

# 4-Input Video Multiplexer with 75MHz Current Feedback Amplifier

## **FEATURES**

- 0.1dB Gain Flatness > 30MHz
- Channel Separation at 10MHz: 90dB
- 40mV Switching Transient, Input Referred
- -3dB Bandwidth,  $A_V = 2$ ,  $R_L = 150\Omega$ : 75MHz
- Channel-to-Channel Switching Time: 120ns
- Easy to Expand for More Inputs
- Large Input Range: ±6V
- 0.04% Differential Gain,  $R_1 = 150\Omega$
- $0.06^{\circ}$  Differential Phase,  $R_{I} = 150\Omega$
- High Slew Rate: 1000V/µs
- Output Swing,  $R_1 = 400\Omega$ :  $\pm 13V$
- Wide Supply Range: ±5V to ±15V

## **APPLICATIONS**

- Broadcast Quality Video Multiplexing
- Large Matrix Routing
- Medical Imaging
- Large Amplitude Signal Multiplexing
- Programmable Gain Amplifiers

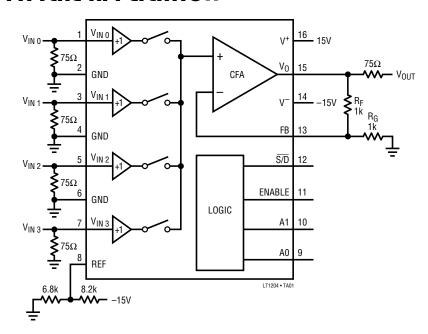
## DESCRIPTION

The LT1204 is a 4-input video multiplexer designed to drive  $75\Omega$  cables and easily expand into larger routing systems. Wide bandwidth, high slew rate, and low differential gain and phase make the LT1204 ideal for broadcast quality signal routing. Channel separation and disable isolation are greater than 90dB up to 10MHz. The channel-to-channel output switching transient is only  $40\text{mV}_{P-P}$ , with a 50ns duration, making the transition imperceptible on high quality monitors.

A unique feature of the LT1204 is its ability to expand into larger routing matrices. This is accomplished by a patent pending circuit that bootstraps the feedback resistors in the disable condition, raising the true output impedance of the circuit. The effect of this feature is to eliminate cable misterminations in large systems.

The large input and output signal levels supported by the LT1204 when operated on  $\pm 15$ V supplies make it ideal for general purpose analog signal selection and multiplexing. A shutdown feature reduces the supply current to 1.5mA.

## TYPICAL APPLICATION

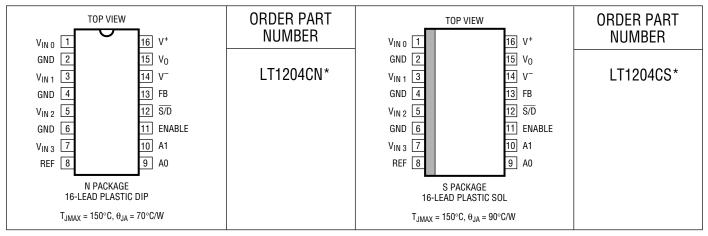


# All Hostile Crosstalk Surface Mount PCB Measurements $-20 \\ V_S = \pm 15V \\ V_{IN \ 0} = GND \\ V_{IN \ 1,2,3} = 0dBm \\ R_L = 100\Omega \\ -120 \\ 10 \\ TREQUENCY \ (MHz)$

## **ABSOLUTE MAXIMUM RATINGS**

Supply Voltage ±1	8V
- Input Current (Pin 13) ±15	mΑ
+Input and Control/Logic Current (Note 1) ±50	
Output Short-Circuit Duration (Note 2) Continue	ous
Specified Temperature Range (Note 3) 0°C to 70	

## PACKAGE/ORDER INFORMATION



<sup>\*</sup>See Note 3

## **ELECTRICAL CHARACTERISTICS**

 $0^{\circ}C \le T_A \le 70^{\circ}C$ ,  $\pm 5V \le V_S \le \pm 15V$ ,  $V_{CM}$  = 0V, Pin 8 grounded and pulse tested unless otherwise noted.

SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
$\overline{V_{0S}}$	Input Offset Voltage	Any Positive Input, T <sub>A</sub> = 25°C			5	14	mV
			•			16	mV
	Offset Matching	Between Any Positive Input, $V_S = \pm 15V$	•		0.5	5	mV
	Input Offset Voltage Drift	Any Positive Input	•		40		μV/°C
I <sub>IN</sub> <sup>+</sup>	Positive Input Bias Current	Any Positive Input, T <sub>A</sub> = 25°C			3	8	μА
			•			10	μΑ
I <sub>IN</sub> -	Negative Input Bias Current	T <sub>A</sub> = 25°C			±10	±50	μΑ
			•			±75	μA
e <sub>n</sub>	Input Noise Voltage	$f = 1kHz$ , $R_F = 1k$ , $R_G = 10\Omega$ , $R_S = 0\Omega$			7		nV/√Hz
+i <sub>n</sub>	Noninverting Input Noise Current Density	f = 1kHz			1.5		pA/√Hz
-i <sub>n</sub>	Inverting Input Noise Current Density	f = 1kHz			40		pA/√Hz
C <sub>IN</sub>	Input Capacitance	Input Selected			3.0		pF
		Input Deselected			3.5		pF
C <sub>OUT</sub>	Output Capacitance	Disabled, Pin 11 Voltage = 0V			8		pF
R <sub>IN</sub>	Positive Input Resistance, Any Positive Input	$V_S = \pm 5V$ , $V_{IN} = -1.5V$ , $2V$ , $T_A = 25^{\circ}C$		5	20		MΩ
		$V_{S} = \pm 15V, V_{IN} = \pm 5V$	•	4	20		MΩ

## **ELECTRICAL CHARACTERISTICS**

 $0^{\circ}C \leq T_{A} \leq 70^{\circ}C, \, \pm 5V \leq V_{S} \leq \pm 15V, \, V_{CM} = 0V, \, Pin \, 8 \, \, grounded \, \, and \, \, pulse \, tested \, unless \, otherwise \, noted.$ 

SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
	Input Voltage Range, Any Positive Input	$V_S = \pm 5V$ , $T_A = 25^{\circ}C$		2.0 -1.5	2.5 -2.0		V
		$V_S = \pm 15V$	•	±5.0	±6.0		V
		$V_S = \pm 15V$ , Pin 8 Voltage = $-5V$	•	3.75	4.0		V
CMRR	Common-Mode Rejection Ratio	$V_S = \pm 5V$ , $V_{CM} = -1.5V$ , $2V$ , $T_A = 25^{\circ}C$		48	55		dB
		$V_S = \pm 15V, V_{CM} = \pm 5V$	•	48	58		dB
	Negative Input Current	$V_S = \pm 5V$ , $V_{CM} = -1.5V$ , $2V$ , $T_A = 25^{\circ}C$			0.05	1	μA/V
	Common-Mode Rejection	$V_S = \pm 15V, V_{CM} = \pm 5V$	•		0.05	1	μA/V
PSRR	Power Supply Rejection Ratio	$V_S = \pm 4.5 \text{V to } \pm 15 \text{V}$	•	60	76		dB
	Negative Input Current Power Supply Rejection	$V_S = \pm 4.5 \text{V to } \pm 15 \text{V}$	•		0.5	5	μA/V
A <sub>VOL</sub>	Large-Signal Voltage Gain	$V_S = \pm 15V, V_{OUT} = \pm 10V, R_L = 1k$	•	57	73		dB
		$V_S = \pm 5V, V_{OUT} = \pm 2V, R_L = 150\Omega$	•	57	66		dB
R <sub>OL</sub>	Transresistance	$V_S = \pm 15V, V_{OUT} = \pm 10V, R_L = 1k$	•	115	310		kΩ
	$\Delta V_0/\Delta I_{IN}^-$	$V_S = \pm 5V$ , $V_{OUT} = \pm 2V$ , $R_L = 150\Omega$	•	115	210		kΩ
V <sub>OUT</sub>	Output Voltage Swing	$V_S = \pm 15V, R_L = 400\Omega, T_A = 25^{\circ}C$		±12	±13.5		V
			•	±10			V
		$V_S = \pm 5V, R_L = 150\Omega, T_A = 25^{\circ}C$		±3.0	±3.7		V
			•	±2.5			V
I <sub>OUT</sub>	Output Current	$R_L = 0\Omega$ , $T_A = 25$ °C		35	55	125	mA
Is	Supply Current (Note 5)	Pin 11 = 5V	•		19	24	mA
		Pin 11 = 0V	•		19	24	mA
		Pin 12 = 0V	•		1.5	3.5	mA
	Disabled Output Resistance	$V_S = \pm 15V$ , Pin 11 = 0V, $V_0 = \pm 5V$ ,					
		$R_F = R_G = 1k$	•	14	25		kΩ
		$V_S = \pm 15V$ , Pin 11 = 0V, $V_0 = \pm 5V$ ,					
		$R_F = 2k$ , $R_G = 222\Omega$	•	8	20		kΩ

## DIGITAL INPUT CHARACTERISTICS

 $0^{\circ}C \leq T_A \leq 70^{\circ}C,~V_S=\pm 15V,~R_F=2k,~R_G=220\Omega,~R_L=400\Omega$  unless otherwise noted.

SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
$\overline{V_{IL}}$	Input Low Voltage	Pins 9, 10, 11, 12	•			0.8	V
$\overline{V_{IH}}$	Input High Voltage	Pins 9, 10, 11, 12	•	2			V
I <sub>IL</sub>	Input Low Current	Pins 9, 10 Voltage = 0V	•		1.5	6	μА
I <sub>IH</sub>	Input High Current	Pins 9, 10 Voltage = 5V	•		10	150	nA
	Enable Low Input Current	Pin 11 Voltage = 0V	•		4.5	15	μА
	Enable High Input Current	Pin 11 Voltage = 5V	•		200	300	μА
I <sub>S/D</sub>	Shutdown Input Current	Pin 12 Voltage $0V \le V_{\overline{S/D}} \le 5V$	•		20	80	μА
t <sub>sel</sub>	Channel-to-Channel Select Time (Note 6)	Pin 8 Voltage = −5V, T <sub>A</sub> = 25°C			120	240	ns
t <sub>dis</sub>	Disable Time (Note 7)	Pin 8 Voltage = −5V, T <sub>A</sub> = 25°C			40	100	ns
t <sub>en</sub>	Enable Time (Note 8)	Pin 8 Voltage = −5V, T <sub>A</sub> = 25°C			110	200	ns
t <sub>S/D</sub>	Shutdown Assert or Release Time (Note 9)	Pin 8 Voltage = −5V, T <sub>A</sub> = 25°C			1.4	3.4	μS



AC CHARACTERISTICS	$T_A = 25$ °C, $V_S = \pm 15$ V, $R_F = R_G = 1$ k, unless otherwise noted.
	$1\Delta - 20$ 0, $1S - 100$ , $11F - 111, - 111, annuous stinut whose instead$

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
$t_r, t_f$	Small-Signal Rise and Fall Time	$R_L = 150\Omega$ , $V_{OUT} = \pm 125$ mV		5.6		ns
SR	Slew Rate (Note 10)	$R_L = 400\Omega$	500	1000		V/µs
	Channel Select Output Transient	All $V_{IN}$ = 0V, $R_L$ = 400 $\Omega$ , Input Referred		40		mV
t <sub>S</sub>	Settling Time	0.1%, V <sub>OUT</sub> = 10V, R <sub>L</sub> = 1k		70		ns
	All Hostile Crosstalk (Note 11)	SO PCB #028, $R_L$ = 100Ω, $R_S$ = 10Ω		92		dB
	Disable Crosstalk (Note 11)	SO PCB #028, Pin 11 Voltage = 0V, $R_L = 100\Omega$ , $R_S = 50\Omega$		95		dB
	Shutdown Crosstalk (Note 11)	SO PCB #028, Pin 12 Voltage = 0V, $R_L = 100\Omega$ , $R_S = 50\Omega$		92		dB
	All Hostile Crosstalk (Note 11)	P-DIP PCB #029, $R_L = 100Ω$ , $R_S = 10Ω$		76		dB
	Disable Crosstalk (Note 11)	P-DIP PCB #029, Pin 11 Voltage = 0V, $R_L = 100\Omega$ , $R_S = 50\Omega$		81		dB
	Shutdown Crosstalk (Note 11)	P-DIP PCB #029, Pin 12 Voltage = 0V, $R_L = 100\Omega$ , $R_S = 50\Omega$		76		dB
	Differential Gain (Note 12)	$V_S = \pm 15V$ , $R_L = 150\Omega$ $V_S = \pm 5V$ , $R_L = 150\Omega$		0.04 0.04		% %
	Differential Phase (Note 12)	$V_S = \pm 15V$ , $R_L = 150\Omega$ $V_S = \pm 5V$ , $R_L = 150\Omega$		0.06 0.12		DEG DEG

The lacktriangle denotes specifications which apply over the specified operating temperature range.

