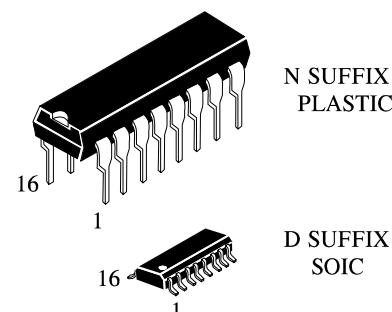


IL2010B

PHASE CONTROL CIRCUIT FOR CURRENT FEEDBACK

Description

The IL2010B is designed as a phase-control circuit in bipolar technology. It enables load-current detection and has a soft-start function as well as reference voltage output. Motor control with load-current feedback and overload protection are preferred applications.



Features

- Full wave current sensing
- Mains supply variation compensated
- Programmable load-current limitation with over- and high-load output
- Variable soft-start
- Voltage and current synchronization
- Automatic retriggering switchable
- Triggering pulse typical 125 mA

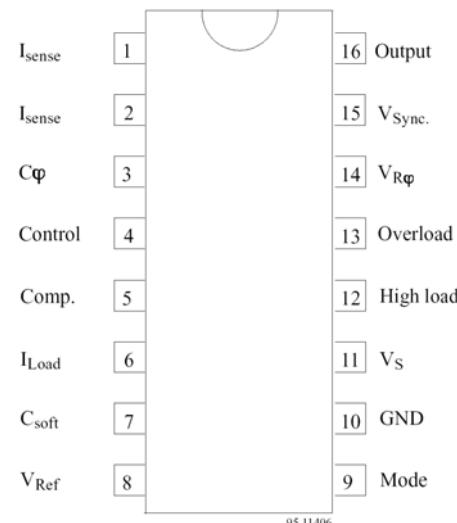
- Internal supply voltage monitoring
- Current requirement ≤ 3 mA
- Temperature compensated reference voltage

Applications

- Advanced motor control
- Grinder
- Drilling machine

Pin Description

| Pin | Symbol | Function |
|-----|--------------------|-------------------------|
| 1 | I _{sense} | Load current sensing |
| 2 | I _{sense} | Load current sensing |
| 3 | C _φ | Ramp voltage |
| 4 | Control | Control input |
| 5 | Comp. | Compensation output |
| 6 | I _{Load} | Load current limitation |
| 7 | C _{soft} | Soft start |
| 8 | V _{Ref} | Reference voltage |
| 9 | Mode | Mode selection |
| 10 | GND | Ground |
| 11 | V _S | Supply voltage |
| 12 | High load | High load indication |
| 13 | Overload | Overload indication |
| 14 | V _{Rφ} | Ramp current adjust |
| 15 | V _{Sync.} | Voltage synchronization |
| 16 | Output | Trigger output |

