



# **Digital Signal Processor for Karaoke Systems**

## Overview

The LC83026E provides the audio signal processing required in karaoke systems, including pitch shift, microphone echo, voice muting, and simple surround simulation. It is a special-purpose DSP that implements karaoke processing with the addition of a single external 256-Kb DRAM. The LC83026E includes on-chip A/D and D/A converters and supports both digital and analog inputs and outputs. Its functions and characteristics can be modified to match the needs of the end product by sending coefficient data from the microcontroller over a serial interface.

#### **Features**

- · Application features
  - Pitch shift

The LC83026E supports pitch shifting of  $\pm 15$  quarter tone steps, or  $\pm 1$  octave in scale tone units as specified by command data. This pitch shifting can be applied either to the music track or to the microphone input. It is also possible to set up pitch shifting of  $\pm 1$  octave in arbitrary steps by setting coefficient values.

- Microphone echo

The LC83026E can apply echo processing to the input signal from the microphone A/D converter. The echo coefficients, including amount of echo and delay time, can be set.

— Voice muting

The LC83026E provides attenuation of monaural components in the music signal. This allows CDs that include vocals to be used for karaoke. The voice muting function is turned on or off by command data transferred over the serial interface.

— Simple surround

The LC83026E implements a simple surround simulation function by adding delay components to the music signal. The LC83026E includes six sets of simple surround coefficients as preset data, and these can be selected and switched using command data transferred over the serial interface. User-original surround effects can be implemented by setting

coefficients, but the algorithm is fixed.

Versatile input mixing

The LC83026E supports hybrid mixing of digital music inputs and analog music inputs for both the left and right channels to support the processing of a wide range of disks.

Audio inputs and outputs

— Inputs: Digital One system (stereo)

A/D converters Three channels

Outputs: Digital One system (stereo)

D/A converters Two channels

A/D converters

Second-order delta-sigma modulation

Three channels

D/A converters

2× oversampling digital filters + third-order noise shaper system Two channels

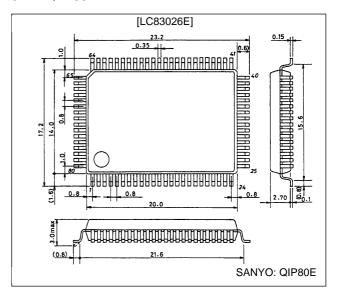
Master clock: 768fs

- External memory: Up to two 256K (64K × 4 bits) external DRAMs can be used.
- Microcontroller input: Synchronous 8-bit serial data
- Power-supply voltage: 5V single-voltage supply
- Package: QFP80E