**Note 1:** Analog and digital inputs (Pins 1, 3, 5, 7, 9, 10, 11 and 12) are protected against ESD and overvoltage with internal SCRs. For inputs  $<\pm6V$  the SCR will not fire, voltages above 6V will fire the SCRs and the DC current should be limited to 50mA. To turn off the SCR the pin voltage must be reduced to less than 2V or the current reduced to less than 10mA.

**Note 2:** A heat sink may be required depending on the power supply voltage.

**Note 3:** Commercial grade parts are designed to operate over the temperature range of  $-40^{\circ}$ C to 85°C but are neither tested nor guaranteed beyond 0°C to 70°C. Industrial grade parts specified and tested over  $-40^{\circ}$ C to 85°C are available on special request. Consult factory.

**Note 4:**  $T_J$  is calculated from the ambient temperature  $T_A$  and power dissipation  $P_D$  according to the following formulas:

LT1204CN:  $T_J = T_A + (P_D \times 70^{\circ}C/W)$ LT1204CS:  $T_J = T_A + (P_D \times 90^{\circ}C/W)$ 

**Note 5:** The supply current of the LT1204 has a negative temperature coefficient. For more information see Typical Performance Characteristics.

**Note 6:** Apply 0.5V DC to Pin 1 and measure the time for the appearance of 5V at Pin 15 when Pin 9 goes from 5V to 0V. Pin 10 Voltage = 0V. Apply 0.5V DC to Pin 3 and measure the time for the appearance of 5V at Pin 15 when Pin 9 goes from 0V to 5V. Pin 10 Voltage = 0V. Apply 0.5V DC to Pin 5 and measure the time for the

appearance of 5V at Pin 15 when Pin 9 goes from 5V to 0V. Pin 10 Voltage = 5V. Apply 0.5V DC to Pin 7 and measure the time for the appearance of 5V at Pin 15 when Pin 9 goes from 0V to 5V. Pin 10 Voltage = 5V.

**Note 7:** Apply 0.5V DC to Pin 1 and measure the time for the disappearance of 5V at Pin 15 when Pin 11 goes from 5V to 0V. Pins 9 and 10 are at 0V.

**Note 8:** Apply 0.5V DC to Pin 1 and measure the time for the appearance of 5V at Pin 15 when Pin 11 goes from 0V to 5V. Pins 9 and 10 are at 0V. Above a 1MHz toggle rate, ten reduces.

**Note 9:** Apply 0.5V DC at Pin 1 and measure the time for the appearance of 5V at Pin 15 when Pin 12 goes from 0V to 5V. Pins 9 and 10 are at 0V. Then measure the time for the disappearance of 5V DC to 500mV at Pin 15 when Pin 12 goes from 5V to 0V.

**Note 10:** Slew rate is measured at  $\pm 5V$  on a  $\pm 10V$  output signal while operating on  $\pm 15V$  supplies with  $R_F = 2k$ ,  $R_G = 220\Omega$  and  $R_L = 400\Omega$ .

**Note 11:**  $V_{IN}=0$ dBm (0.223 $V_{RMS}$ ) at 10MHz on any 3 inputs with the 4th input selected. For Disable crosstalk and Shutdown crosstalk all 4 inputs are driven simultaneously. A 6dB output attenuator is formed by a  $50\Omega$  series output resistor and the  $50\Omega$  input impedance of the HP4195A Network Analyzer.  $R_F=R_G=1$ k.

**Note 12:** Differential Gain and Phase are measured using a Tektronix TSG120 YC/NTSC signal generator and a Tektronix 1780R Video Measurement Set. The resolution of this equipment is 0.1% and 0.1°. Five identical MUXs were cascaded giving an effective resolution of 0.02% and 0.02°.

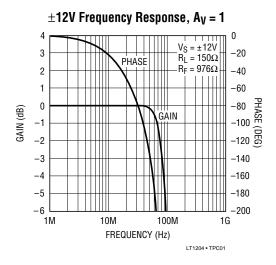
# TYPICAL AC PERFORMANCE Measurements taken from SO Demonstration Board #028.

V <sub>S</sub> (V)	A <sub>V</sub>	$R_L(\Omega)$	$R_F(\Omega)$	<b>R</b> <sub>G</sub> (Ω)	SMALL SIGNAL -3dB BW (MHz)	SMALL SIGNAL 0.1dB BW (MHz)	SMALL SIGNAL PEAKING (dB)
±15	1	150 1k	1.1k 1.6k	None None	88.5 95.6	48.3 65.8	0.1 0
±12	1	150 1k	976 1.3k	None None	82.6 90.2	49.1 63.6	0.1 0.1
±5	1	150 1k	665 866	None None	65.5 68.2	43.6 42.1	0.1 0.1
±15	2	150 1k	787 887	787 887	75.7 82.2	45.8 61.3	0 0.1
±12	2	150 1k	750 845	750 845	71.9 77.5	45.0 52.1	0
±5V	2	150 1k	590 649	590 649	58.0 62.1	32.4 42.7	0 0.1
±15	10	150 1k	866 1k	95.3 110	44.3 47.4	28.7 30.9	0.1 0.1
±12	10	150 1k	825 931	90.9 100	43.5 46.3	27.2 32.1	0 0.1
±5	10	150 1k	665 750	73.2 82.5	37.2 39.3	22.1 27.8	0 0.1

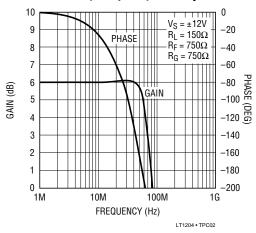
# TRUTH TABLE

A1	A0	ENABLE	SHUTDOWN	CHANNEL SELECTED
0	0	1	1	V <sub>IN 0</sub>
0	1	1	1	V <sub>IN 1</sub>
1	0	1	1	V <sub>IN 2</sub>
1	1	1	1	V <sub>IN 3</sub>
Χ	Χ	0	1	High Z Output
X	Χ	Χ	0	Off