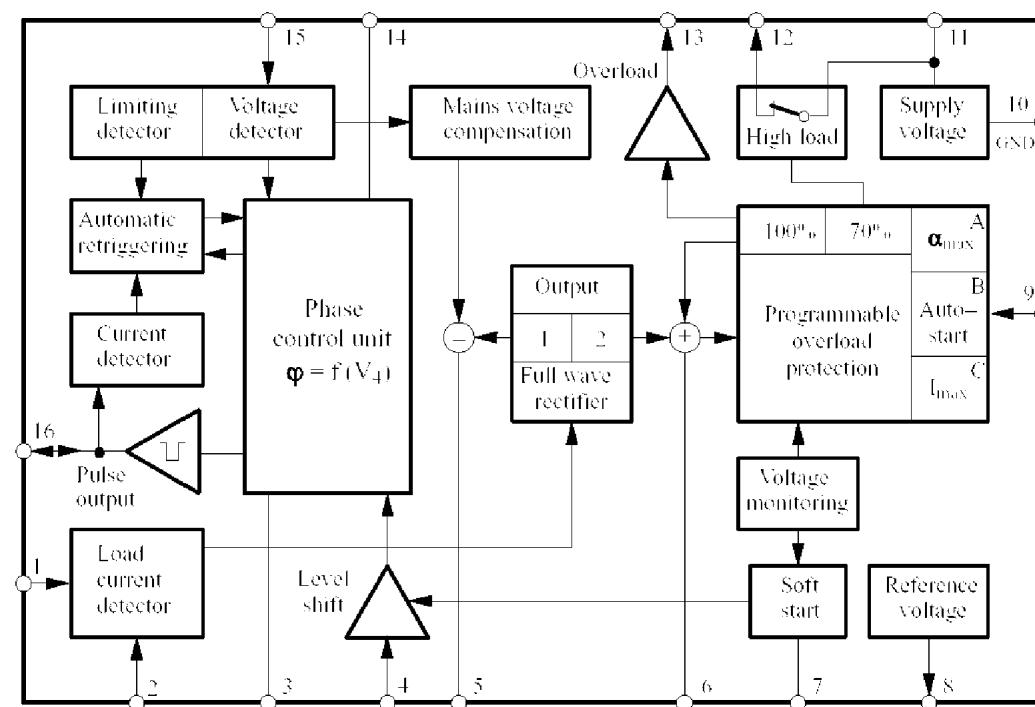


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Block Diagram



Absolute Maximum Ratings

Reference point Pin 10, unless otherwise specified

| Parameters | Pin | Symbol | Value | Unit |
|---------------------------------|---------|---------------------|--------------------|------|
| Sink current t ≤ 10us | 11 | -I _S | 30 | mA |
| | | -I _s | 100 | |
| Sync. currents t ≤ 10us | 15 | ±I _{syncV} | 5 | mA |
| | | ±I _{syncV} | 20 | |
| Phase control | | | | |
| Control voltage | 4 and 8 | -V _I | 0 – V _B | V |
| Input current | 4 | ± I _I | 500 | uA |
| Charging current | 14 | -I _{φ max} | 0.5 | mA |
| Soft-start | | | | |
| Input voltage | 7 and 8 | -V _I | 0 – V _B | V |
| Pulse output | | | | |
| Input voltage | 16 | +V _I | 2 | V |
| | | -V _I | V ₁₁ | |
| Reference voltage source | | | | |
| Output current t ≤ 10us | 8 | I ₀ | 10 | mA |
| | | i ₀ | 30 | mA |
| Load current sensing | | | | |
| Input currents | 1 and 2 | ± I _i | 1 | mA |
| Input voltages | 5 and 6 | -V _i | 0 – V _B | V |
| Overload output | 13 | I _L | 1 | mA |
| High-load output t ≤ 10us | 12 | I _L | 30 | mA |
| | | i _L | 100 | mA |
| Storage temperature range | | T _{stg} | -40 to +125 | °C |
| Junction temperature range | | T _j | 125 | °C |
| Ambient temperature range | | T _{amb} | -10 to +100 | °C |



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IL2010B**Electrical Characteristics** $V_S = -13 \text{ V}$, $T_{\text{amb}} = 25^\circ\text{C}$, reference point Pin 10, unless otherwise specified

