resistor. 12 W vitreous enamelled wirewound is recommended, of an impedance to match the grid 2 drive pulse circuit. Components  $R_1$  and  $R_2$  should be mounted as close to the tube as possible.

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#### **OUTLINE**

#### (All dimensions without limits are nominal)

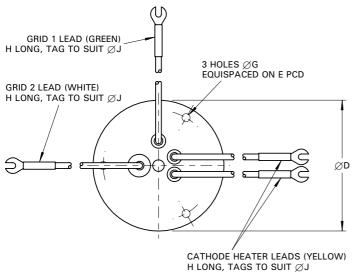


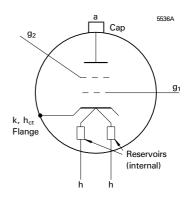
| Ref | Millimetres      | Inches            |
|-----|------------------|-------------------|
| A   | 301.0 max        | 11.850 max        |
| В   | 84.12 max        | 3.312 max         |
| С   | $215.9 \pm 13.0$ | $8.500 \pm 0.512$ |
| D   | 111.1            | 4.375             |
| Е   | 95.25            | 3.750             |
| F   | 1.6              | 0.063             |
| G   | 6.5              | 0.256             |
| Н   | 215.9            | 8.500             |
| J   | 6.35             | 0.250             |
| K   | $14.38 \pm 0.18$ | $0.566 \pm 0.007$ |
| L   | 12.7 min         | 0.500 min         |

Inch dimensions have been derived from millimetres.

#### **Outline Notes**

- 1. The recommended hole in the mounting plate is 76 mm (3.0 inches) diameter.
- 2. A minimum clearance of 44.45 mm (1.75 inches) must be allowed below the mounting surface.
- 3. The mounting flange is the cathode connection and this is connected internally to the mid-point of the heater.





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