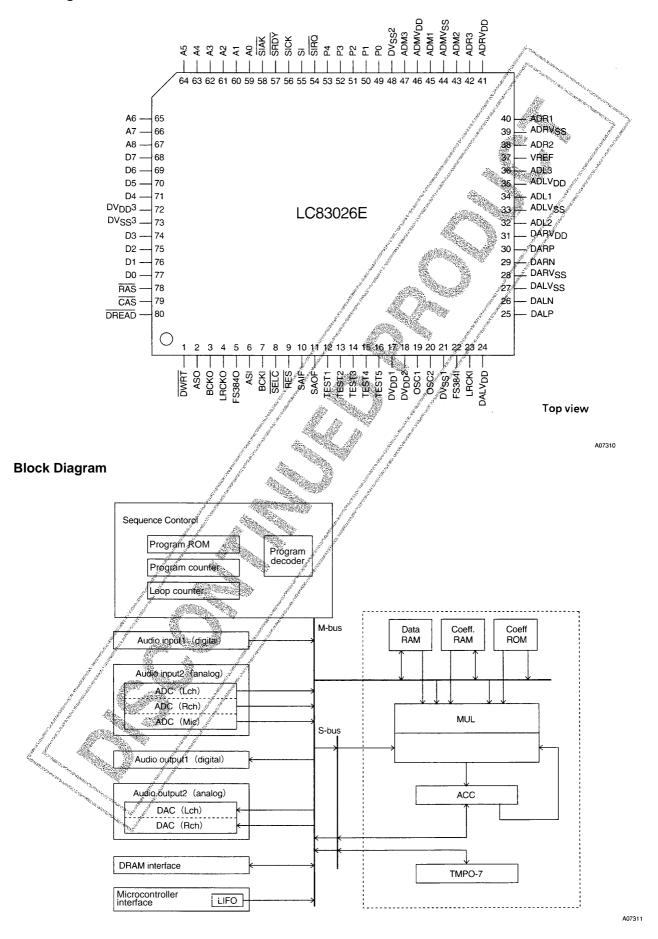
## **Package Dimensions**

unit: mm

#### 3174-QFP80E



## **Pin Assignment**



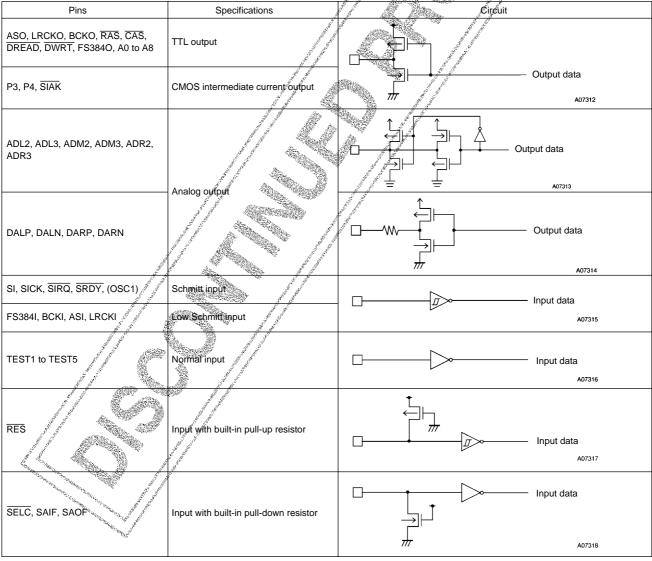
## **Pin Functions**

	Pin	Pin No.	I/O	Function
	OSC1	19	ı	Crystal oscillator connection (768fs)
	OSC2	20	0	Crystal oscillator connection (768fs)
	FS384I	22	1	384fs input
	SELC	8	1	Audio clock source switching (High: external, low: internal)
,,	SAIF	10	1	Digital audio input mode switching (Low: backward packing, high: forward packing)
pins	SAOF	11		Digital audio output mode switching (Low: 48fs, high 64fs)
Control	RES	9	1	Reset
S	TEST5 to 1	16 to 12	1	Test (Must be connected to ground during normal operation.)
	P0	49	ı	Coefficient transfer mode control
	P2 to P1	51, 50	1	Initial operating mode control (A high level should be applied for normal operation).
	P3	52	0	Microphone signal input level: Yes (low output)/No (high output) output
	P4	53	0	Music signal input level: Yes (low output)/No (high output) output
8	RAS	78	0	RAS signal output
terfa	CAS	79	0	CAS signal output
r j	DREAD	80	0	External memory read signal output
emo	DWRT	1	0	External memory write signal output
la L	A8 to A0	67 to 59	0	Address output
External memory interface	D7 to D0	68 to 71,	I/O	Data input and output (Normally only D0 to D3 are used)
ш		74 to 77		
	LRCKI	23		ASI L/R clock input (1fs)
	LRCKO	4	0	ASO L/R clock output (1fs)
	BCKI	7		ASI bit clock input (32fs or higher)
	BCKO FS384O	3 5	0	ASO bit clock output (48fs or 64fs) ASO 384fs output
	ASI	6	ı	Digital audio data input (16-bits, MSB first)
	ASO	2	0	Digital audio data input (16-bits, MSB first; backward packed)
	ADL1	34	ı	A/D converter input (left channel)
l e	ADL1	32	0	A/D converter input (fert channel)
erfa	ADL3	36	0	A/D converter output (left charine)
int	ADR1	40	ı	A/D converter input (right change)
Audio interface	ADR2	38	0	A/D converter output (right change).
`	ADR3	42	0	A/D converter output (right channel)
	ADM1	45	ı	A/D converter input (microphone)
	ADM2	43	0	A/D converter output (microphone)
	ADM3	47	0	A/D converter output (microphone)
	DALP	25	Q	D/A converter output (left channel)
	DALN	26	jo,	D/A converter output (left channel)
	DARP	30	O	D/Aconverter output (right channel)
	DARN	29/	0	D/A converter output (right channel)
ace	SIRQ	54	I/	Input for the serial input request signal
r inter	SIAK	58	0	Output that indicates that a serial input is in progress
Microcontroller interface	SI	55		Serial data input from the control microcontroller (8-bit serial input)
Cocor	SICK	56		Supin transfer clock input
ğ	SRDY /	57	15.5° L	Ready signal input (from the control microcontroller) that indicates the completion of a serial data input.