| Parameters | Test Conditions | Pins | Symbol | Min. | Typ. | Max. | Unit | | | |
|---|---|-----------|------------------------|----------------------------|--------|------|-------|--|--|--|
| Supply | | | | | | | | | | |
| Supply voltage limitation | $-I_S = 5.5 \text{ mA}$ | 11 | $-V_S$ | 14.5 | | 16.5 | V | | | |
| | $-I_S = 30 \text{ mA}$ | | | 14.6 | | 16.8 | | | | |
| Current requirement | $-V_S = 13.0 \text{ V}$ (Pins 1, 2, 8 and 15 open) | Pin 11 | $-I_S$ | | | 5.2 | mA | | | |
| | | | | | | | | | | |
| Reference voltage source | | | | | | | | | | |
| Reference voltage | $I_L = 10 \text{ uA}$ | 8 | $-V_{\text{Ref}}$ | 8.7 | 9.0 | 9.3 | V | | | |
| | $I_L = 2.5 \text{ mA}$ | | | 8.5 | 8.8 | 9.2 | | | | |
| Temperature coefficient | $I_S = 2.5 \text{ mA}$ | | $TC_{V\text{Ref}}$ | | -0.004 | | %/K | | | |
| | $I_S = 10 \text{ uA}$ | | | | +0.006 | | | | | |
| Voltage monitoring | | | | | | | | | | |
| Turn-on threshold | | 11 | $-V_{\text{Son}}$ | | 11.3 | 12.3 | V | | | |
| Phase control – synchronization | | | | | | | | | | |
| Voltage limitation | $\pm I_L = 2 \text{ mA}$ | | $\pm V_{\text{syncV}}$ | 8.0 | 8.5 | 9.0 | V | | | |
| Input current | Current sync. | 16 | $\pm I_{\text{syncI}}$ | 3 | | 30 | uA | | | |
| Reference ramp, fig. 1 | | | | | | | | | | |
| Charging current | | 14 | $-I_\phi$ | 1 | | 100 | uA | | | |
| Start voltage | | 3 | $-V_{\max}$ | 2.00 | 2.15 | 2.20 | V | | | |
| Temperature coefficient of start voltage | | 3 | TC_R | | -0.003 | | %/K | | | |
| Final voltage | | 3 | $-V_{\min}$ | $(V_8 \pm 200 \text{ mV})$ | | | | | | |
| R_ϕ reference voltage | $I_\phi = 10 \text{ uA}$ | 14 and 11 | $V_{R\phi}$ | 0.96 | 1.02 | 1.10 | V | | | |
| Temperature coefficient | $I_{\phi_0} = 10 \text{ uA}$ | 14 | $TC_{VR\phi}$ | | 0.03 | | %/K | | | |
| | $I_\phi = 1 \text{ uA}$ | | | | 0.06 | | | | | |
| Pulse output current | $V_{16} = -1.2 \text{ V}$, fig. 2, | 16 | I_0 | 100 | 125 | 150 | mA | | | |
| Output pulse width | $C_3 = 3.3 \text{ nF}$, fig. 3 | 16 | t_p | | 50 | | us | | | |
| Automatic retriggering | | | | | | | | | | |
| Repetition rate | $I_{15} = 150 \text{ uA}$ | | t_{pp} | 3 | 5 | 7.5 | t_p | | | |
| Threshold voltage | | 16 | $\pm V_I$ | 20 | | 100 | mV | | | |
| Soft start, figure 7 and 8 | | | | | | | | | | |
| Starting current | $V_7 = V_8$ | 7 | $-I_0$ | 5 | 10 | 20 | uA | | | |
| Final current | $V_{7-10} = -1 \text{ V}$ | | $-I_0$ | 20 | 25 | 50 | uA | | | |
| Discharge current | | | $+I_0$ | 0.5 | | | mA | | | |
| Output current | | 4 | $+I_0$ | 0.2 | | 2 | mA | | | |
| Supply voltage compensation, | | | | | | | | | | |
| Transfer gain | fig. 6 I_{15}/I_5 Pin 15/5 (Pins 1 and 2 open) | | | G_i | 12 | | 18 | | | |
| Output offset current | $V_{(R6)} = V_{15} = V_5 = 0$ | | | $\pm I_0$ | | 2 | uA | | | |
| Load current detection $R_1 = R_2 = 3 \text{ k}\Omega$, $V_{15} = 0$, $V_5 = V_6 = V_8$, fig. 7 | | | | | | | | | | |
| Transfer gain | $I_5/150 \text{ mV}$, $I_6/150 \text{ mV}$ | | | G_l | 0.28 | 0.32 | 0.37 | | | |
| Output offset currents | 5, 6 - 8 | | | $-I_0$ | 0 | 3 | 6 | | | |
| Reference voltage | $I_1, I_2 = 100 \text{ uA}$ | | | $-V_{\text{Ref}}$ | 300 | | 450 | | | |
| Shunt voltage amplitude | | | | $\pm V_{(R6)}$ | | 250 | mV | | | |



