## 96-Bit AC-PDP DRIVER

The $\mu$ PD16334 is a high-voltage CMOS driver designed for flat display panels such as PDPs, VFDs and ELs. It consists of a 96-bit bi-directional shift register, 96-bit latch and high-voltage CMOS driver. The logic block is designed to operate using a 5-V power supply/3.3-V interface enabling direct connection to a gate array or a microcontroller. In addition, the $\mu$ PD16334 achieves low power dissipation by employing the CMOS structure while having a high withstand voltage output ( $80 \mathrm{~V}, 50 \mathrm{~mA}$ ).

## FEATURES

- Selectable by IBS pin; three 32-bit bi-directional shift register circuits configuration or six 16-bit bi-directional shift register circuits configuration
- Data control with transfer clock (external) and latch
- High-speed data transfer ( $f_{\max }=25 \mathrm{MHz} \min$. at data fetch)
( $f_{\text {max. }}=15 \mathrm{MHz} \mathrm{min}$. at cascade connection)
- High withstand output voltage ( $80 \mathrm{~V}, 50 \mathrm{mAmax}$.)
- 3.3 V CMOS input interface
- High withstand voltage CMOS structure
- Capable of reversing all driver outputs by $\overline{\mathrm{PC}}$ pin


## ORDERING INFORMATION

| Part Number | Package |
| :---: | :---: |
| $\mu$ PD16334 | COB $^{*}$ |

* Please consult with an NEC sales representative about COB.

BLOCK DIAGRAM (IBS = H, 3-BIT INPUT, 32-BIT LENGTH SHIFT REGISTER)


## BLOCK DIAGRAM (IBS = L, 6-BIT INPUT, 16-BIT LENGTH SHIFT REGISTER)



PIN DESCRIPTION

| Symbol | Pin Name | Description |
| :---: | :---: | :---: |
| $\overline{\mathrm{PC}}$ | Polarity change input | $\overline{\mathrm{PC}}=\mathrm{L}$ : All driver output invert |
| BLK | Blank input | BLK $=\mathrm{H}$ : All output $=\mathrm{H}$ or L |
| LE | Latch enable input | Automatically executes latch by setting high at rising edge of the clock |
| OE | Output enable | Make output high impedance by input H |
| $\mathrm{A}_{1}$ to $\mathrm{A}_{3}(6)$ | RIGHT data input/output (Note) | When $\mathrm{R} / \mathrm{L}=\mathrm{H}$ (values in parentheses are for 6-bit input) <br> $A_{1}$ to $A_{3(6)}$ : Input $B_{1}$ to $B_{3(6)}$ : Output |
| $B_{1}$ to $\mathrm{B}_{3}(6)$ | LEFT data input/output (Note) | When $R / \bar{L}=L$ (values in parentheses are for 6-bit input) <br> $A_{1}$ to $A_{3(6)}$ : Output $B_{1}$ to $B_{3(6)}$ : Input |
| $\overline{\text { CLK }}$ | Clock input | Shift executed on fall |
| R/L | Shift control input | Right shift mode when R/ $\bar{L}=\mathrm{H}$ <br> $\mathrm{SR}_{1}: \mathrm{A} 1 \rightarrow \mathrm{~S}_{1} \ldots \mathrm{~S}_{94} \rightarrow \mathrm{~B} 1$ (Same direction for $\mathrm{SR}_{2}$ to $\mathrm{SR}_{6}$ ) <br> Left shift mode when $R / \bar{L}=L$ <br> $\mathrm{SR}_{1}: \mathrm{B}_{1} \rightarrow \mathrm{~S}_{94} \ldots \mathrm{~S}_{1} \rightarrow \mathrm{~A}_{1}$ (Same direction for $\mathrm{SR}_{2}$ to $\mathrm{SR}_{6}$ ) |
| IBS | Input mode switch | H: 32-bit length shift register, 3-bit input <br> L: 16-bit length shift register, 6-bit input |
| O 1 to O96 | High withstand voltage output | $80 \mathrm{~V}, 50 \mathrm{mAmax}$. |
| VDD1 | Power supply for logic block | $5 \mathrm{~V} \pm 10$ \% |
| VDD2 | Power supply for driver block | 10 to 70 V |
| Vss1 | Logic GND | Connect to system GND |
| Vss2 | Driver GND | Connect to system GND |

