8-bit Proprietary Microcontroller

CMOS

F²MC-8L MB89860/850 Series

MB89865/867/P867/W867 MB89855/857/P857/W857/T855

DESCRIPTION

The MB89860/850 series has been developed as a general-purpose version of the F²MC*-8L family consisting of proprietary 8-bit, single-chip, microcontrollers.

In addition to the F2MC-8L CPU core which can operate at low voltage but at high speed, the microcontrollers contain a variety of peripheral functions such as a timer unit, PWM timers, a UART, a serial interface, a 10-bit A/D converter, and an external interrupt.

The MB89860/850 series is applicable to a wide range of applications from welfare products to industrial equipment, including portable devices.

*: F²MC stands for FUJITSU Flexible Microcontroller.

■ FEATURES

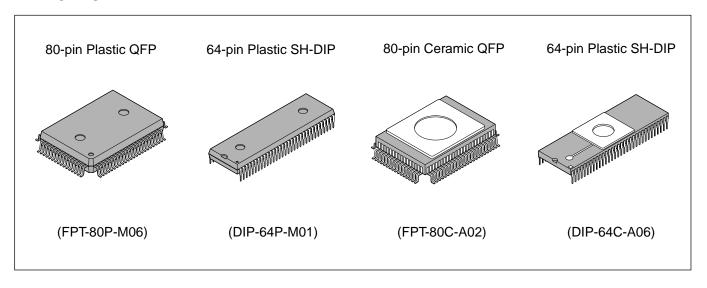
 Various package options QFP package (80 pins): MB89860 SDIP package (64 pins): MB89850

· High-speed processing at low voltage

Minimum execution time: 0.4 µs/3.5 V, 0.8 µs/2.7 V

(Continued)

■ PACKAGE



(Continued)

• F²MC-8L family CPU core

Instruction set optimized for controllers

Multiplication and division instructions 16-bit arithmetic operations Test and branch instructions Bit manipulation instructions, etc.

8-bit PWM timers: 2 channels
 Also usable as a reload timer

UART

Full-duplex double buffer

Synchronous and asynchronous data transfer

• 8-bit serial I/O

Switchable transfer direction allows communication with various equipment.

 10-bit A/D converter Conversion time: 13.2 μs

Activation by an external input or a timer unit capable

• External interrupt: 4 channels

Four channels are independent and capable of wake-up from low-power consumption modes (with an edge detection function).

• Low-power consumption modes

Stop mode (Oscillation stops to minimize the current consumption.)

Sleep mode (The CPU stops to reduce the current consumption to approx. 1/3 of normal.)

· Bus interface functions

Including hold and ready functions

• Timer unit

Outputs non-overlap three-phase waveforms to control an AC inverter motor.

Also usable as a PWM timer (4 channels)

■ PRODUCT LINEUP

| Part number Parameter | MB89855 MB89T855 | MB89865 | MB89857 | MB89867 | MB89P857 MB89W857 | MB89P867 MB89W867 |
|---|--|--|----------------------------------|--|----------------------|----------------------|
| Classification | Mass production products (mask ROM products) One-time PROM pruducts EPROM products, also used for evaluation | | | | | |
| ROM size | (internal m NoteInMB891 | x 8 bits nask ROM) 855 nunternal redbutexternal | < 8 bits nask ROM) | 32 K × 8 bits (internaPROMprogramming withgeneral-purpos&PROM programmer) | | |
| RAM size | 512× | 8 bits | | 1 K× | 8 bits | |
| CPU functions | Instruc Instruc Data b Minimu | er of instruction tion bit length: tion length: it length: Im execution til ot processing t | 8 bit 1 to 1, 8 me: 0.4 | s 3 bytes , 16 bits us/10 MHz us/10 MHz | | |
| Ports | Input ports: 5 (All also serve as peripherals) Output ports (N-ch open drain): 8 (All also serve as peripherals) I/O ports (N-ch open drain): 15 (MB89860 series only) Output ports (CMOS): 8 (All also serve as bus control pins) I/O ports (CMOS): 32 (All also serve as bus pins or peripherals) Total: 68 (53 pins for MB89850 series) | | | | | |
| Timer unit | 10-bit up/down count timer × 1 Compare registers with buffer × 4 Compare timer unit clear register with buffer × 1 Zero detection pin control 4 output channels Non-overlap three-phase waveform output Independent three-phase dead-time timer | | | | | |
| 8-bit PWM timer 1, 8-bit PWM timer 2 | 8-bit reload timer operation (toggled output capable, operating clock cycle: 0.4 μs to 25.6 μs) 8-bit resolution PWM operation (conversion cycle: 102 μs to 6.528 ms) | | | | | |
| UART | 8 bits Clock synchronous/asynchronous data transfer capable | | | | | |
| 8-bit serial I/O | 8 bits LSB first/MSB first selectability One clock selectable from four transfer clocks (one external shift clock, three internal shift clocks: 0.8 μs, 3.2 μs, 12.8 μs) | | | | | |
| 10-bit A/D converter | 10-bit resolution × 8 channels A/D conversion time: 13.2 μs Continous activation by a compare channel 0 in timer unit or an external activation capable | | | | | |
| External interrupt | 4 independent channels (edge selection, interrupt vector, source flag) Rising edge/falling edge selectability. Usedalsoforwake-upfromstop/sleepmode.(Edgedetectionisalsopermittedinstopmode.) | | | | | |
| Standby modes | | | Sleep mode | e, stop mode | | |
| Process | CMOS | | | | | |
| Operating voltage* | | 2.7 V t | o 6.0 V | | 2.7 V t | o 5.5 V |

^{*:} Varies with conditions such as the operating frequency. (See section "■ Electrical Characteristics.")

■ PACKAGE AND CORRESPONDING PRODUCTS

| Package | MB89855 MB89T855 MB89857 MB89P857 | MB89W857 | MB89865 MB89867 MB89P867 | MB89W867 |
|-------------|--|----------|--------------------------------|----------|
| DIP-64P-M01 | 0 | × | × | × |
| DIP-64C-A06 | × | 0 | × | × |
| FPT-80P-M06 | × | × | 0 | × |
| FPT-80C-A02 | × | × | × | 0 |

○ : Available ×: Not available

Note: For more information about each package, see section "■ Package Dimensions."

■ DIFFERENCES AMONG PRODUCTS

1. Memory Size

Before evaluating using the OTPROM (one-time PROM) products (also used for evaluation), verify its differences from the product that will actually be used.

Take particular care on the following point:

• The stack area, etc., is set at the upper limit of the RAM.

2. Current Consumption

When operated at low speed, the product with an OTPROM or an EPROM will consume more current than the product with a mask ROM.

However, the current consumption in sleep/stop modes is the same.

3. Mask Options

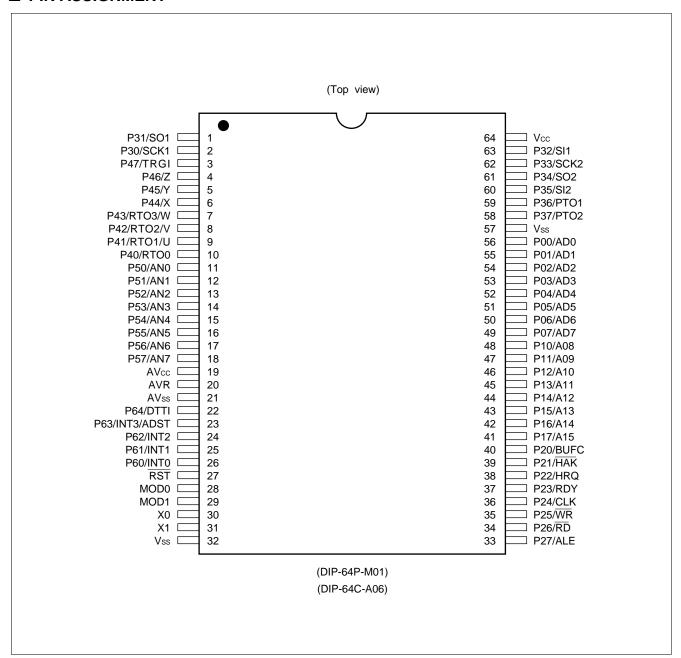
In the MB89P857/W857/P867/W867/T855, no option can be set.

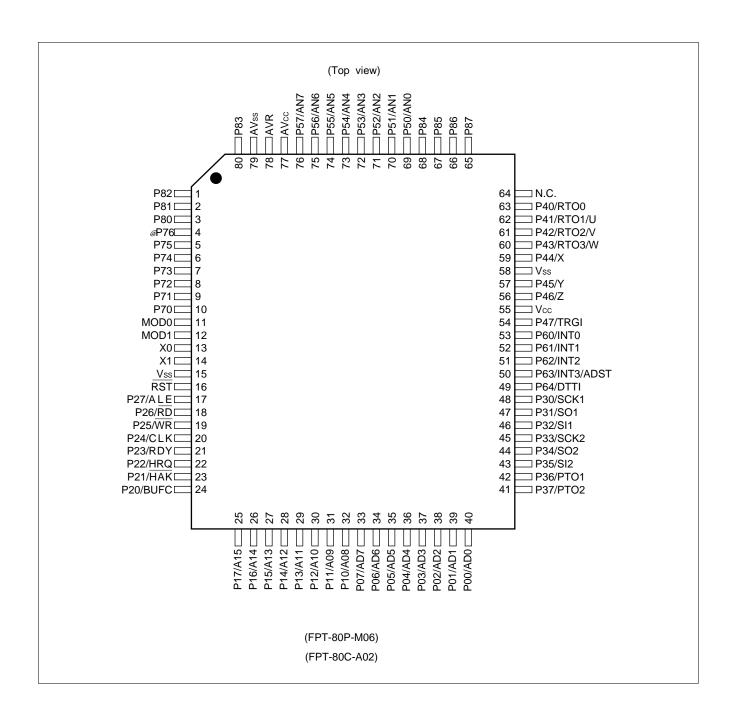
Before using options check section "■ Mask Options."

Take particular care on the following point:

A pull-up resistor can be set for P00 to P07, P10 to P17 and P20 to P27 only at single-chip mode.

■ PIN ASSIGNMENT





■ PIN DESCRIPTION

| Pin | no. | | Circuit | | |
|----------|----------|------------------------|---------|--|--|
| SH-DIP*1 | QFP*2 | Pin name | type | Function | |
| 30 | 13 | X0 | А | Crystal oscillator pins (10 MHz) | |
| 31 | 14 | X1 | | | |
| 28 | 11 | MOD0 | В | Operating mode selection pins | |
| 29 | 12 | MOD1 | | Connect directly to Vcc or Vss. | |
| 27 | 16 | RST | С | Reset I/O pin This pin is an N-ch open-drain output type with a pull-up resistor, and a hysteresis input type. "L" is output from this pin by an internal reset source. The internal circuit is initialized by the input of "L". | |
| 56 to 49 | 40 to 33 | P00 /AD0 to P07/AD7 | D | General-purpose I/O ports When an external bus is used, these ports function as multiplex pins of lower address output and data I/O. | |
| 48 to 41 | 32 to 25 | P10 /A08 to P17/A15 | D | General-purpose I/O ports When an external bus is used, these ports function as upper address output. | |
| 40 | 24 | P20/BUFC | F | General-purpose output port When an external bus is used, this port can also be used as a buffer control output. | |
| 39 | 23 | P21/HAK | F | General-purpose output port When an external bus is used, this port can also be used as a hold acknowledge output. | |
| 38 | 22 | P22/HRQ | D | General-purpose output port When an external bus is used, this port can also be used as a hold request input. | |
| 37 | 21 | P23/RDY | D | General-purpose output port When an external bus is used, this port functions as a ready input. | |
| 36 | 20 | P24/CLK | F | General-purpose output port When an external bus is used, this port functions as a clock output. | |
| 35 | 19 | P25/WR | F | General-purpose output port When an external bus is used, this port functions as a write signal output. | |
| 34 | 18 | P26/RD | F | General-purpose output port When an external bus is used, this port functions as a read signal output. | |
| 33 | 17 | P27/ALE | F | General-purpose output port When an external bus is used, this port functions as an address latch signal output. | |
| 2 | 48 | P30/SCK1 | Е | General-purpose I/O port Also serves as the clock I/O for the UART. This port is a hysteresis input type. | |

*1: DIP-64P-M01, DIP-64C-A06

*2: FPT-80P-M06, FPT-80C-A02

(Continued)

| Pin no. | | Pin name Circuit | | Function |
|---------------|------------------|--|------|--|
| SH-DIP*1 | QFP*2 | - Pin name | type | Function |
| 1 | 47 | P31/SO1 | Е | General-purpose I/O port Also serves as the data output for the UART. This port is a hysteresis input type. |
| 63 | 46 | P32/SI1 | Е | General-purpose I/O port Also serves as the data input for the UART. This port is a hysteresis input type. |
| 62 | 45 | P33/SCK2 | Е | General-purpose I/O port Also serves as the clock I/O for the 8-bit serial I/O. This port is a hysteresis input type. |
| 61 | 44 | P34/SO2 | Е | General-purpose I/O port Also serves as the data output for the 8-bit serial I/O. This port is a hysteresis input type. |
| 60 | 43 | P35/SI2 | Е | General-purpose I/O port Also serves as the data input for the 8-bit serial I/O. This port is a hysteresis input type. |
| 59 | 42 | P36/PTO1 | Е | General-purpose I/O port Also serves as the pulse output for the 8-bit PWM timer 1 This port is a hysteresis input type. |
| 58 | 41 | P37/PTO2 | Е | General-purpose I/O port Also serves as the pulse output for the 8-bit PWM timer 2 This port is a hysteresis input type. |
| 10 | 63 | P40/RTO0 | E | General-purpose I/O port Also serves as the pulse output for the timer unit. This port is a hystereisis input type. |
| 9, 8, 7 | 62, 61, 60 | P41/RTO1/U, P42/RTO2/V, P43/RTO3/W | Е | General-purpose I/O ports Also serve as the pulse output for the timer unit or a non overlap three-phase waveform output. These ports are a hysteresis input type. |
| 6, 5, 4 | 59, 57, 56 | P44/X, P45/Y, P46/Z | Е | General-purpose I/O ports Also serve as a non-overlap three-phase output. These ports are a hysteresis input type. |
| 3 | 54 | P47/TRGI | E | General-purpose I/O port Also serves as the trigger input for the timer unit. This port is a hysteresis input type. |
| 11 to 18 | 69 to 76 | P50/AN0 to P57/AN7 | Н | N-ch open-drain output ports Also serve as the analog input for the A/D converter. |
| 26 to 24 | 53 to 51 | P60/INT0 to P62/INT2 | I | General-purpose input ports Also serve as an external interrupt input. These ports are a hysteresis input type. |
| 23 | 50 | P63/INT3/ ADST | I | General-purpose input port Also serves as an external interrupt input and as the activation trigger input for the A/D converter. This port is a hysteresis input type. |

