LB1938T



1ch, Low-saturation Forward/Reverse Motor Driver

Overview

The LB1938T is an H-bridge motor driver that supports low-voltage drive and features low-saturation outputs in an ultraminiature slim package. The LB1938T provides forward, reverse, brake, and standby modes controlled by two input signals, and is an optimal DC motor driver for notebook personal computers, digital cameras, cell phones, and other portable equipment.

Functions and Features

- Ultraminiature MSOP-8 package $(3.0 \times 4.9 \times 0.93 \text{ mm})$
- The low saturation voltage means that the voltage applied to the motor is higher and IC heat generation is reduced. This allows this IC to be used in environments with higher ambient operating temperatures.

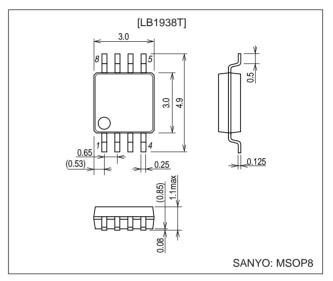
Output saturation voltage (high side + low side): V_{O} sat = 0.15 V typical (I_O = 100 mA)

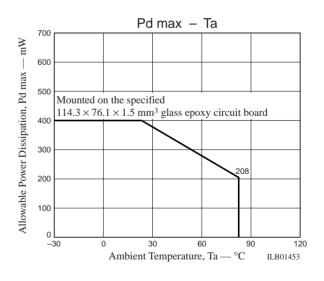
- The wide usable voltage range and the low standby mode current drain of 0.1 µA make this IC optimal for battery operated equipment.
- There are no constraints on the relationship between the input signal voltage and the supply voltage. For example, this IC can be use at $V_{CC} = 3$ V and $V_{IN} = 5$ V.
- Thermal protection circuit limits the drive current and prevents the IC from causing a fire or being destroyed if the IC chip temperature reaches or exceeds 180°C due to large currents flowing when the outputs are shorted due to, for example, motor layer shorting or other phenomena.

Package Dimensions

unit: mm

3245A-MSOP8





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Specifications Absolute Maximum Ratings at $Ta = 25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	V _{CC} max		10.5	V
Allowable Power dissipation	Pd max	Mounted on a board *	400	mW
Output current	I _{OUT} max		800	mA
Output voltage	V _{OUT} max		V _{CC} + V _{SF}	V
Input applied voltage	V _{IH} max		10	V
Operating temperature	Topr		-30 to +85	°C
Storage temperature	Tstg		-55 to +150	°C

Note: * Mounted on the specified board (114.3 × 76.1 × 1.5 mm³: Glass epoxy, wiring density 20%)

Allowable Operating Range at $Ta = 25^{\circ}C$

Parameter	Parameter Symbol Conditions		Ratings	Unit
Supply voltage	V _{CC}		2.2 to 10	V
Input high-level voltage	VIH		2.0 to 9.5	V
Input low-level voltage	VIL		-0.3 to +0.3	V

Electrical Characteristics at Ta = 25° C, V_{CC} = 3 V

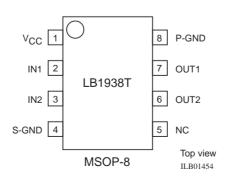
Parameter	Symbol	Conditions	Ratings			- Unit
Parameter	Symbol	nbol Conditions		typ	max	Unit
	I _{CC} 1	Standby		0.1	5	μA
Circuit Current	I _{CC} 2	Forward/reverse drive		14	19	mA
	I _{CC} 3	Brake		20	29	mA
	V _O sat1	Upper+lower I _O = 100 mA for forward/ reverse rotation		0.15	0.2	V
Output saturation voltage	V _O sat2	Upper+lower I _O = 300 mA for forward/ reverse rotation		0.35	0.5	V
	V _O sat3	Upper I _O = 100 mA for braking		0.1	0.15	V
Spark killer diode forward voltage	V _{SF}	I _O = 300 mA		0.9	1.7	V
Spark killer diode inverse current	I _{RS}	V _{OUT} = 10 V		0.1	5	μA
Input current	I _{IN}	V _{IN} = 5 V		75	98	μA
Thermal protection operating temperature	TSD	Design target value*		180		°C

Note: * Design target value : Measurement with a single unit not made.

