

## CMOS 4-BIT MICROCONTROLLER

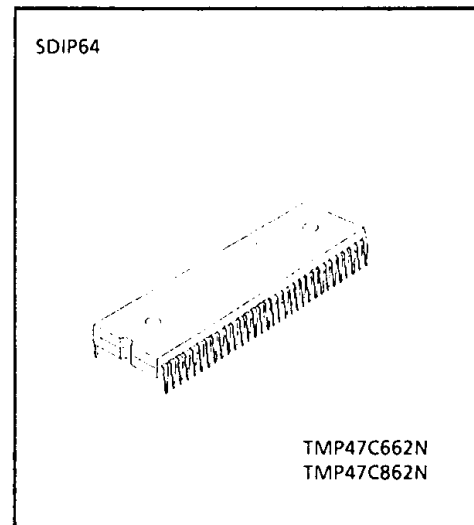
## TMP47C662N, TMP47C862N

The 47C662/862 have extended I/O ports, A/D converter, programmable pulse generator, and high breakdown voltage outputs based on the TLCS-470 series.

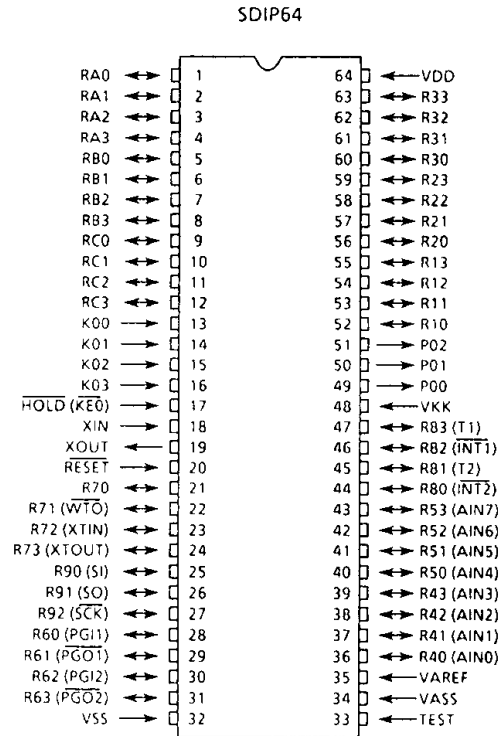
PART No.	ROM	RAM	RACKAGE
TMP47C662N	6144 × 8-bit	384 × 4-bit	SDIP64
TMP47C862N	8192 × 8-bit	512 × 4-bit	

## FEATURES

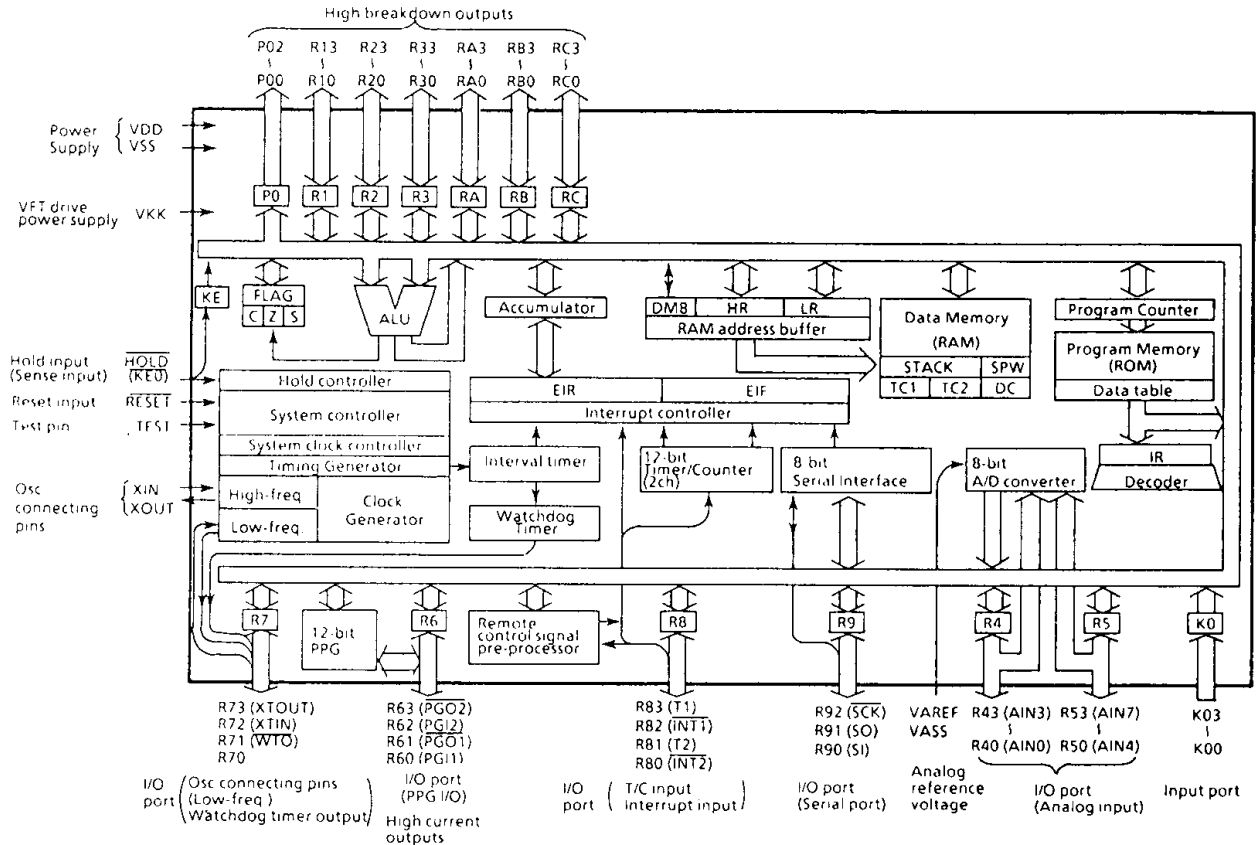
- ◆ 4-bit single chip microcomputer
- ◆ Instruction execution time: 1.3 $\mu$ s(at 6MHz), 244 $\mu$ s (at 32.8KHz)
- ◆ 92 basic instructions
- ◆ Table look-up instructions
- ◆ 5-bit to 8-bit data conversion instruction
- ◆ Subroutine nesting: 15 levels max.
- ◆ 6 interrupt sources (External: 2, Internal: 4)
  - All sources have independent latches each, and multiple interrupt control is available.
- ◆ I/O port (55 pins)
  - Input 2 ports 5 pins
  - Output 1 port 3 pins
  - I/O 12 ports 47 pins
- ◆ Interval Timer
- ◆ Two 12-bit Timer/Counters
  - Timer, event counter, and pulse width measurement mode
- ◆ Watchdog Timer
- ◆ Serial Interface with 8-bit buffer
  - Simultaneous transmission and reception capability
  - 8/4-bit transfer, external/internal clock, and leading/trailing edge shift mode
- ◆ Two 12-bit Programmable Pulse Generator
  - One-shot/continuous output, external/internal trigger, rising/falling edge trigger (external) mode
- ◆ 8-bit successive approximate type A/D converter
  - With sample and hold
  - 8 analog inputs
  - Conversion time : 32  $\mu$ s(at 6 MHz)
- ◆ Remote control signal pre-processing capability
- ◆ High current outputs
  - LED direct drive capability (typ. 20mA × 4 bits)
- ◆ High breakdown voltage outputs
  - VFT direct drive capability (max. 42V × 27 bits)
- ◆ Dual-clock operation
  - High-speed/Low-power-consumption operating mode
- ◆ Hold function
  - Battery/Capacitor back-up
- ◆ Real Time Emulator : BM47C862



