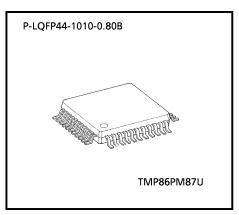
CMOS 8-Bit Microcontroller

TMP86PM87U

The TMP86PM87 is a high-speed, high-performance 8-bit single chip microcomputer, which has 32 K bits One-Time PROM. The TMP86PM87 is pin compatible with the TMP86CH87/M87. The operations possible with the TMP86CH87/M87 can be performed by writing programs to PROM. The TMP86PM87 can write and verify in the same way as the TC571000D/AD using an adapter socket and a general-purpose PROM programmer.

Product No.	OTP	RAM	Package	Adapter socket
TMP86PM87U	32 K × 8 bits	1 K × 8 bits	P-LQFP44-1010-0.80B	BM11187



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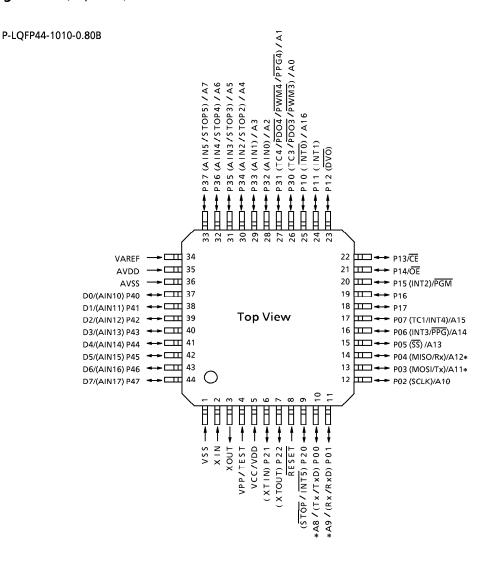
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Pin Assignments (Top View)



* The CAN transmit/receive pins have their connected ports changed depending on how the Multifunction Register (MULSEL) is set.

Pin Function

The TMP86PM87 has two modes: MCU and PROM.

(1) MCU mode

In the MCU mode, the TMP86PM87 is a pin compatible with the TMP86CH87/M87 (fix the TEST pin at low level).

Under Development

(2) PROM mode

Pin Name (PROM mode)	Input/Output	Functions	Pin Name (MCU mode)
A16			P10
A15 to A8	Input	Program memory address inputs	P07 to P00
A7 to A0	1		P37 to P30
D7 to D0	1/0	Program memory data input/outputs	P47 to P40
CE		Chip enable signal input	P13
ŌĒ	Input	Output enable signal input	P14
PGM	1	Program mode signal input	P15
VPP		+ 12.75 V/5 V (Power supply volatge)	TEST
VCC, AVDD	Power supply	+ 6.25 V/5 V	VDD
GND, VAREF, AVSS	1	0 V	VSS, VAREF
P11, P21		PROM mode setting pins. Be fixed at high level.	•
P12, P20, P22	1/0		
RESET	1	PROM mode setting pins. Be fixed at low level.	
P16, P17	I/O	Open	
XIN	Input	Connect on SMIII assillator to stabilize the internal state	
XOUT	Output	Connect an 8 MHz oscillator to stabilize the internal state.	

Operational Description

The configuration and function of the TMP86PM87 are the same as those of the TMP86CH87/M87, except in that a one-time PROM is used instead of an on-chip mask ROM.

1. Operating Mode

The TMP86PM87 has two modes: MCU and PROM.

1.1 MCU Mode

The MCU mode is activated by fixing the TEST/VPP pin at low level.

In the MCU mode, operation is the same as with the TMP86CH87/M87 (TEST/VPP pin cannot be used open because it has no built in pull-down resistance.)

1.1.1 Program Memory

The TMP86PM87 have an 32 Kbytes (addresses 8000 to FFFF_H in the MCU mode, addresses 0000 to 7FFF_H in the PROM mode) one-time PROM.

When the TMP86PM87 is used as a system evaluation of the TMP86CH87/M87, the data is written to the program storage area shown in Figure 1-1.

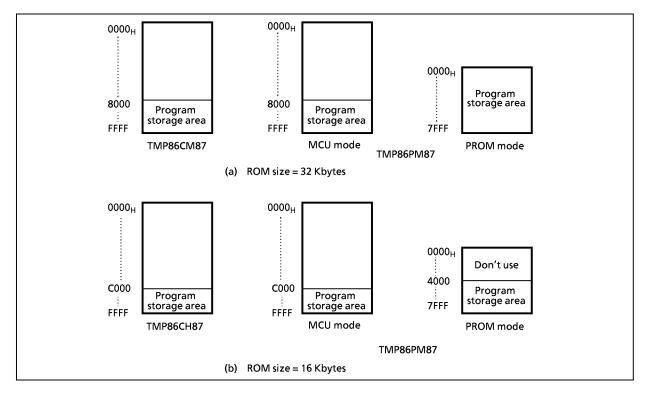


Figure 1-1. Program Memory Area

Note: Either write the data FF_H to the unused area or set the general-purpose PROM programmer to access only the program storage area