Note When input mode is 3-bit, set unused input and output pins "L" level.
TRUTH TABLE 1 (Shift Register Block)

| Input |  | Output |  | Shift Register |
| :---: | :---: | :--- | :--- | :--- |
| R/ $\bar{L}$ | $\overline{\text { CLK }}$ | A | B |  |
| H | $\downarrow$ | Input | Output Note1 | Right shift execution |
|  | H | H or L |  | Output |
| L | $\downarrow$ | Output Note2 | Input | Left shift execution |
| L | H or L | Output |  | Hold |

Notes 1. The data of $S_{91}$ to $S_{93}\left(S_{85}\right.$ to $S_{90}$ ) shifts to $S_{94}$ to $S_{96}\left(S_{91}\right.$ to $S_{96}$ ) and is output from $B_{1}$ to $B_{3}\left(B_{1}\right.$ to $\left.B_{6}\right)$ at the falling edge of the clock, respectively. (Values in parentheses are for 6-bit input)
2. The data of $S_{4}$ to $S_{6}\left(S_{7}\right.$ to $\left.S_{12}\right)$ shifts to $S_{1}$ to $S_{3}\left(S_{1}\right.$ to $\left.S_{6}\right)$ and is output from $A_{1}$ to $A_{3}\left(A_{1}\right.$ to $\left.A_{6}\right)$ at the falling edge of the clock, respectively (Values in parentheses are for 6-bit input)

## TRUTH TABLE 2 (Latch Block)

| LE | $\overline{\text { CLK }}$ | Output State of Latch Block $\left(\overline{L_{n}}\right)$ |
| :---: | :---: | :--- |
| H | $\uparrow$ | Latch Sn data and hold output data |
|  | $\downarrow$ | Hold latch data |
| L | X | Hold latch data |

## TRUTH TABLE 3 (Driver Block)

| $\overline{L_{n}}$ | BLK | $\overline{\text { PC }}$ | OE | Output State of Driver Block |
| :--- | :---: | :---: | :---: | :--- |
| X | H | H | L | H (All driver outputs: H) |
| X | H | L | L | L (All driver outputs: L) |
| X | L | H | L | Output latch data $\left(\overline{\mathrm{L}_{n}}\right)$ |
| X | L | L | L | Output inverted latch data $\left(\overline{\mathrm{L}_{n}}\right)$ |
| X | X | X | H | Set output impedance high |

X: H or L, H: High level, L: Low level

TIMING CHART (WHEN IBS=" H ": 3-BIT INPUT, RIGHT SHIFT)
Values in parentheses in the following chart are when $R / \bar{L}=L$.


TIMING CHART (WHEN IBS="L": 6-BIT INPUT, RIGHT SHIFT)
Values in parentheses in the following chart are when $R / \bar{L}=L$.


ABSOLUTE MAXIMUM RATINGS ( $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{Vss} 1=\mathrm{Vss} 2=0 \mathrm{~V}$ )

| Parameter | Symbol | Ratings | Unit |
| :--- | :---: | :---: | :---: |
| Logic Block Supply Voltage | $\mathrm{V}_{\text {DD } 1}$ | -0.5 to +7.0 | V |
| Driver Block Supply Voltage | VDD 2 | -0.5 to +80 | V |
| Logic Block Input Voltage | VI | -0.5 to $\mathrm{VDD1}+0.5$ | V |
| Driver Block Output Current | lo 2 | 50 | mA |
| Junction Temperature | $\mathrm{T}_{\mathrm{j}}$ | +125 | ${ }^{\circ} \mathrm{C}$ |
| Storage Temperature | $\mathrm{T}_{\text {stg }}$ | -65 to +150 | ${ }^{\circ} \mathrm{C}$ |

RECOMMENDED OPERATING CONDITIONS ( $\mathrm{T}_{\mathrm{A}}=-\mathbf{4 0}$ to $+85^{\circ} \mathrm{C}, \mathrm{Vss} 1=\mathrm{Vss} 2=0 \mathrm{~V}$ )

| Parameter | Symbol | MIN. | TYP. | MAX. | Unit |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Logic Block Supply Voltage | VDD1 $^{\prime \prime}$ | 4.75 | 5.0 | 5.25 | V |
| Driver Block Supply Voltage | $\mathrm{V}_{\text {DD2 }}$ | 10 |  | 70 | V |
| High-Level Input Voltage | $\mathrm{V}_{\mathrm{IH}}$ | 2.7 |  | $\mathrm{~V}_{\text {DD1 }}$ | V |
| Low-Level Input Voltage | $\mathrm{V}_{\mathrm{IL}}$ | 0 |  | 0.6 | V |
| Driver Output Current | Іон2 |  |  | -40 | mA |
|  | loL2 |  |  | +40 | mA |