PIN ASSIGNMENT (TOP VIEW)



BLOCK DIAGRAM



## PIN FUNCTION

PIN NAME	Input/Output	FUNCTIONS		
K03 - K00	Input	4-bit input port		
R53 (AIN7) - R40 (AIN0)	I/O (Input)	4-bit I/O port with latch. When using as input port, watchdog timer output, analog input, PPG (programmable pulse generator) output, or PPG trigger input, the latch must be set to "1".  Set to Dual-clock operating mode, when R73, R72 pin use as clock generator.  Can be set, cleared, and tested for each bit as specified by L register indirect addressing bit manipulation instructions.	A/D converter analog input	
R63 ( $\overline{\text{PGO}}_2$ )	I/O (Output)		PPG2 output	
R62 (PGI2)	I/O (Input)		PPG2 external trigger input	
R61 ( $\overline{\text{PGO}}_1$ )	I/O (Output)		PPG1 output	
R60 (PGI1)	I/O (Input)		PPG1 external trigger input	
R73 (XTOUT)	I/O (Output)		Resonator connecting pin (Low-freq.). For inputting external clock, XTIN is used and XTOUT is opened.	
R72 (XTIN)	I/O (Input)			
R71 ( $\overline{\text{WTO}}$ )	I/O (Output)			Watchdog timer output
R70	I/O			
R83 (T1)	I/O (Input)		4-bit I/O port with latch. When using as input port, external interrupt input pin, or timer/counter external input pin, the latch must be set to "1".	Timer/Counter 1 external input
R82 ( $\overline{\text{INT}}_1$ )		External interrupt 1 input		
R81 (T2)		Timer/Counter 2 external input		
R80 ( $\overline{\text{INT}}_2$ )		External interrupt 2 or REMO-CON input		
R92 ( $\overline{\text{SCK}}$ )	I/O (I/O)	3-bit I/O port with latch. When using as input port or serial port, the latch must be set to "1".	Serial clock I/O	
R91 (SO)	I/O (Output)		Serial data output	
R90 (SI)	I/O (Input)		Serial data input	
P02 - P00	Output	3-bit high breakdown voltage output port with latch		
R13 - R10	I/O	4-bit high breakdown voltage I/O port with latch.		
R23 - R20		8-bit data are output by the 5-bit to 8-bit data conversion instruction [OUTB @HL]. When using as input port, the latch must be cleared to "0".		
R33 - R30	I/O	4-bit high breakdown voltage I/O port with latch.		
RA3 - RA0		When using as input port, the latch must be cleared to "0".		
RB3 - RB0				
RC3 - RC0				
XIN, XOUT	Input, Output	Resonator connecting pin (High-frequency). For inputting external clock, XIN is used and XOUT is opened.		
RESET	Input	Reset signal input		
HOLD ( $\overline{\text{KE}}_0$ )	Input (Input)	Hold request/release signal input	Sence input	
TEST	Input	Test pin for out-going test. Be opened or fixed to low level.		
VDD, VSS	Power supply	+ 5V, 0V (GND)		
VAREF, VASS		A/D converter analog reference voltage		
VKK		VFT drive power supply		

## OPERATIONAL DESCRIPTION

Concerning the 47C662/862, the hardware configuration and operation are described.

As the description include mainly differences from the 47C660/860, the technical data sheets for the 47C660/860 shall also be referred to.