*1: DIP-64P-M01, DIP-64C-A06

*2: FPT-80P-M06, FPT-80C-A02

(Continued)

| Pin | no. | Pin name | Circuit | Function |
|----------|-------------------------|--------------|---------|--|
| SH-DIP*1 | QFP*2 | Pili liaille | type | Function |
| 22 | 49 | P64/DTTI | I | General-purpose input port Also serves as a dead-time timer disable input. This port is a hysteresis input type. DTTI input is with a noise canceller. |
| _ | 10 to 4 | P70 to P76 | G | N-ch open-drain I/O ports These ports are a hysteresis input type. |
| _ | 3 to 1, 80, 68 to 65 | P80 to P87 | G | N-ch open-drain I/O ports These ports are a hysteresis input type. |
| 64 | 55 | Vcc | _ | Power supply pin |
| 32, 57 | 15, 58 | Vss | _ | Power supply (GND) pins |
| 19 | 77 | AVcc | _ | A/D converter power supply pin |
| 20 | 78 | AVR | _ | A/D converter reference voltage input pin |
| 21 | 79 | AVss | _ | A/D converter power supply (GND) pin Use this pin at the same voltage as Vss. |
| _ | 64 | N.C. | _ | Internally connected pin Be sure to leave it open. |

*1: DIP-64P-M01, DIP-64C-A06 *2: FPT-80P-M06, FPT-80C-A02

■ I/O CIRCUIT TYPE

| Туре | Circuit | Remarks |
|------|--|--|
| A | X1 X0 X0 X0 X1 X0 X1 X0 X1 X0 X1 X1 X1 X1 X1 X1 X1 X1 X1 X1 X1 X1 X1 | At an oscillation feedback resitor of approximately 1 MΩ/5.0 V |
| В | | |
| С | R P-ch N-ch | At an output pull-up resistor (P-ch) of approximately 50 kΩ/5.0 V Hysteresis input |
| D | P-ch P-ch N-ch | CMOS output CMOS input Pull-up resistor optional (Mask ROM products) At a pull-up resistor of approximately 50 kΩ/5.0 V |
| E | P-ch N-ch N-ch | CMOS output Hysteresis input Pull-up resistor optional (Mask ROM products) At a pull-up resistor of approximately 50 kΩ/5.0 V |

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(Continued)

| Туре | Circuit | Remarks |
|------|------------------------|---|
| F | P-ch N-ch | CMOS output Pull-up resistor optional (Mask ROM products) At a pull-up resistor of approximately 50 kΩ/5.0 V |
| G | R P-ch P-ch N-ch | N-ch open-drain output Hysteresis input Pull-up resistor optional (Mask ROM products) At a pull-up resistor of approximately 50 kΩ/5.0 V |
| Н | P-ch N-ch Analog input | N-ch open-drain output Analog input |
| I | R D | Hysteresis input Pull-up resistor optional (Mask ROM products) At a pull-up resistor of approximately 50 kΩ/5.0 V |

■ HANDLING DEVICES

1. Preventing Latchup

Latchup may occur on CMOS ICs if voltage higher than Vcc or lower than Vss is applied to input and output pins other than medium- to high-voltage pins or if higher than the voltage which shows on "1. Absolute Maximum Ratings" in section "■ Electrical Characteristics" is applied between Vcc and Vss.

When latchup occurs, power supply current increases rapidly and might thermally damage elements. When using, take great care not to exceed the absolute maximum ratings.

Also, take care to prevent the analog power supply (AVcc and AVR) and analog input from exceeding the digital power supply (Vcc) when the analog system power supply is turned on and off.

2. Treatment of Unused Input Pins

Leaving unused input pins open could cause malfunctions. They should be connected to a pull-up or pull-down resistor.

3. Treatment of Power Supply Pins on Microcontrollers with A/D and D/A Converters

Connect to be AVcc = DAVC = Vcc and AVss = AVR = Vss even if the A/D and D/A converters are not in use.

4. Treatment of N.C. Pin

Be sure to leave (internally connected) N.C. pin open.

5. Power Supply Voltage Fluctuations

Although $V_{\rm CC}$ power supply voltage is assured to operate within the rated range, a rapid fluctuation of the voltage could cause malfunctions, even if it occurs within the rated range. Stabilizing voltage supplied to the IC is therefore important. As stabilization guidelines, it is recommended to control power so that $V_{\rm CC}$ ripple fluctuations (P-P value) will be less than 10% of the standard $V_{\rm CC}$ value at the commercial frequency (50 to 60 Hz) and the transient fluctuation rate will be less than 0.1 V/ms at the time of a momentary fluctuation such as when power is switched.

6. Precautions when Using an External Clock

Even when an external clock is used, oscillation stabilization time is required for power-on reset (optional) and wake-up from stop mode.

■ PROGRAMMING TO THE EPROM ON THE MB89P867/W867/P857/W857

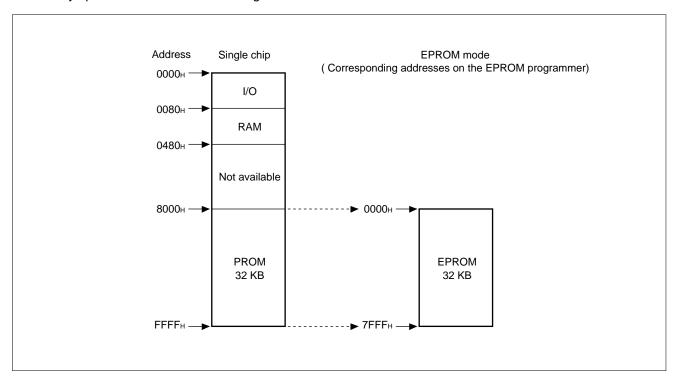
The MB89P867/W867/P857/W857 are an OTPROM version of the MB89860/850 series.

1. Features

- 32-Kbyte PROM on chip
- Equivalency to the MBM27C256A in EPROM mode (when programmed with the EPROM programmer)

2. Memory Space

Memory space in EPROM mode is diagrammed below.



3. Programming to the EPROM

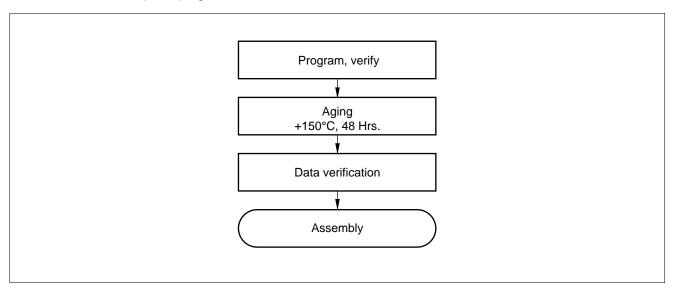
In EPROM mode, the MB89P867/W867/P857/W857 functions equivalent to the MBM27C256A. This allows the PROM to be programmed with a general-purpose EPROM programmer (the electronic signature mode cannot be used) by using the dedicated socket adapter.

· Programming procedure

- (1) Set the EPROM programmer to the MBM27C256A.
- (2) Load program data into the EPROM programmer at 0000_H to 7FFF_H (note that addresses 8000_H to FFFF_H while operating as a single chip assign to addresses 0000_H to 7FFF_H in EPROM mode.)
- (3) Program to 0000H to 7FFFH with the EPROM programmer.

4. Recommended Screening Conditions

High-temperature aging is recommended as the pre-assembly screening procedure for a product with a blanked OTPROM microcomputer program.



5. Programming Yield

All bits cannot be programmed at Fujitsu shipping test to a blanked OTPROM microcomputer, due to its nature. For this reason, a programming yield of 100% cannot be assured at all times.

6. Erasure

In order to clear all locations of their programmed contents, it is necessary to expose the internal EPROM to an ultraviolet light source. A dosage of 10 W-seconds/cm² is required to completely erase an internal EPROM. This dosage can be obtained by exposure to an ultraviolet lamp (wavelength of 2537 Angstroms (Å)) with intensity of 12000 μ W/cm² for 15 to 21 minutes. The internal EPROM should be about one inch from the source and all filters should be removed from the UV light source prior to erasure.

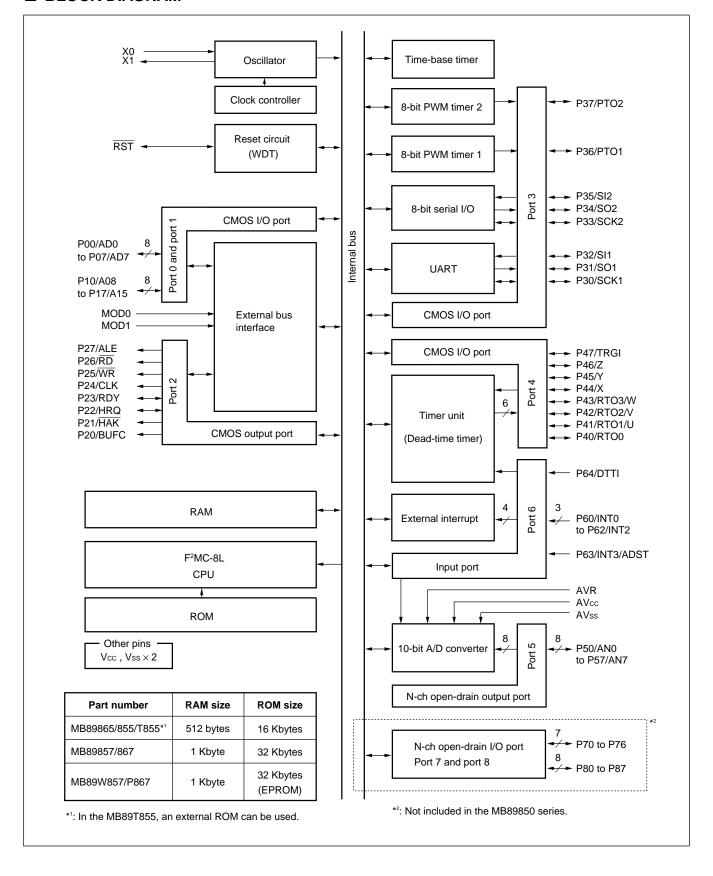
It is important to note that the internal EPROM and similar devices, will erase with light sources having wavelengths shorter than 4000 Å. Although erasure time will be much longer than with UV source at 2537 Å, nevertheless the exposure to fluorescent light and sunlight will eventually erase the internal EPROM, and exposure to them should be prevented to realize maximum system reliability. If used in such an environment, the package windows should be covered by an opaque label or substance.

7. EPROM Programmer Socket Adapter

| Package | Compatible socket adapter |
|-------------|---------------------------|
| DIP-64P-M01 | ROM-64SD-28DP-8L* |
| FPT-80P-M01 | ROM-80QF-28DP-8L2 |

^{*:} Connect the adapter jumper pin to Vss when using. Inquiry: Sun Hayato Co., Ltd.: TEL 81-3-3802-5760

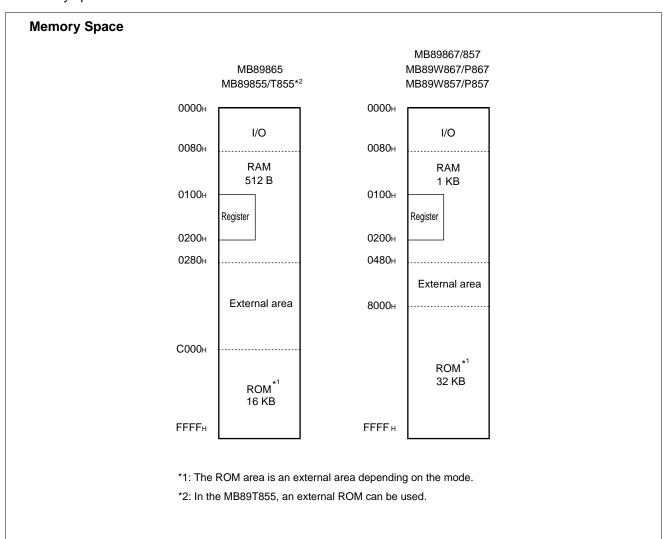
■ BLOCK DIAGRAM



■ CPU CORE

1. Memory Space

The microcontrollers of the MB89860/850 series offer a memory space of 64 Kbytes for storing all of I/O, data, and program areas. The I/O area is located at the lowest address. The data area is provided immediately above the I/O area. The data area can be divided into register, stack, and direct areas according to the application. The program area is located at exactly the opposite end, that is, near the highest address. Provide the tables of interrupt reset vectors and vector call instructions toward the highest address within the program area. The memory space of the MB89860/850 series is structured as illustrated below.



2. Registers

The F²MC-8L family has two types of registers; dedicated registers in the CPU and general-purpose registers in the memory. The following dedicated registers are provided:

Program counter (PC): A 16-bit register for indicating instruction storage positions

Accumulator (A): A 16-bit temporary register for storing arithmetic operations, etc. When the

instruction is an 8-bit data processing instruction, the lower byte is used.

