

SHINDENGEN

Stepping Motor Driver ICs

MTD Series

MTD2005

FEATURES

- Constant-current chopping function
(Frequency fixed, separate-oscillation)
- 2-phase input
(ENA input is useful for half step drive)
- Selectable slow/fast current decay for improved micro stepping
- A noise cancel function is provided
(No externally attached filter needed)
- Protection for penetration current
- Built-in thermal alarm
- Built-in flywheel diodes

RATINGS

● Absolute Maximum Ratings (Ta=25°C)

Item	Symbol	Ratings	Unit
Output Voltage	V _{CEO(SUS)}	60	V
Output Current	I _O	1.3	A
Logic Supply Voltage	V _{CC}	0~6	V
Logic Input Voltage	V _{IN}	0~V _{CC}	V
Total Power Dissipation	P _T	5	W
Junction Temperature	T _j	150	°C
Storage Temperature	T _{stg}	-40~150	°C

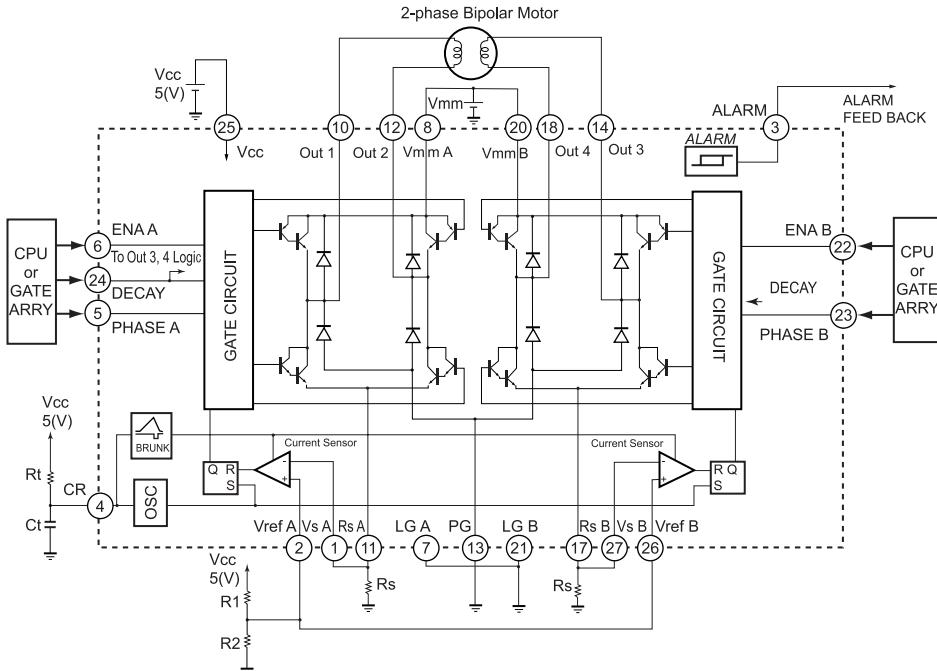
● Electrical Characteristics (Ta=25°C)