### 1. SYSTEM CONFIGURATION

- (1) I/O Ports
- (2) Programmable Pulse Generator

### 2. PERIPHERAL HARDWARE FUNCTION

#### 2.1 I/O Ports

47C662/862 have 15 I/O ports (55pins) each as follows:

- ① K0 ; 4-bit input
- ② P0 ; 3-bit output
- ③ R1, R2 ; 4-bit input/output
- ④ R4, R5 ; 4-bit input/output (shared with A/D converter analog inputs)
- ⑤ R6 ; 4-bit input/output (shared with programmable pulse generator I/O)
- ⑥ R7 ; 4-bit input/output (shared with the low-frequency resonator connecting pins and the watchdog timer output)
- ⑦ R8 ; 4-bit input/output (shared with external interrupt request input and timer/counter input)
- ⑧ R9 ; 3-bit input/output (shared with serial port)
- ⑨ R3, RA, RB, RC ; 4-bit input/output
- ⑩ KE ; 1-bit sense input (shared with hold request/release signal input)

This section describes ports of ②, ③, ⑤ and ⑨ which are changed from the 47C660/860.

Table 2-1 lists the port address assignments and the I/O instructions that can access the ports.

#### (1) Ports P0 (P03-P00)

Ports P0 is 3-bit high breakdown voltage output ports with latch. The latch is initialized to "0" during reset.

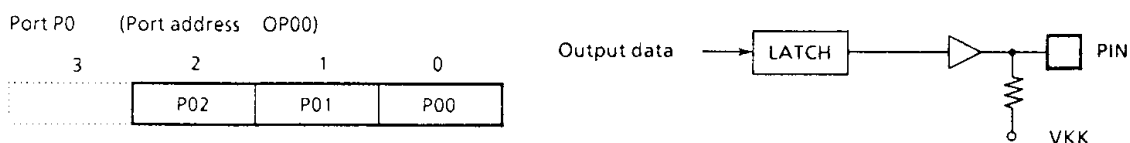


Figure 2-1. Ports P0

#### (2) Ports R1 (R13~R10), R2 (R23~R20)

The 4-bit high breakdown voltage I/O ports with latch, which can directly Vacume Fuolrescent Tubes (VFT) . The latch should be cleared to "0" when used as an ininput port. The latch is initialized to "0" during reset.

8-bit data can be output through ports R1 and R2 by using the 5-bit to 8-bit data conversion instruction; therefore, ports can also be effectively utilized as segment output pins.

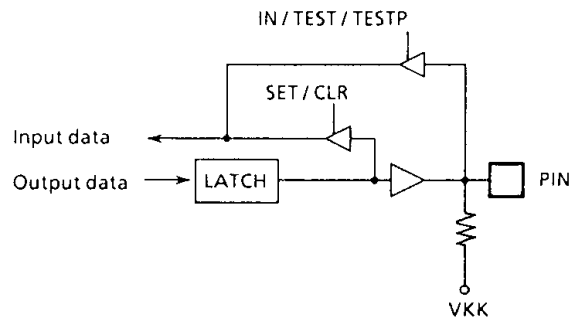
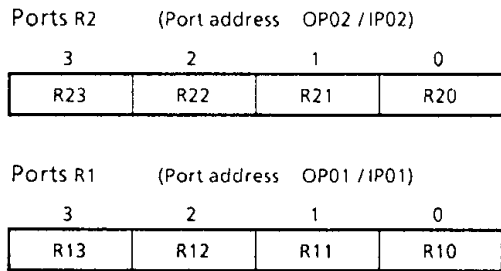


Figure 2-2. Ports R1, R2

(3) Ports R3 (R33~R30), RA (RA3~RA0), RB (RB3~RB0), RC (RC3~RC0)

The 4-bit high breakdown voltage I/O ports with latch, which can directly drive Vacume Fluorescent Tubes (VFT). The latch should be cleared to "0" when used as an input port. The latch is initialized to "0" during reset.

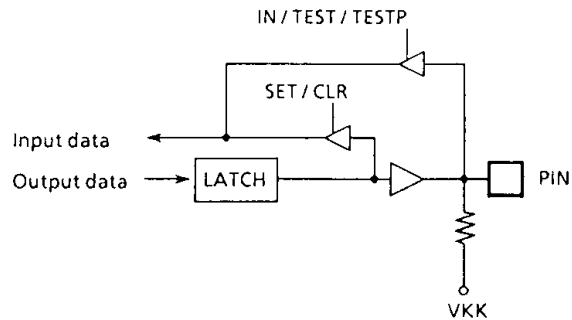
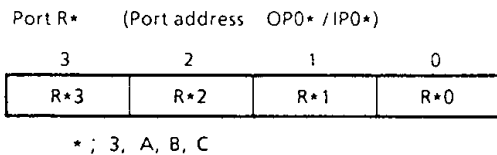


Figure2-3. Ports R3, RA, RB, RC

※ Connecting VKK (power supply for driving Vacume Fluorescent Tube) pin.

The 27 pins of the R1, R2, R3, RA, RB, RC and P0 ports are P-channel open drain construction with pulldown resistor. Each pin is connected to a VKK pin via a pulldown resistor (TYP. 80kΩ). Thus, Vacume Fluorescent Tubes (VFT) can be driven by applying a negative (-) voltage (-35V max) to the VKK pin, without using external resistor.

(4) Port R6 (R63~R60)

Port R6 is 4 bit I/O ports with latch shared with the PPG (programmable pulse generator) I/O ports. When used as an input ports or PPG I/O, the latch should be set to "1". The latch is initialized to "1" during reset.