Electrical Characteristics

Absolute Maximum Ratings

 $(V_{SS} = 0 V)$

Parameter	Symbol	Pins	Rating	Unit
Supply Voltage	V_{DD}		- 0.3 to 6.5	
Input Voltage	V_{IN}		- 0.3 to V _{DD} + 0.3	
Output Valtage	V _{OUT1}	P21, P22, RESET, Tri-state Port	- 0.3 to V _{DD} + 0.3	V
Output Voltage	V _{OUT2}	P20, Sink Open Drain Port	– 0.3 to 5.5	
Output Current (Per 1 pin)	I _{OUT1} I _{OH}	P0, P1, P3, P4 Port	- 1.8	
	I _{OUT2} I _{OL}	P1, P2, P3, P4 Port	3.2	
	I _{OUT3} I _{OL}	P0 Port	30	
	Σ l _{OUT1}	P0, P1, P3, P4 Port	- 30	mA
Output Current (Total)	Σ I _{OUT2}	P1, P2, P3, P4 Port	60	
	Σ I _{OUT3}	P0 Port	80	
Power Dissipation [T _{opr} = 85°C]	PD		350	mW
Soldering Temperature (time)	Tsld		260 (10 s)	
Storage Temperature	Tstg		– 55 to 150	°C
Operating Temperature	Topr		– 40 to 85	

Note: The absolute maximum ratings are rated values which must not be exceeded during operation, even for an instant. Any one of the ratings must not be exceeded. If any absolute maximum rating is exceeded, a device may break down or its performance may be degraded, causing it to catch fire or explode resulting in injury to the user. Thus, when designing products which include this device, ensure that no absolute maximum rating value will ever be exceeded.

Recommended Operating Condition

 $(V_{SS} = 0 \text{ V}, \text{ Topr} = -40 \text{ to } 85^{\circ}\text{C})$

Parameter	Symbol	Pins		Condition	Min	Max	Unit
				NORMAL1, 2 mode			
			fc = 16 MHz	IDLE0, 1, 2 mode			
Supply Voltage				NORMAL1, 2 mode			
	V_{DD}		fc = 8 MHz	IDLE0, 1, 2 mode	4.5	5.5	
			fs =	SLOW1, 2 mode			
			32.768 kHz	SLEEP0, 1, 2 mode			l v
				STOP mode			_ v
	V _{IH1}	Except Hysteresis input	$V_{DD} \ge 4.5 V$		$V_{DD} \times 0.70$		
Input high Level	V_{IH2}	Hysteresis input			$V_{DD} \times 0.75$	V_{DD}	
	V _{IH3}		\ \	/ _{DD} < 4.5 V	$V_{DD} \times 0.90$		
	V _{IL1}	Except Hysteresis input	,	. > 4 E.V.		$V_{DD} \times 0.30$	
Input low Level	V_{IL2}	Hysteresis input	\ 	_{DD} ≥ 4.5 V	0	$V_{DD} \times 0.25$	
	V_{IL3}		\ 	_{'DD} < 4.5 V		$V_{DD} \times 0.10$	
Clask Fraguency	fc	XIN, XOUT	V _{DD} = 4.5 to 5.5 V		1.0	16.0	MHz
Clock Frequency	fs	XTIN, XTOUT	V _{DD}	= 4.5 to 5.5 V	30.0	34.0	kHz

Note: The recommended operating conditions for a device are operating conditions under which it can be guaranteed that the device will operate as specified. If the device is used under operating conditions other than the recommended operating conditions (supply voltage, operating temperature range, specified AC/DC values etc.), malfunction may occur. Thus, when designing products which include this device, ensure that the recommended operating conditions for the device are always adhered to.

DC Standard (tentatively Standard)

DC Characteristics $(V_{SS} = 0 \text{ V}, \text{ Topr} = -40 \text{ to } 85^{\circ}\text{C})$