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| Parameters | Test Conditions | Pins | Symbol | Min. | Typ. | Max. | Unit |
|---|--|-------|------------|------|------|------|------|
| Load current limitation figs. 8 to 13 | | | | | | | |
| High load switching | Threshold V_{T70} | 6-8 | V_{T70} | 4 | 4.35 | 4.7 | V |
| Overload switching | Threshold V_{T100} | | V_{T100} | 5.8 | 6.2 | 6.6 | V |
| Restart switching | Threshold V_{T25} | | V_{T25} | 1.25 | 1.55 | 1.85 | V |
| Input current | Enquiry mode | | I_i | | | 1 | uA |
| Output impedance | Switching mode | | R_0 | 2 | 4 | 8 | kΩ |
| Programming input | | | | | | | |
| Input voltage - auto-start | Pin 9 open | 9 | $-V_9$ | 3.8 | 4.3 | 4.7 | V |
| Input current | $V_9 = 0 (\alpha_{max})$ | | $-I_9$ | 5 | 10 | 20 | uA |
| | $V_9 = V_8 (I_{max})$ | | I_9 | 5 | 10 | 20 | |
| High load output, V_{T70}, fig. 9, $I_{12} = -3$ mA, | | | | | | | |
| Saturation voltages | $V_{6-8} \leq V_{T70}$ | 11-12 | V_{sat} | 0.5 | 0.75 | 1.0 | V |
| | $V_{6-8} \geq V_{T70}$ | | V_{lim} | 7.3 | | 8.1 | |
| Overload output, V_{T100}, $V_9 = \text{open}$ or $V_9 = V_{10}$, fig. 10 | | | | | | | |
| Leakage current | $V_{6-8} \geq V_{T25}$ $V_{13} = (V_{11}+1)V$ | 13 | I_{lkg} | | | 0.5 | uA |
| Saturation voltages | $V_{6-8} \geq V_{T100}$, $I_{13} = 10$ uA | 11-13 | V_{sat} | | | 0.15 | V |
| Output current, max. load | $V_9 = V_8$, fig. 10 | 13 | I_{13} | | | 1 | mA |
| Leakage current | $V_6 \leq V_{T100}$ | 13 | I_{lkg} | | | 4 | uA |
| Output impedance | Open collector $V_6 \leq V_{T100}$ | 13 | R_0 | 2 | 4 | 8 | kΩ |

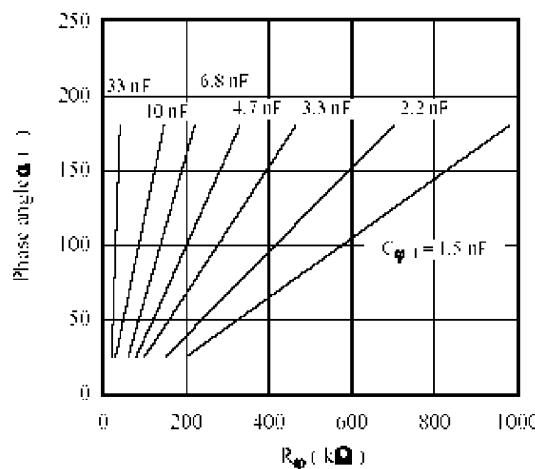


Fig.1

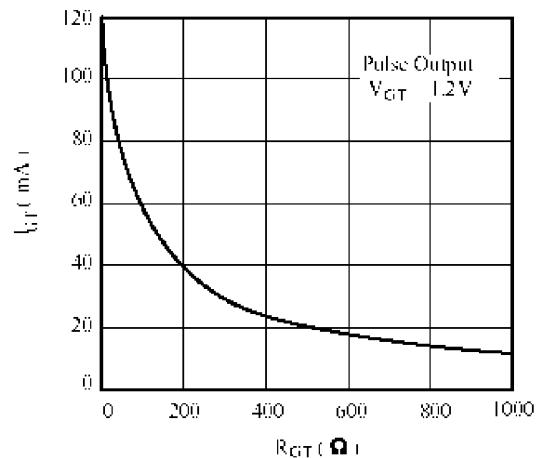


Fig.2



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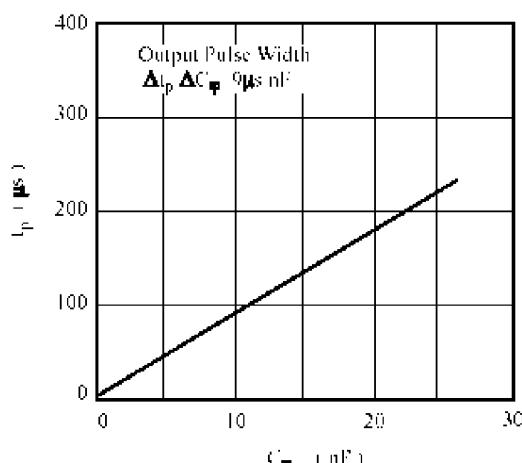