Temporary accumulator (T): A 16-bit register which performs arithmetic operations with the accumulator

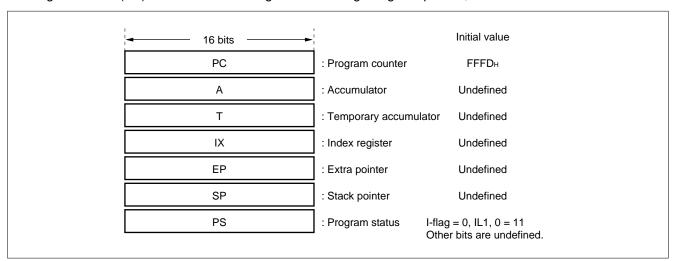
When the instruction is an 8-bit data processing instruction, the lower byte is used.

Index register (IX): A 16-bit register for index modification

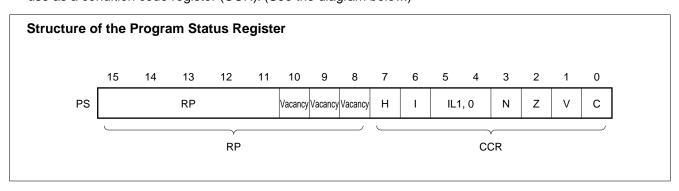
Extra pointer (EP): A 16-bit pointer for indicating a memory address

Stack pointer (SP): A 16-bit register for indicating a stack area

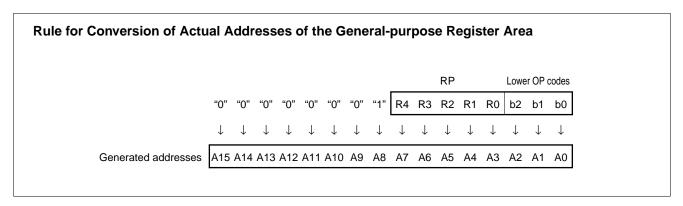
Program status (PS): A 16-bit register for storing a register pointer, a condition code



The PS can further be divided into higher 8 bits for use as a register bank pointer (RP) and the lower 8 bits for use as a condition code register (CCR). (See the diagram below.)



The RP indicates the address of the register bank currently in use. The relationship between the pointer contents and the actual address is based on the conversion rule illustrated below.



The CCR consists of bits indicating the results of arithmetic operations and the contents of transfer data and bits for control of CPU operations at the time of an interrupt.

H-flag: Set when a carry or a borrow from bit 3 to bit 4 occurs as a result of an arithmetic operation. Cleared otherwise. This flag is for decimal adjustment instructions.

I-flag: Interrupt is allowed when this flag is set to 1. Interrupt is prohibited when the flag is set to 0. Set to 0 when reset.

IL1, 0: Indicates the level of the interrupt currently allowed. Processes an interrupt only if its request level is higher than the value indicated by this bit.

| IL1 | IL0 | Interrupt level | High-low |
|-----|-----|-----------------|--------------------|
| 0 | 0 | 1 | High |
| 0 | 1 | l | † |
| 1 | 0 | 2 | |
| 1 | 1 | 3 | Low = no interrupt |

N-flag: Set if the MSB is set to 1 as the result of an arithmetic operation. Cleared when the bit is set to 0.

Z-flag: Set when an arithmetic operation results in 0. Cleared otherwise.

V-flag: Set if the complement on 2 overflows as a result of an arithmetic operation. Reset if the overflow does not occur.

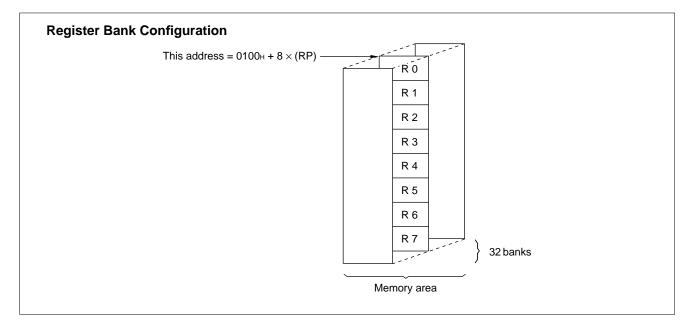
C-flag: Set when a carry or a borrow from bit 7 occurs as a result of an arithmetic operation. Cleared otherwise. Set to the shift-out value in the case of a shift instruction.

The following general-purpose registers are provided:

General-purpose registers: An 8-bit register for storing data

The general-purpose registers are 8 bits and located in the register banks of the memory. One bank contains eight registers and up to a total of 32 banks can be used on the MB89860/850 series. The bank currently in use is indicated by the register bank pointer (RP).

Note: The number of register banks that can be used varies with the RAM size.



■ I/O MAP

| 00н 01н 02н 03н 04н 05н 06н 07н 08н 09н 0Ан 0Вн 0Сн 0Dн | (R/W) (W) (R/W) (W) (R/W) | PDR0 DDR0 PDR1 | Port 0 data register Port 0 data direction register | |
|--|---------------------------|----------------------|--|--|
| 02н 03н 04н 05н 06н 07н 08н 09н 0Ан 0Вн 0Сн | (R/W) (W) | PDR1 | • | |
| 03н 04н 05н 06н 07н 08н 09н 0Ан 0Вн 0Сн | (W) | | | |
| 04н 05н 06н 07н 08н 09н 0Ан 0Вн 0Сн | | | Port 1 data register | |
| 05н 06н 07н 08н 09н 0Ан 0Вн 0Сн | (R/W) | DDR1 | Port 1 data direction register | |
| 06н 07н 08н 09н 0Ан 0Вн 0Сн | ` ' | PDR2 | Port 2 data register | |
| 07н 08н 09н 0Ан 0Вн 0Сн | (W) | BCTR | External bus pin control register | |
| 08н 09н 0Ан 0Вн 0Сн | | | Vacancy | |
| 09н 0Ан 0Вн 0Сн 0Dн | | | Vacancy | |
| 0Ан 0Вн 0Сн 0Dн | (R/W) | STBC | Standby control register | |
| 0Вн 0Сн 0Dн | (W) | WDTC | Watchdog timer control register | |
| 0Сн 0Dн | (R/W) | TBTC | Time-base timer control register | |
| 0Дн | | | Vacancy | |
| | (R/W) | PDR3 | Port 3 data register | |
| 0Ен | (W) | DDR3 | Port 3 data direction register | |
| | (R/W) | PDR4 | Port 4 data register | |
| 0Fн | (W) | DDR4 | Port 4 data direction register | |
| 10н | (R/W) | PDR5 | Port 5 data register | |
| 11н | | | Vacancy | |
| 12н | (R) | PDR6 | Port 6 data register | |
| 13н | | | Vacancy | |
| 14н | (R/W) | PDR7 | Port 7 data register | |
| 15н | | | Vacancy | |
| 16н | (R/W) | PDR8 | Port 8 data register | |
| 17н to 1Вн | | | Vacancy | |
| 1Сн | (R/W) | CTR1 | PWM control register 1 | |
| 1Dн | (W) | CMR1 | PWM compare register 1 | |
| 1Ен | (R/W) | CTR2 | PWM control register 2 | |
| 1Fн | (W) | CMR2 | PWM compare register 2 | |
| 20н | (R/W) | SMC | UART serial mode control register | |
| 21н | (R/W) | SRC | UART serial rate control register | |
| 22н | (R/W) | SSD | UART serial status/data register | |
| 23н | (R/W) | SIDR/SODR | UART serial data register | |
| 24н | (R/W) | SMR | Serial mode register | |
| 25н | • | | | |

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| Address | Read/write | Register name | Register description |
|-------------|------------|---------------|--|
| 26н | (R/W) | EIC1 | External interrupt control register 1 |
| 27н | (R/W) | EIC2 | External interrupt control register 2 |
| 28н | (R/W) | ADC1 | A/D converter control register 1 |
| 29н | (R/W) | ADC2 | A/D converter control register 2 |
| 2Ан | (R) | ADDH | A/D converter data register (H) |
| 2Вн | (R) | ADDL | A/D converter data register (L) |
| 2Сн | | | Vacancy |
| 2Dн | (W) | ZOCTR | Zero detection output control register |
| 2Ен | (W) | CLRBRH | Compare clear buffer register (H) |
| 2Fн | (W) | CLRBRL | Compare clear buffer register (L) |
| 30н | (R/W) | TCSR | Timer control status register |
| 31н | (R/W) | CICR | Compare interrupt control register |
| 32н | (R/W) | TMCR | Timer mode control register |
| 33н | (R/W) | COER | Compare/port selection register |
| 34н | (R/W) | CMCR | Compare buffer mode control register |
| 35н | (R/W) | DTCR | Dead-time timer control register |
| 36н | (W) | DTSR | Dead-time setting register |
| 37н | (R/W) | OCTBR | Output control buffer register |
| 38н | (W) | OCPBR0H | Output compare buffer register 0 (H) |
| 39н | (W) | OCPBR0L | Output compare buffer register 0 (L) |
| ЗАн | (W) | OCPBR1H | Output compare buffer register 1 (H) |
| 3Вн | (W) | OCPBR1L | Output compare buffer register 1 (L) |
| 3Сн | (W) | OCPBR2H | Output compare buffer register 2 (H) |
| 3Dн | (W) | OCPBR2L | Output compare buffer register 2 (L) |
| 3Ен | (W) | OCPBR3H | Output compare buffer register 3 (H) |
| 3Fн | (W) | OCPBR3L | Output compare buffer register 3 (L) |
| 40н to 7Вн | | | Vacancy |
| 7Сн | (W) | ILR1 | Interrupt level setting register 1 |
| 7Dн | (W) | ILR2 | Interrupt level setting register 2 |
| 7Ен | (W) | ILR3 | Interrupt level setting register 3 |
| 7 Fн | | | Vacancy |

Notes: • Do not use vacancies.

• When a read-modify-write instruction (such as bit set) is used to access a write-only register or a register containing a write-only bit, a bit designated by the instruction will have a predetermined value. However, a write-only bit included, if any, in bits not defined by the instruction will cause a malfunction. So no access to the register should be tried with any read-modefy-write instruction.

■ ELECTRICAL CHARACTERISTICS

1. Absolute Maximum Ratings

(AVss = Vss = 0.0 V)

| Barrantan | Coursels at | Va | lue | 11:4 | Damanla | |
|--|-----------------|-------------|-----------|------|---|--|
| Parameter | Symbol | Min. | Max. | Unit | Remarks | |
| Power supply voltage | Vcc AVcc | Vss - 0.3 | Vss + 7.0 | V | * | |
| A/D converter reference input voltage | AVR | Vss - 0.3 | Vss + 7.0 | V | AVR must not exceed AVcc + 0.3 V. | |
| Program voltage | VPP | Vss - 0.3 | 13.0 | V | MOD1 pins of MB89P867/ W867 and MB89P857/W857 | |
| Input voltage | Vı | Vss - 0.3 | Vcc + 0.3 | V | | |
| Output voltage | Vo | Vss - 0.3 | Vss + 0.3 | V | | |
| "L" level maximum output current | loL | _ | 20 | mA | | |
| "L" level average output current | lolav1 | _ | 4 | mA | P00 to P07, P10 to P17, P20 to P27, P30 to P37, P50 to P57, P70 to P76, P80 to P87 | |
| | lolav2 | _ | 15 | mA | P40 to P47 | |
| "L" level total average output current | Σ lolav1 | _ | 30 | mA | P00 to P07, P10 to P17, P20 to P27, P30 to P37, P50 to P57, P70 to P76, P80 to P87 | |
| | \sum lolav2 | _ | 50 | mA | P40 to P47 | |
| "H" level maximum output current | Іон | _ | -20 | mA | | |
| "H" level average output current | Іонач | _ | -4 | mA | | |
| "H" level total maximum output current | ΣІон | _ | -20 | mA | | |
| Power consumption | Po | _ | 300 | mW | | |
| Operating temperature | TA | -40 | +85 | °C | | |
| Storage temperature | Tstg | - 55 | +150 | °C | | |

^{*:} Use AVcc and Vcc set at the same voltage.

Take care so that AVcc does not exceed Vcc, such as when power is turned on.

Precautions: Permanent device damage may occur if the above "Absolute Maximum Ratings" are exceeded. Functional operation should be restricted to the conditions as detailed in the operational sections of this data sheet. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

2. Recommended Operating Conditions

(AVss = Vss = 0.0 V)

| Parameter | Symbol | Va | lue | Unit | Remarks |
|---------------------------------------|-------------|------|------|-------|---|
| raiailletei | Syllibol | Min. | Max. | Offic | Neillaiks |
| Power supply voltage | | 2.7* | 6.0* | V | Normal operation assurance range* MB89867/865, MB89857/855 |
| | Vcc AVcc | 2.7* | 5.5* | V | Normal operation assurance range* MB89P867/W867, MB89P857/W855/T855 |
| | | 1.5 | 6.0 | V | Retains the RAM state in stop mode |
| A/D converter reference input voltage | AVR | 0.0 | AVcc | V | |
| Operating temperature | TA | -40 | +85 | °C | |

^{*:} These values vary with the operating frequency, instruction cycle, and analog assurance range. See Figure 1 and "5. A/D Converter Electrical Characteristics."

Note: Connect the MOD0 and MOD1 pins to Vcc or Vss.