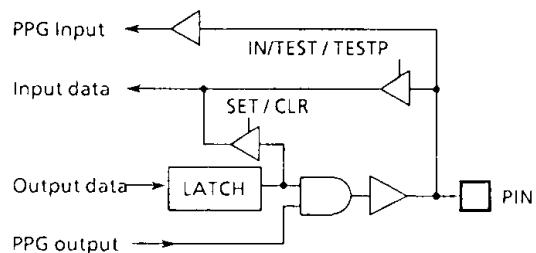
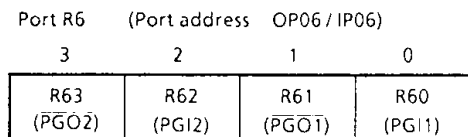


Figure 2-4. Port R6



## 2.2 Programmable Pulse Generator (PPG)

The 47C662/862 contains 2 channel pulse generators (PPG) available to set the output pulse delay and width independently with 12-bit resolution for each channel. One-shot or continuous pulse output can be selected and output pulse can be synchronized by external trigger input. PPG1 outputs to the  $\overline{PG01}$  pin and PPG2 outputs to the  $\overline{PG02}$  pin. External triggers are input to pins PGI1 and PGI2. Pins PGI1 and PGI2 can also be used as normal input/output ports in the internal clock mode.

### 2.2.1 Circuit configuration

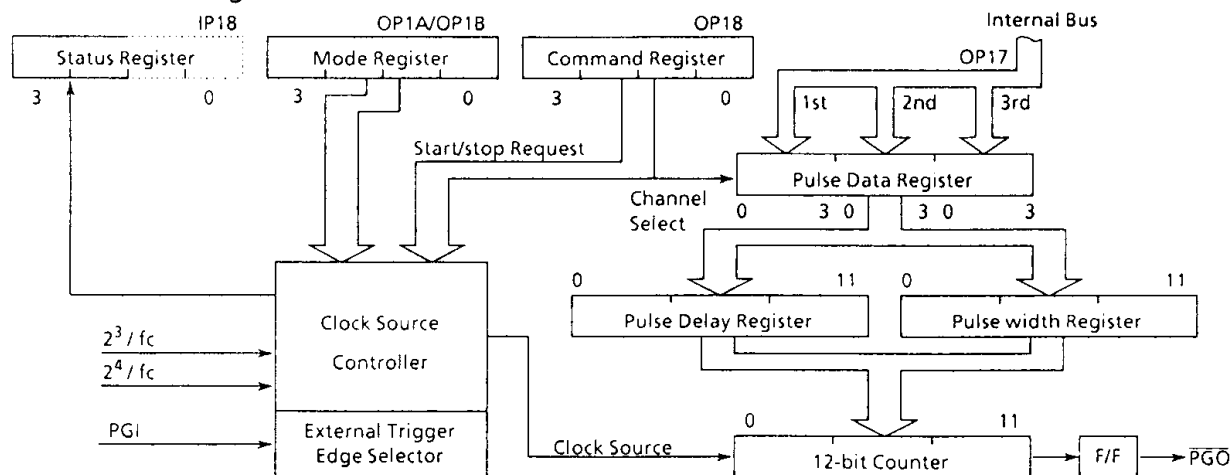


Figure 2-5. Programmable Pulse Generator (2 channels)

### 2.2.2 PPG Control

PPG is controlled by the data register (OP17), command register (OP18), mode registers (OP1A, OP1B) and status register (IP18).

#### (1) Pulse data register

Both PPG1 and PPG2 have a pulse delay register (PDR) and pulse width register (PWR) to which values set to the pulse data register (OP17) are transferred. The pulse data register is set by accessing OP17 three times: the lower 4 bits the first time, the middle 4 bits the second time and the higher 4 bits the last time. Any attempt to access OP17 four or more times is ignored. These pulse data are transferred to PDR and PWR by accessing the command register (OP18). The data transferred to PDR and PWR are alternately preset as 12-bit count preset data by 12-bit counter overflows; therefore, any output pulse width can be set at either "H" level or "L" level.

Example : Set PPG1 and PPG2 to the operating mode and set the value read from the RAM in the pulse data register and start both operating at the same time.

Main routine		Subroutine (writing pulse data)	
LD	A, #1111B	PDW :	PWW :
OUT	A, %OP1A	:	:
LD	A, #0000B	; DELAY DATA SET	
OUT	A, %OP1B	LD	HL, #20H
CALL	PDW	OUT	@HL, %OP17
LD	A, #1100B	INC	L
OUT	A, %OP18	OUT	@HL, %OP17
CALL	PWW	INC	L
LD	A, #1101B	OUT	@HL, %OP17
OUT	A, %OP18	:	:
LD	A, #1111B	:	:
OUT	A, %OP18	RET	RET

(2) PPG Command Register

The higher 2 bits of the command register (OP18) are used as the PPG1 and PPG2 selectors. The two channels of PPG can be controlled either simultaneously or independently by setting/clearing SPG1 and SPG2. Pulse data transfer requests and operating start/stop requests are accepted by setting "1" to SPG1 and SPG2. For example, PPG2 can be controlled without influencing PPG1 output by operating PPG1 and then clearing SPG1 to "0". Table 2-2 shows several examples of OP18 settings.

Note: pulse data transfer requests are disabled each time pulse data are transferred to PDR or PWR, so OP17 must be accessed each time. Transfer requests are accepted only after accessing OP17 three times, even when it is not necessary to change the middle and higher 4 bits.

OP18				Operation
MSB			LSB	
0	1	0	0	Data transfer to PDR of PPG1
1	1	0	1	Data transfer to PDR of PPG1 and 2 at the same time
1	0	1	1	Instruct output start PPG2 only
1	1	1	1	Instruct output start PPG1 and 2
0	1	1	0	Instruct output end PPG1 only

Table 2-2. Examples of OP18 settings

(3) PPG Mode Register

PPG1 is controlled by the OP1A mode register, PPG2 is controlled by the OP1B mode register, and each can be set independently.

A variety of pulses can be output by using different combinations of internal/external trigger and one-shot/continuous output.

a. Internal clock mode

Using the timing generator output as the count pulse, pulse output starts at the first rise after issuing a operation start request with command register (OP18). Only one cycle is output in the one-shot output mode and pulses are output until an operation stop request is accepted in the continuous output mode. Pulse output is started anew whenever an operation start request is accepted, even during pulse output.