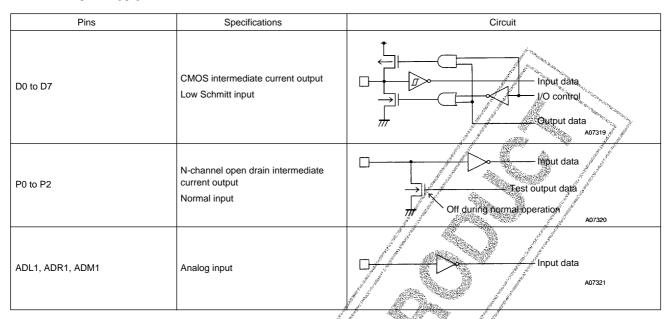
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	Pin	Pin No.	I/O	Function	
	DV <sub>DD</sub> 1 to 3	17, 18, 72	_	Digital block V <sub>DD</sub> (Must be connected to +5 V.)	
				<make any="" as="" between="" connections="" differences="" no="" occur="" of="" possible="" potential="" short="" so="" that="" the="" v<sub="">DD pins.&gt;</make>	
	DV <sub>SS</sub> 1 to 3	21, 48, 73	_	Digital block V <sub>SS</sub> (Must be connected to ground.)	
				<make any="" as="" between="" connections="" differences="" no="" occur="" of="" possible="" potential="" short="" so="" that="" the="" v<sub="">SS pins.&gt;</make>	
	ADLV <sub>DD</sub>	35	_	A/D converter V <sub>DD</sub> (left channel) (Connect to +5 V.)	
<u>&gt;</u>	ADRV <sub>DD</sub>	41	_	A/D converter V <sub>DD</sub> (right channel) (Connect to +5 V.)  Design the wiring so that potential differences do	
supply	ADMV <sub>DD</sub>	46	_	A/D converter V <sub>DD</sub> (microphone) (Connect to +5 V.)  not occur between the analog system V <sub>DD</sub> pins and either other analog system V <sub>DD</sub> pins or the digital.	
	DALV <sub>DD</sub>	24	_	D/A converter V <sub>DD</sub> (left channel) (Connect to +5 V.) system V <sub>DD</sub> pins.	
Power	DARV <sub>DD</sub>	31	_	D/A converter V <sub>DD</sub> (right channel) (Connect to +5 V.)	
	ADLV <sub>SS</sub>	33	_	A/D converter V <sub>SS</sub> (left channel) (Connect to ground.)	
	ADRV <sub>SS</sub>	39	_	A/D converter V <sub>SS</sub> (right channel) (Connect to ground.) Design the wiring so that potential differences do	
	ADMV <sub>SS</sub>	44	_	A/D converter V <sub>SS</sub> (microphone) (Connect to ground.) not occur between the analog system V <sub>SS</sub> pins and	
	DALV <sub>SS</sub>	27	_	D/A converter V <sub>SS</sub> (left channel) (Connect to ground.)  either other analog system V <sub>SS</sub> pins or the digital system V <sub>SS</sub> pins.	
	DARV <sub>SS</sub>	28	_	D/A converter V <sub>SS</sub> (right channel) (Connect to ground.)	

### **Pin Circuits**



Continued from preceding page.



# **Specifications**

Absolute Maximum Ratings at  $Ta = 25^{\circ}C$ ,  $V_{SS} = 0$ 

Parameter	Symbol	Conditions	Ratings	Unit	Notes
Maximum supply voltage	V <sub>DD</sub> max		-0.3 to +7.0	V	
Input voltage	V <sub>IN</sub>		-0.3 to V <sub>DD</sub> +0.3	V	
Output voltage	V <sub>O</sub> 1	OSC2 output	Values up to the oscillator voltage are allowable.	V	
	V <sub>0</sub> 2	Outputs other than OSC2	-0.3 to V <sub>DD</sub> +0.3	V	
	√Î <sub>Q</sub> ∌1	Audio interface, external RAM interface	-2 to +4	mA	1
Peak output current	√ A <sub>OP</sub> 2	Microcontroller interface, P3, P4	−2 to +10	mA	2
je god	I <sub>OA</sub> 1	Audio interface, external RAM interface: Per pin	-2 to +4	mA	1
get and the second of the seco	I <sub>OA</sub> 2	Microcontroller interface, P3, P4: Per pin	−2 to +10	mA	2
Average output current	∑lo <sub>A</sub> 1	FS384O, LRCKO, BCKO, ASO : Total	-10 to +10	mA	
graph of the state	< Σ1 <sub>0A</sub> 2	DWRT, DREAD, RAS, CAS, A0 to A8, D0 to D7, SIAK, P3, P4, Total	-10 to +10	mA	
Allowable power dissipation	Pd max	Ta = ,⊬3,0 to +70°C	700	mW	
Operating temperature	Topr		-30 to +70	°C	
Storage temperature	Tstg	11	-40 to +125	°C	

# Allowable Operating Ranges at Ta = -30 to $\pm 70^{\circ}$ C, all $V_{DD} = 4.75$ to 5.25 V, all $V_{SS} = 0$ V unless otherwise specified

Determeter	Sambol	Conditions		Ratings			Notes
Parameter	Symbol	Conditions	min	typ	max	Offic	Notes
Operating supply voltage	$V_{DD}$		4.75		5.25	V	
	V <sub>IH</sub> 1	Audio interface and external RAM interface	2.4			V	4
Input high-level vortage	V <sub>IH</sub> 2	P0 to P2, SELC, SAIF, SAOF, TEST1 to TEST5	0.7 V <sub>DD</sub>			V	5
	V <sub>IH</sub> 3	RES, OSC1, and the microcontroller interface	0.75 V <sub>DD</sub>			V	6
	V <sub>IL</sub> 1	Audio interface and external RAM interface			0.8	V	4
Input low-level voltage	V <sub>IL</sub> 2	P0 to P2, SELC, SAIF, SAOF, TEST1 to TEST5			0.3 V <sub>DD</sub>	V	5
	V <sub>IL</sub> 3	RES, OSC1, and the microcontroller interface			0.25 V <sub>DD</sub>	V	6
Instruction cycle time	t <sub>CYC</sub>		58		59.11	ns	