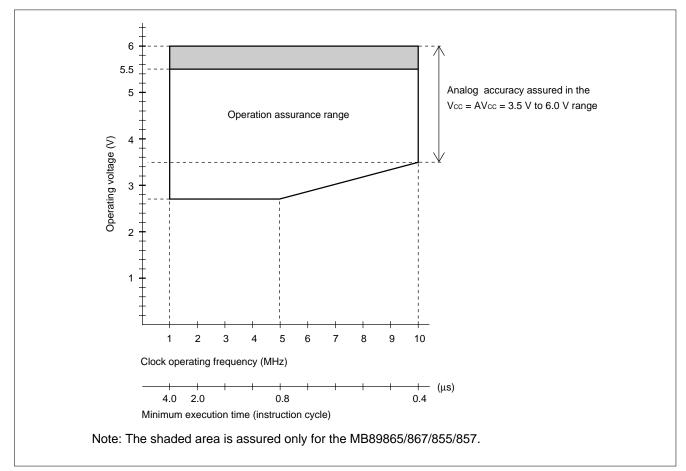


Figure 1 Operating Voltage vs. Clock Operating Frequency

3. DC Characteristics

 $(AVcc = Vcc = +5.0 \text{ V}, AVss = Vss = 0.0 \text{ V}, T_A = -40^{\circ}\text{C to } +85^{\circ}\text{C})$

| _ , | | D . | 0 1111 | | Value | | | |
|-----------------------|------------------|--|---|---------|-------|---------|------|----------------------|
| Parameter | Symbol | Pin | Condition | Min. | Тур. | Max. | Unit | Remarks |
| | ViH | P00toP07,P10toP17, P22, P23 | _ | 0.7 Vcc | _ | Vcc+0.3 | V | |
| "H'ilevelinputvoltage | Vihs | RST, P30 to P37, P40toP47,P60toP64, P70toP76,P80toP87 | _ | 0.8 Vcc | _ | Vcc+0.3 | V | |
| | VıL | P00toP07,P10toP17, P22, P23 | _ | Vss-0.3 | _ | 0.3 Vcc | V | |
| "L"levelinputvoltage | VILS | RST, P30 to P37, P40toP47,P60toP64, P70toP76,P80toP87 | _ | Vss-0.3 | _ | 0.2 Vcc | V | |
| "Hievebutputvoltage | Vон | P00toP07,P10toP17, P20toP27,P30toP37, P40 to P47 | Iон = −2.0 mA | 2.4 | _ | _ | V | |
| "L'levebutputvoltage | V _{OL1} | P00toP07,P10toP17, P20toP27,P30toP37, P50toP57,P70toP76, P80 to P87 | IoL = 1.8 mA | _ | _ | 0.4 | V | |
| | V _{OL2} | P40 to P47 | IoL = 15 mA | _ | _ | 1.5 | V | |
| Inpulteackagecurrent | I _{L11} | P00toP07,P10toP17, P20toP27,P30toP37, P40toP47,P60toP64, P70toP76,P80toP87, MOD0, MOD1 | 0.0V <vı<vcc< td=""><td>_</td><td>_</td><td>±5</td><td>μА</td><td></td></vı<vcc<> | _ | _ | ±5 | μА | |
| Pull-up resistance | RPULL | RST | Vı = 0.0 V | 25 | 50 | 100 | kΩ | Withpull-up resistor |
| | Icc | | Fc = 10 MHz Normal operatiomode (Externælock) | _ | 15 | 18 | mA | |
| Powersupplycurrent | Iccs | Vcc | Fc = 10 MHz Sleep mode (Externælock) | _ | 6 | 8 | mA | |
| | Іссн | | Stop mode T _A = +25°C | _ | _ | 10 | μА | |
| | IA | AVcc | Fc = 10 MHz, when A/D conversion is activated | _ | 6 | _ | mA | |
| Input capacitance | Cin | OtherthanAVcc,AVss, Vcc, and Vss | f = 1 MHz | _ | 10 | _ | pF | |

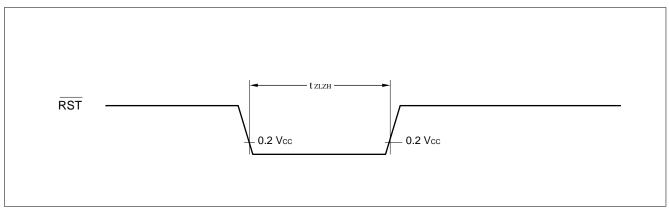
4. AC Characteristics

(1) Reset Timing

 $(Vcc = +5.0 V\pm 10\%, AVss = Vss = 0.0 V, TA = -40^{\circ}C to +85^{\circ}C)$

| Parameter | Symbol | Condition | Val | ue | Unit | Remarks | |
|---------------------|---------------|-----------|-----------|------|-------|---------|--|
| Parameter | Syllibol | Condition | Min. | Max. | Oilit | Kemarks | |
| RST "L" pulse width | t zlzh | _ | 16 txcyL* | _ | ns | | |

*: txcyL is the oscillation cycle (1/Fc) to input to the X0 pin.



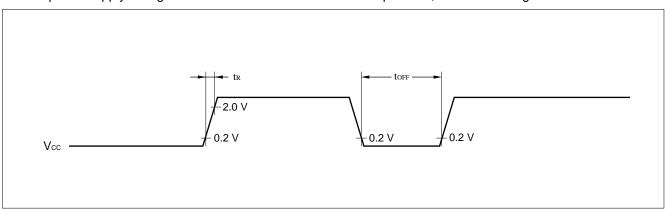
(2) Power-on Reset

$$(AVss = Vss = 0.0 \text{ V}, T_A = -40^{\circ}\text{C to } +85^{\circ}\text{C})$$

| Parameter | Symbol | Condition | Va | lue | Unit | Remarks | |
|---------------------------|------------------|-----------|------|------|----------------------------|------------------------------|--|
| raidilietei | Symbol Condition | | Min. | Max. | Oiiit | Kemarks | |
| Power supply rising time | t _R | | _ | 50 | ms | Power-on reset function only | |
| Power supply cut-off time | toff | 1 — m | | ms | Due to repeated operations | | |

Note: Make sure that power supply rises within the selected oscillation stabilization time.

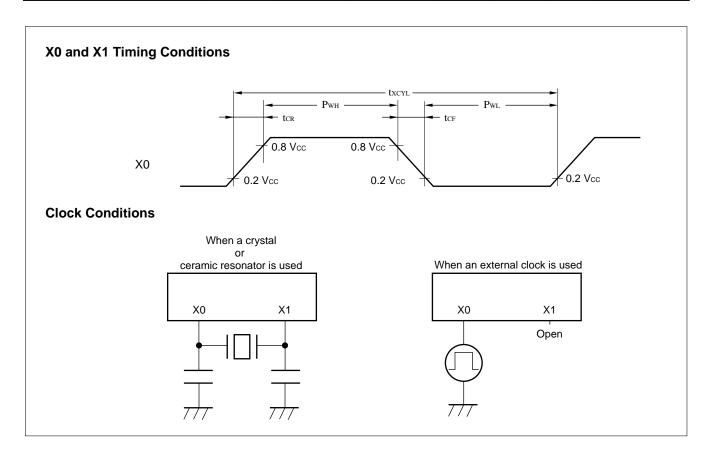
If power supply voltage needs to be varied in the course of operation, a smooth voltage rise is recommended.



(3) Clock Timing

$$(AVss = Vss = 0.0 \text{ V}, T_A = -40^{\circ}\text{C to } +85^{\circ}\text{C})$$

| Parameter | Symbol Pin | Din | Condition | Value | | Unit | Remarks |
|---------------------------------|------------|-----------|-----------|-------|------|-------|----------------|
| rarameter | Syllibol | | Condition | Min. | Max. | Oilit | Kemarks |
| Clock frequency | Fc | X0, X1 | | 1 | 10 | MHz | |
| Clock cycle time | txcyL | Λυ, Λι | | 100 | 1000 | ns | |
| Input clock pulse width | Pwh PwL | XO | <u> </u> | 20 | _ | ns | External clock |
| Input clock rising/falling time | tcr tcr | 70 | | _ | 10 | ns | External clock |

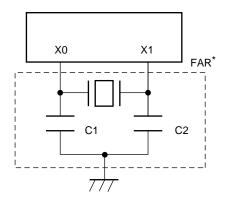


(4) Instruction Cycle

| Parameter | Symbol | Value (typical) | Unit | Remarks |
|--|--------|-----------------|------|--|
| Instruction cycle (minimum execution time) | tinst | 4/Fc | μs | $t_{inst} = 0.4 \mu s$ when operating at Fc = 10 MHz |

(5) Recommended Resonator Manufacturers

Sample Application of Piezoelectric Resonator (FAR Series)

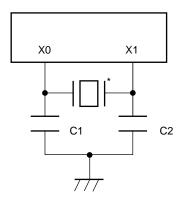


*: Fujitsu Acoustic Resonator C1 = C2 = 20 pF±8 pF (built-in FAR)

| FAR part number (built-in capacitor type) | Frequency | Initial deviation of FAR frequency (T _A = +25°C) | Temperature characteristics of FAR frequency (T _A = -25°C to +60°C) |
|---|-----------|---|--|
| FAR-C4CB-08000-M02 | 8.00 MHz | ±0.5% | ±0.5% |
| FAR-C4CB-10000-M02 | 10.00 MHz | ±0.5% | ±0.5% |

Inquiry: FUJITSU LIMITED

Sample Application of Ceramic Resonator



| Resonator manufacturer* | Resonator | Frequency | C1 (pF) | C2 (pF) | R (k Ω) |
|-------------------------|-------------|-----------|---------|---------|------------------------|
| Kyocera Corporation | KBR-7.68MWS | 7.68 MHz | 33 | 33 | _ |
| | KBR-8.0MWS | 8.0 MHz | 33 | 33 | _ |
| Murata Mfg. Co., Ltd. | CSA8.00MTZ | 8.0 MHz | 30 | 30 | _ |

Inquiry: Kyocera Corporation

AVX Corporation

North American Sales Headquarters: TEL 1-803-448-9411

AVX Limited

European Sales Headquarters: TEL 44-1252-770000

AVX/Kyocera H.K. Ltd.

Asian Sales Headquarters: TEL 852-363-3303

Murata Mfg. Co., Ltd.

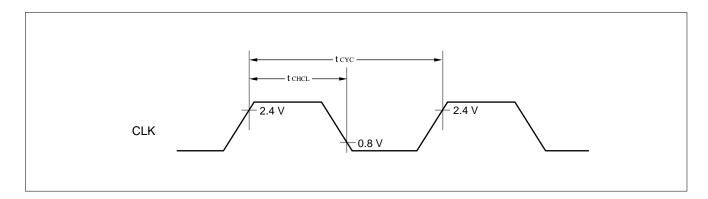
• Murata Electronics North America, Inc.: TEL 1-404-436-1300

- Murata Europe Management GmbH: TEL 49-911-66870
- Murata Electronics Singapore (Pte.) Ltd.: TEL 65-758-4233

(6) Clock Output Timing

 $(Vcc = +5.0 V\pm 10\%, AVss = Vss = 0.0 V, T_A = -40^{\circ}C to +85^{\circ}C)$

| Parameter | Symbol Pin | | Condition | Va | lue | Unit | Remarks | |
|---|---------------|-----|-----------------|------|------|-------|--------------------------------------|--|
| Parameter | Syllibol | | Condition | Min. | Max. | Offic | Remarks | |
| Cycle time | tere | CLK | Load condition: | 200 | _ | ns | txcyL × 2 at 10 MHz oscillation | |
| $CLK \uparrow \rightarrow CLK \downarrow$ | t chcL | CLK | 50 pF | 30 | 100 | ns | Approx. tcyc/2 at 10 MHz oscillation | |

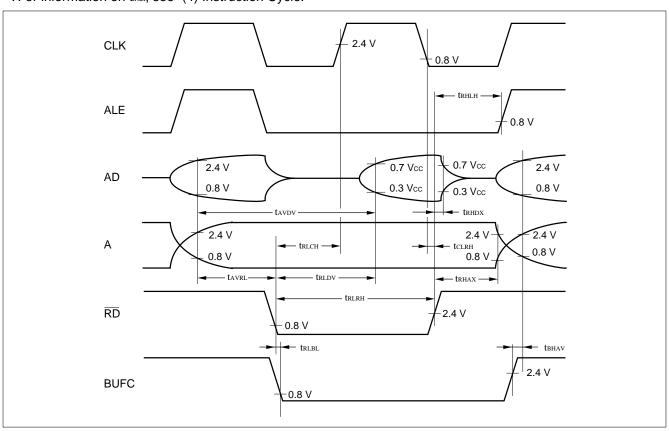


(7) Bus Read Timing

 $(Vcc = +5.0 V\pm 10\%, Fc = 10 MHz, AVss = Vss = 0.0 V, TA = -40°C to +85°C)$

| Parameter | Symbol | Pin | Condition | Value (| 10 MHz) | Unit | Remarks |
|---|---------------|------------------------------------|------------|-----------------------------|--------------------|-------|---------|
| Farameter | Syllibol | riii | Condition | Min. | Max. | Oilit | Remarks |
| Valid address \rightarrow \overline{RD} \downarrow time | t avrl | RD, A15to A08, AD7 to AD0 | | 1/4t _{inst} *-64ns | _ | ns | |
| RD pulse width | t rlrh | RD | | 1/2tinst*-20ns | _ | ns | |
| Valid address → data read time | tavdv | AD7toAD0,A15 to A08 | | _ | 1/2 t inst* | ns | No wait |
| $\overline{RD} \downarrow \to data \ read \ time$ | trldv | RD, AD7to AD0 | | _ | 1/2tinst*-80ns | ns | No wait |
| $\overline{RD} \uparrow \to data \; hold \; time$ | t RHDX | AD7toAD0,RD | Load | 0 | _ | ns | |
| $\overline{RD} \uparrow \to ALE \uparrow time$ | t RHLH | RD, ALE | condition: | 1/4tinst*-40ns | _ | ns | |
| RD↑→addressinvalidtime | t rhax | RD, A15 to A08 | 50 pF | 1/4tinst*-40ns | _ | ns | |
| $\overline{RD} \downarrow \to CLK \uparrow time$ | t RLCH | RD, CLK | | 1/4tinst*-60ns | _ | ns | |
| $CLK \downarrow \to \overline{RD} \uparrow time$ | t CLRH | KD, CLK | | 0 | _ | ns | |
| $\overline{RD} \downarrow \to BUFC \downarrow time$ | t RLBL | RD, BUFC | | -5 | _ | ns | |
| BUFC ↑ → valid address time | t BHAV | A15 to A08, AD7 to AD0, BUFC | | 5 | _ | ns | |

^{*:} For information on tinst, see "(4) Instruction Cycle."