Parameter	Symbol	Pins	Condition	Min	Тур.	Max	Unit
Hysteresis Voltage	V_{HS}	Hysteresis input		_	0.9	-	V
	I _{IN1}	TEST					
Input Current	I _{IN2}	Sink Open Drain, Tri-state Port	V _{DD} = 5.5 V, V _{IN} = 5.5 V/0 V	_	_	± 2	μΑ
	I _{IN3}	RESET, STOP					
Input Resistance	R _{IN}	RESET Pull-Up		100	220	450	kΩ
Output Leakage Current	I _{LO}	Sink Open Drain, Tri-state Port	V _{DD} = 5.5 V, V _{OUT} = 5.5 V/0 V	-	-	± 2	μA
Output High Voltage	V _{OH2}	P0, P1, P3, P4 Port	$V_{DD} = 4.5 \text{ V}, I_{OH} = -0.7 \text{ mA}$	4.1	-	-	V
Output Low Voltage	V_{OL}	P1, P2, P3, P4 Port	$V_{DD} = 4.5 \text{ V}, I_{OL} = 1.6 \text{ mA}$	ı	-	0.4]
Output Low Current	l _{OL}	High Current Port (P0 Port)	$V_{DD} = 4.5 \text{ V}, V_{OL} = 1.0 \text{ V}$	1	20	-	
Supply Current in			$V_{DD} = 5.5 \text{ V}$ $V_{IN} = 5.3/0.2 \text{ V}$	_	10	15	
NORMAL 1, 2 mode			fc = 16.0 MHz				
Supply Current in			fs = 32.768 kHz	_	8	12	mA
IDLE 1, 2 mode			When using CAN controller				l ma
Supply Current in			$V_{DD} = 5.5 \text{ V}$ $V_{IN} = 5.3/0.2 \text{ V}$	_	7.5	9	
NORMAL 1, 2 mode	ł		fc = 16.0 MHz				-
Supply Current in IDLE 0, 1, 2 mode			fs = 32.768 kHz When not using CAN controller	_	5.5	6.5	
Supply Current in	I_{DD}		When her asking a ween a one.				
SLOW 1 mode				_	15	35	
Supply Current in	1		$V_{DD} = 5.5 V$		_		
SLEEP 1 mode			V _{IN} = 5.3 V/0.2 V	_	7	25	١.
Supply Current in	1		fs = 32.768 kHz			25	μA
SLEEP 0 mode				_	6	25	
Supply Current in			V _{DD} = 5.5 V	_	0.5	15]
STOP mode			V _{IN} = 5.3 V/0.2 V		0.5	.5	

Note 1: Typical values show those at Topr = 25° C, $V_{DD} = 5 \text{ V}$

Note 2: Input current (I_{IN1} , I_{IN3}); The current through pull-up or pull-down resistor is not included.

Note 3: I_{DD} does not include I_{REF} current.

Note 4: The power supply current in STOP2 and SLEEP2 modes each are the same as in IDLEO, 1, and 2 modes.

Note 5: The supply current in NORMAL 1, 2 and IDLE 1, 2 modes varies with use/non-use of the CAN controller.

AD Conversion Characteristics

(V_{SS} = 0.0 V, 4.5 V \leq V_{DD} \leq 5.5 V, Topr = -40 to 85°C)

Parameter	Symbol	Condition	Min	Тур.	Max	Unit
Analog Reference Voltage	V_{AREF}		A _{VDD} – 1.0	_	A _{VDD}	
Power Supply Voltage of	A_{VDD}			V_{DD}		
Analog Control Circuit	A _{VSS}			V_{SS}		\ \
Analog Reference Voltage Range (Note 4)	ΔV_{AREF}	V _{AREF} – A _{VSS}	3.5	-	_	
Analog Input Voltage	V_{AIN}		A _{VSS}	-	V _{AREF}	1 I
Power Supply Current of Analog Reference Voltage	I _{REF}	$V_{DD} = A_{VDD} = V_{AREF} = 5.5 \text{ V}$ $V_{SS} = A_{VSS} = 0.0 \text{ V}$	_	0.6	1.0	mA
Non linearity			-	-	± 2	
Zero Point Error		$V_{DD} = A_{VDD} = 5.0 \text{ V},$ $V_{AREF} = 5.0 \text{ V},$ $A_{VSS} = 0.0 \text{ V}$	-	-	± 2	LSB
Full Scale Error			-	-	± 2	1 220
Total Error			-	_	± 2	1

Note 1: The total error includes all errors except a quantization error, and is defined as a maximum deviation from the ideal

Note 2: Conversion time is different in recommended value by power supply voltage.

About conversion time, please refer to "2.11.2 Register Configuration".

Note 3: Please use input voltage to AIN input Pin in limit of V_{AREF} – A_{VSS}.

When voltage of range outside is input, conversion value becomes unsettled and gives affect to other channel conversion value.