## Continued from preceding page.

Parameter	Symbol Conditions			Ratings				
Parameter	Symbol	Conditions	min	typ	max	Uniii	Notes	
[External Clock Input Conditions]								
Frequency	f <sub>EXT</sub>	Related to the FS384I pin. See Figure 1.	16.85	11	17.01	MHz		
Dula a widelik	f <sub>EXTH</sub>	maximum: 44.1 kHz × 384 × 1.005	23	11	A. S. Carlotte	ns		
Pulse width	f <sub>EXTL</sub>	minimum: 44.1 kHz × 384 × 0.995	23,**	1 19	1.00	ns		
Rise time	t <sub>EXTR</sub>				9	ns		
Fall time	t <sub>EXF</sub>		A Part of	2000	9	ns		
[Self-Excited Oscillation Conditions(crystal oscill	ator)]		gard galder					
Oscillator frequency	fosc	OSC1 and OSC2. See Figure 2.	33.84		40,55	MHz		
Community modules	.030	44.1 kHz/48 kHz × 768 ±0.1%	/ 0010 1.5		77			
Oscillator stabilization period	toscs	See Figure 3.	A Carry		/ 100	ms		
[Audio Data Input Conditions]			p Signal					
Transfer bit clock period	t <sub>BCYC</sub>	Related to BCKI. See Figure 4	354	J.	1	ns		
Transfer bit clock pulse width	t <sub>BCW</sub>		100	J <sup>e</sup>		ns		
Data setup time	ts		70	pa <sup>ce</sup> pe		ns		
Data hold time	t <sub>H</sub>	//	70	and the second		ns		
[Serial I/O Clock Conditions]			e e e e e e e e e e e e e e e e e e e	A. C.				
Serial clock period	t <sub>SCYC</sub>		/ 480°	<i>y</i> **		ns		
Serial clock pulse width	t <sub>SCW</sub>		200			ns		
Data setup time	t <sub>SS</sub>	Related to the microcontroller interface.  See Figure 5. (Related to SICK, SI, and	7/70			ns		
Data hold time	t <sub>SH</sub>	SRDY.)	<i>[</i> ] 70			ns		
SRDY hold time	tsyH		a <sup>th</sup> 200			ns		
SRDY pulse width	t <sub>SYW</sub>		200			ns		
[DRAM Input Conditions]	[DRAM Input Conditions]							
Input data setup time	t <sub>DSI</sub>	Related to external DRAM data input. See	20			ns		
Input data hold time	t <sub>DHI</sub>	Figure 6. (Related to CAS and D0 to D7.)	0			ns		

# Electrical Characteristics 1 at Ta = -30 to +70 °C, all $V_{DD} = 4.75$ to 5.25 V, all $V_{SS} = 0$ V unless otherwise specified

Doromotor	// sumba	Conditions		1.1	Notes			
Parameter	Symbol		min	typ	max	Offic	Notes	
Input high-level current	I <sub>IH</sub> 1	SEEC, SAIF, SAOF, V <sub>IN</sub> = V <sub>DD</sub> (Input pins with pull-down resistors)		100	250	μA	8	
input riigh-level current	11-12	P0 to P2, V <sub>IN</sub> = V <sub>DD</sub> (Nch transistor OFF)			10	μΑ		
	-\ <sub>H</sub> 3	Other input-only pins			10	μA		
	I <sub>IL</sub> 1	RES, V <sub>IN</sub> = V <sub>SS</sub> (Input pins with pull-up resistors)	-250	-100		μA	8	
Input low-level current	√ I <sub>IL</sub> 2√ √	P0 to P2, V <sub>IN</sub> = V <sub>SS</sub>	-10			μΑ		
	l <sub>l</sub> L3	Other input-only pins	-10			μA		
Outside to A. Australia	V <sub>ØH</sub> 1	$I_{OH} = -0.4 \text{ mA}$	4.0	4.98		V	1, 8	
Output high-level voltage	√ No <sub>H</sub> 2	I <sub>OH</sub> = -50 μA	V <sub>DD</sub> -1.2	4.997		V	2,3,8	
	√ V <sub>OL</sub> 1	I <sub>OL</sub> = 2 mA		0.065	0.4	V	1, 8	
Output low-level voltage	V <sub>OL</sub> 2	I <sub>OL</sub> = 10 mA		0.32	1.5	V	2,3,8	
Output off leakage current	l <sub>OFF</sub>	$V_O = V_{SS}, V_{DD}$	-40		+40	μA		
Input and output capacitance	C <sub>IO</sub>				10	pF		
[Audio Data Output Timing]								
Output data hold time	tон	BCK0 and ASO. See Figure 7.	-30			ns	7	
Output data delay time	t <sub>OD</sub>	DONO and AGO. Gee I igule 1.			50	ns	7	