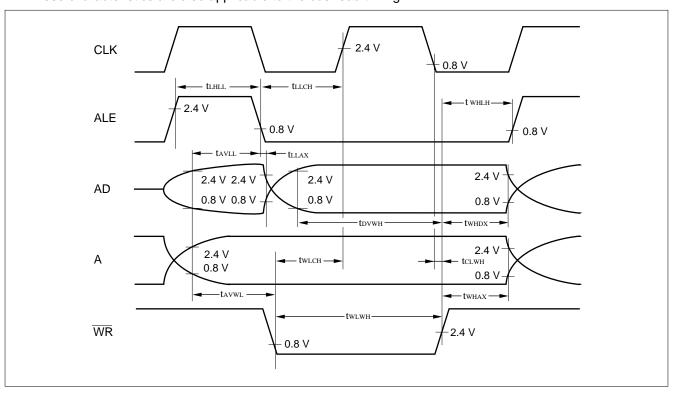


(8) Bus Write Timing

 $(Vcc = +5.0 V\pm 10\%, Fc = 10 MHz, AVss = Vss = 0.0 V, T_A = -40^{\circ}C to +85^{\circ}C)$

| Parameter | Symbol | Pin | Condition | Value (1 | IO MHz) | Unit | Remarks |
|--|---------------|---------------|-----------------------------|------------------------------|---------|-------|---------|
| Parameter | Symbol | FIII | Condition | Min. | Max. | Ullit | Remarks |
| $\begin{array}{c} \text{Valid address} \rightarrow \text{ALE} \downarrow \\ \text{time} \end{array}$ | tavll | AD7 to AD0, | | 1/4t _{inst} *1–64ns | _ | ns | |
| $\begin{array}{c} ALE \downarrow time \to address \\ invalid \ time \end{array}$ | tLLAX | ALE,A15toA08 | 3 | 5 | _ | ns | |
| Validaddress→WR↓time | t avwl | WR, ALE | | 1/4tinst*1-60ns | _ | ns | |
| WR pulse width | twlwh | WR | | 1/2tinst*1-20ns | _ | ns | |
| Write data $\rightarrow \overline{\text{WR}} \uparrow \text{time}$ | t DVWH | AD7toAD0,WR | Load condition: 50 pF | 1/2tinst*1-60ns | _ | ns | |
| $\overline{\overline{WR}} \uparrow \to \text{address invalid} \\ \text{time}$ | twhax | WR, A15to A08 | | 1/4t _{inst} *1-40ns | _ | ns | |
| $\overline{ m WR} \uparrow ightarrow$ data hold time | twhox | AD7toAD0,WR | | 1/4tinst*1-40ns | _ | ns | |
| $\overline{WR} \uparrow \to ALE \uparrow time$ | twhlh | WR, ALE | | 1/4tinst*1-40ns | _ | ns | |
| $\overline{WR} \downarrow \to CLK \uparrow time$ | t wlch | WR, CLK | | 1/4tinst*1-60ns | _ | ns | |
| $CLK \downarrow \to \overline{WR} \uparrow time$ | t clwH | VVK, CLK | | 0 | _ | ns | |
| ALE pulse width | t LHLL | ALE | | txcyl - 35 ns*2 | _ | ns | |
| $ALE \downarrow \to CLK \uparrow time$ | t llCH | ALE, CLK | | txcyL – 35 ns*2 | _ | ns | |

- *1: For information on t_{inst}, see "(4) Instruction Cycle."
- *2: These characteristics are also applicable to the bus read timing.

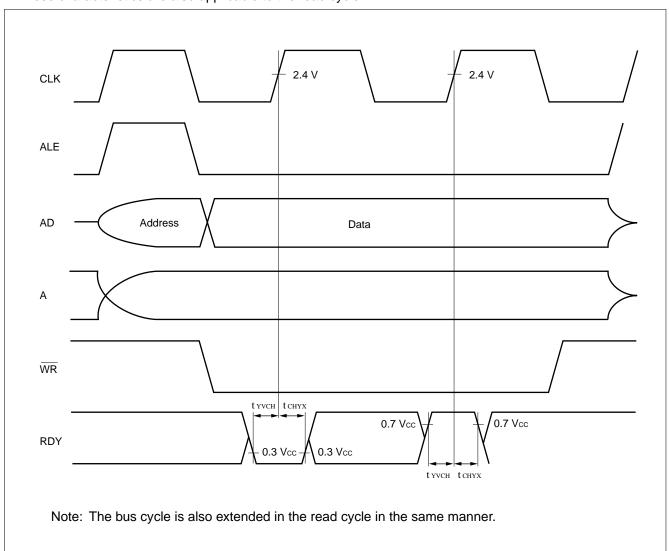


(9) Ready Input Timing

(Vcc = +5.0 V \pm 10%, Fc = 10 MHz, AVss = Vss = 0.0 V, Ta = -40°C to +85°C)

| Parameter | Symbol | Pin | Condition | Va | lue | Unit | Remarks |
|---|---------------|-------------|--------------------------|------|------|------|-------------|
| | Symbol | ' ''' | Condition | Min. | Max. | | iveillai ks |
| RDY valid \rightarrow CLK \uparrow time | tyvcн | RDY, CLK | Load condition: 50 pF | 60 | _ | ns | * |
| $CLK \uparrow \to RDY$ invalid time | t chyx | | | 0 | _ | ns | * |

^{*:} These characteristics are also applicable to the read cycle.

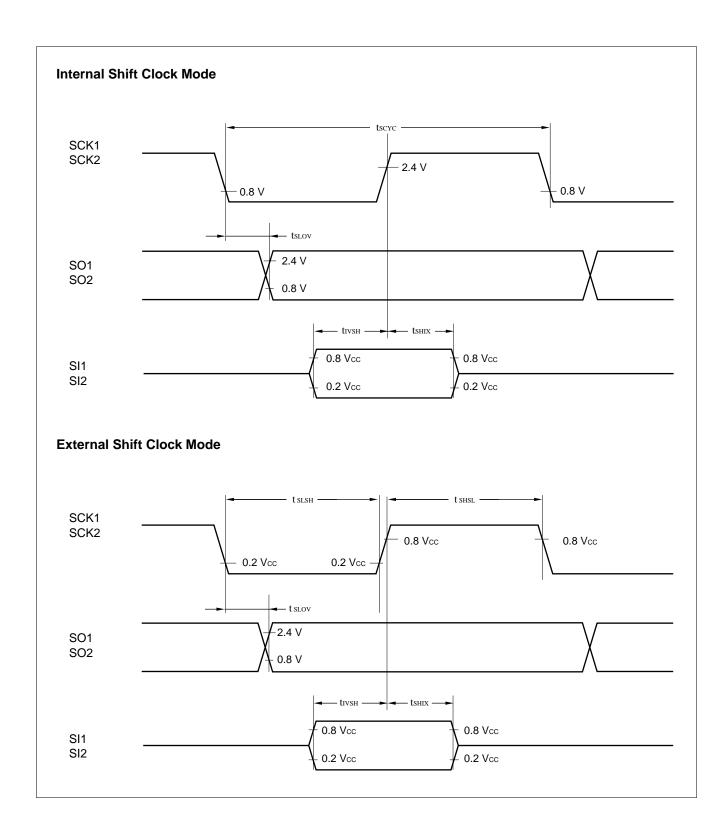


(10) UART and Serial I/O Timing

 $(Vcc = +5.0 V\pm 10\%, AVss = Vss = 0.0 V, T_A = -40^{\circ}C to +85^{\circ}C)$

| Parameter | Symbol | Pin | Condition | Val | lue | Unit | Remarks |
|---|---------------|--|---|--------------------|------|------|---------|
| | | PIN | Condition | Min. | Max. | | |
| Serial clock cycle time | tscyc | SCK1,SCK2 | Internal shift clock mode | 2 tinst* | _ | μs | |
| $\begin{array}{c} SCK1 \downarrow \to SO1 \ time \\ SCK2 \downarrow \to SO2 \ time \end{array}$ | tslov | SCK1, SO1 SCK2, SO2 | | -200 | 200 | ns | |
| Valid SI1 → SCK1 ↑ Valid SI2 → SCK2 ↑ | tıvsh | SI1, SCK1 SI2, SCK2 | Load condition: 50 pF | 1/2 t inst* | _ | μs | |
| SCK1↑→validSI1holdtime SCK2↑→validSI2holdtime | t shix | SCK1, SI1 SCK2, SI2 | - 30 βι | 1/2 t inst* | _ | μs | |
| Serial clock "H" pulse width | t shsl | SCK1, SCK2 | External shift clock mode Load condition: | 1 tinst* | _ | μs | |
| Serial clock "L" pulse width | t slsh | SUNT, SUNZ | | 1 tinst* | _ | μs | |
| $\begin{array}{c} SCK1 \downarrow \to SO1 \ time \\ SCK2 \downarrow \to SO2 \ time \end{array}$ | tslov | SCK1, SO1 SCK2, SO2 SI1, SCK1 SI2, SCK2 | | 0 | 200 | ns | |
| Valid SI1 → SCK1 ↑ Valid SI2 → SCK2 ↑ | t ivsH | | | 1/2 t inst* | _ | μs | |
| SCK1↑→validSI1holdtime SCK2↑→validSI2holdtime | t sнıx | SCK1, SI1 SCK2, SI2 | 1 1 | 1/2 t inst* | | μs | |

^{*:} For information on t_{inst}, see "(4) Instruction Cycle."

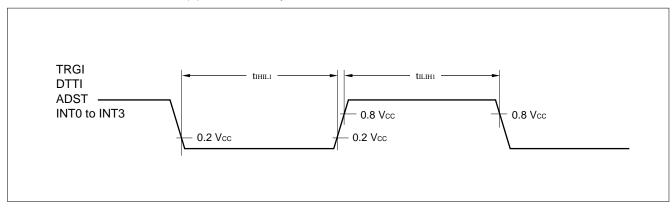


(11) Peripheral Input Timing

 $(Vcc = +5.0 V \pm 10\%, AVss = Vss = 0.0 V, T_A = -40^{\circ}C to +85^{\circ}C)$

| Parameter | Symbol | Pin | Condition | Value | | Unit | Remarks |
|------------------------------------|--------------------|--------------------------------------|-----------------------------|----------|------|-------|---------|
| | | | | Min. | Max. | Offic | Nemarks |
| Peripheral input "H" pulse width 1 | tılıH1 | TRGI, DTTI, ADST, INT0 to INT3 | Load condition: 50 pF | 2 tinst* | _ | μs | |
| Peripheral input "L" pulse width 1 | t _{IHIL1} | | | 2 tinst* | _ | μs | |

^{*:} For information on tinst, see "(4) Instruction Cycle."



5. A/D Converter Electrical Characteristics

 $(AVcc = Vcc = +3.5 \text{ V to } +6.0 \text{ V}, Fc = 10 \text{ MHz}, AVss = Vss = 0.0 \text{ V}, T_A = -40^{\circ}\text{C to } +85^{\circ}\text{C})$

| Parameter | Symbol | Pin | Condition | Value | | | l lmi4 | Damarka |
|-------------------------------|------------------|---------------|-------------|----------|-----------|----------|--------|---------|
| | | | | Min. | Тур. | Max. | Unit | Remarks |
| Resolution | | | AVcc = Vcc | _ | _ | 10 | bit | |
| Linearity error | _ | | | _ | _ | ±2.0 | LSB | |
| Differential linearity error | | | | _ | _ | ±1.5 | LSB | |
| Total error | | | | _ | _ | ±3.0 | LSB | |
| Zero transition voltage | Vот | AN0 to AN7 | | AVss-1.5 | AVss+0.5 | AVss+2.5 | LSB | |
| Full-scale transition voltage | V _{FST} | | | AVR-3.5 | AVR-1.5 | AVR+0.5 | LSB | |
| Interchannel disparity | | | | _ | _ | 4 | LSB | |
| A/D mode conversion time | _ | _ | _ | _ | 33 tinst* | _ | μs | |
| Analog port input current | Iain | AN0 to | _ | _ | _ | 10 | μΑ | |
| Analog input voltage | | AN7 | _ | 0 | _ | AVR | V | |
| Reference voltage | 1 <u> </u> | A)/D | _ | 0 | _ | AVcc | V | |
| Referenceoltageupplycurrent | IR | AVR | AVR = 5.0 V | _ | 200 | _ | μΑ | |

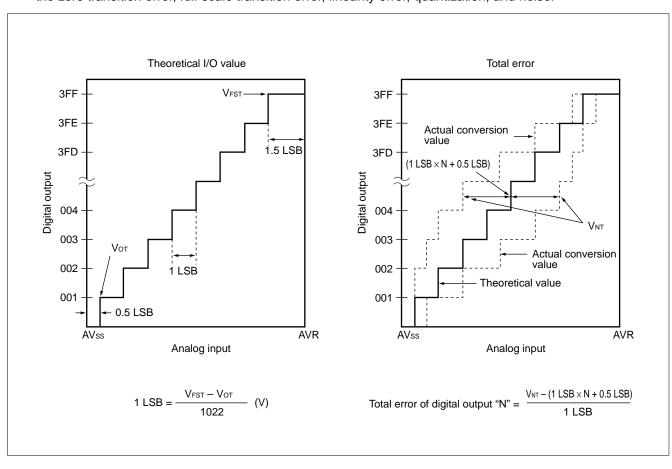
^{*:} For information on tinst, see "(4) Instruction Cycle" in "4. AC Characteristics."

