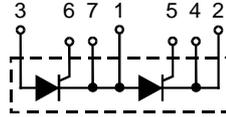


Thyristor Module

Preliminary data

| | | |
|-----------|-----------|----------------|
| V_{RSM} | V_{RRM} | Type |
| V_{DSM} | V_{DRM} | |
| V | V | |
| 1700 | 1600 | MCC 60-16io1 B |

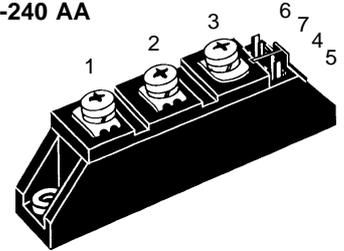


$$I_{TRMS} = 2 \times 100 \text{ A}$$

$$I_{TAVM} = 2 \times 64 \text{ A}$$

$$V_{RRM, DRM} = 1600 \text{ V}$$

TO-240 AA



| Symbol | Conditions | Maximum Ratings | | |
|------------------------------------|--|---|--------------------------------|------------------------------------|
| I_{TRMS}, I_{FRMS} I_{TAVM} | $T_{VJ} = T_{VJM}$ $T_C = 85^\circ\text{C}; 180^\circ \text{ sine}$ | 100 64 | A A | |
| I_{TSM}, I_{FSM} | $T_{VJ} = 45^\circ\text{C};$ $V_R = 0$ | $t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$ | A A | |
| | $T_{VJ} = T_{VJM}$ $V_R = 0$ | $t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$ | A A | |
| P_{dt} | $T_{VJ} = 45^\circ\text{C}$ $V_R = 0$ | $t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$ | $A^2\text{s}$ $A^2\text{s}$ | |
| | $T_{VJ} = T_{VJM}$ $V_R = 0$ | $t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$ | $A^2\text{s}$ $A^2\text{s}$ | |
| $(di/dt)_{cr}$ | $T_{VJ} = T_{VJM}$ $f = 50\text{Hz}, t_p = 200\mu\text{s}$ $V_D = \frac{2}{3} V_{DRM}$ $I_G = 0.45 \text{ A}$ $di_G/dt = 0.45 \text{ A}/\mu\text{s}$ | repetitive, $I_T = 150 \text{ A}$ non repetitive, $I_T = I_{TAVM}$ | 150 500 | $A/\mu\text{s}$ $A/\mu\text{s}$ |
| $(dv/dt)_{cr}$ | $T_{VJ} = T_{VJM};$ $R_{GK} = \infty; \text{method 1 (linear voltage rise)}$ | $V_{DR} = \frac{2}{3} V_{DRM}$ | 1000 | $V/\mu\text{s}$ |
| P_{GM} | $T_{VJ} = T_{VJM}$ $I_T = I_{TAVM}$ | $t_p = 30 \mu\text{s}$ $t_p = 300 \mu\text{s}$ | 10 5 | W W |
| P_{GAV} | | | 0.5 | W |
| V_{RGM} | | | 10 | V |
| T_{VJ} | | | -40...+140 | $^\circ\text{C}$ |
| T_{VJM} | | | 140 | $^\circ\text{C}$ |
| T_{stg} | | | -40...+125 | $^\circ\text{C}$ |
| V_{ISOL} | 50/60 Hz, RMS $I_{ISOL} \leq 1 \text{ mA}$ | $t = 1 \text{ min}$ $t = 1 \text{ s}$ | 3000 3600 | V~ V~ |
| M_d | Mounting torque (M5) Terminal connection torque (M5) | | 2.5-4.0/22-35 2.5-4.0/22-35 | Nm/lb.in. Nm/lb.in. |
| Weight | Typical including screws | | 90 | g |

Features

- International standard package
- Direct copper bonded Al_2O_3 -ceramic base plate
- Planar passivated chips
- Isolation voltage 3600 V~
- Gate-cathode twin pins

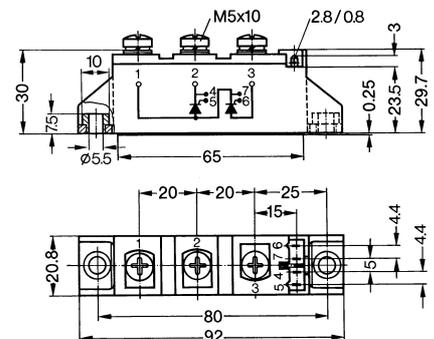
Applications

- DC motor control
- Softstart AC motor controller
- Light, heat and temperature control

Advantages

- Space and weight savings
- Simple mounting with two screws
- Improved temperature and power cycling
- Reduced protection circuits

Dimensions in mm (1 mm = 0.0394")



