Presettable 4-Bit Binary Up/Down Counter

The SN74LS193 is an UP/DOWN MODULO-16 Binary Counter. Separate Count Up and Count Down Clocks are used and the circuits can operate synchronously. The outputs change state synchronous with the LOW-to-HIGH transitions on the clock inputs.

Separate Terminal Count Up and Terminal Count Down outputs are provided which are used as the clocks for a subsequent stages without extra logic, thus simplifying multistage counter designs. Individual preset inputs allow the circuits to be used as programmable counters. Both the Parallel Load (\overline{PL}) and the Master Reset (MR) inputs asynchronously override the clocks.

- Low Power . . . 95 mW Typical Dissipation
- High Speed . . . 40 MHz Typical Count Frequency
- Synchronous Counting
- Asynchronous Master Reset and Parallel Load
- Individual Preset Inputs
- Cascading Circuitry Internally Provided
- Input Clamp Diodes Limit High Speed Termination Effects

GUARANTEED OPERATING RANGES

Symbol	Parameter	Min	Тур	Max	Unit
V _{CC}	Supply Voltage	4.75	5.0	5.25	V
T _A	Operating Ambient Temperature Range	0	25	70	°C
I _{OH}	Output Current – High			-0.4	mA
I _{OL}	Output Current – Low			8.0	mA

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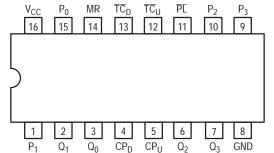


SOIC D SUFFIX CASE 751B

ORDERING INFORMATION

Device	Package	Shipping	
SN74LS193N 16 Pin DIP		2000 Units/Box	
SN74LS193D	16 Pin	2500/Tape & Reel	

CONNECTION DIAGRAM DIP (TOP VIEW)



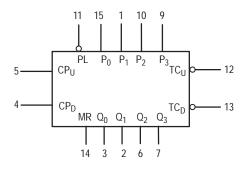
NOTE: The Flatpak version has the same pinouts (Connection Diagram) as the Dual In-Line Package.

		LOADING	(Note a)
PIN NAMES		HIGH	LOW
CPU	Count Up Clock Pulse Input	0.5 U.L.	0.25 U.L.
CPD	Count Down Clock Pulse Input	0.5 U.L.	0.25 U.L.
MR	Asynchronous Master Reset (Clear) Input	0.5 U.L.	0.25 U.L.
PL	Asynchronous Parallel Load (Active LOW) Input	0.5 U.L.	0.25 U.L.
P_n	Parallel Data Inputs	0.5 U.L.	0.25 U.L.
Q_n	Flip–Flop Outputs	10 U.L.	5 U.L.
TC _D	Terminal Count Down (Borrow) Output	10 U.L.	5 U.L.
TCU	Terminal Count Up (Carry) Output	10 U.L.	5 U.L.

NOTES:

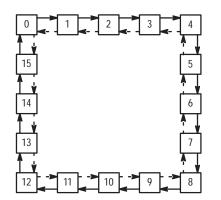
a) 1 TTL Unit Load (U.L.) = $40 \mu A HIGH/1.6 mA LOW$.

LOGIC SYMBOL



V_{CC} = PIN 16 GND = PIN 8

STATE DIAGRAM

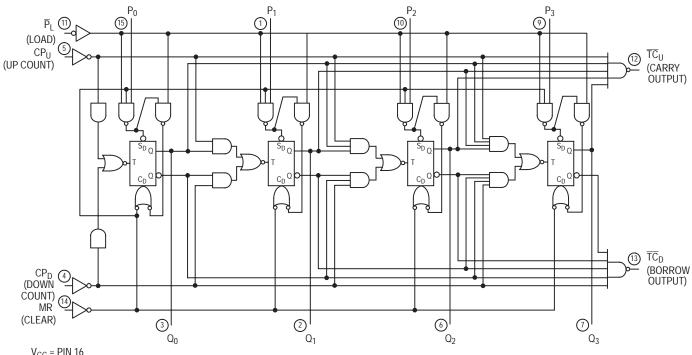


LOGIC EQUATIONS FOR TERMINAL COUNT

$$\begin{split} \overline{TC}_U &= \underline{Q}_0 \cdot \underline{Q}_1 \cdot \underline{Q}_2 \cdot \underline{Q}_3 \cdot \overline{CP}_U \\ \overline{TC}_D &= \overline{Q}_0 \cdot \overline{Q}_1 \cdot \overline{Q}_2 \cdot \overline{Q}_3 \cdot \overline{CP}_D \end{split}$$

COUNT UP COUNT DOWN

LOGIC DIAGRAM



V_{CC} = PIN 16 GND = PIN 8

= PIN NUMBERS

FUNCTIONAL DESCRIPTION

The LS193 is a 4-Bit Binary Synchronous UP/DOWN (Reversable) Counter. Each circuit contains four master/slave flip-flops, with internal gating and steering logic to provide master reset, individual preset, count up and count down operations.