Note 4: Analog Reference Voltage Range: $\Delta V_{AREF} = V_{AREF} - A_{VSS}$

SEI Operating Conditions (Slave mode) $| (V_{SS} = 0.0 \text{ V}, 4.5 \text{ V} \le V_{DD} \le 5.5 \text{ V}, \text{Topr} = -40 \text{ to } 85^{\circ}\text{C}) |$

Parameter	Symbol	Condition	Min	Тур.	Max	Unit
Transfer Rate			15.625 k	-	fc/4	bps

AC Characteristics

 $(V_{SS} = 0 \text{ V}, V_{DD} = 4.5 \text{ to } 5.5 \text{ V}, Topr = -40 \text{ to } 85^{\circ}\text{C})$

Parameter	Symbol	Condition	Min	Тур.	Max	Unit
Machine Cycle Time		NORMAL 1, 2 mode				
	tov	IDLE 0, 1, 2 mode	0.25	-	4	_ ا
	tcy	SLOW 1, 2 mode	447.6		422.2	μS
		SLEEP 0, 1, 2 mode	117.6	_	133.3	
High Level Clock Pulse Width	twcH	For external clock operation (XIN input)	_			ns
Low Level Clock Pulse Width	twcL	fc = 16 MHz	25	-	_	115
High Level Clock Pulse Width	twcH	For external clock operation (XTIN input)	447			
Low Level Clock Pulse Width	twcL	fs = 32.768 kHz	14.7	-	-	μS

$(V_{SS} = 0 \text{ V}, V_{DD} = 2.7 \text{ to } 4.5 \text{ V}, Topr = -40 \text{ to } 85^{\circ}\text{C})$

Parameter	Symbol	Condition	Min	Тур.	Max	Unit
Machine Cycle Time		NORMAL 1, 2 mode		-		
	+614	IDLE 0, 1, 2 mode	0.5		4	
	tcy	SLOW 1, 2 mode	117.6		122.2	μS
		SLEEP 0, 1, 2 mode	117.6	_	133.3	
High Level Clock Pulse Width	twcH	For external clock operation (XIN input)				ns
Low Level Clock Pulse Width	twcL	fc = 8 MHz	50	_	_	113
High Level Clock Pulse Width	twcH	For external clock operation (XTIN input)	147			c
Low Level Clock Pulse Width	twcL	fs = 32.768 kHz	14.7	_	_	μS

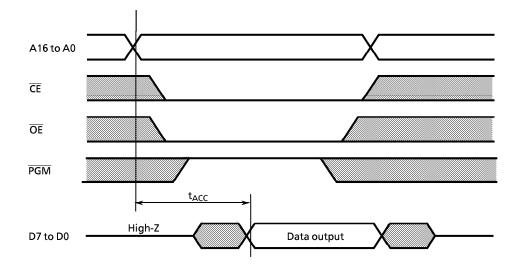
DC Characteristics, AC Characteristics (PROM mode)

 $(V_{SS} = 0 \text{ V, Topr} = -40 \text{ to } 85^{\circ}\text{C})$

(1) Read operation in PROM mode

Parameter	Symbol	Conditions	Min	Тур.	Max	Unit
High level input voltage (TTL)	V _{IH4}		2.2	-	V _{CC}	
Low leve input voltage (TTL)	V _{IL4}		0	-	0.8	V
Power supply	V _{CC}		4.75	5.0	5.25	
Power supply of program	V_{PP}		4.73	5.0	5.25	
Address access time	t _{ACC}	V _{CC} = 5.0 ± 0.25 V	-	1.5 tcyc + 300	-	ns

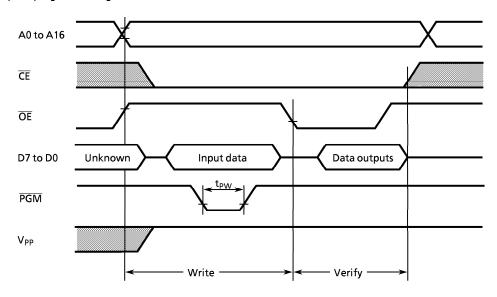
Note: tcyc = 500 ns at 8 MHz



(2) Program operation (High-speed) (Topr = $25 \pm 5^{\circ}$ C)

Parameter	Symbol	Conditions	Min	Тур.	Max	Unit
High level input voltage (TTL)	V _{IH4}		2.2	-	V _{CC}	
Low leve input voltage (TTL)	V _{IL4}		0	-	0.8	v
Power supply	V _{CC}		6.0	6.25	6.5	
Power supply of program	V _{PP}		12.5	12.75	13.0	
Pulse width of initializing program	t _{PW}	V _{CC} = 6.0 V	0.095	0.1	0.105	ms

High-speed program writing



- Note 1: The power supply of V_{PP} (12.75 V) must be set power-on at the same time or the later time for a power supply of V_{CC} and must be clear power-on at the same time or early time for a power supply of V_{CC} .
- Note 2: The pulling up/down device on the condition of V_{PP} = 12.75 V \pm 0.25 V causes a damage for the device. Do not pull up/down at programming.
- Note 3: Use the recommended adapter (see 1.2.2 (1)) and mode (see 1.2.2 (3) i).

 Using other than the above condition may cause the trouble of the writting.