Fig.3

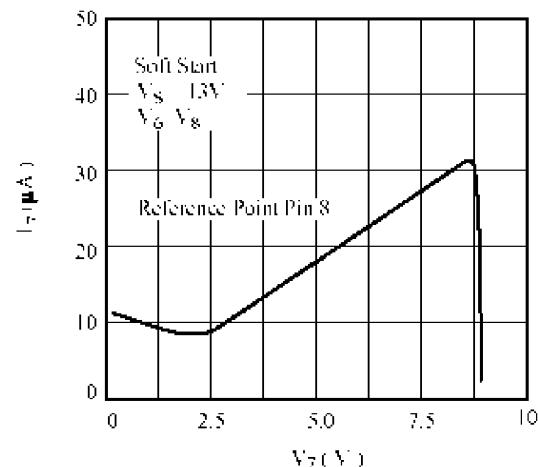


Fig.4

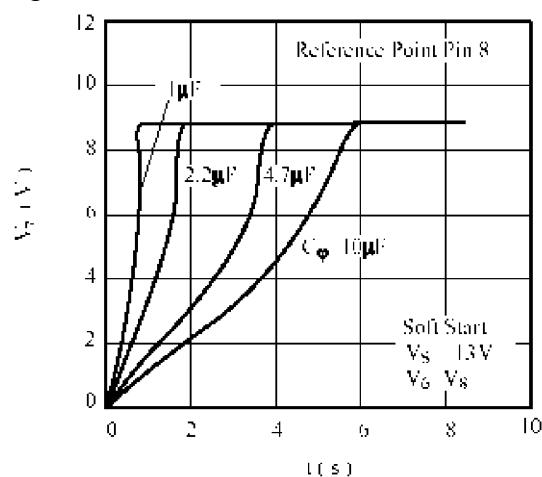


Fig.5

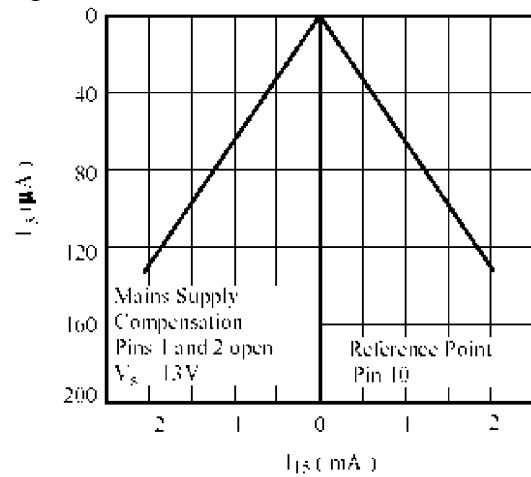


Fig.6

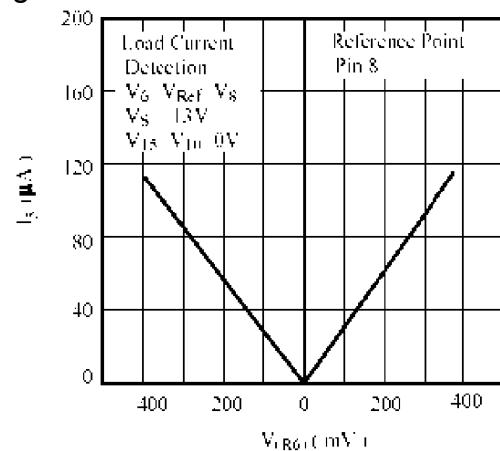


Fig.7

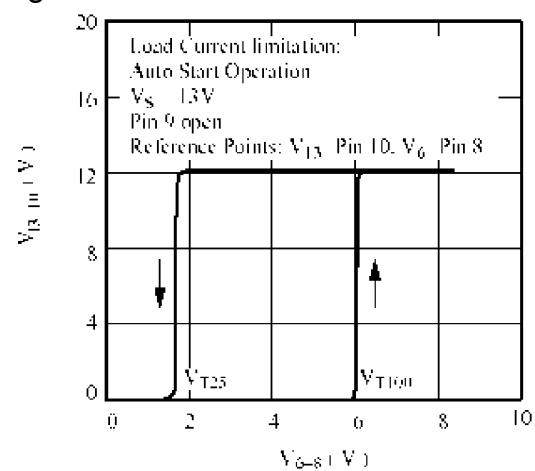


Fig.8



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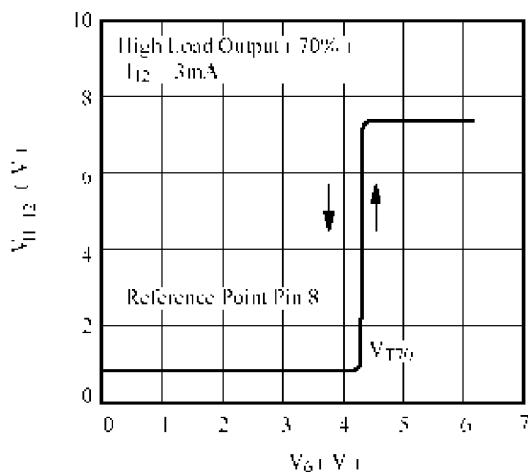