Each flip-flop contains JK feedback from slave to master such that a LOW-to-HIGH transition on its T input causes the slave, and thus the Q output to change state. Synchronous switching, as opposed to ripple counting, is achieved by driving the steering gates of all stages from a common Count Up line and a common Count Down line, thereby causing all state changes to be initiated simultaneously. A LOW-to-HIGH transition on the Count Up input will advance the count by one; a similar transition on the Count Down input will decrease the count by one. While counting with one clock input, the other should be held HIGH. Otherwise, the circuit will either count by twos or not at all, depending on the state of the first flip-flop, which cannot toggle as long as either Clock input is LOW.

The Terminal Count Up (\overline{TC}_U) and Terminal Count Down (\overline{TC}_D) outputs are normally HIGH. When a circuit has

reached the maximum count state of 15, the next HIGH-to-LOW transition of the Count Up Clock will cause \overline{TC}_U to go LOW. \overline{TC}_U will stay LOW until CP_U goes HIGH again, thus effectively repeating the Count Up Clock, but delayed by two gate delays. Similarly, the \overline{TC}_D output will go LOW when the circuit is in the zero state and the Count Down Clock goes LOW. Since the TC outputs repeat the clock waveforms, they can be used as the clock input signals to the next higher order circuit in a multistage counter.

Each circuit has an asynchronous parallel load capability permitting the counter to be preset. When the Parallel Load (\overline{PL}) and the Master Reset (MR) inputs are LOW, information present on the Parallel Data inputs (P_0, P_3) is loaded into the counter and appears on the outputs regardless of the conditions of the clock inputs. A HIGH signal on the Master Reset input will disable the preset gates, override both Clock inputs, and latch each Q output in the LOW state. If one of the Clock inputs is LOW during and after a reset or load operation, the next LOW-to-HIGH transition of that Clock will be interpreted as a legitimate signal and will be counted.

MODE SELECT TABLE

MR	PL	CPU	CPD	MODE
Н	Х	Х	Х	Reset (Asyn.)
L	L	Χ	X	Preset (Asyn.)
L	Н	Н	Н	No Change
L	Н	Г	Н	Count Up
L	Н	H	J	Count Down

L = LOW Voltage Level

H = HIGH Voltage Level

X = Don't Care

 \int = LOW-to-HIGH Clock Transition

DC CHARACTERISTICS OVER OPERATING TEMPERATURE RANGE (unless otherwise specified)

		Limits						
Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions		
V _{IH}	Input HIGH Voltage	2.0			V	Guaranteed Input HIGH Voltage for All Inputs		
V _{IL}	Input LOW Voltage			0.8	V	Guaranteed Input LOW Voltage for All Inputs		
V _{IK}	Input Clamp Diode Voltage		-0.65	-1.5	V	$V_{CC} = MIN, I_{IN} = -18 \text{ mA}$		
V _{OH}	Output HIGH Voltage	2.7	3.5		V	$V_{CC} = MIN$, $I_{OH} = MAX$, $V_{IN} = V_{IH}$ or V_{IL} per Truth Table		
M	0		0.25	0.4	V	I _{OL} = 4.0 mA	$V_{CC} = V_{CC} MIN,$	
V _{OL}	Output LOW Voltage		0.35	0.5	V	I _{OL} = 8.0 mA	V _{IN} = V _{IL} or V _{IH} per Truth Table	
	In north HCLL Comment			20	μΑ	V _{CC} = MAX, V _{IN} = 2.7 V		
I _{IH}	Input HIGH Current			0.1	mA	V _{CC} = MAX, V _{IN} = 7.0 V		
I _{IL}	Input LOW Current			-0.4	mA	V _{CC} = MAX, V _{IN} = 0.4 V		
I _{OS}	Short Circuit Current (Note 1)	-20		-100	mA	V _{CC} = MAX		
I _{CC}	Power Supply Current			34	mA	V _{CC} = MAX		

Note 1: Not more than one output should be shorted at a time, nor for more than 1 second.

AC CHARACTERISTICS $(T_A = 25^{\circ}C)$

			Limits			
Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions
f _{MAX}	Maximum Clock Frequency	25	32		MHz	
t _{PLH} t _{PHL}	CP _U Input to TC _U Output		17 18	26 24	ns	
t _{PLH} t _{PHL}	CP _D Input to TC _D Output		16 15	24 24	ns	V _{CC} = 5.0 V C _L = 15 pF
t _{PLH} t _{PHL}	Clock to Q		27 30	38 47	ns	C _L = 15 pF
t _{PLH} t _{PHL}	PL to Q		24 25	40 40	ns	
t _{PHL}	MR Input to Any Output		23	35	ns	

AC SETUP REQUIREMENTS $(T_A = 25^{\circ}C)$

		Limits					
Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions	
t _W	Any Pulse Width	20			ns		
t _s	Data Setup Time	20			ns	V 50V	
t _h	Data Hold Time	5.0			ns	$V_{CC} = 5.0 \text{ V}$	
t _{rec}	Recovery Time	40			ns		

DEFINITIONS OF TERMS

SETUP TIME (t_s) is defined as the minimum time required for the correct logic level to be present at the logic input prior to the \overline{PL} transition from LOW-to-HIGH in order to be recognized and transferred to the outputs.