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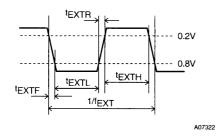
Parameter	Symbol	Conditions		Ratings	Unit	Notes	
Parameter	Symbol	Conditions	min	typ	max	Unit	Notes
[External DRAM Access Timing]				12			
RAS high-level pulse width	t <sub>RP</sub>		80	A Street Street		ns	7
RAS low-level pulse width	t <sub>RAS</sub>		700		and the state of t	ns	7
CAS high-level pulse width	t <sub>CP</sub>		50-	1 100	The state of the s	, ns	7
CAS low-level pulse width	t <sub>CAS</sub>		/95 <sup>47</sup>	A.S.	Contract of the Contract of th	ns	7
CAS cycle time	t <sub>PC</sub>		175	18		/ ns	7
RAS to CAS delay time	t <sub>RCD</sub>		<i>A</i> 60			ns	7
CAS hold time	t <sub>CSH</sub>	L	170		distrib <sup>1</sup> Market	ns	7
RAS hold time	t <sub>RSH</sub>	Output timing to the external DRAM.  See Figure 8.	95	1000		ns	7
RAS address setup time	t <sub>ASR</sub>	Goo'r Igaro o.	60		111	ns	7
RAS address hold time	t <sub>RAH</sub>		20			ns	7
CAS address setup time	t <sub>ASC</sub>		30		J.	ns	7
CAS address hold time	t <sub>CAH</sub>	a company	90	1 1 1		ns	7
DWRT pulse width	t <sub>WP</sub>		95	Reflect to the second		ns	7
Write command setup time	t <sub>WCS</sub>	// 🗞	12	11		ns	7
Write command hold time	t <sub>WCH</sub>		65			ns	7
Output data setup time	t <sub>DSO</sub>	Output timing to the external DRAM	30	į.		ns	7
Output data hold time	t <sub>DHO</sub>	See Figure 8.	100			ns	7
	C1		\$ 1	13		pF	8
Crystal oscillator	C2	OSC1 and OSC2. See Figure 2.	11	29		pF	8
	L		4	1.5		μΗ	8
Current drain	I <sub>DD</sub>	For V <sub>DD</sub> 1, V <sub>DD</sub> 2, and V <sub>DD</sub> 3 when operating at 33,8688 MHz.		60	95	mA	9

# Electrical Characteristics 2 at $Ta = 25^{\circ}C$ , all $V_{DD} = 5.0$ V, all $V_{SS} = 0$ V unless otherwise specified

Parameter	Symbol	Ratings			Unit	Notes
Faiametei		min	typ	max	01111	NOIGS
[A/D Converter Block]						
Total harmonic distortion	A-THD 1 kHz, at 0 dB		0.05		%	10
Signal-to-noise ratio	A-S/N 1 KHz, at 0 dB	75	80		dB	10,11
Crosstalk	A-C 1 kHz, at 0 dB		-75		dB	10,11
[D/A Converter Block]						
Total harmonic distortion	DETHO 1 kHz, at 0 dB		0.01		%	10
Signal-to-noise ratio	D-S/N 1, kHž, at 0 dB		85		dB	10,11
Crosstalk	D-C · T /1,kHz, at 0 dB		-80		dB	10,11

Notes: 1. TTL output level pins: ASQ, F\$384Q, BCKO, LRCKO, D0 to D7, A0 to A8, RAS, CAS, DREAD, DWRT

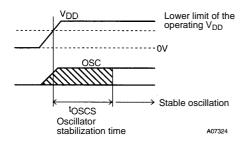
- 2. CMOS intermediate current output pins: P3, P4, SIAK
- 3. N-channel open drain intermediate current output pins: P0 to P2
- 4. Low Schmitt input pins; BCKI, ASI, LRCKI, D0 to D7, FS384I
- 5. Normal input pins. P0 to P2, TEST1 to TEST5, SELC, SAIF, SAOF
- 6. Schmitt input pins:  $\overline{\text{RES}}$  SI, SICK,  $\overline{\text{SIRQ}}$ ,  $\overline{\text{SRDY}}$ , OSC1
- 7. When the load capacitance is 50 pF.
- 8. The values for the oscillator capacitors C1 and C2 include the line capacitances.
- 9. The typical values for the current drain are for  $V_{DD}$  = 5 V, room temperature, and typical samples.
- 10. Fs = 44.1 kHz and 20 kHz low-pass filter used. Measurement is with the external circuit structure and constants in the Sanyo evaluation board.
- 11. With the weight A filter used.



OSC1 OSC2 1000pF C1 C2 S A07323

Figure 1 External Clock Input Waveform (FS384I)