Fig.9

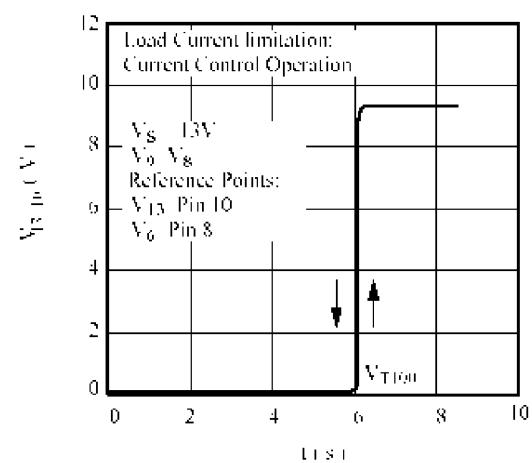


Fig.10

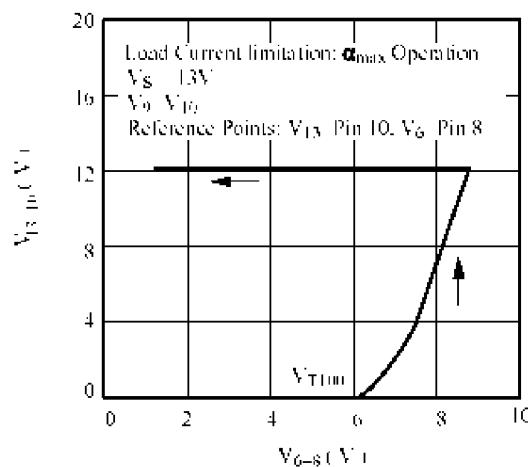


Fig.11

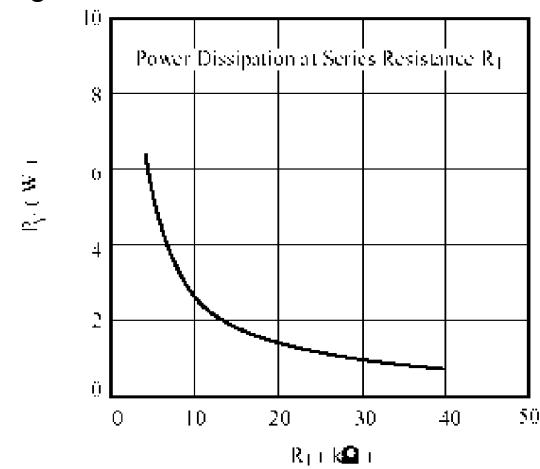


Fig.12