HOLD TIME (t_h) is defined as the minimum time following the \overline{PL} transition from LOW-to-HIGH that the logic level must be maintained at the input in order to ensure continued

recognition. A negative HOLD TIME indicates that the correct logic level may be released prior to the \overline{PL} transition from LOW-to-HIGH and still be recognized.

RECOVERY TIME (t_{rec}) is defined as the minimum time required between the end of the reset pulse and the clock transition from LOW-to-HIGH in order to recognize and transfer HIGH data to the Q outputs.

AC WAVEFORMS

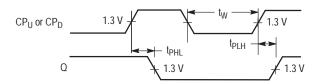


Figure 1.

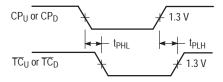


Figure 2.

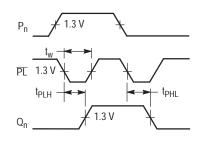
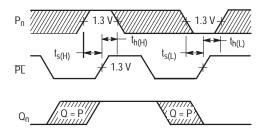
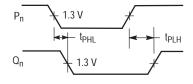


Figure 4.



* The shaded areas indicate when the input is permitted to change for predictable output performance

Figure 6.



NOTE: $\overline{PL} = LOW$ Figure 3.

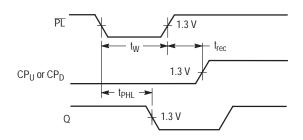


Figure 5.

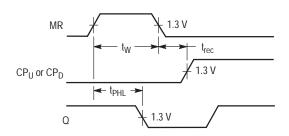
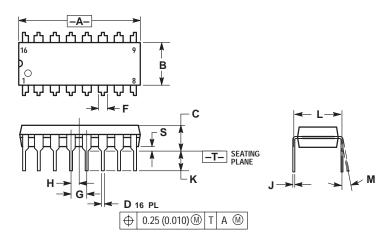


Figure 7.

PACKAGE DIMENSIONS

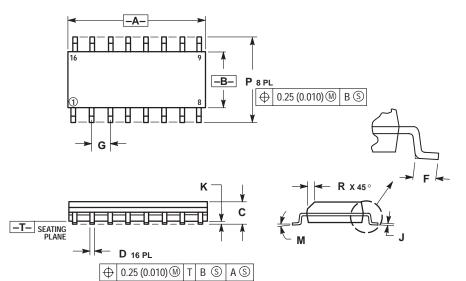
N SUFFIX PLASTIC PACKAGE CASE 648-08 ISSUE R



- NOTES:
 1. DIMENSIONING AND TOLERANCING PER ANSI
- Y14.5M, 1982. CONTROLLING DIMENSION: INCH.
- 2. CONTROLLING DIMENSION: INCH.
 3. DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL.
 4. DIMENSION B DOES NOT INCLUDE MOLD FLASH.
 5. ROUNDED CORNERS OPTIONAL.

	INC	HES	MILLIN	IETERS	
DIM	MIN	MIN MAX		MAX	
Α	0.740	0.770	18.80	19.55	
В	0.250	0.270	6.35	6.85	
С	0.145	0.175	3.69	4.44	
D	0.015	0.021	0.39	0.53	
F	0.040	0.70	1.02	1.77	
G	0.100	BSC	2.54 BSC		
Н	0.050	BSC	1.27 BSC		
J	0.008	0.015	0.21	0.38	
K	0.110	0.130	2.80	3.30	
L	0.295	0.305	7.50	7.74	
М	0°	10 °	0°	10 °	
S	0.020	0.040	0.51	1.01	

D SUFFIX PLASTIC SOIC PACKAGE CASE 751B-05 **ISSUE J**



NOTES

- DIMENSIONING AND TOLERANCING PER ANSI
- 714.5M, 1982.
 CONTROLLING DIMENSION: MILLIMETER.
 DIMENSIONS A AND B DO NOT INCLUDE
 MOLD PROTRUSION.
- MAXIMUM MOLD PROTRUSION 0.15 (0.006)
 PER SIDE.
- PER SIDE.
 DIMENSION D DOES NOT INCLUDE DAMBAR
 PROTRUSION. ALLOWABLE DAMBAR
 PROTRUSION SHALL BE 0.127 (0.005) TOTAL
 IN EXCESS OF THE D DIMENSION AT
 MAXIMUM MATERIAL CONDITION.

	MILLIN	METERS	INC	HES		
DIM	MIN	MAX	MIN	MAX		
Α	9.80	10.00	0.386	0.393		
В	3.80	4.00	0.150	0.157		
С	1.35	1.75	0.054	0.068		
D	0.35	0.49	0.014	0.019		
F	0.40	1.25	0.016	0.049		
G	1.27	BSC	0.050 BSC			
J	0.19	0.25	0.008	0.009		
K	0.10	0.25	0.004	0.009		
M	0 °	7°	0°	7°		
Р	5.80	6.20	0.229	0.244		
R	0.25	0.50	0.010	0.019		

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