Data according to IEC 60747 and refer to a single thyristor/diode unless otherwise stated. IXYS reserves the right to change limits, test conditions and dimensions

| Symbol | Conditions | Characteristic Values | |
|--------------------|--|-----------------------|------------------|
| I_{RRM}, I_{DRM} | $T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$ | 20 | mA |
| V_T, V_F | $I_T, I_F = 200 \text{ A}; T_{VJ} = 25^\circ\text{C}$ | 1.70 | V |
| V_{T0} | $T_{VJ} = 125^\circ\text{C};$ For power-loss calculations only | 0.85 | V |
| r_T | $T_{VJ} = T_{VJM}$ | 4.8 | m Ω |
| V_{GT} | $V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$ | 1.4 | V |
| | $T_{VJ} = -40^\circ\text{C}$ | 1.6 | V |
| I_{GT} | $V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$ | 100 | mA |
| | $T_{VJ} = -40^\circ\text{C}$ | 200 | mA |
| V_{GD} | $T_{VJ} = T_{VJM}; V_D = \frac{2}{3} V_{DRM}$ | 0.2 | V |
| I_{GD} | | 10 | mA |
| I_L | $T_{VJ} = 25^\circ\text{C}; t_p = 10 \mu\text{s}, V_D = 6 \text{ V}$ $I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$ | 450 | mA |
| I_H | $T_{VJ} = 25^\circ\text{C}; V_D = 6 \text{ V}; R_{GK} = \infty$ | 200 | mA |
| t_{gd} | $T_{VJ} = 25^\circ\text{C}; V_D = \frac{1}{2} V_{DRM}$ $I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$ | 2 | μs |
| t_q | $T_{VJ} = T_{VJM}; I_T = 120 \text{ A}, t_p = 200 \mu\text{s}; -di/dt = 10 \text{ A}/\mu\text{s typ.}$ $V_R = 100 \text{ V}; dv/dt = 20 \text{ V}/\mu\text{s}; V_D = \frac{2}{3} V_{DRM}$ | 150 | μs |
| Q_S | $T_{VJ} = T_{VJM}; I_T, I_F = 50 \text{ A}, -di/dt = 0.64 \text{ A}/\mu\text{s}$ | 110 | μC |
| I_{RM} | | 12 | A |
| R_{thJC} | per thyristor/diode; DC current | 0.5 | K/W |
| | per module | 0.25 | K/W |
| R_{thCH} | per thyristor/diode; DC current | typ. | 0.1 |
| d_s | Creepage distance on surface | 12.7 | mm |
| d_A | Strike distance through air | 9.6 | mm |
| a | Maximum allowable acceleration | 50 | m/s ² |

Optional accessories for module-type MCC 60 version 1 B

Keyed gate/cathode twin plugs with wire length = 350 mm, gate = yellow, cathode = red

Type **ZY 200L** (L = Left for pin pair 4/5) } UL 758, style 1385,
 Type **ZY 200R** (R = right for pin pair 6/7) } CSA class 5851, guide 460-1-1

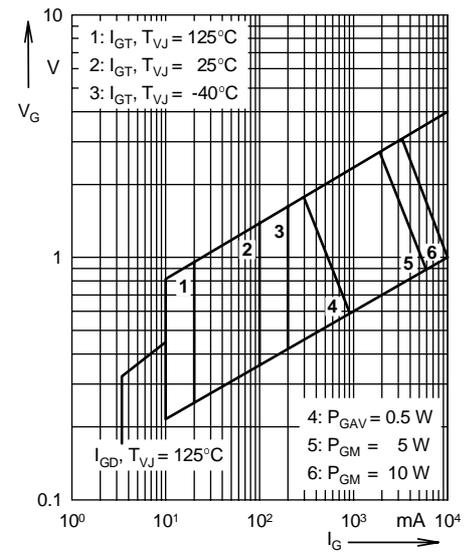


Fig. 1 Gate trigger characteristics

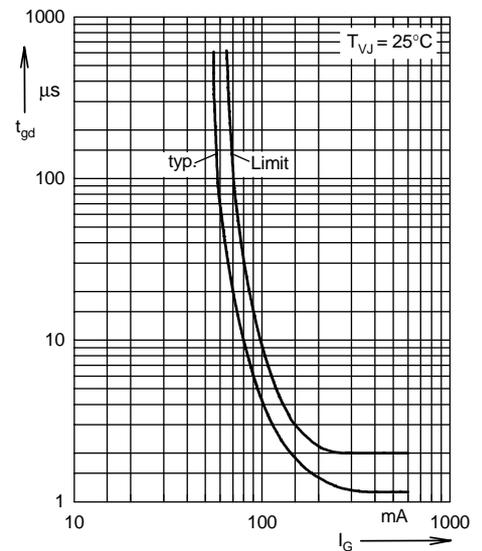


Fig. 2 Gate trigger delay time