(1) A/D Glossary

- Resolution
 - Analog changes that are identifiable with the A/D converter
- · Linearity error
 - The deviation of the straight line connecting the zero transition point ("00 0000 0000" \leftrightarrow "00 0000 0001") with the full-scale transition point ("11 1111 1111" \leftrightarrow "11 1111 1110") from actual conversion characteristics
- Differential linearity error

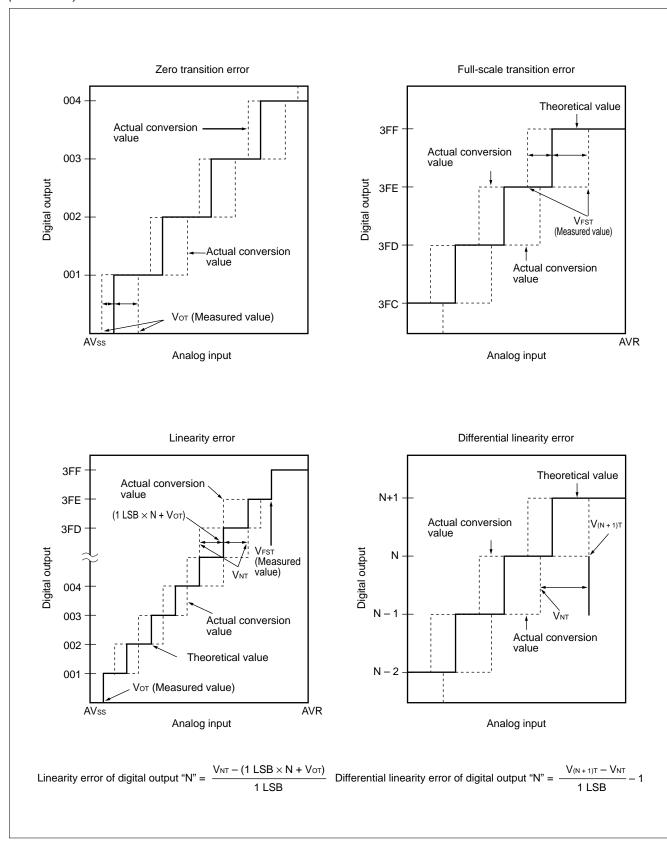
 The deviation of input voltage needed to change the output code by 1 LSB from the theoretical value
- · Total error

The total error indicates the difference between the actual value and theoretical value. This error is caused by the zero transition error, full-scale transition error, linearity error, quantization, and noise.



(Continued)

(Continued)



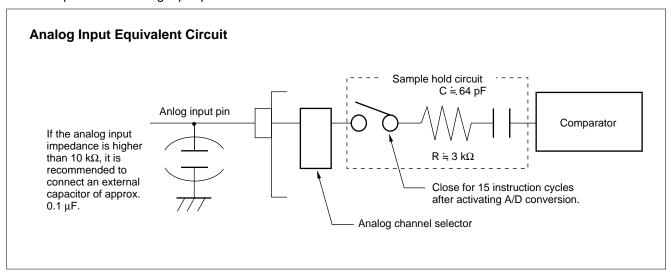
(2) Precautions

· Input impedance of the analog input pins

The A/D converter used for the MB89860/850 series contains a sample hold circuit as illustrated below to fetch analog input voltage into the sample hold capacitor for fifteen instruction cycles after activation A/D conversion.

For this reason, if the output impedance of the external circuit for the analog input is high, analog input voltage might not stabilize within the analog input sampling period. Therefore, it is recommended to keep the output impedance of the external circuit low (below 10 k Ω).

Note that if the impedance connot be kept low, it is recommended to connect an external capacitor of about 0.1 μ F for the analog input pin.

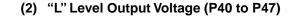


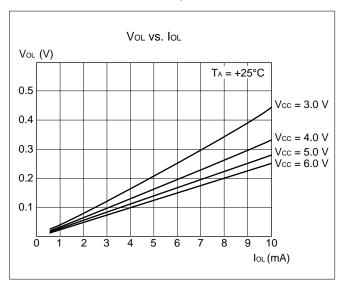
Error

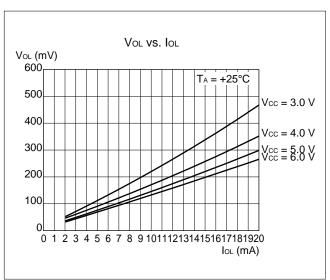
The smaller the | AVR – AVss |, the greater the error would become relatively.

■ EXAMPLE CHARACTERISTICS

(1) "L" Level Output Voltage (P00 to P07, P10 to P17, P20 to P27, P30 to P37, P50 to P57, P70 to P76, and P80 to P87)

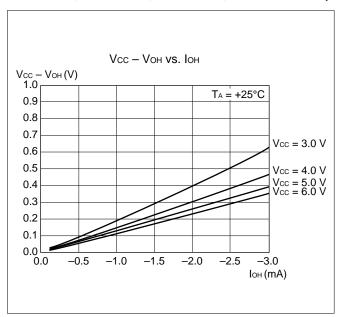


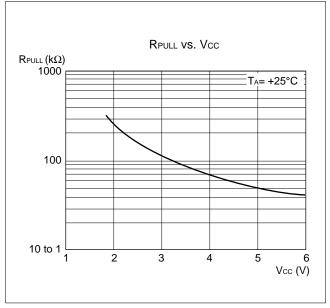




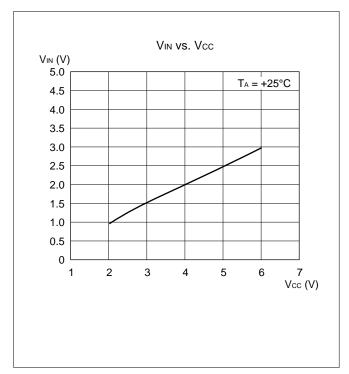
(3) "H" Level Output Voltage (P00 to P07, P10 to P17, P20 to P27, P30 to P37, and P40 to P47)

(4) Pull-up Resistance

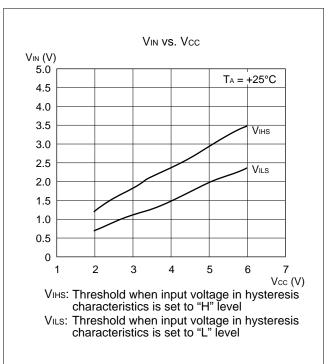




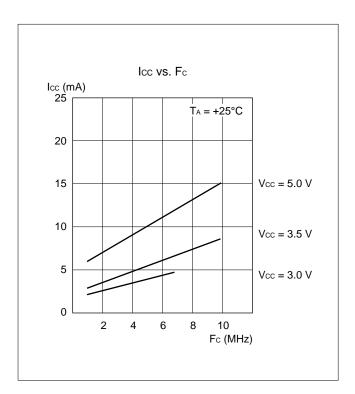
(5) "H" Level Input Voltage/"L" Level Input Voltage (CMOS Input)



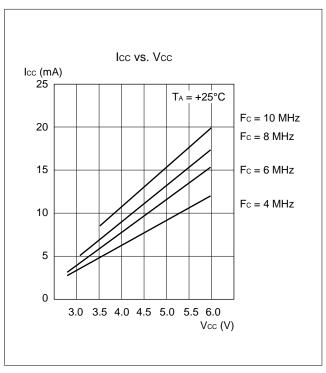
(6) "H" Level Input Voltage/"L" level Input Voltage (Hysteresis Input)



(7) Operating Supply Current vs. Frequency



(8) Operating Supply Current vs. Vcc



(9) Sleep Power Supply Current vs. Frequency

Iccs vs. Fc Iccs (mA) TA = +25°C Vcc = 5.0 V Vcc = 3.5 V

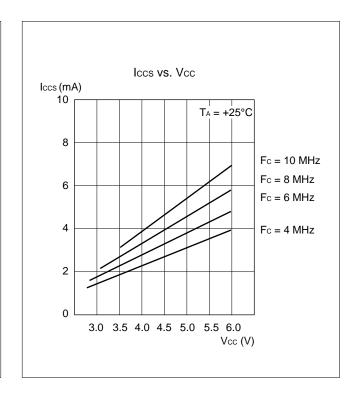
6

8

10

Fc (MHz)

(10) Sleep Power Supply Current vs. Vcc



■ INSTRUCTIONS

Execution instructions can be divided into the following four groups:

- Transfer
- Arithmetic operation
- Branch
- Others

Table 1 lists symbols used for notation of instructions.

Table 1 Instruction Symbols

| Symbol | Meaning |
|--------|---|
| dir | Direct address (8 bits) |
| off | Offset (8 bits) |
| ext | Extended address (16 bits) |
| #vct | Vector table number (3 bits) |
| #d8 | Immediate data (8 bits) |
| #d16 | Immediate data (16 bits) |
| dir: b | Bit direct address (8:3 bits) |
| rel | Branch relative address (8 bits) |
| @ | Register indirect (Example: @A, @IX, @EP) |
| А | Accumulator A (Whether its length is 8 or 16 bits is determined by the instruction in use.) |
| AH | Upper 8 bits of accumulator A (8 bits) |
| AL | Lower 8 bits of accumulator A (8 bits) |
| Т | Temporary accumulator T (Whether its length is 8 or 16 bits is determined by the instruction in use.) |
| TH | Upper 8 bits of temporary accumulator T (8 bits) |
| TL | Lower 8 bits of temporary accumulator T (8 bits) |
| IX | Index register IX (16 bits) |

(Continued)

(Continued)

| Symbol | Meaning |
|--------|---|
| EP | Extra pointer EP (16 bits) |
| PC | Program counter PC (16 bits) |
| SP | Stack pointer SP (16 bits) |
| PS | Program status PS (16 bits) |
| dr | Accumulator A or index register IX (16 bits) |
| CCR | Condition code register CCR (8 bits) |
| RP | Register bank pointer RP (5 bits) |
| Ri | General-purpose register Ri (8 bits, i = 0 to 7) |
| × | Indicates that the very \times is the immediate data. (Whether its length is 8 or 16 bits is determined by the instruction in use.) |
| (×) | Indicates that the contents of \times is the target of accessing. (Whether its length is 8 or 16 bits is determined by the instruction in use.) |
| ((×)) | The address indicated by the contents of \times is the target of accessing. (Whether its length is 8 or 16 bits is determined by the instruction in use.) |

Columns indicate the following:

Mnemonic: Assembler notation of an instruction

~: Number of instructions

#: Number of bytes

Operation: Operation of an instruction

TL, TH, AH: A content change when each of the TL, TH, and AH instructions is executed. Symbols in

the column indicate the following:

• "-" indicates no change.

• dH is the 8 upper bits of operation description data.

AL and AH must become the contents of AL and AH immediately before the instruction

is executed.

• 00 becomes 00.

N, Z, V, C: An instruction of which the corresponding flag will change. If + is written in this column,

the relevant instruction will change its corresponding flag.

OP code: Code of an instruction. If an instruction is more than one code, it is written according to

the following rule:

Example: 48 to $4F \leftarrow$ This indicates 48, 49, ... 4F.

Table 2 Transfer Instructions (48 instructions)