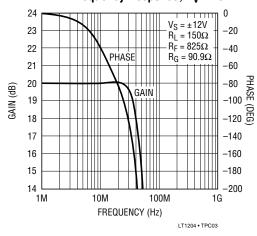




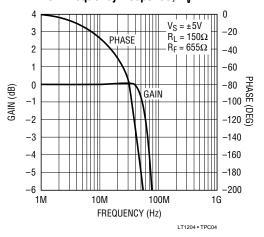




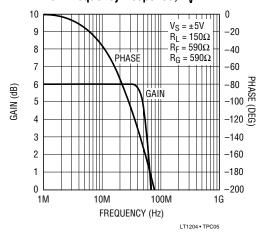
## $\pm 12V$ Frequency Response, $A_V = 10$



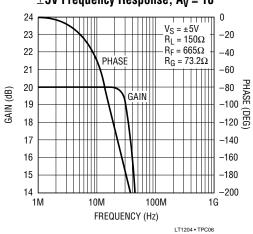
## $\pm$ 5V Frequency Response, A<sub>V</sub> = 1



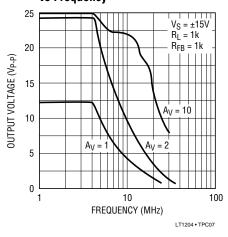
#### $\pm$ 5V Frequency Response, A<sub>V</sub> = 2



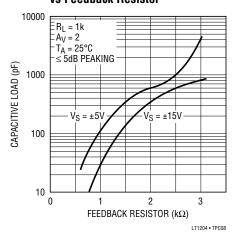
## $\pm$ 5V Frequency Response, A<sub>V</sub> = 10



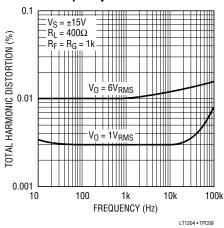
# Maximum Undistorted Output vs Frequency



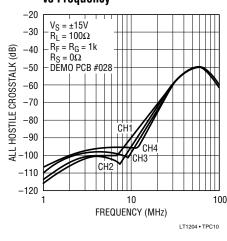
# Maximum Capacitive Load vs Feedback Resistor



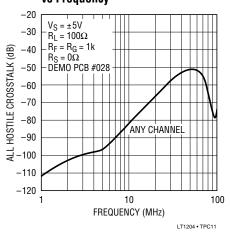
# Total Harmonic Distortion vs Frequency



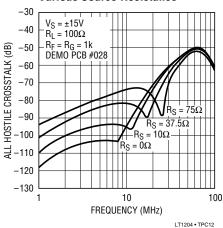
# ±15V All Hostile Crosstalk vs Frequency



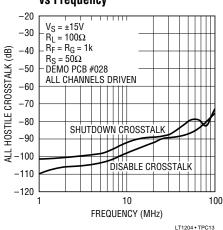
±5V All Hostile Crosstalk vs Frequency



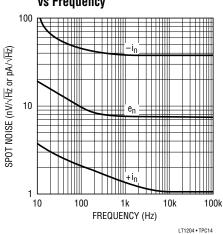
All Hostile Crosstalk vs Frequency, Various Source Resistance



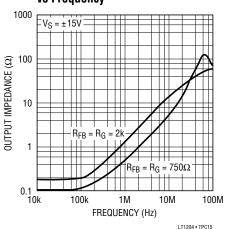
# Disable and Shutdown Crosstalk vs Frequency



Spot Noise Voltage and Current vs Frequency

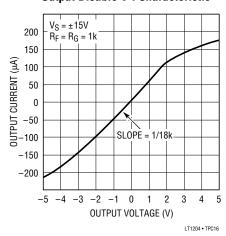


Amplifier Output Impedance vs Frequency

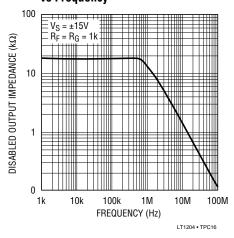




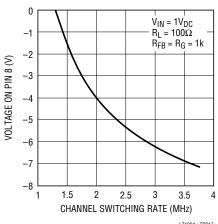
## **Output Disable V-I Characteristic**



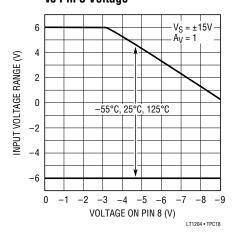
#### **Disabled Output Impedance** vs Frequency



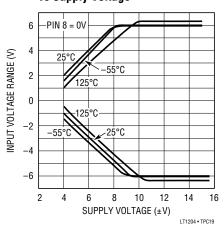
## **Maximum Channel Switching** Rate vs Pin 8 Voltage



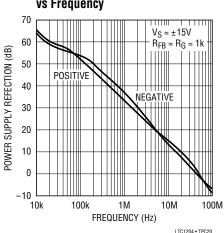
#### **Input Voltage Range** vs Pin 8 Voltage



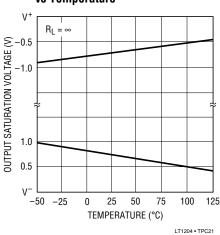
**Input Voltage Range** vs Supply Voltage



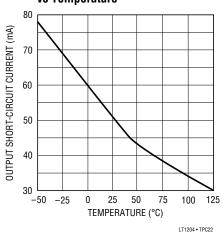
**Power Supply Rejection** vs Frequency



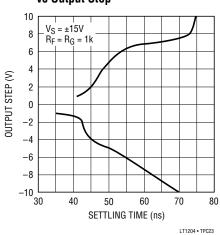
**Output Saturation Voltage** vs Temperature



**Output Short-Circuit Current** vs Temperature



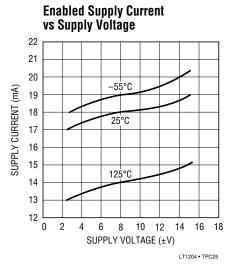
Settling Time to 10mV vs Output Step

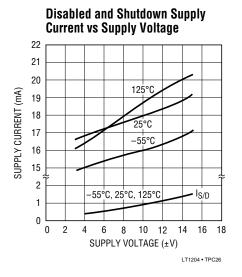




Settling Time to 1mV vs Output Step 10  $V_{S} = \pm 15V$ 8  $R_F = R_G = 1k$ 6 4 OUTPUT STEP (V) 0 -2 -4 -6 -8

6 8





## APPLICATIONS INFORMATION

10 12 14

SETTLING TIME (µs)

16 18 20

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## **Logic Inputs**

The logic inputs of the LT1204 are compatible with all 5V logic. All pins have ESD protection (>2kV), and shorting them to 12V or 15V will cause excessive currents to flow. Limit the current to less than 50mA when driving the logic above 6V.