Figure 2 Crystal Oscillator Circuit



**Figure 3 Oscillator Stabilization Time** 

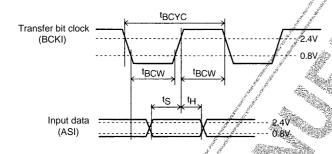


Figure 4 Audio Data Input Conditions

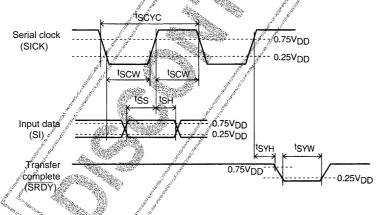
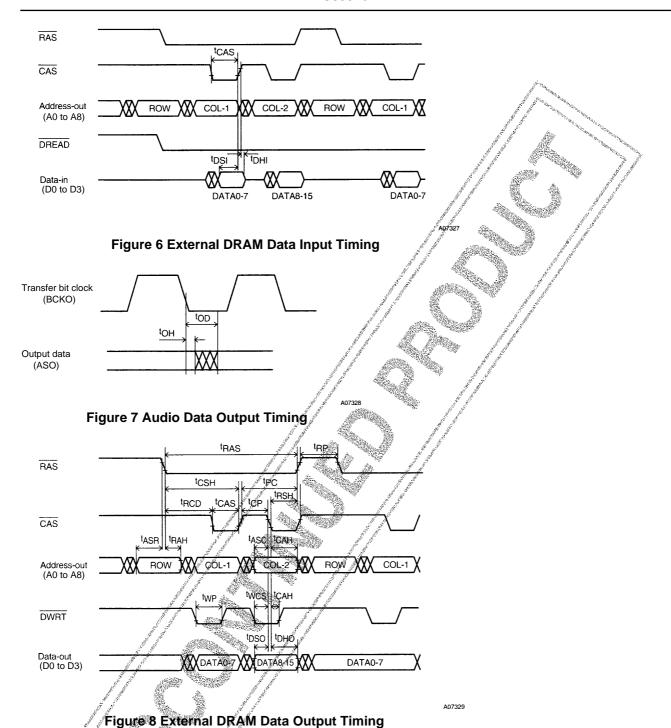


Figure 5 Microcontroller Interface

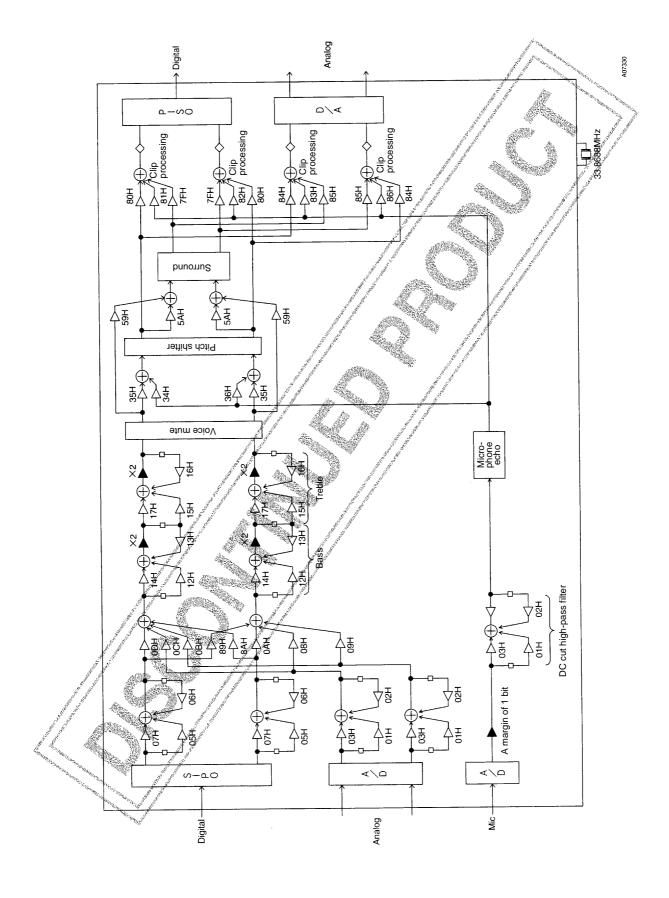
A07326



## Differences between the LC83025E and the LC83026E

Parameter	LC83025E	LC83026E					
	Decimation filter improved						
	Input compar	Input comparator improved					
A/D converter-block	The $V_{REF}$ pin was added in association with the improvements to the input comparator. The $V_{REF}$ pin external capacitor must be located as close as possible to the LC83026E, and must be connected with lines that are as short as possible.						
42.	4 × oversampling filters used	2 × oversampling filters used					
D/A converter block	Second-order noise shaping	Third-order noise shaping					
	Single-pin output used.	Two-pin output operation					
Reset time	One or more sampling period	Two or more sampling periods					
When no digital input is provided (when the SELC pin is low)	The LRCKI and BCKI pins must be connected to the LRCKO and BCKO pins.	The LRCKI and BCKI pins must be connected to either V <sub>DD</sub> or V <sub>SS</sub> ; they do not need to be connected to the LRCKO and BCKO pins.					