Truth Table

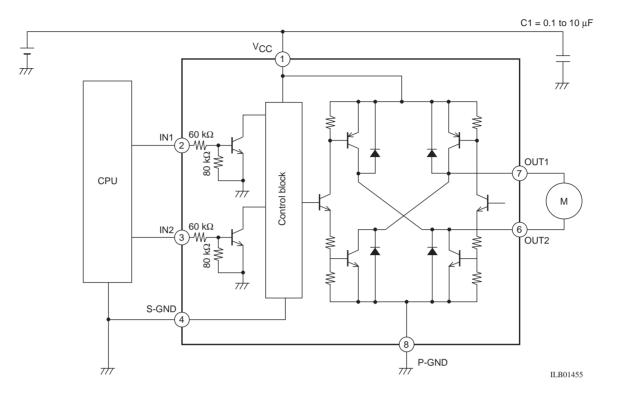
IN1	IN2	OUT1	OUT2	Mode
L	L	OFF	OFF	Standby
н	L	Н	L	Forward rotation
L	Н	L	Н	Reverse rotation
Н	Н	Н	Н	Brake

Pin Assignment



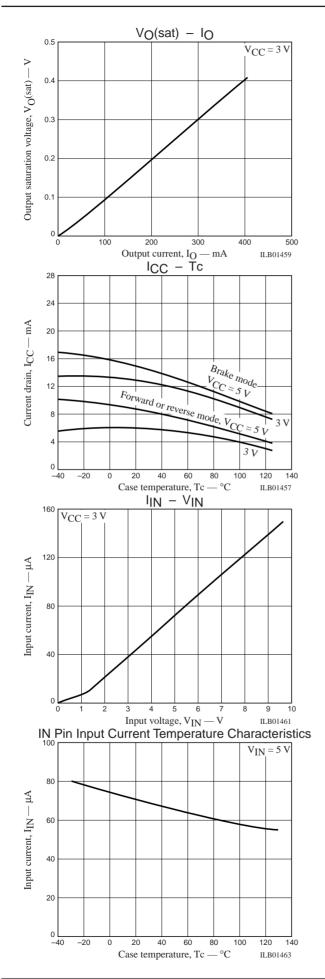
S-GND: GND for the control system P-GND: GND for the power system

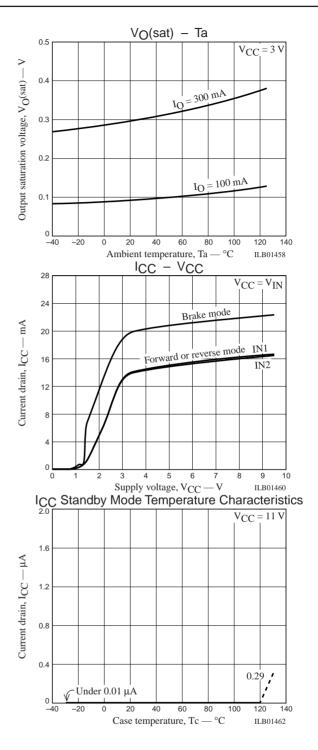
Sample Application Circuit



Cautions:

- V_{CC} and GND lines suffer substantial fluctuation in the current quantity, causing a problem of line oscillation in certain cases. In this case, take following points into account:
- (1) Use a thick and short wiring to reduce the wiring inductance.
- (2) Insert a capacitor with satisfactory frequency characteristics near IC.
- (3) Connect S-GND to the control system GND on the CPU side and P-GND to the power system GND.





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