PPG command register

(Port address : OP18 Initial value : 0000)

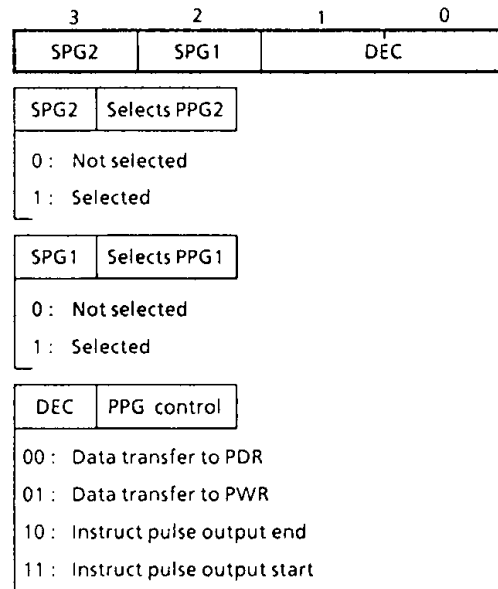
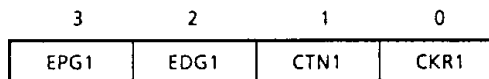


Figure 2-6. Command register

PPG1 mode register

(Port address : OP1A Initial value : 0000)



PPG2 mode register

(port address : OP1B Initial value : 0000)

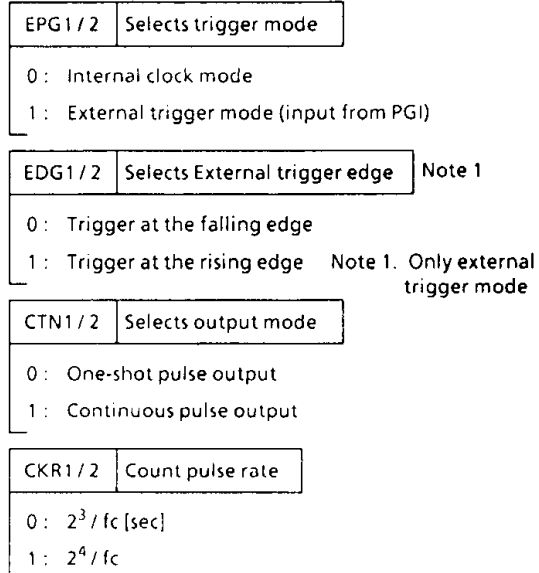
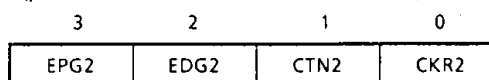


Figure 2-7. PPG mode register



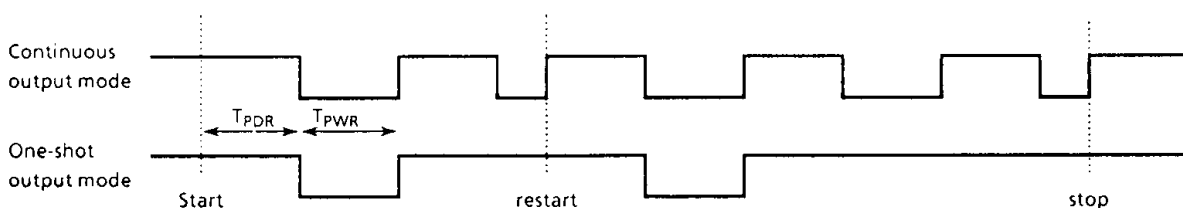


Figure 2-8. Internal clock mode

b. External trigger mode

The timing generator output is used as the count pulse and pulse output is synchronized with the external input (PGI). In the continuous mode, a pulse is output each time an external trigger edge is sensed. Trigger edges (rise or fall) can be selected with EDG of OP1A and OP1B.

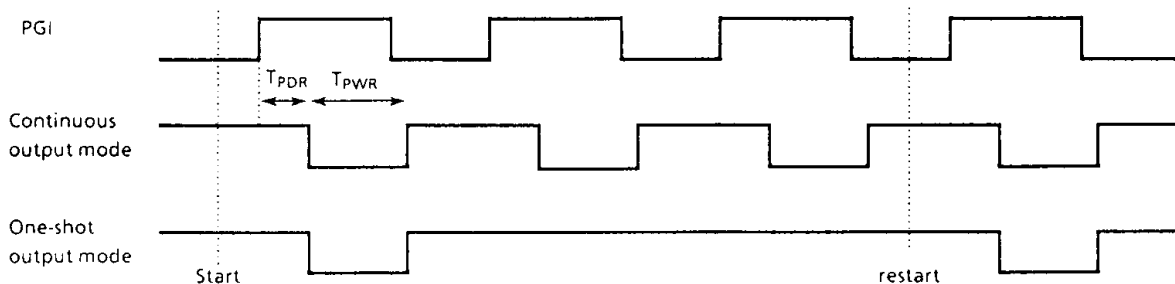


Figure 2-9. External trigger mode (at the rising edge)

c. Period of PPG output

The pulse width during "H" level output is determined by the PDR setting value and the pulse width during "L" level output is determined by the PWR setting value, as shown in Table 2-3; therefore, the basic period is  $T_{PDR} + T_{PWR}$  when  $T_{PDR}$  is "H" level width and  $T_{PWR}$  is "L" level width.