## **Power Supplies**

The LT1204 will operate from  $\pm 5V$  (10V total) to  $\pm 15V$ (30V total) and is specified over this range. It is not necessary to use equal value supplies, however, the offset voltage and inverting input bias current will change. The offset voltage changes about 600µV per volt of supply mismatch. The inverting bias current changes about 2.5µA per volt of supply mismatch. The power supplies should be bypassed with quality tantalum capacitors.

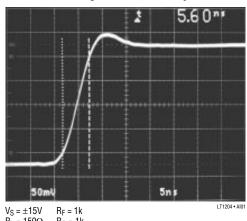
## **Feedback Resistor Selection**

The small-signal bandwidth of the LT1204 is set by the external feedback resistors and internal junction capacitors. As a result the bandwidth is a function of the supply voltage, the value of the feedback resistor, the closedloop gain and the load resistor. These effects are outlined in the resistor selection guide of the Typical AC Performance table. Bandwidths range as high as 95MHz and are

specified over a very wide range of conditions. An advantage of the current feedback topology used in the LT1204 is well-controlled frequency response. In all cases of the performance table the peaking is 0.1dB or less. If more peaking can be tolerated, larger bandwidths can be obtained by lowering the feedback resistor. For gains of 2 or less, the 0.1dB bandwidth is greater than 30MHz for all loads and supply voltages.

At high gains (low values of R<sub>G</sub>) the disabled output resistance drops slightly due to loading of the internal buffer amplifier as discussed in Multiplexer Expansion.

Small-Signal Rise Time,  $A_V = 2$ 



 $R_L = 150\Omega$  $R_G = 1k$ 



## Capacitance on the Inverting Input

Current feedback amplifiers require resistive feedback from the output to the inverting input for stable operation. Take care to minimize the stray capacitance between the output and the inverting input. Capacitance on the inverting input to ground will cause peaking in the frequency response and overshoot in the transient response.

## **Capacitive Loads**

The LT1204 can drive capacitive loads directly when the proper value of feedback resistor is used. The graph of Maximum Capacitive Load vs Feedback Resistor should be used to select the appropriate value. The value shown is for 5dB peaking when driving a 1k load at a gain of 2. This is a worst case condition. The amplifier is more stable at higher gains and driving heavier loads. Alternatively, a small resistor ( $10\Omega$  to  $20\Omega$ ) can be put in series with the output to isolate the capacitive load from the amplifier output. This has the advantage that the amplifier bandwidth is only reduced when the capacitive load is present. The disadvantage is that the gain is a function of load resistance.

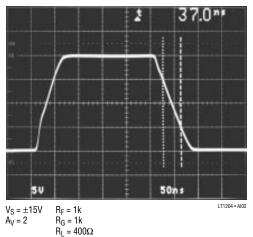
#### Slew Rate

The slew rate of the current feedback amplifier on the LT1204 is not independent of the amplifier gain the way slew rate is in a traditional op amp. This is because both the input and the output stage have slew rate limitations. In high gain settings the signal amplitude between the negative input and any driven positive input is small and the overall slew rate is that of the output stage. For gains less than 10, the overall slew rate is limited by the input stage.

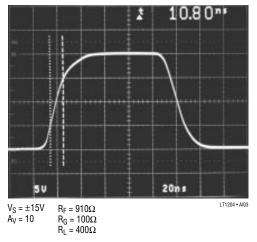
The input slew rate of the LT1204 is approximately 135V/  $\mu s$  and is set by internal currents and capacitances. The output slew rate is set by the value of the feedback resistors and the internal capacitances. At a gain of 10 with a 1k feedback resistor and  $\pm 15$  supplies, the output slew rate is typically  $1000V/\mu s$ . Larger feedback resistors will reduce the slew rate as will lower supply voltages, similar to the way the bandwidth is reduced.

The graph, Maximum Undistorted Output vs Frequency, relates the slew rate limitations to sinusoidal inputs for various gain configurations.

#### **Large-Signal Transient Response**



**Large-Signal Transient Response** 

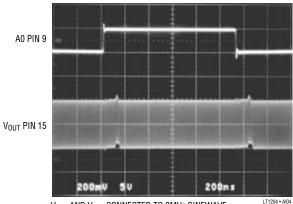


## **Switching Characteristics and Pin 8**

Switching between channels is a "make-before-break" condition where both inputs are on momentarily. The buffers isolate the inputs when the "make-before-break" switching occurs. The input with the largest positive voltage determines the output level. If both inputs are equal, there is only a 40mV error at the input of the CFA during the transition. The reference adjust (pin 8) allows the user to trade off positive input voltage range for switching time. For example, on  $\pm 15$ V supplies, setting the voltage on pin 8 to -6.8V reduces the switching transient to a 50ns duration, and reduces the positive input range from 6V to 2.35V. The negative input range remains unchanged at -6V. When switching video "in picture," this short transient is imperceptible even on high quality

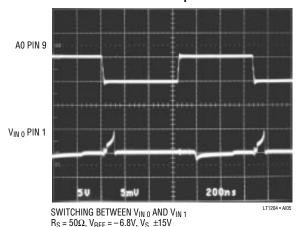
monitors. The reference pin has no effect when the LT1204 is operating on  $\pm 5$ V, and should be grounded. On supply voltages above  $\pm 8$ V, the range of voltages for pin 8 should be between -6.5V and -7.5V. Reducing pin 8 voltage below -7.5V turns "on" the "off" tee switch, and the isolation between channels is lost.

#### **Channel-to-Channel Switching**



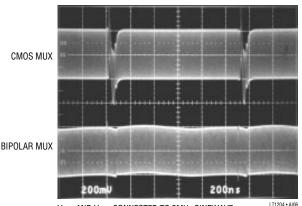
 $V_{\text{IN 0}}$  and  $V_{\text{IN 1}}$  connected to 2MHz sinewave PIN 8 Voltage = -6.8V,  $V_{\text{S}} = \pm 15$ V

#### **Transient at Input Buffer**



Competitive video multiplexers built in CMOS are bidirectional and suffer from poor output-to-input isolation and cause transients to feed to the inputs. CMOS MUXs have been built with "break-before-make" switches to eliminate the talking between channels, but these suffer from output glitches large enough to interfere with sync circuitry. Multiplexers built on older bipolar processes that switch lateral PNP transistors take several µs to settle and blur the transition between pictures.