Caution In order to prevent latch-up breakage, be sure to enter the power to $\mathrm{V}_{\mathrm{DD} 1}$, logic signal and $\mathrm{V}_{\mathrm{DD}}$ in that order, and turn off the power in the reverse order, keep this order also during a transition period.


| Parameter | Symbol | Conditions | MIN. | TYP. | MAX. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| High-Level Output Voltage | Vон1 | Logic, $\mathrm{I}_{\text {OH1 }}=-1.0 \mathrm{~mA}$ | $0.9 \cdot \mathrm{VDD}^{1}$ |  | VDD1 | V |
| Low-Level Output Voltage | Vol1 | Logic, loL1 $=1.0 \mathrm{~mA}$ | 0 |  | $0.1 \mathrm{VDD1}$ | V |
| High-Level Output Voltage | Voh21 | $\mathrm{O}_{1}$ to $\mathrm{O}_{96}, \mathrm{loн}_{2}=-1 \mathrm{~mA}$ | 69 |  |  | V |
|  | VoH22 | $\mathrm{O}_{1}$ to $\mathrm{O}_{96}, \mathrm{Ioh2}^{2}=-10 \mathrm{~mA}$ | 65 |  |  | V |
| Low-Level Output Voltage | VoL21 | $\mathrm{O}_{1}$ to $\mathrm{O}_{96}, \mathrm{loL2}=5 \mathrm{~mA}$ |  |  | 1.0 | V |
|  | VoL22 | O1 to $\mathrm{O}_{96}, \mathrm{loL}_{2}=40 \mathrm{~mA}$ |  |  | 10 | V |
| Input Leakage Current | IIL | $\mathrm{V}_{1}=\mathrm{V}_{\text {DD } 1}$ or $\mathrm{V}_{\text {SS } 1}$ |  |  | $\pm 1.0$ | $\mu \mathrm{A}$ |
| High-Level Input Voltage | VIH | $V_{\text {DD } 1}=4.75$ to 5.25 V | 2.7 |  |  | V |
| Low-Level Input Voltage | VIL | $\mathrm{V}_{\mathrm{DD} 1}=4.75$ to 5.25 V |  |  | 0.6 | V |
| Static Current Dissipation | IdD1 | Logic, $\mathrm{T}_{\mathrm{A}}=-40$ to $+85^{\circ} \mathrm{C}$ |  |  | $10^{\text {Note }}$ | mA |
|  | IdD1 | Logic, $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ |  |  | $10^{\text {Note }}$ | mA |
|  | Ido2 | Driver, $\mathrm{T}_{\mathrm{A}}=-40$ to $+85^{\circ} \mathrm{C}$ |  |  | 1000 | $\mu \mathrm{A}$ |
|  | IdD2 | Driver, $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ |  |  | 100 | $\mu \mathrm{A}$ |

Note When all inputs are high-level ( $\mathrm{V}_{1 H}=2.7 \mathrm{~V}$ to $\mathrm{V}_{\mathrm{DD} 1}$, the $\mathrm{R} / \mathrm{L}$ and IBS pins are fixed to $\mathrm{V}_{\mathrm{I}}=\mathrm{V}_{S S 1}$ or $\mathrm{V}_{\mathrm{DD} 1}$ )