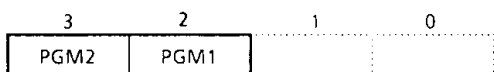
Count pulse rate	PDR, PWR setting value (HEX)	$T_{PDR}, T_{PWR} (n = 0 \sim 4095)$
$2^3 / f_c$ [sec]	0~FFF	$(4096 - n) \times (2^3 / f_c)$ [sec]
$2^4 / f_c$	0~FFF	$(4096 - n) \times (2^4 / f_c)$

Table 2-3. Output Pulse Width

(4) Operating status input

The PPG operating status can be monitored. "1" is read during pulse output by accessing IP18.

PPG status register  
(Port address: IP18)



PGM2	Monitors PPG2 output
0	Pulse output is terminated
1	Pulse output is in progress
PGM1	Monitors PPG1 output
0	Pulse output is terminated
1	Pulse output is in progress

Figure 2-10. PPG status register

ELECTRICAL CHARACTERISTICS

ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub> = 0V)

PARAMETER	SYMBOL	PINS	RATING	UNIT
Supply Voltage	V <sub>DD</sub>		- 0.5~7	V
Input Voltage	V <sub>IN</sub>		- 0.3~V <sub>DD</sub> + 0.3	V
Output Voltage	V <sub>OUT1</sub>	R7, XOUT	- 0.3~V <sub>DD</sub> + 0.3	V
	V <sub>OUT2</sub>	P0~P2, R6, R8, R9	- 0.3~10	
	V <sub>OUT3</sub>	Source open drain pin	- 35~V <sub>DD</sub> + 0.3	
Output Current (per 1 pin)	I <sub>OUT1</sub>	R6	30	mA
	I <sub>OUT2</sub>	R4, R5, R7-R9	3.2	
	I <sub>OUT3</sub>	P0, R1, R2	- 12	
	I <sub>OUT4</sub>	R3, RA, RB, RC	- 25	
Output Current (Total)	ΣI <sub>OUT1</sub>	R6	120	mA
	ΣI <sub>OUT4</sub>	R3, RA, RB, RC	- 100	
Power Dissipation [T <sub>opr</sub> = 70°C]	PD		600	mW
Soldering Temperature (time)	T <sub>slid</sub>		260 (10sec)	°C
Storage Temperature	T <sub>stg</sub>		- 55~125	°C
Operating Temperature	T <sub>opr</sub>		- 40~70	°C

RECOMMENDED OPERATING CONDITIONS

(V<sub>SS</sub> = 0V, T<sub>opr</sub> = - 40~70°C)

PARAMETER	SYMBOL	PINS	CONDITIONS	Min.	Max.	UNIT
Supply Voltage	V <sub>DD</sub>		In the Normal mode	4.5	6.0	V
			In the SLOW mode	2.7		
			In the HOLD mode	2.0		
Input High Voltage	V <sub>IH1</sub>	Except Hysteresis Input	V <sub>DD</sub> ≥ 4.5V	V <sub>DD</sub> × 0.7	V <sub>DD</sub>	V
	V <sub>IH2</sub>	Hysteresis Input		V <sub>DD</sub> × 0.75		
	V <sub>IH3</sub>		V <sub>DD</sub> < 4.5V	V <sub>DD</sub> × 0.9		
Input Low Voltage	V <sub>IL1</sub>	Except Hysteresis Input	V <sub>DD</sub> ≥ 4.5V	0	V <sub>DD</sub> × 0.3	V
	V <sub>IL2</sub>	Hysteresis Input			V <sub>DD</sub> × 0.25	
	V <sub>IL3</sub>		V <sub>DD</sub> < 4.5V	V <sub>DD</sub> × 0.1		
Clock Frequency	f <sub>c</sub>	XIN, XOUT		0.4	6.0	MHz
	f <sub>s</sub>	XTIN, XTOUT		30.0	34.0	KHz

Note. : Input voltage V<sub>IH3</sub>, V<sub>IL3</sub> : in the SLOW or HOLD mode

D.C. CHARACTERISTICS (V<sub>SS</sub> = 0V, T<sub>opr</sub> = -40~70°C)

PARAMETER	SYMBOL	PINS	CONDITIONS	Min.	Typ.	Max.	UNIT
Hysteresis Voltage	V <sub>HS</sub>	Hysteresis Input		—	0.7	—	V
Input Current	I <sub>IN1</sub>	K0, TEST, $\overline{\text{RESET}}$ , HOLD	V <sub>DD</sub> = 5.5V,	—	—	± 2	μA
	I <sub>IN2</sub>	R ports (open drain)	V <sub>IN</sub> = 5.5V / 0V				
Input Resistance	R <sub>IN1</sub>	K0 port with pull-up/pull-down		30	70	150	KΩ
	R <sub>IN2</sub>	$\overline{\text{RESET}}$		100	220	450	
Pull-down resistance	R <sub>K</sub>	source open drain	V <sub>DD</sub> = 5.5V, V <sub>KK</sub> = -30V	—	80	—	
Output Leakage Current	I <sub>LO1</sub>	sink open drain	V <sub>DD</sub> = 5.5V, V <sub>IN</sub> = 5.5V	—	—	2	μA
	I <sub>LO2</sub>	source open drain	V <sub>DD</sub> = 5.5V, V <sub>OUT</sub> = -32V	—	—	-2	
Output Level High Voltage	V <sub>OH</sub>	P0, R1, R2	V <sub>DD</sub> = 4.5V, I <sub>OH</sub> = -5mA	2.4	—	—	V
Output Level Low Voltage	V <sub>OL</sub>	R4, R5, R7-R9	V <sub>DD</sub> = 4.5V, I <sub>OL</sub> = 1.6mA	—	—	0.4	V
Output Level High Voltage	I <sub>OH</sub>	R3, RA, RB, RC	V <sub>DD</sub> = 4.5V, V <sub>OL</sub> = 2.4V	—	15	—	mA
Output Level Low Voltage	I <sub>OL</sub>	R6	V <sub>DD</sub> = 4.5V, V <sub>OL</sub> = 1.0V	—	20	—	mA
Supply Current (in the Normal mode)	I <sub>DD</sub>		V <sub>DD</sub> = 5.5V, f <sub>C</sub> = 4MHz	—	3	6	mA
Supply Current (in the SLOW mode)	I <sub>DDS</sub>		V <sub>DD</sub> = 3.0V, f <sub>S</sub> = 32.768KHz	—	30	60	μA
Supply Current (in the HOLD mode)	I <sub>DDH</sub>		V <sub>DD</sub> = 5.5V	—	0.5	10	μA