## **Overall Signal Flow**



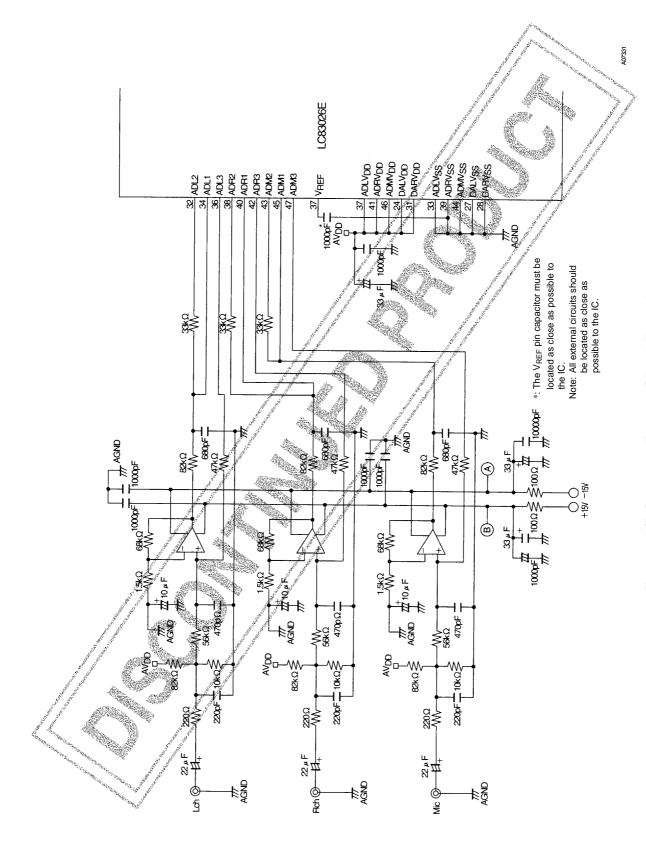
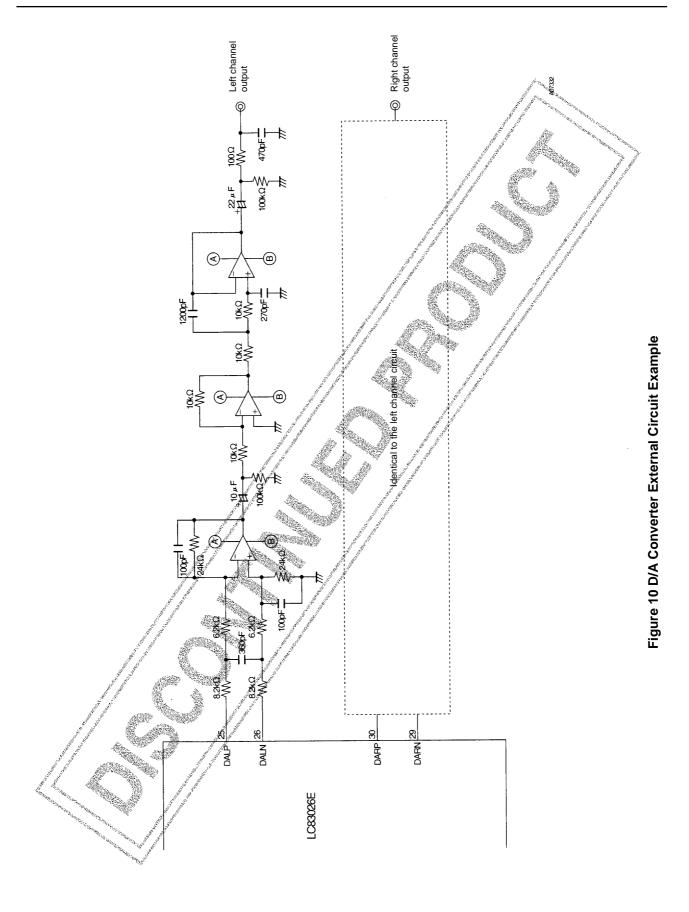
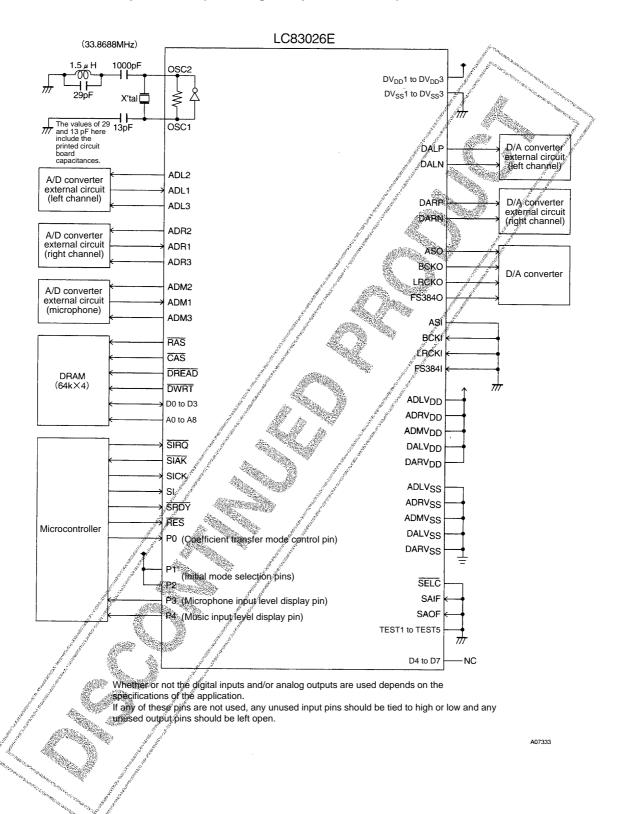