| Mnemonic | ~ | # | Operation | TL | TH | AH | NZVC | OP code |
|------------------|---|-----|--|----|----|----|------|----------|
| MOV dir,A | 3 | 2 | $(dir) \leftarrow (A)$ | _ | _ | _ | | 45 |
| MOV @IX +off,A | 4 | 2 | $((IX) + off) \leftarrow (A)$ | _ | _ | _ | | 46 |
| MOV ext,A | 4 | 3 | $(ext) \leftarrow (A)$ | _ | _ | _ | | 61 |
| MOV @EP,A | 3 | 1 | $((EP)) \leftarrow (A)$ | _ | _ | _ | | 47 |
| MOV Ri,A | 3 | 1 | $(Ri) \leftarrow (A)$ | _ | _ | _ | | 48 to 4F |
| MOV A,#d8 | 2 | 2 | (A) ← d8 | AL | _ | _ | ++ | 04 |
| MOV A,dir | 3 | 2 | $(A) \leftarrow (dir)$ | AL | _ | _ | ++ | 05 |
| MOV A,@IX +off | 4 | 2 | $(A) \leftarrow ((IX) + off)$ | AL | _ | _ | ++ | 06 |
| MOV A,ext | 4 | 3 | $(A) \leftarrow (ext)$ | AL | _ | _ | ++ | 60 |
| MOV A,@A | 3 | 1 | $(A) \leftarrow (A)$ | AL | _ | _ | ++ | 92 |
| MOV A,@EP | 3 | 1 | $(A) \leftarrow ((EP))$ | ΑL | _ | _ | ++ | 07 |
| MOV A,Ri | 3 | 1 | $(A) \leftarrow (Ri)$ | AL | _ | _ | · · | 08 to 0F |
| MOV dir,#d8 | 4 | 3 | $(dir) \leftarrow (dir)$ | /L | | | | 85 |
| MOV @IX +off,#d8 | 5 | 3 | $((IX) \leftarrow dS$ $((IX) + off) \leftarrow dS$ | _ | _ | _ | | 86 |
| | 4 | 2 | | _ | _ | _ | | 87 |
| MOV @EP,#d8 | 4 | 2 | ((EP)) ← d8 | _ | _ | _ | | |
| MOV Ri,#d8 | | | $(Ri) \leftarrow d8$ | _ | _ | _ | | 88 to 8F |
| MOVW dir,A | 4 | 2 | $(dir) \leftarrow (AH), (dir + 1) \leftarrow (AL)$ | _ | _ | _ | | D5 |
| MOVW @IX +off,A | 5 | 2 | $((IX) + off) \leftarrow (AH),$ | _ | _ | _ | | D6 |
| | _ | | $((IX) + off + 1) \leftarrow (AL)$ | | | | | |
| MOVW ext,A | 5 | 3 | $(ext) \leftarrow (AH), (ext + 1) \leftarrow (AL)$ | _ | _ | _ | | D4 |
| MOVW @EP,A | 4 | 1 | $((EP)) \leftarrow (AH), ((EP) + 1) \leftarrow (AL)$ | _ | _ | _ | | D7 |
| MOVW EP,A | 2 | 1 | (EP) ← (A) | - | _ | _ | | E3 |
| MOVW A,#d16 | 3 | 3 | (A) ← d16 | AL | AH | dH | ++ | E4 |
| MOVW A,dir | 4 | 2 | $(AH) \leftarrow (dir), (AL) \leftarrow (dir + 1)$ | AL | AH | dH | ++ | C5 |
| MOVW A,@IX +off | 5 | 2 | $(AH) \leftarrow ((IX) + off),$ | AL | AH | dΗ | ++ | C6 |
| | | | $(AL) \leftarrow ((IX) + off + 1)$ | | | | | |
| MOVW A,ext | 5 | 3 | $(AH) \leftarrow (ext), (AL) \leftarrow (ext + 1)$ | AL | AH | dH | ++ | C4 |
| MOVW A,@A | 4 | 1 | $(AH) \leftarrow (A)$, $(AL) \leftarrow (A)$ | AL | AH | dH | ++ | 93 |
| MOVW A,@EP | 4 | 1 | $(AH) \leftarrow ((EP)), (AL) \leftarrow ((EP) + 1)$ | AL | AH | dH | ++ | C7 |
| MOVW A,EP | 2 | 1 | $(A) \leftarrow (EP)$ | _ | _ | dΗ | | F3 |
| MOVW EP,#d16 | 3 | 3 | (EP) ← d16 | _ | _ | _ | | E7 |
| MOVW IX,A | 2 | 1 | $(IX) \leftarrow (A)$ | _ | _ | _ | | E2 |
| MOVW A,IX | 2 | 1 | $(A) \leftarrow (IX)$ | _ | _ | dH | | F2 |
| MOVW SP,A | 2 | 1 | $(SP) \leftarrow (A)$ | _ | _ | _ | | E1 |
| MOVW A,SP | 2 | i i | $(A) \leftarrow (SP)$ | _ | _ | dH | | F1 |
| MOV @A,T | 3 | | $(A) \leftarrow (B)$ | | | | | 82 |
| MOVW @A,T | 4 | | $(A) \leftarrow (I)$ $(A) \leftarrow (TH),(A) + 1) \leftarrow (TL)$ | _ | | | | 83 |
| MOVW @A,1 | 3 | 3 | | _ | _ | _ | | E6 |
| | _ | l . | $(IX) \leftarrow d16$ | _ | _ | | | |
| MOVW A,PS | 2 | 1 | $(A) \leftarrow (PS)$ | _ | _ | dH | | 70 |
| MOVW PS,A | 2 | 1 | (PS) ← (A) | _ | _ | _ | ++++ | 71 |
| MOVW SP,#d16 | 3 | 3 | (SP) ← d16 | _ | _ | _ | | E5 |
| SWAP | 2 | 1 | $(AH) \leftrightarrow (AL)$ | _ | _ | AL | | 10 |
| SETB dir: b | 4 | 2 | (dir): b ← 1 | _ | _ | _ | | A8 to AF |
| CLRB dir: b | 4 | 2 | (dir): b ← 0 | _ | - | - | | A0 to A7 |
| XCH A,T | 2 | 1 | $(AL) \leftrightarrow (TL)$ | AL | | | | 42 |
| XCHW A,T | 3 | 1 | $(A) \leftrightarrow (T)$ | AL | AH | dH | | 43 |
| XCHW A,EP | 3 | 1 | $(A) \leftrightarrow (EP)$ | _ | _ | dH | | F7 |
| XCHW A,IX | 3 | 1 | $(A) \leftrightarrow (IX)$ | _ | _ | dH | | F6 |
| XCHW A,SP | 3 | 1 | $(A) \leftrightarrow (SP)$ | _ | _ | dH | | F5 |
| MOVW A,PC | 2 | 1 | $(A) \leftarrow (PC)$ | _ | _ | dH | | F0 |

Notes: • During byte transfer to A, T \leftarrow A is restricted to low bytes.

• Operands in more than one operand instruction must be stored in the order in which their mnemonics are written. (Reverse arrangement of F²MC-8 family)

Table 3 Arithmetic Operation Instructions (62 instructions)

| Mnemonic | ~ | # | Operation | TL | TH | АН | NZVC | OP code |
|--------------------------|--------|-----|--|----|----|-------|---------|----------|
| ADDC A,Ri | 3 | 1 | (A) ← (A) + (Ri) + C | _ | _ | _ | ++++ | 28 to 2F |
| ADDC A,#d8 | 2 | 2 | $(A) \leftarrow (A) + d8 + C$ | _ | _ | - | ++++ | 24 |
| ADDC A,dir | 3 | 2 | $(A) \leftarrow (A) + (dir) + C$ | _ | _ | _ | ++++ | 25 |
| ADDC A,@IX +off | 4 | 2 | $(A) \leftarrow (A) + ((IX) + off) + C$ | _ | _ | _ | ++++ | 26 |
| ADDC A,@EP | 3 | 1 | $(A) \leftarrow (A) + ((EP)) + C$ | _ | _ | | ++++ | 27 |
| ADDCW A | 3 | 1 | $(A) \leftarrow (A) + (T) + C$ | _ | _ | dH | ++++ | 23 |
| ADDC A | 2 | 1 | $(AL) \leftarrow (AL) + (TL) + C$ | _ | _ | - | ++++ | 22 |
| SUBC A,Ri | 3 2 | 1 2 | $(A) \leftarrow (A) - (Ri) - C$ | _ | _ | _ | ++++ | 38 to 3F |
| SUBC A,#d8 SUBC A,dir | 3 | 2 | $(A) \leftarrow (A) - d8 - C$ $(A) \leftarrow (A) - (dir) - C$ | _ | _ | _ | ++++ | 34 35 |
| SUBC A,@IX +off | 4 | 2 | | | _ | _ | ++++ | 36 |
| SUBC A,@EP | 3 | 1 | $(A) \leftarrow (A) - ((IX) + off) - C$ $(A) \leftarrow (A) - ((EP)) - C$ | | | _ | ++++ | 37 |
| SUBCW A | 3 | 1 | $(A) \leftarrow (A) - ((EF)) - C$ $(A) \leftarrow (T) - (A) - C$ | | _ | dH | ++++ | 33 |
| SUBC A | 2 | 1 | $(A) \leftarrow (1) - (A) - C$ $(AL) \leftarrow (TL) - (AL) - C$ | | | _ uii | ++++ | 32 |
| INC Ri | 4 | 1 | $(Ri) \leftarrow (Ri) + 1$ | | _ | _ | +++- | C8 to CF |
| INCW EP | 3 | 1 | $(EP) \leftarrow (EP) + 1$ | _ | _ | _ | | C3 |
| INCW IX | 3 | 1 | $(X) \leftarrow (X) + 1$ | _ | _ | _ | | C2 |
| INCW A | 3 | 1 | $(A) \leftarrow (A) + 1$ | _ | _ | dH | ++ | C0 |
| DEC Ri | 4 | 1 | $(Ri) \leftarrow (Ri) - 1$ | _ | _ | _ | +++- | D8 toDF |
| DECW EP | 3 | 1 | $(EP) \leftarrow (EP) - 1$ | _ | _ | _ | | D3 |
| DECW IX | 3 | 1 | $(IX) \leftarrow (IX) - 1$ | _ | _ | _ | | D2 |
| DECW A | 3 | 1 | $(A) \leftarrow (A) - 1$ | _ | _ | dH | ++ | D0 |
| MULU A | 19 | 1 | $(A) \leftarrow (AL) \times (TL)$ | _ | _ | dH | | 01 |
| DIVU A | 21 | 1 | $(A) \leftarrow (T) / (AL), MOD \rightarrow (T)$ | dL | 00 | 00 | | 11 |
| ANDW A | 3 | 1 | $(A) \leftarrow (A) \land (T)$ | _ | _ | dH | ++R- | 63 |
| ORW A | 3 | 1 | $ (A) \leftarrow (A) \lor (T)$ | _ | _ | dH | + + R – | 73 |
| XORW A | 3 | 1 | $(A) \leftarrow (A) \forall (T)$ | _ | _ | dH | ++R- | 53 |
| CMP A | 2 | 1 | (TL) – (AL) | _ | _ | - | ++++ | 12 |
| CMPW A | 3 | 1 | (T) - (A) | _ | _ | _ | ++++ | 13 |
| RORC A | 2 | 1 | \rightarrow C \rightarrow A \rightarrow | _ | _ | _ | ++-+ | 03 |
| ROLC A | 2 | 1 | | _ | _ | _ | ++-+ | 02 |
| CMP A,#d8 | 2 | 2 | (A) – d8 | _ | _ | _ | ++++ | 14 |
| CMP A,dir | 3 | 2 | (A) – (dir) | _ | _ | _ | ++++ | 15 |
| CMP A,@EP | 3 | 1 | (A) – ((EP)) | _ | _ | _ | ++++ | 17 |
| CMP A,@IX +off | 4 | 2 | (A) - ((IX) + off) | _ | _ | _ | ++++ | 16 |
| CMP A,Ri | 3 | 1 | (A) – (Ri) | _ | _ | _ | ++++ | 18 to 1F |
| DAA | 2 | 1 | Decimal adjust for addition | _ | _ | _ | ++++ | 84 |
| DAS | 2 | 1 | Decimal adjust for subtraction | _ | _ | _ | ++++ | 94 |
| XOR A | 2 | 1 | $(A) \leftarrow (AL) \forall (TL)$ | _ | _ | _ | ++R- | 52 |
| XOR A,#d8 | 2 | 2 | $(A) \leftarrow (AL) \forall d8$ | _ | _ | _ | ++R- | 54 |
| XOR A,dir | 3 | 2 | $(A) \leftarrow (AL) \forall (dir)$ | _ | _ | _ | ++R- | 55 |
| XOR A,@EP | 3 | 1 | $(A) \leftarrow (AL) \forall (EP)$ | _ | - | _ | + + R – | 57 |
| XOR A,@IX +off | 4 | 2 | $(A) \leftarrow (AL) \ \forall \ ((IX) + off)$ | _ | _ | _ | + + R – | 56 |
| XOR A,Ri | 3 | 1 | $ (A) \leftarrow (AL) \ \forall (Ri)$ | _ | _ | _ | + + R – | 58 to 5F |
| AND A | 2 | 1 | $(A) \leftarrow (AL) \wedge (TL)$ | _ | _ | - | ++R- | 62 |
| AND A,#d8 | 2 | 2 | $(A) \leftarrow (AL) \wedge d8$ | _ | _ | - | ++R- | 64 |
| AND A,dir | 3 | 2 | $(A) \leftarrow (AL) \land (dir)$ | _ | _ | _ | + + R – | 65 |

(Continued)

(Continued)

| Mnemonic | ? | # | Operation | TL | TH | AH | NZVC | OP code |
|------------------|---|---|--|----|----|----|---------|----------|
| AND A,@EP | 3 | 1 | $(A) \leftarrow (AL) \land ((EP))$ | _ | _ | _ | + + R – | 67 |
| AND A,@IX +off | 4 | 2 | $(A) \leftarrow (AL) \land ((IX) + off)$ | _ | _ | _ | ++R- | 66 |
| AND A,Ri | 3 | 1 | $(A) \leftarrow (AL) \land (Ri)$ | _ | _ | _ | ++R- | 68 to 6F |
| OR A | 2 | 1 | $(A) \leftarrow (AL) \lor (TL)$ | _ | _ | _ | ++R- | 72 |
| OR A,#d8 | 2 | 2 | $(A) \leftarrow (AL) \lor d8$ | _ | _ | _ | ++R- | 74 |
| OR A,dir | 3 | 2 | $(A) \leftarrow (AL) \lor (dir)$ | _ | _ | _ | ++R- | 75 |
| OR A,@EP | 3 | 1 | $(A) \leftarrow (AL) \lor ((EP))$ | _ | _ | _ | ++R- | 77 |
| OR A,@IX +off | 4 | 2 | $(A) \leftarrow (AL) \lor ((IX) + off)$ | _ | _ | _ | ++R- | 76 |
| OR A,Ri | 3 | 1 | $(A) \leftarrow (AL) \lor (Ri)$ | _ | _ | _ | ++R- | 78 to 7F |
| CMP dir,#d8 | 5 | 3 | (dir) – d8 | _ | _ | _ | ++++ | 95 |
| CMP @EP,#d8 | 4 | 2 | ((EP)) – d8 | _ | _ | _ | ++++ | 97 |
| CMP @IX +off,#d8 | 5 | 3 | ((IX) +off) – d8 | _ | _ | _ | ++++ | 96 |
| CMP Ri,#d8 | 4 | 2 | (Ri) – d8 | _ | _ | _ | ++++ | 98 to 9F |
| INCW SP | 3 | 1 | (SP) ← (SP) + 1 | _ | _ | _ | | C1 |
| DECW SP | 3 | 1 | (SP) ← (SP) – 1 | _ | _ | – | | D1 |