- Note 1. Typ. values show those at T<sub>opr</sub> = 25°C, V<sub>DD</sub> = 5V.
- Note 2. Input Current I<sub>IN1</sub> ; The current through resistor is not included, when the input resistor (pull-up/pull-down) is contained.
- Note 3. Supply Current I<sub>DD</sub>, I<sub>DDH</sub> ; V<sub>IN</sub> = 5.3V/0.2V  
The K0 port is open when the input resistor is contained. The voltage applied to the R port is within the valid range.
- Note 4. Supply Current I<sub>DDS</sub> ; V<sub>IN</sub> = 2.8V/0.2V  
Low frequency clock is only osillated (connecting XTIN, XTOUT).

A / D CONVERSION CHARACTERISTICS (T<sub>opr</sub> = -40 to 70°C)

PARAMETER	SYMBOL	CONDITIONS	Min.	Typ.	Max.	UNIT
Analog Reference Voltage	V <sub>AREF</sub>		V <sub>DD</sub> - 1.5	—	V <sub>DD</sub>	V
	V <sub>ASS</sub>		V <sub>SS</sub>	—	1.5	
Analog Reference Voltage Range	ΔV <sub>AREF</sub>	V <sub>AREF</sub> - V <sub>ASS</sub>	2.5	—	—	V
Analog Input Voltage	V <sub>AIN</sub>		V <sub>ASS</sub>	—	V <sub>AREF</sub>	V
Analog Supply Current	I <sub>REF</sub>		—	0.5	1.0	mA
Nonlinearity Error		V <sub>DD</sub> = 5.0V, V <sub>SS</sub> = 0.0V V <sub>AREF</sub> = 5.000V V <sub>ASS</sub> = 0.000V	—	—	± 1	LSB
Zero Point Error			—	—	± 1	
Full Scale Error			—	—	± 1	
Total Error			—	—	± 2	

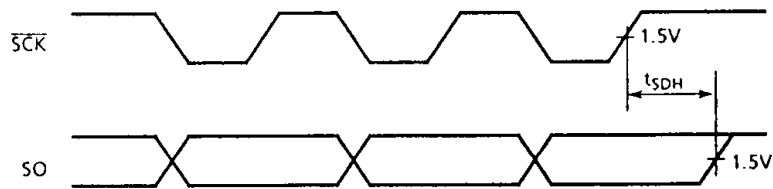
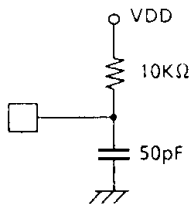
**A. C. CHARACTERISTICS** ( $V_{SS} = 0V, V_{DD} = 4.5 \text{ to } 6.0V, T_{opr} = -40 \text{ to } 70^\circ C$ )

PARAMETER	SYMBOL	CONDITIONS	Min.	Typ.	Max.	UNIT
Instruction Cycle Time	$t_{cy}$	In the Normal mode	1.9	—	20	ns
		In the SLOW mode	235	—	267	
High level Clock pulse Width	$t_{wCH}$	External clock mode	80	—	—	ns
Low level Clock pulse Width	$t_{wCL}$					
A / D Sampling Time	$t_{AIN}$	$f_c = 4MHz$	—	4	—	$\mu s$
Shift Data Hold Time	$t_{SDH}$		$0.5t_{cy} - 300$	—	—	ns

Note. Shift Data Hold Time

External circuit for  $\overline{SCK}$  pin and SO pin

Serial port (completion of transmission)



**RECOMMENDED OSCILLATING CONDITIONS**

( $V_{SS} = 0V, V_{DD} = 4.5 \text{ to } 6.0V, T_{opr} = -40 \text{ to } 70^\circ C$ )

(1) 6MHz

Ceramic Resonator

CSA6.00MGU

(MURATA)

$C_{XIN} = C_{XOUT} = 30pF$

KBR-6.00MS

(KYOCERA)

$C_{XIN} = C_{XOUT} = 30pF$

(2) 4MHz

Ceramic Resonator

CSA4.00MG

(MURATA)

$C_{XIN} = C_{XOUT} = 30pF$

KBR-4.00MS

(KYOCERA)

$C_{XIN} = C_{XOUT} = 30pF$

Crystal Oscillator

204B-6F 4.0000

(TOYOCOM)

$C_{XIN} = C_{XOUT} = 20pF$

(3) 400KHz

Ceramic Resonator

CSB400B

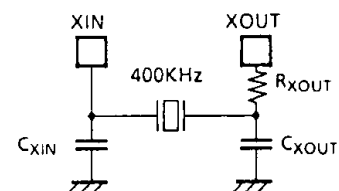
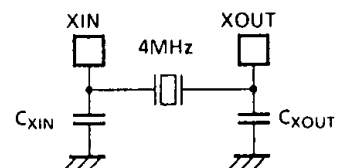
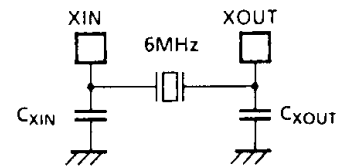
(MURATA)