#### **Competitive MUXs**



VIN 0 AND VIN 1 CONNECTED TO 2MHz SINEWAVE

#### Crosstalk

The crosstalk, or more accurately all hostile crosstalk, is measured by driving a signal into any 3 of the 4 inputs and selecting the 4th input with the logic control. This 4th input is either shorted to ground or terminated in an impedance. All hostile crosstalk is defined as the ratio in dB of the signal at the output of the CFA to the signal on the 3 driven inputs, and is input referred. Disable crosstalk is measured with all 4 inputs driven and the part disabled. Crosstalk is critical in many applications where video multiplexers are used. In professional video systems a crosstalk figure of -72dB is a desirable specification.

The key to the outstanding crosstalk performance of the LT1204 is the use of tee switches (see Figure 1). When the tee switch is on (Q2 off) Q1 and Q3 are a pair of emitter followers with excellent AC response for driving the CFA. When the decoder turns off the tee switch (Q2 on) the

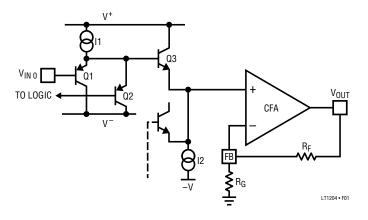


Figure 1. Tee Switch



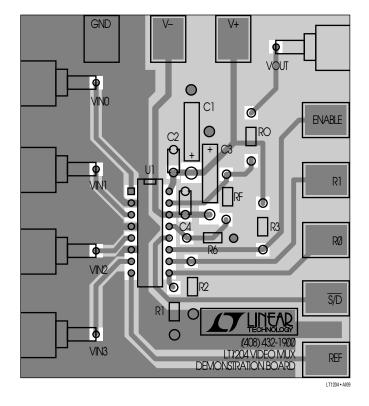
emitter base junctions of Q1 and Q3 become reverse biased while Q2 emitter absorbs current from I1. Not only do the reverse biased emitter base junctions provide good isolation, but any signal at  $V_{IN\ 0}$  coupling to Q1 emitter is further attenuated by the shunt impedance of Q2 emitter. Current from I2 is routed to any on switch.

Crosstalk performance is a strong function of the IC package, the PC board layout as well as the IC design. The die layout utilizes grounds between each input to isolate adjacent channels, while the output and feedback pins are on opposite sides of the die from the input. The layout of a PC board that is capable of providing -90dB all hostile crosstalk at 10MHz is not trivial. That level corresponds to a  $30\mu V$  output below a 1V input at 10MHz. A demonstration board has been fabricated to show the component and ground placement required to attain these crosstalk numbers. A graph of all hostile crosstalk for both the P-DIP and

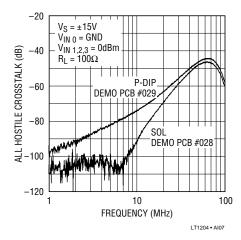
these PC boards that capacitive coupling across the package of greater than 3fF (0.003pF) will diminish the rejection, and it is recommended that this proven layout be copied into designs. The key to the success of the SOL PC board #028 is the use of a ground plane guard around pin 13, the feedback pin.

SO packages is shown. It has been found empirically from

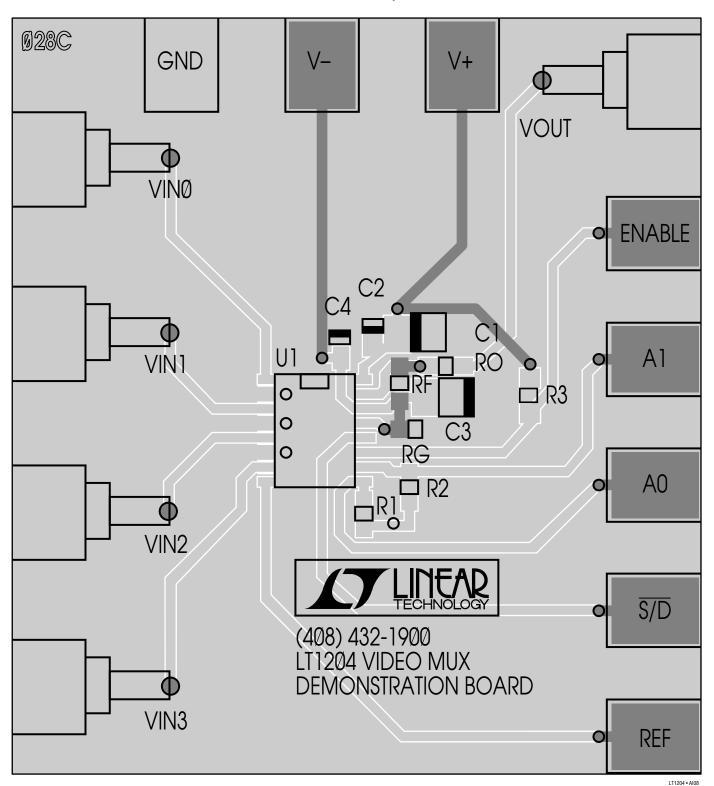
## P-DIP PC Board #029, Component Side



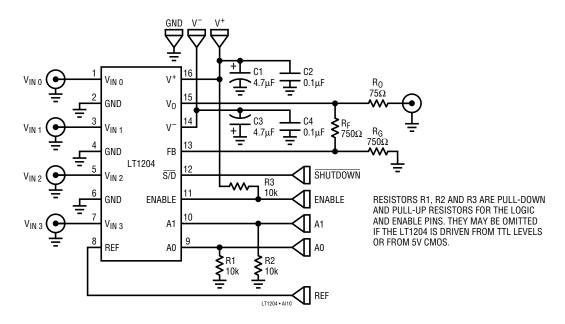
#### **All Hostile Crosstalk**



SOL PC Board #028, Component Side



## **Demonstration PC Board Schematic**



#### All Hostile Crosstalk Test Setup\*

HP4195A

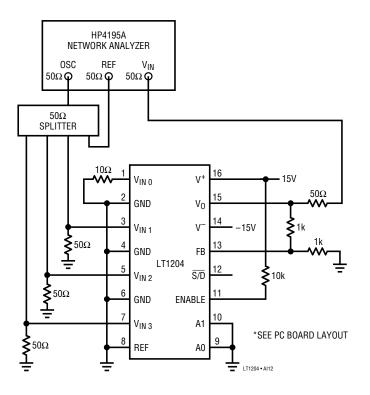
REF

#### NETWORK ANALYZER OSC REF $V_{IN}$ 50Ω 🛱 $50\Omega \mathbf{Q}$ $50\Omega \mathbf{Q}$ $50\Omega$ SPLITTER ۷+ V<sub>IN 0</sub> $50\Omega$ GND $V_0$ -15V ٧ V<sub>IN 1</sub> GND FB LT1204 S/D $V_{\text{IN 2}}$ **≨**10k ENABLE GND Α1 V<sub>IN 3</sub> \*SEE PC BOARD LAYOUT