Table 4 Branch Instructions (17 instructions)

| Mnemonic | ~ | # | Operation | TL | TH | AH | NZVC | OP code |
|----------------|---|---|--|----|----|----|---------|----------|
| BZ/BEQ rel | 3 | 2 | If $Z = 1$ then $PC \leftarrow PC + rel$ | _ | _ | _ | | FD |
| BNZ/BNE rel | 3 | 2 | If $Z = 0$ then $PC \leftarrow PC + rel$ | _ | _ | _ | | FC |
| BC/BLO rel | 3 | 2 | If $C = 1$ then $PC \leftarrow PC + rel$ | _ | _ | _ | | F9 |
| BNC/BHS rel | 3 | 2 | If $C = 0$ then $PC \leftarrow PC + rel$ | _ | _ | _ | | F8 |
| BN rel | 3 | 2 | If N = 1 then PC ← PC + rel | _ | _ | _ | | FB |
| BP rel | 3 | 2 | If N = 0 then PC \leftarrow PC + rel | - | _ | _ | | FA |
| BLT rel | 3 | 2 | If $V \forall N = 1$ then $PC \leftarrow PC + rel$ | _ | _ | _ | | FF |
| BGE rel | 3 | 2 | If $V \forall N = 0$ then $PC \leftarrow PC + rel$ | _ | _ | _ | | FE |
| BBC dir: b,rel | 5 | 3 | If (dir: b) = 0 then $PC \leftarrow PC + rel$ | _ | _ | _ | -+ | B0 to B7 |
| BBS dir: b,rel | 5 | 3 | If (dir: b) = 1 then $PC \leftarrow PC + rel$ | _ | _ | _ | -+ | B8 to BF |
| JMP @A | 2 | 1 | $(PC) \leftarrow (A)$ | _ | _ | _ | | E0 |
| JMP ext | 3 | 3 | (PC) ← ext | _ | _ | _ | | 21 |
| CALLV #vct | 6 | 1 | Vector call | _ | _ | _ | | E8 to EF |
| CALL ext | 6 | 3 | Subroutine call | _ | _ | _ | | 31 |
| XCHW A,PC | 3 | 1 | $(PC) \leftarrow (A), (A) \leftarrow (PC) + 1$ | _ | _ | dH | | F4 |
| RET | 4 | 1 | Return from subrountine | _ | _ | _ | | 20 |
| RETI | 6 | 1 | Return form interrupt | _ | _ | _ | Restore | 30 |

Table 5 Other Instructions (9 instructions)

| Mnemonic | ~ | # | Operation | TL | TH | AH | NZVC | OP code |
|----------|---|---|-----------|----|----|----|------|---------|
| PUSHW A | 4 | 1 | | _ | _ | _ | | 40 |
| POPW A | 4 | 1 | | _ | _ | dH | | 50 |
| PUSHW IX | 4 | 1 | | - | _ | _ | | 41 |
| POPW IX | 4 | 1 | | - | _ | - | | 51 |
| NOP | 1 | 1 | | - | _ | _ | | 00 |
| CLRC | 1 | 1 | | - | _ | - | R | 81 |
| SETC | 1 | 1 | | - | _ | - | S | 91 |
| CLRI | 1 | 1 | | - | _ | - | | 80 |
| SETI | 1 | 1 | | - | _ | _ | | 90 |

■ INSTRUCTION MAP

| 0 1 | [7] | | 2 | 3 | 4 | 5 | 9 | 7 | 80 | 6 | 4 | В | ပ | ٥ | Е | ш |
|----------------|------------|----------------|-----------------|-----------------|----------------|----------------|---------------|--------------|-----------------|-----------------|----------------|-------------------|----------------|----------------|-----------------|--------------|
| MON | | SWAP | RET | RETI | PUSHW A | POPW A | MOV A,ext | MOVW A,PS | CLRI | SETI | CLRB dir: 0 | BBC dir: 0,rel | INCW A | DECW A | JMP @A | MOVW A,PC |
| MULU | | DIVU | JMP addr16 | CALL addr16 | PUSHW IX | POPW IX | MOV ext,A | MOVW PS,A | CLRC | SETC | CLRB dir: 1 | BBC dir: 1,rel | INCW SP | DECW | MOVW SP,A | MOVW A,SP |
| ROLC | | CMP | ADDC A | SUBC | XCH A, T | XOR | AND | OR A | MOV @A,T | MOV A,@A | CLRB dir: 2 | BBC dir: 2,rel | INCW IX | DECW | MOVW IX,A | MOVW A,IX |
| RORC | | CMPW | ADDCW A | SUBCW | XCHW A, T | XORW | ANDW | ORW A | MOVW @A,T | MOVW A,@A | CLRB dir: 3 | BBC dir: 3,rel | INCW | DECW | MOVW EP,A | MOVW A,EP |
| MOV A,#d8 | · · | CMP A,#d8 | ADDC A,#d8 | SUBC A,#d8 | | XOR A,#d8 | AND A,#d8 | OR A,#d8 | DAA | DAS | CLRB dir: 4 | BBC dir: 4,rel | MOVW A,ext | MOVW ext,A | MOVW A,#d16 | XCHW A,PC |
| MOV A,dir | | CMP A,dir | ADDC A,dir | SUBC A,dir | MOV dir,A | XOR A,dir | AND A,dir | OR A,dir | MOV dir,#d8 | CMP dir,#d8 | CLRB dir: 5 | BBC dir: 5,rel | MOVW A,dir | MOVW dir,A | MOVW SP,#d16 | XCHW A,SP |
| MOV A,@IXtd | 7 | CMP A,@IXtd | ADDC A,@IXtd | SUBC A,@IXtd | MOV @IX+d,A | XOR A,@IXtd | AND A,@I¾d | OR A,@I¾d | MOV @I¥d,#d8 | CMP @I¥d,#d8 | CLRB dir: 6 | BBC dir: 6,rel | MOVW A,@I¥d | MOVW @I¾d,A | MOVW IX,#d16 | XCHW A,IX |
| MOV A,@EP | _ <u>_</u> | CMP A,@EP | ADDC A,@EP | SUBC A,@EP | MOV @EP,A | XOR A,@EP | AND A,@EP | OR A,@EP | MOV @EP,#d8 | CMP @EP;#d8 | CLRB dir: 7 | BBC dir: 7,rel | MOVW A,@EP | MOVW @EP,A | MOVW EP,#d16 | XCHW A,EP |
| MOV A,R0 | 0 | CMP A,R0 | ADDC A,R0 | SUBC A,R0 | MOV R0,A | XOR A,R0 | AND A,R0 | OR A,R0 | MOV R0,#d8 | CMP R0,#d8 | SETB dir: 0 | BBS dir: 0,rel | INC R0 | DEC R0 | CALLV #0 | BNC |
| MOV A,R1 | _ | CMP A,R1 | ADDC A,R1 | SUBC A,R1 | MOV R1,A | XOR A,R1 | AND A,R1 | OR A,R1 | MOV R1,#d8 | CMP R1,#d8 | SETB dir: 1 | BBS dir: 1,rel | INC R1 | DEC R1 | CALLV #1 | BC rel |
| MOV A,R2 | N 0 | CMP A,R2 | ADDC A,R2 | SUBC A,R2 | MOV R2,A | XOR A,R2 | AND A,R2 | OR A,R2 | MOV R2,#d8 | CMP R2,#d8 | SETB dir:2 | BBS dir: 2,rel | INC R2 | DEC R2 | CALLV #2 | BP rel |
| MOV A,R3 | က | CMP A,R3 | ADDC A,R3 | SUBC A,R3 | MOV R3,A | XOR A,R3 | AND A,R3 | OR A,R3 | MOV R3,#d8 | CMP R3,#d8 | SETB dir:3 | BBS dir: 3,rel | INC R3 | DEC R3 | CALLV #3 | BN rel |
| MOV A,R4 | 4 | CMP A,R4 | ADDC A,R4 | SUBC A,R4 | MOV R4,A | XOR A,R4 | AND A,R4 | OR A,R4 | MOV R4,#d8 | CMP R4,#d8 | SETB dir: 4 | BBS dir: 4,rel | INC R4 | DEC R4 | CALLV #4 | BNZ rel |
| MOV A,R5 | IO. | CMP A,R5 | ADDC A,R5 | SUBC A,R5 | MOV R5,A | XOR A,R5 | AND A,R5 | OR A,R5 | MOV R5,#d8 | CMP R5,#d8 | SETB dir: 5 | BBS dir: 5,rel | INC R5 | DEC R5 | CALLV #5 | BZ rel |
| MOV A,R6 | (0 | CMP A,R6 | ADDC A,R6 | SUBC A,R6 | MOV R6,A | XOR A,R6 | AND A,R6 | OR A,R6 | MOV R6,#d8 | CMP R6,#d8 | SETB dir: 6 | BBS dir: 6,rel | INC R6 | DEC R6 | CALLV #6 | BGE rel |
| MOV A,R7 | _ | CMP A,R7 | ADDC A,R7 | SUBC A,R7 | MOV R7,A | XOR A,R7 | AND A,R7 | OR A,R7 | MOV R7,#d8 | CMP R7,#d8 | SETB dir: 7 | BBS dir: 7,rel | INC R7 | DEC R7 | CALLV #7 | BLT rel |
| | 1 | | | | | | | | | | | | | | | |

■ MASK OPTIONS (MB89855/857/865/867)

| Option type | Option selection | Remarks |
|---|--|--|
| Power-on reset | 0: Without power-on reset 1: With power-on reset | _ |
| Initial value of oscillation stabilization delay time | 0: 2 ¹⁸ /Fc (s) (Crystal oscillator) 1: 2 ¹⁴ /Fc (s) (Ceramic oscillator) | Selects the initial value of the OSCS bit in the STBC register during power-on reset. |
| Reset pin output | 0: Without reset output 1: With reset output | _ |
| Pull-up resistor at port pin P00 to P07, P10 to P17, P20 to P27, P30 to P37, P40 to P47, P60 to P64, P70 to P76, P80 to P87 | 1: Without pull-up resistor 0: With pull-up resistor | Can be set per pin. P70 to P76, and P80 to P87 are used in the MB89860 series only. P00 to P07, P10 to P17, and P20 to P27 with a pull-up resistor can be set only for single-chip mode. |

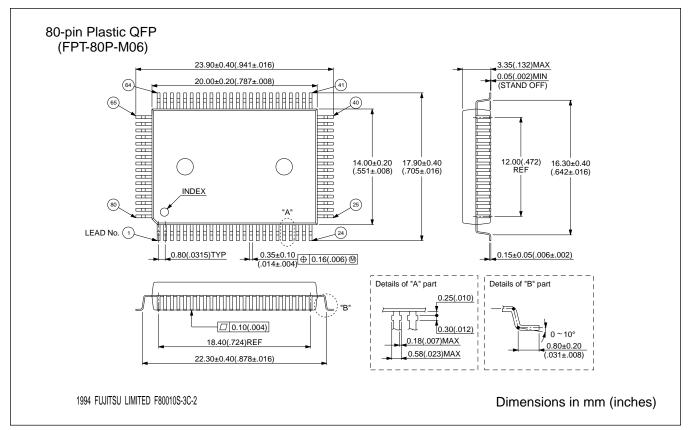
■ STANDARD OPTION LIST

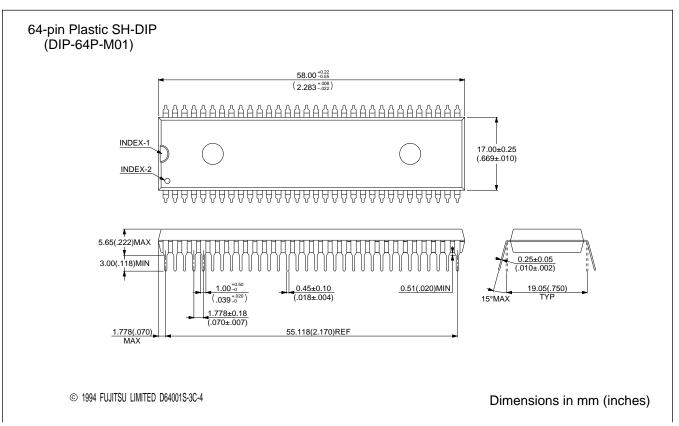
| Part number Parameter | MB89P857/W857/ P867/W867/T855 |
|---|----------------------------------|
| Power-on reset | Available |
| Initial value of oscillation stabilization delay time | 2 ¹⁸ /Fc (s) |
| Output at reset pin | Available |
| Pull-up resistor at port pin | Not available |

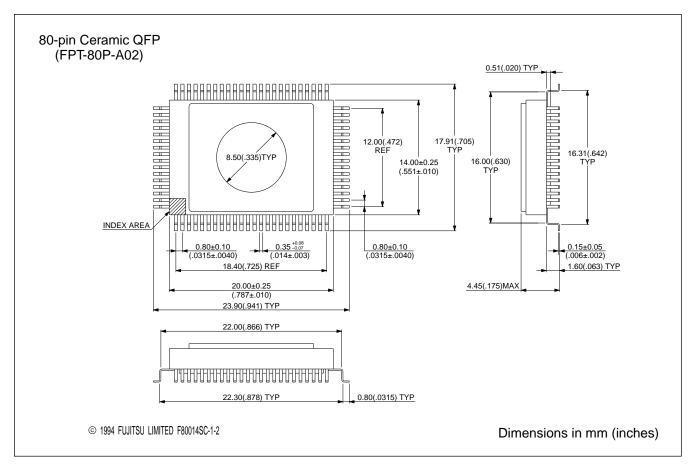
■ ORDERING INFORMATION

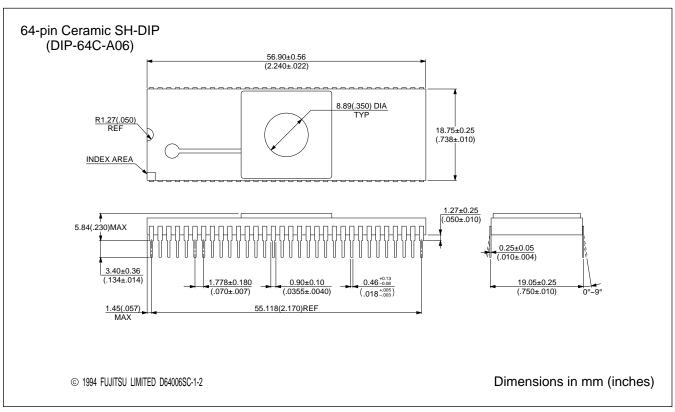
| Part number | Package | Remarks |
|--|--|---------------|
| MB89865PF MB89867PF MB89P867PF | 80-pin Plastic QFP (FPT-80P-M06) | |
| MB89855P-SH MB89T855P-SH MB89857P-SH MB89P857P-SH | 64-pin Plastic SH-DIP (DIP-64P-M01) | |
| MB89W867CF | 80-pin Ceramic QFP (FPT-80C-A02) | ES level only |
| MB89W857C-SH | 64-pin Ceramic SH-DIP (DIP-64C-A06) | ES level only |

■ PACKAGE DIMENSIONS









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