$C_{XIN} = C_{XOUT} = 220pF, R_{XOUT} = 6.8K\Omega$

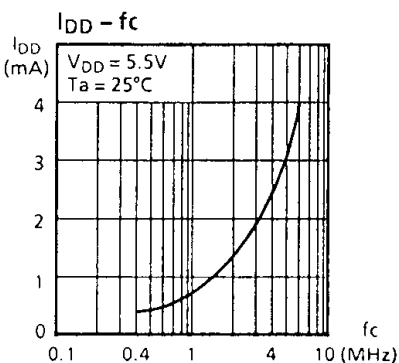
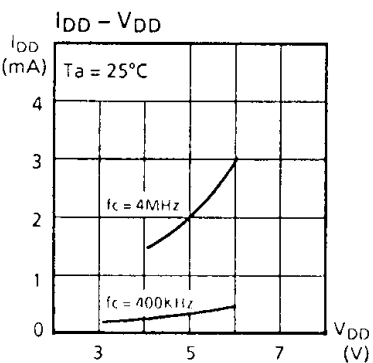
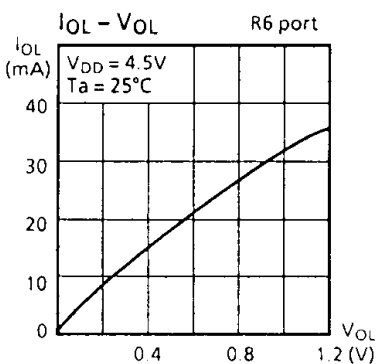
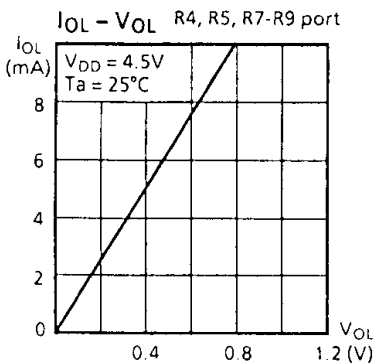
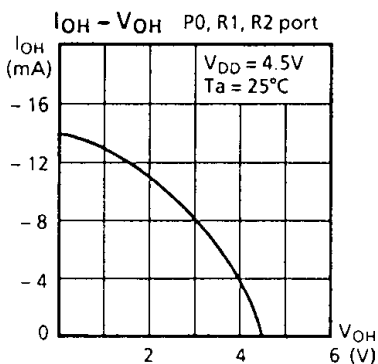
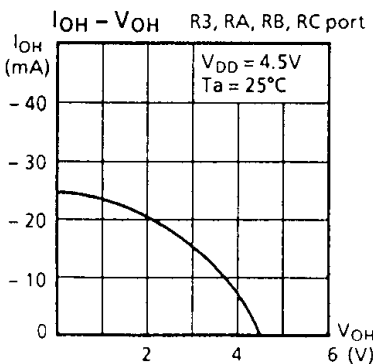
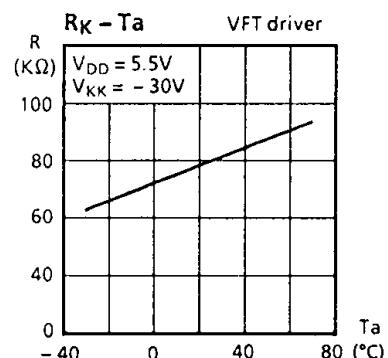
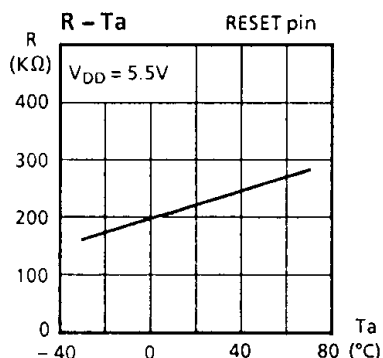
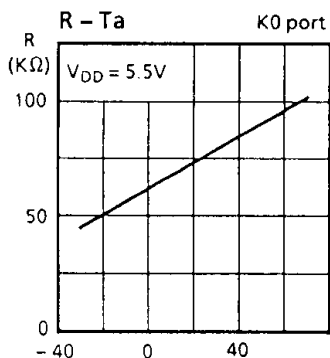
KBR-400B

(KYOCERA)

$C_{XIN} = C_{XOUT} = 100pF, R_{XOUT} = 10K\Omega$



TYPICAL CHARACTERISTICS



INPUT/OUTPUT CIRCUITRY

(1) Control pins

Input/Output circuitries of the 47C662/862 control pins are similar to the 47C660/860.

(2) I/O Ports

The input/output circuitries of the 47C662/862 I/O ports are shown as belows any one of the circuitries can be chosen by a code (IA~IC) by a code as a mast option.

PORT	I/O	INPUT/OUTPUT CIRCUIT (CODE)			REMARKS
		IA	IB	IC	
K0	Input				Contained pull-up/pull-down resistor $R_{IN} = 70K\Omega$ (typ.) $R = 1K\Omega$ (typ.)
P0	Output				Source open drain output Initial "Hi-Z" High voltage break down $R_K = 80K\Omega$ (typ.)
R1 R2 R3 RA RB RC	I/O				Source open drain output Initial "Hi-Z" High voltage break down $R_K = 80K\Omega$ (typ.) $R = 1K\Omega$ (typ.)
R4 R5	Output				Sink open drain output Initial "Hi-Z" $R = 1K\Omega$ (typ.) Analog input $R_A = 5K\Omega$ (typ.) $C_A = 12pF$ (typ.)
R7	I/O				Sink open drain output Initial "Hi-Z" $R = 1K\Omega$ (typ.)
R6 R8 R9	I/O				Sink open drain output Initial "Hi-Z" High current (R6) $I_{OL} = 20mA$ (typ.) Hysteresis input $R = 1K\Omega$ (typ.)