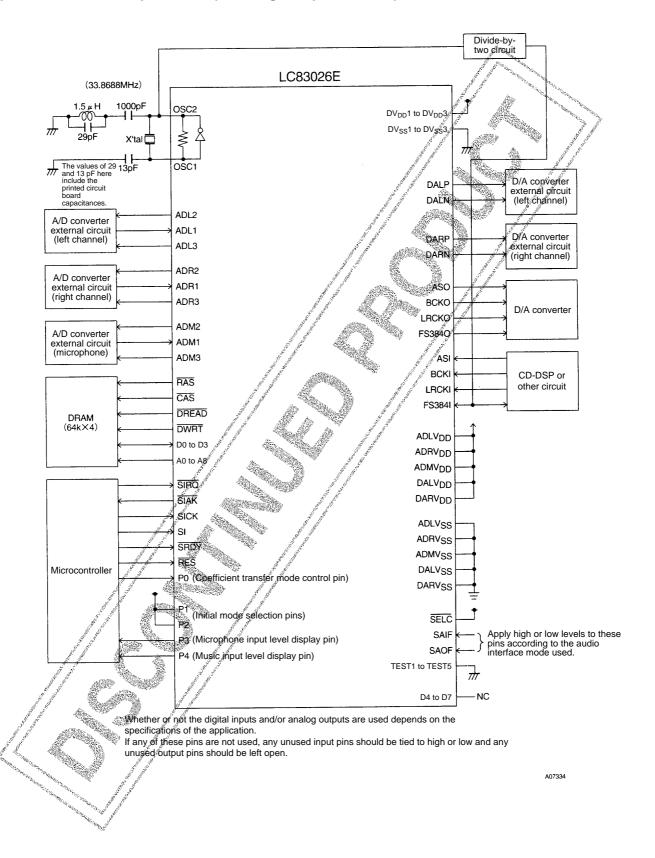
Figure 9 A/D Converter External Circuit Example



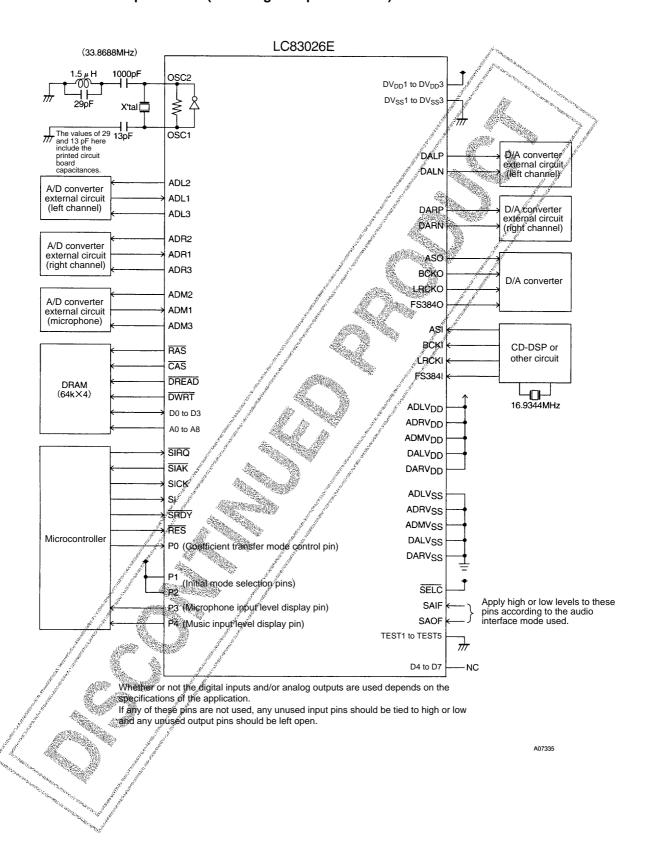
## Application Circuit Example Outline (When digital input is not used)

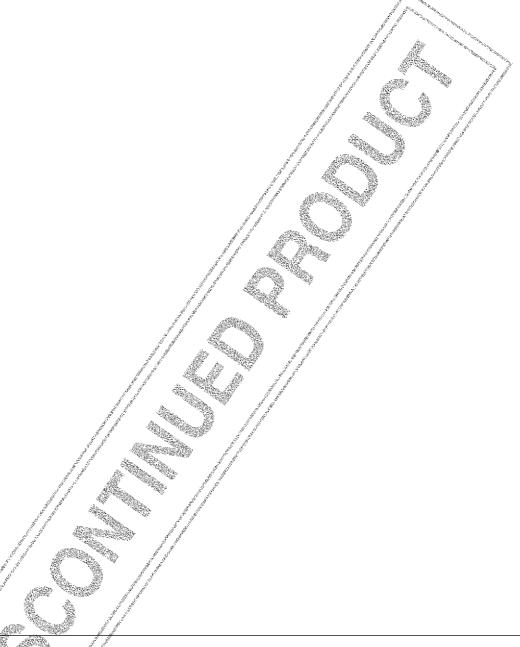


## Application Circuit Example Outline (When digital input is used 1)



## Application Circuit Example Outline (When digital input is used 2)





- No products described or contained herein are intended for use in surgical implants, life-support systems, aerospace equipment, nuclear power control systems, vehicles, disaster/crime-prevention equipment and the like, the failure of which may directly or indirectly cause injury, death or property loss.
- Anyone purchasing any products described or contained herein for an above-mentioned use shall:
  - D. Acceptfull responsibility and indemnify and defend SANYO ELECTRIC CO., LTD., its affiliates, subsidiaries and distributors and all their officers and employees, jointly and severally, against any and all claims and litigation and all damages, cost and expenses associated with such use:
  - Not impose any responsibility for any fault or negligence which may be cited in any such claim or litigation on SANYO ELECTRIC CO., LTD., its affiliates, subsidiaries and distributors or any of their officers and employees jointly or severally.
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