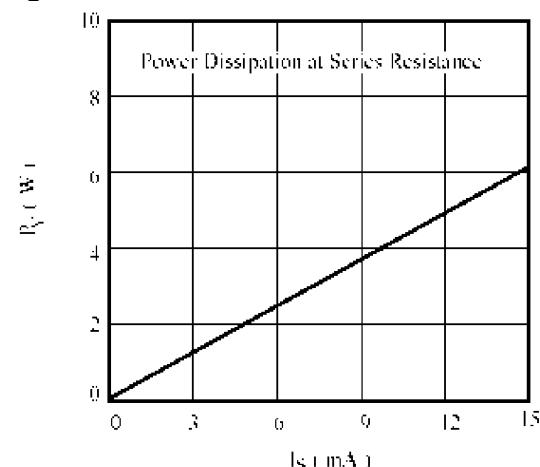


Fig.13

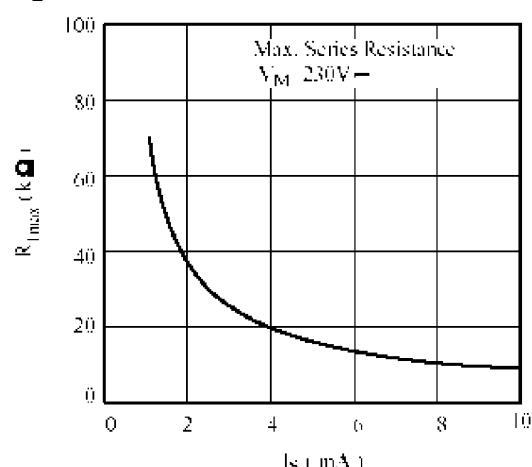


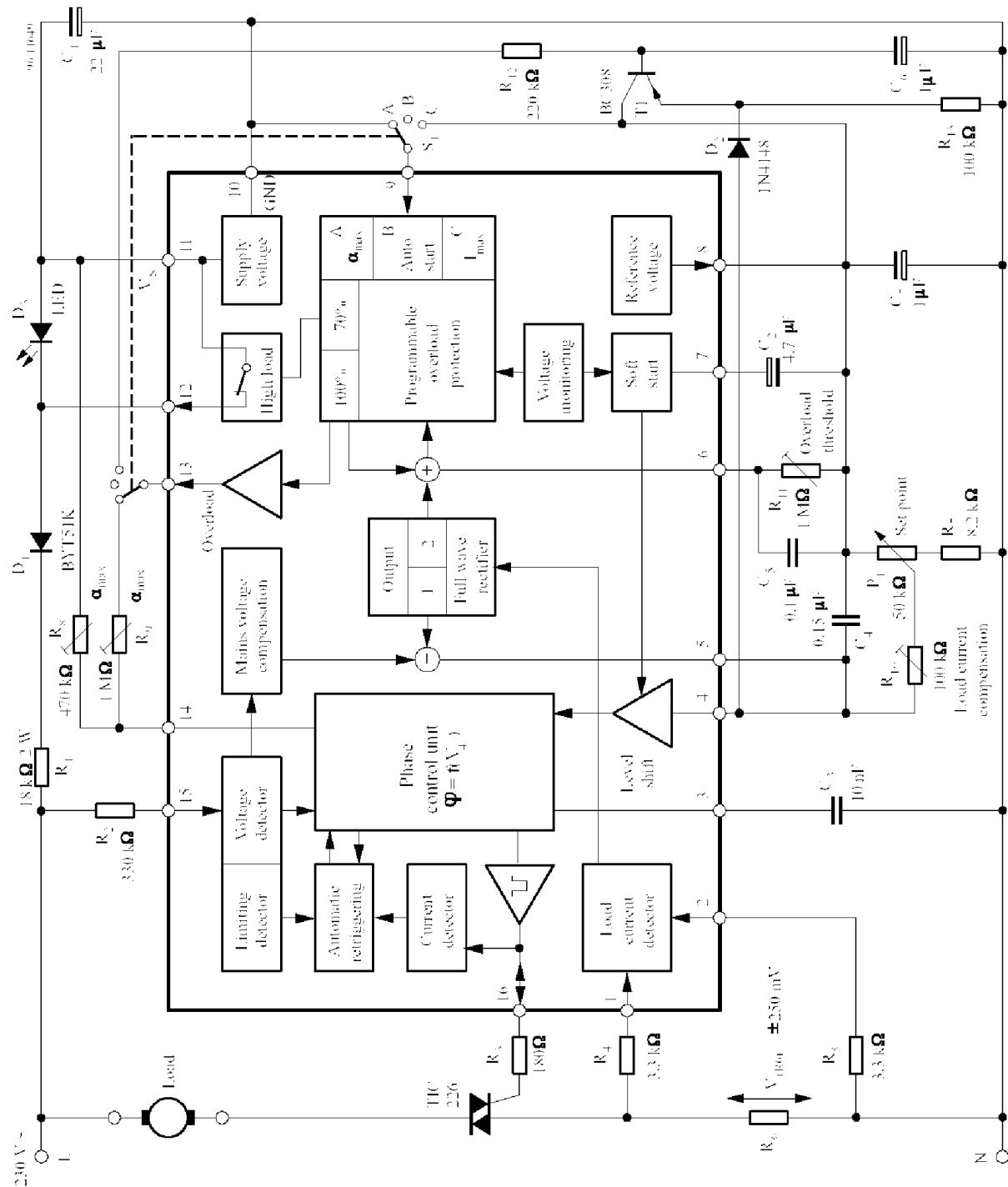
Fig.14



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