Item	Symbol	Test Conditions	min.	typ.	max.	Unit
Output Saturation Voltage(Upper side)	V _{CE} (sat)H	I _O =0.8A		1.0	1.4	V
Output Saturation Voltage(Lower side)	V _{CE} (sat)L	I _O =0.8A		1.0	1.4	V
Output Leakage Current(Upper side)	I _{rH}	V _{mm} =60V,V _{out} =0V		10	μ A	
Output Leakage Current(Lower side)	I _{rL}	V _{out} =60V,V _{RS} =0V		10	μ A	
Logic Supply Current(Standby)	I _{CC} (OFF)	V _{CC} =5V,V _{ENA} ="H"		19	26	mA
Logic Supply Current(All Circuit ON)	I _{CC} (ON)	V _{CC} =5V,V _{ENA} ="L"		25	33	mA
Phase "H"Input Voltage	V _{phaH}	V _{CC} = 5V	2.7		V _{CC}	V
Phase "L"Input Voltage	V _{phaL}	V _{CC} = 5V	GND	0.8		V
Phase "H"Input Current	I _{phaH}	V _{CC} = 5V,V _{pha} =5V		10	μ A	
Phase "L"Input Current	I _{phaL}	V _{CC} = 5V,V _{pha} =0V		-100	-150	μ A
Enable "H"Input Voltage	V _{ENAH}	V _{CC} =5V	2.7		V _{CC}	V
Enable "L"Input Voltage	V _{ENAL}	V _{CC} =5V	GND	0.8		V
Enable "H"Input Current	I _{ENAH}	V _{CC} =5V,V _{ENA} =5V		10	μ A	
Enable "L"Input Current	I _{ENAL}	V _{CC} =5V,V _{ENA} =0V		-100	-150	μ A
DECAY "H"Input Voltage	V _{DECH}	V _{CC} =5V	2.7		V _{CC}	V
DECAY "L"Input Voltage	V _{DECL}	V _{CC} =5V	GND	0.8		V
DECAY "H"Input Current	I _{DECH}	V _{CC} =5V,V _{DEC} =5V		10	μ A	
DECAY "L"Input Current	I _{DECL}	V _{CC} =5V,V _{DEC} =0V		-200	-300	μ A
Reference Input Current	I _{ref}	V _{CC} =5V,V _{ref} =0V	-1	-10	μ A	
Input Current(Current Sensor)	I _{sense}	V _{CC} =5V,V _s =0V	-1	-10	μ A	
Maximum Sensing Voltage	V _{S(max.)}	V _{CC} =5V		1.0		V
Pulse Blanking Time	t _b	V _{CC} =5V,C _t =3300pF		1.35		μ s
Thermal Alarm Cutoff Current	I _{ralm}	V _{CC} =5V,V _{alm} =5V		10	μ A	
Thermal Alarm Output Current	I _{alm}	V _{CC} =5V,V _{alm} =0.5V		2		mA
Thermal Alarm Temperature	T _{alm}			140		°C

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● Equivalent Circuit • Basic Application Circuit



● Pin Assignment

Pin 27	Vs B
Pin 26	Vref B
Pin 25	Vcc
Pin 24	Decay
Pin 23	Phase B
Pin 22	ENA B
Pin 21	LG B
Pin 20	Vmm B
Pin 19	NC
Pin 18	Out 4
Pin 17	Rs B
Pin 16	NC
Pin 15	NC
Pin 14	Out 3
Pin 13	PG
Pin 12	Out 2
Pin 11	Rs A
Pin 10	Out 1
Pin 9	NC
Pin 8	Vmm A
Pin 7	LG A
Pin 6	ENA A
Pin 5	Phase A
Pin 4	CR
Pin 3	ALARM
Pin 2	Vref A
Pin 1	Vs A

Package
ZIP-27

● True Table

ENA A or B	ENA A or B	Out 1 or 4	Out 2 or 3
L	L	L	H
L	H	H	L
H	x	OFF	OFF

x : don't care

● True Table for Current Decay

DECAY	Current Decay Mode
L	FAST (Sink+Source Chopping)
H	SLOW (Source Chopping)

● Setting of Output Current and Chopping Frequency

Fig.1 shows constant current chopping wave form.

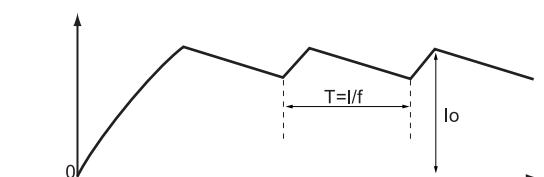
○ Output Current setting

$$I_o = \frac{R_2}{R_1 + R_2} \cdot \frac{V_{cc}}{R_s}$$

○ Chopping Frequency Setting

$$f = \frac{1}{0.72 \cdot C_t \cdot R_t}$$

Fig.1 Constant current wave form (Motor current / phase)



● Recommended Operating Conditions (Ta=25°C)

Item	Symbol	min.	typ.	max.	Unit
Motor Supply Voltage	Vmm			50	V
Output Current	I _o			1	A
Output Emitter Voltage	V _E			1	V
Logic Supply Voltage	V _{cc}	4.75		5.25	V
Chopping Frequency	f _{chop}		20		kHz
Operating Temperature	T _{op}	-25		120	°C