Α0

\_\_\_\_ LT1204 • Al11

## Alternate All Hostile Crosstalk Setup\*

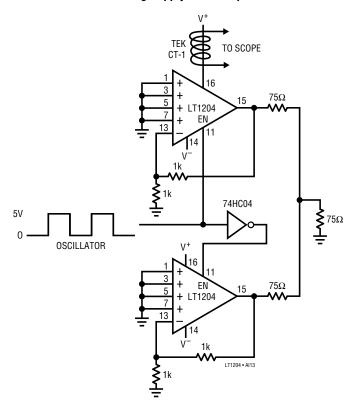


**≸**50Ω

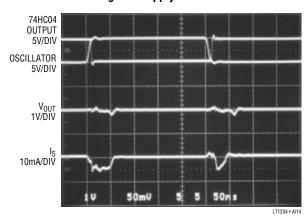
## Multiplexer Expansion Pin 11 and Pin 12

To expand the number of MUX inputs, LT1204s can be paralleled by shorting their outputs together. The multiplexer disable logic has been designed to prevent shoot-through current when two or more amplifiers have their outputs shorted together. (Shoot-through current is a spike of power supply current caused by both amplifiers being on at once.)

#### **Monitoring Supply Current Spikes**



#### **Timing and Supply Current Waveforms**



The multiplexer uses a circuit to ensure the disabled amplifiers do not load or alter the cable termination. When the LT1204 is disabled (pin 11 low) the output stage is turned off and an active buffer senses the output and drives the feedback pin to the CFA (Figure 2). This bootstraps the feedback resistors and raises the true output impedance of the circuit. For the condition where  $R_F = R_G = 1k$ , the Disable Output Resistance is typically raised to 25k and drops to 20k for  $A_V = 10$ ,  $R_F = 2k$  and  $R_G = 222\Omega$  due to loading of the feedback buffer. Operating the Disable feature with  $R_G < 100\Omega$  is not recommended.

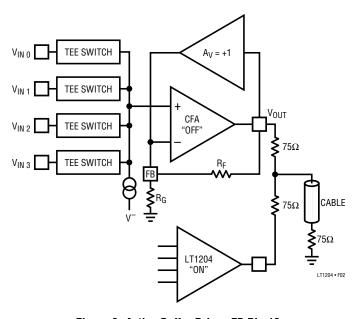


Figure 2. Active Buffer Drives FB Pin 13

A shutdown feature (pin 12 low) reduces the supply current to 1.5mA and lowers the power dissipation when the LT1204 is not in use. If the part is shut down, the bootstrapping is inoperative and the feedback resistors will load the output. If the CFA is operated at a gain of  $\pm 1$ , however, the feedback resistor will not load the output even in shutdown because there is no resistive path to ground, but there will be a  $\pm 6$ dB loss through the cable system.

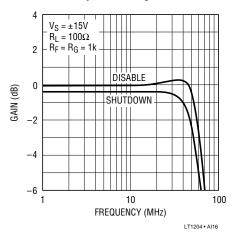
A frequency response plot shows the effect of using the disable feature versus using the shutdown feature. In this example 4 LT1204s were connected together at their outputs forming a 16-to-1 MUX. The plot shows the effect of the bootstrapping circuit that eliminates the



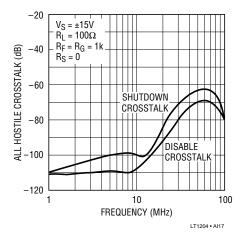
improper cable termination due to feedback resistors loading the cable.

The limit to the number of expanded inputs is set by the acceptable error budget of the system.

16-to-1 MUX Response Using Disable vs Shutdown



16-to-1 Multiplexer All Hostile Crosstalk



For a 64-to-1 MUX we need 16 LT1204s. The equivalent load resistance due to the feedback resistor  $R_{EQ}$  in Disable is 25k/15 = 1.67k. See Figure 3.

$$V_0 = \frac{75R_{EQ}}{75(75) + 150R_{EQ}}, V_0 = 0.489V$$

This voltage represents a 2.1% loading error. If the shutdown feature is used instead of the disable feature, then the LT1204 could expand to only an 8-to-1 MUX for the same error.

As a practical matter the gain error at frequency is also set by capacitive loading. The disabled output capacitance of the LT1204 is about 8pF, and in the case of 16 LT1204s, it would represent a 128pF load. The combination of 1.67k and 128pF correspond to about a 0.3dB roll-off at 5MHz.

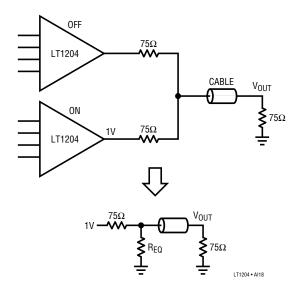


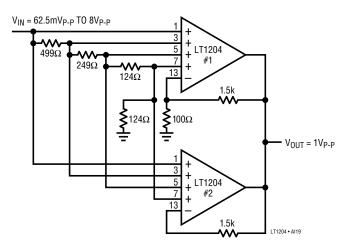
Figure 3. Equivalent Loading Schematic

## TYPICAL APPLICATIONS

## Programable Gain Amplifier (PGA)

Two LT1204s and seven resistors make a Programable Gain Amplifier with a 128-to-1 gain range. The gain is proportional to 2<sup>N</sup> where N is the 3-bit binary value of the select logic. An input attenuator alters the input signal

# Programable Gain Amplifier Accepts Inputs from $62.5mV_{P-P}$ to $8V_{P-P}$

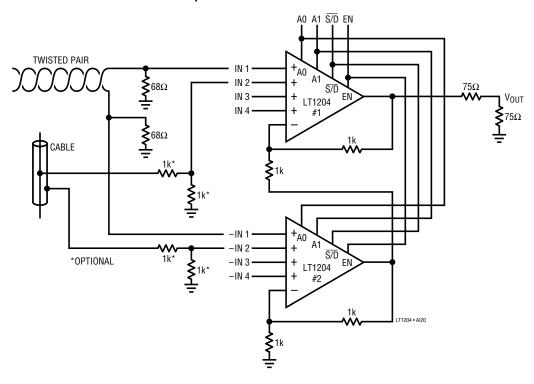


by 1, 0.5, 0.25 and 0.125 to form an amplifier with a gain of 16, 8, 4, 2, when LT1204 #1 is selected. LT1204 #2 is connected to the same attenuator. When enabled (LT1204 #1 disabled), it results in gain of 1, 0.5, 0.25 and 0.125. The wide input common-mode range of the LT1204 is needed to accept inputs of  $8V_{P-P}$ .