SWITCHING CHARACTERISTICS ( $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$, VDD1 $=5 \mathrm{~V}, \mathrm{~V}_{\mathrm{DD} 2}=70 \mathrm{~V}$, $\mathrm{V}_{\mathrm{SS} 1}=\mathrm{V}_{\mathrm{SS} 2}=0 \mathrm{~V}$, Logic $\mathrm{C}_{\mathrm{L}}=$ 15 pF , Driver $\mathrm{CL}=50 \mathrm{pF}, \mathrm{tr}=\mathrm{tt}=\mathbf{6 . 0} \mathrm{ns}$ )

| Parameter | Symbol | Conditions | MIN. | TYP. | MAX. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Transmission Delay time | tPHL1 | $\overline{\mathrm{CLK}} \downarrow \rightarrow \mathrm{A} / \mathrm{B}$ |  |  | 55 | ns |
|  | tPLH1 |  |  |  | 55 | ns |
|  | tphL2 | $\overline{\mathrm{CLK}} \uparrow(\mathrm{LE}=\mathrm{H}) \rightarrow \mathrm{O}_{1}$ to $\mathrm{O}_{96}$ |  |  | 180 | ns |
|  | tPLH2 |  |  |  | 180 | ns |
|  | tPHL3 | $\mathrm{BLK} \rightarrow \mathrm{O}_{1}$ to $\mathrm{O}_{96}$ |  |  | 165 | ns |
|  | tPLH3 |  |  |  | 165 | ns |
|  | tphl4 | $\overline{\mathrm{PC}} \rightarrow \mathrm{O}_{1}$ to $\mathrm{O}_{96}$ |  |  | 160 | ns |
|  | tPLH4 |  |  |  | 160 | ns |
|  | tPHz | $\begin{aligned} & \mathrm{OE} \rightarrow \mathrm{O}_{1} \text { to } \mathrm{O}_{96} \\ & \mathrm{RL}=10 \mathrm{~kL} \Omega \end{aligned}$ |  |  | 300 | ns |
|  | tpzH |  |  |  | 180 | ns |
|  | tplz |  |  |  | 300 | ns |
|  | tpzL |  |  |  | 180 | ns |
| Rise Time | tith | $\mathrm{O}_{1}$ to $\mathrm{O}_{96}$ |  |  | 150 | ns |
|  | ttız | $\begin{aligned} & \mathrm{RL}=10 \mathrm{k} \Omega \\ & \mathrm{O}_{1} \text { to } \mathrm{O}_{96} \end{aligned}$ |  |  | 3 | $\mu \mathrm{s}$ |
|  | tizH |  |  |  | 150 | ns |
| Fall Time | tтHL | $\mathrm{O}_{1}$ to $\mathrm{O}_{96}$ |  |  | 150 | ns |
|  | tThz | $\begin{aligned} & \mathrm{RL}=10 \mathrm{k} \Omega \\ & \mathrm{O}_{1} \text { to } \mathrm{O}_{96} \end{aligned}$ |  |  | 3 | $\mu \mathrm{s}$ |
|  | t tzL |  |  |  | 150 | ns |
| Maximum Clock Frequency | fmax | When data is read, duty $50 \%$ | 25 |  |  | MHz |
|  |  | cascade connection, Duty $50 \%$ | 15 |  |  | MHz |
| Input Capacitance | C। |  |  |  | 15 | pF |

TIMING REQUIREMENT ( $\mathrm{T}_{\mathrm{A}}=\mathbf{- 4 0}$ to $+85^{\circ} \mathrm{C}, \mathrm{VDD1}=4.75$ to $5.25 \mathrm{~V}, \mathrm{Vss} 1,2=0 \mathrm{~V}, \mathrm{tr}=\mathrm{tf}=6.0 \mathrm{~ns}$ )

| Parameter | Symbol | Conditions | MIN. | TYP. | MAX. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Clock Pulse Width | PWCLK |  | 20 |  |  | ns |
| Latch Enable Pulse Width | PWLE |  | 30 |  |  | ns |
| Blank Pulse Width | PWbıк |  | 200 |  |  | ns |
| $\overline{\text { PC Pulse Width }}$ | PW $\overline{\text { PC }}$ |  | 200 |  |  | ns |
| OE Pulse Width | PWoe | $\mathrm{RL}=10 \mathrm{k} \Omega$ | 3.3 |  |  | $\mu \mathrm{s}$ |
| Data Setup Time | tsetup |  | 10 |  |  | ns |
| Data Hold Time | thold |  | 10 |  |  | ns |
| Latch Enable Time 1 | tLE1 |  | 25 |  |  | ns |
| Latch Enable Time 2 | tLE2 |  | 5 |  |  | ns |
| Latch Enable Time 3 | tLe3 |  | 25 |  |  | ns |
| Latch Enable Time 4 | tLE 4 |  | 5 |  |  | ns |

## SWITCHING CHARACTERISTICS WAVEFORM



[MEMO]

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