## **4-Input Differential Receiver**

LT1204s can be connected inverting and noninverting as shown to make a 4-input differential receiver. The receiver can be used to convert differential signals sent over a low cost twisted-pair to a single-ended output or used in video loop-thru connections. The logic inputs A0 and A1 are tied together because the same channels are selected on each LT1204. By using the Disable feature, the number of differential inputs can be increased by adding pairs of LT1204s and tying the outputs of the noninverting LT1204s (#1) together. Switching transients are reduced in this receiver because the transient from LT1204 #2 subtracted from the transient of LT1204 #1.

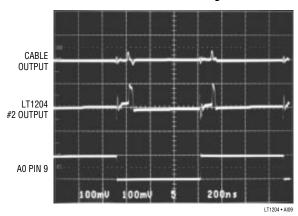
#### 4-Input Differential Receiver



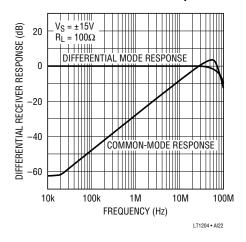


## TYPICAL APPLICATIONS

#### **Differential Receiver Switching Waveforms**



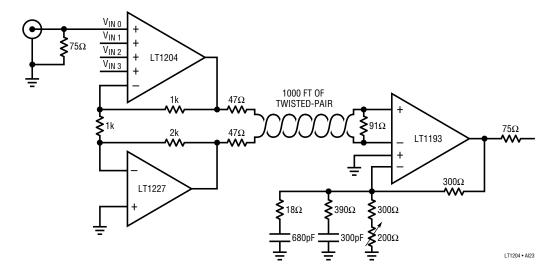
#### **Differential Receiver Response**



#### 4-Input Twisted-Pair Driver

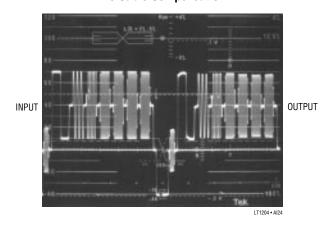
It is possible to send and receive color composite video signals appreciable distances on a low cost twisted-pair. The cost advantage of this technique is significant. Standard  $75\Omega$  RG-59/U coaxial cable cost between 25¢ and 50¢ per foot. PVC twisted-pair is only pennies per foot. Differential signal transmission resists noise because the interference is present as a common-mode signal. The LT1204 can select one of four video cameras for instance. and drive the video signal on to the twisted-pair. The circuit uses an LT1227 current feedback amplifier connected with a gain of -2, and an LT1204 with a gain of 2. The  $47\Omega$ resistors back-terminate the low cost cable in its characteristic impedance to prevent reflections. The receiver for the differential signal is an LT1193 connected for a gain of +2. Resistors R1, R2 and capacitors C1, C2 are used for cable compensation for loss through the twisted-pair. Alternately, a pair of LT1204s can be used to perform the differential to single-ended conversion.

#### 4-Input Twisted-Pair Driver/Receiver

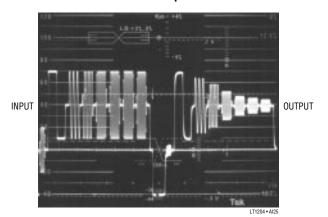


## TYPICAL APPLICATIONS

Multiburst Pattern Passed Through 1000 Feet of Twisted-Pair, No Cable Compensation

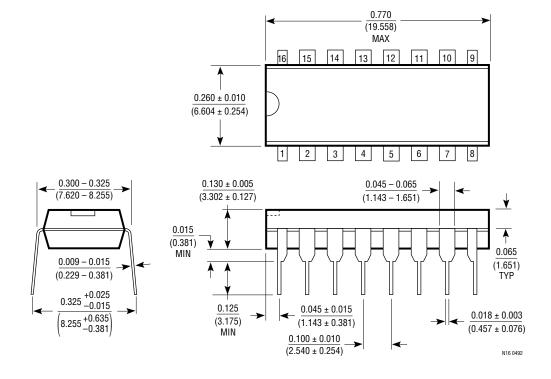


Multiburst Pattern Passed Through 1000 Feet of Twisted-Pair, with Cable Compensation



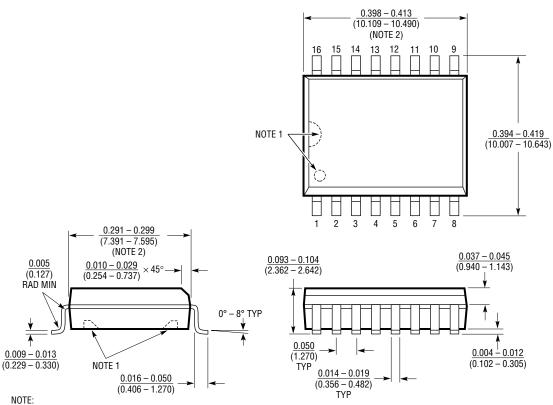
# PACKAGE DESCRIPTION Dimensions in inches (millimeters) unless otherwise noted.

#### N Package 16-Lead Plastic DIP



# PACKAGE DESCRIPTION Dimensions in inches (millimeters) unless otherwise noted.

#### S Package 16-Lead Plastic SOL



1. PIN 1 IDENT, NOTCH ON TOP AND CAVITIES ON THE BOTTOM OF PACKAGES ARE THE MANUFACTURING OPTIONS. THE PART MAY BE SUPPLIED WITH OR WITHOUT ANY OF THE OPTIONS.

2. THESE DIMENSIONS DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS. MOLD FLASH OR PROTRUSIONS SHALL NOT EXCEED 0.006 INCH (0.15mm). SOL16 0392